CLAIMS

1. A drug delivery device having a central axis, the drug delivery device comprising:
a first body part;
a first attachment part attached to the first body part and having a first distal end;
a second attachment part having a second distal end; and
an actuator mechanism configured to move the first distal end towards the second distal end.

2. Drug delivery device according to claim 1, the drug delivery device comprising a second body part, wherein the second attachment part is attached to the second body part, and the actuator mechanism is configured to rotate the first body part in relation to the second body part about a primary axis of the drug delivery device.

3. Drug delivery device according to claim 2, wherein the actuator mechanism comprises a resilient part configured to apply force to the first body part and/or the second body part.

4. Drug delivery device according to claim 3, wherein a first part of the resilient part is connected to the first body part and a second part of the resilient part is connected to the second body part.

5. Drug delivery device according to any of claims 1-4, wherein the first attachment part extends in a direction away from the first body part.

6. Drug delivery device according to any of claims 1-5 as dependent on claim 2, wherein the second attachment part extends in a direction away from the second body part.

7. Drug delivery device according to any of claims 1-6 as dependent on claim 2, wherein the first attachment part has a first attachment axis, and wherein a distance between the first attachment axis and the primary axis is larger than 0.5 mm.

8. Drug delivery device according to any of claims 1-7 as dependent on claim 2, wherein the second attachment part has a second attachment axis, and wherein a distance between the second attachment axis and the primary axis is larger than 0.5 mm.

9. Drug delivery according to any of claims 1-8 as dependent on claim 2, wherein the first body part is configured to rotate in a first direction and the second body part is configured to rotate in a second direction opposite to the first direction.

10. Drug delivery device according to any of claims 1-9, wherein the first distal end of the first attachment part and/or the second distal end of the second attachment part is provided with a tip configured to penetrate a biological tissue.

11. Drug delivery device according to any of claims 1-10, wherein the first distal end of the first attachment part and/or the second distal end of the second attachment part is provided with a gripping part configured to grip a biological tissue.

12. Drug delivery device according to any of claims 1-11, wherein the drug delivery device comprises a first compartment, the drug delivery device being configured to deliver an active drug substance from the first compartment to the surroundings of the drug delivery device.

13. Drug delivery according to any of claims 1-12 as dependent on claim 2, wherein the first attachment part and the second attachment part form an angle when the first distal end and the second distal end are in a plane that includes the primary axis.

14. Drug delivery device according to any of claims 1-13 as dependent on claim 2, wherein the drug delivery device has a first state where the first body part and the second body part are rotationally stationary relative to each other and a second state where the first body part and the second body part are rotationally mobile relative to each other.

15. Drug delivery device according to any of claims 1-14 as dependent on claim 3, wherein the drug delivery device has a first state where the resilient part has a constant resilient force load and a second state where the resilient part at least partly releases the resilient force load.

16. Drug delivery device according to any of claims 1-15, wherein the actuator mechanism is configured to move the first distal end from a first primary position with a first primary radial distance from the central axis of the delivery device to a first secondary position

with a first secondary radial distance from the central axis, wherein the first secondary radial distance is larger than the first primary radial distance.

17. Drug delivery device according to any of claims 1-16, wherein the actuator mechanism is configured to move the first distal end from a first primary angular position of first primary position to a first secondary angular position of first secondary position in relation to a first proximal end of the first attachment part, wherein an angle between the first primary angular position and the first secondary angular position is larger than 10 degrees.

18. Drug delivery device according to any of the preceding claims, wherein the drug delivery device comprises a locking mechanism configured to lock the first body part in relation to the second body part in a first state of the drug delivery device.

19. Drug delivery device according to claim 18, wherein the locking mechanism is configured to lock the first attachment part in a first primary position when the drug delivery device is in the first state.

20. Drug delivery device according to any of claim 1-19 as dependent on claim 2, wherein the first attachment part is rotationally attached to the first body part and configured to rotate about a first rotation axis perpendicular or parallel to the primary axis.

21. Drug delivery device according to any of claims 1-20 as dependent on claim 2, wherein the second attachment part is rotationally attached to the second body part and configured to rotate about a second rotation axis perpendicular or parallel to the primary axis.

22. Pharmaceutical composition comprising a drug delivery device according to any of claims 1-20 and an active drug substance.