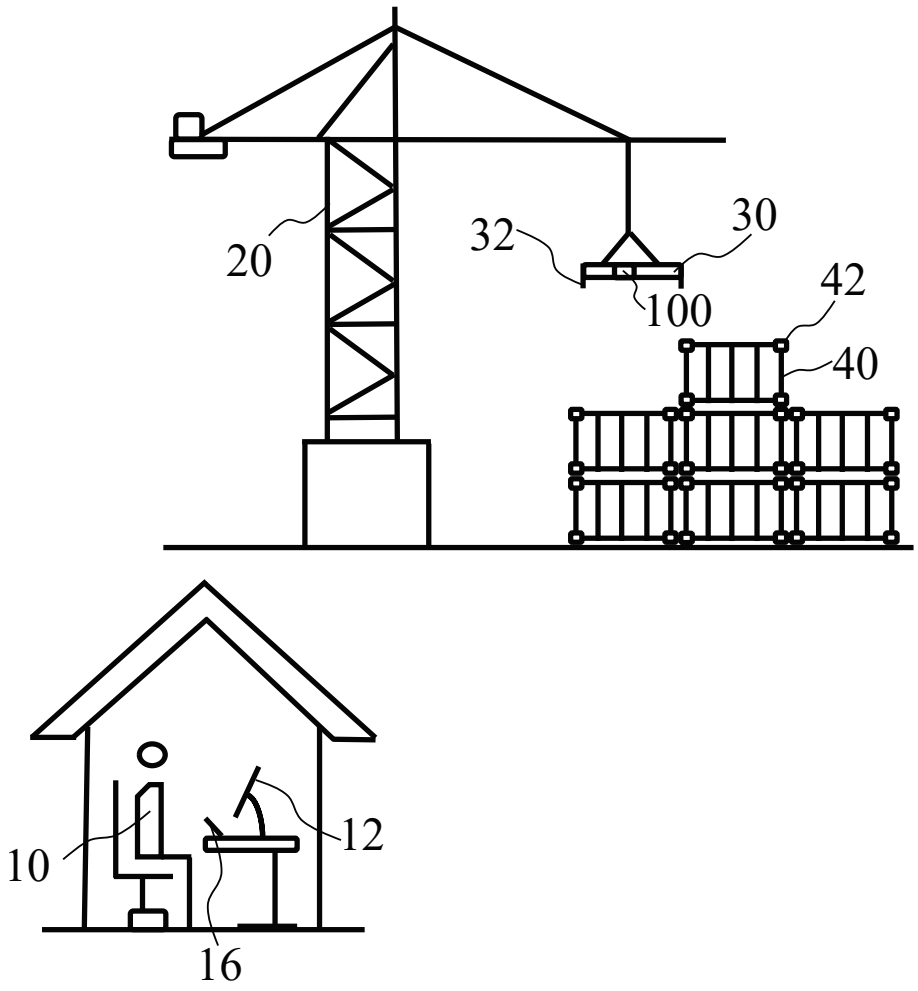


FIG. 1

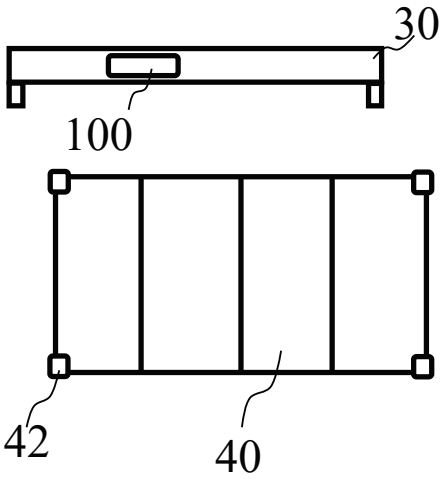


FIG. 2

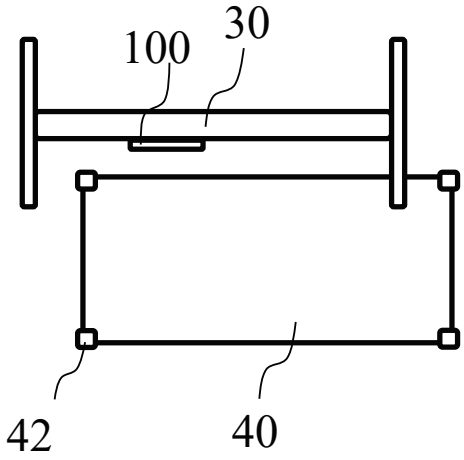


FIG. 3

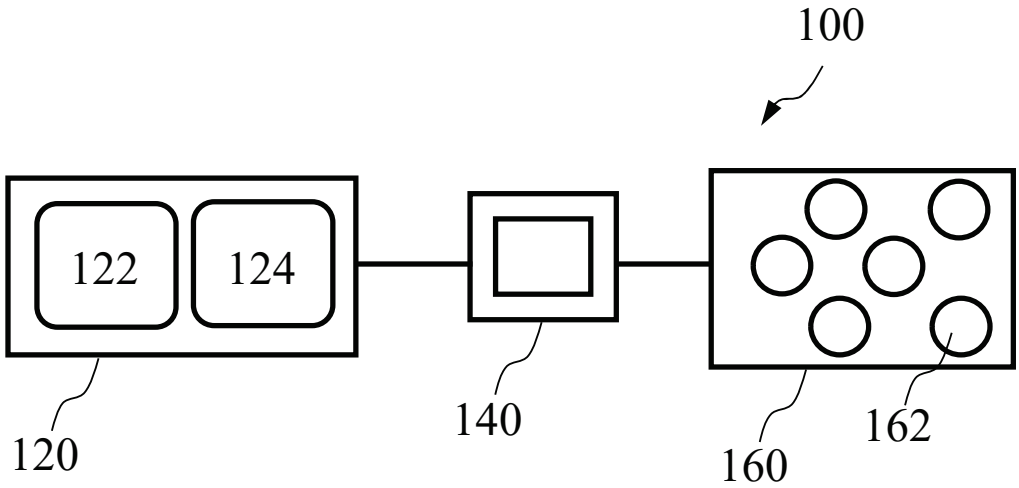


FIG. 4

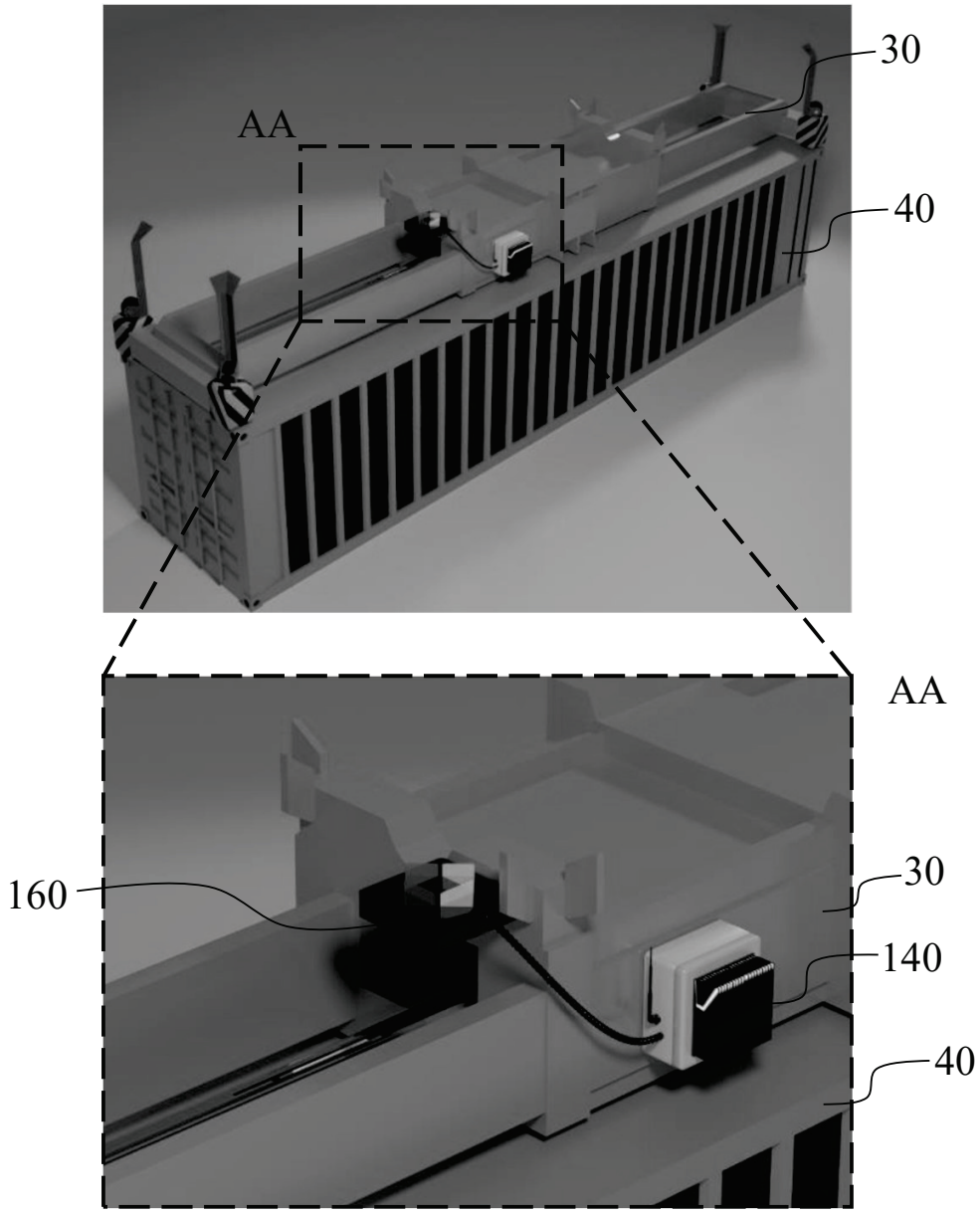


