

ABSTRACT

The present disclosure relates to systems and methods for determining a driving path in autonomous driving. The systems may obtain a plurality of candidate driving paths; obtain one or more coefficients associated with the plurality of candidate driving paths based on a trained coefficient-generating model; determine a travel cost for each of the plurality of candidate driving paths based on the one or more coefficients; and identify a target driving path from the plurality of candidate driving paths based on a plurality of travel costs corresponding to the plurality of candidate driving paths.

(Fig. 4)