

ROBOT-BASED SCRAPE COATING OPERATION METHOD AND DEVICE

ABSTRACT

5 Disclosed are a robot-based scrape coating operation method and device. A robot comprises a
robotic arm and a chassis. The method comprises: obtaining first path planning data, the first path
planning data being used for indicating the movement of the robot in an area for scrape coating; and
controlling the chassis of the robot to move according to the first path planning data, wherein when
the chassis of the robot moves according to the first path planning data, the robotic arm is controlled
10 to perform a scrape coating operation according to a preset motion trajectory.

FIG. 2 accompanies the abstract.