FIG. 5

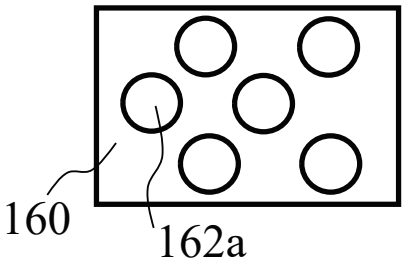


FIG. 6A

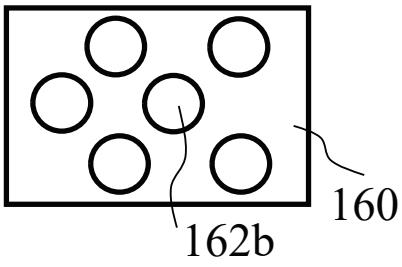


FIG. 6B

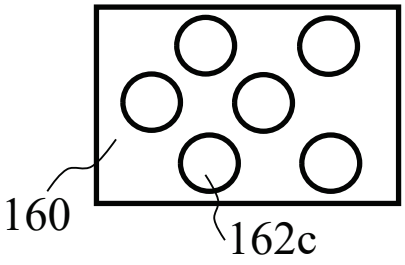


FIG. 6C

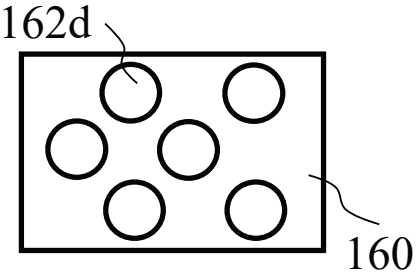


FIG. 6D

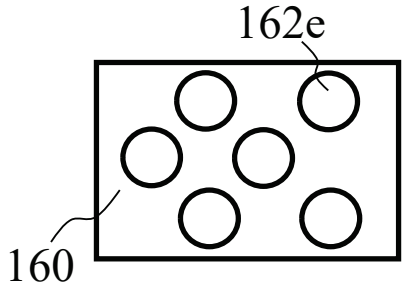


FIG. 6E

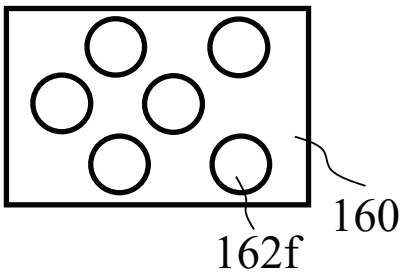


FIG. 6F

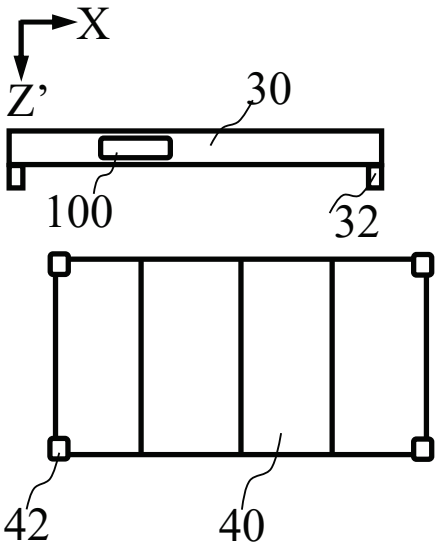


FIG. 7A

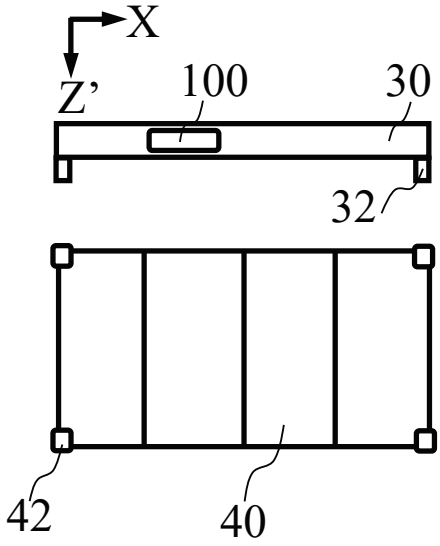


FIG. 7D

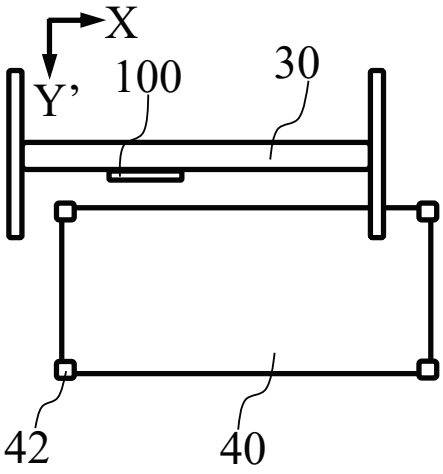


FIG. 7B

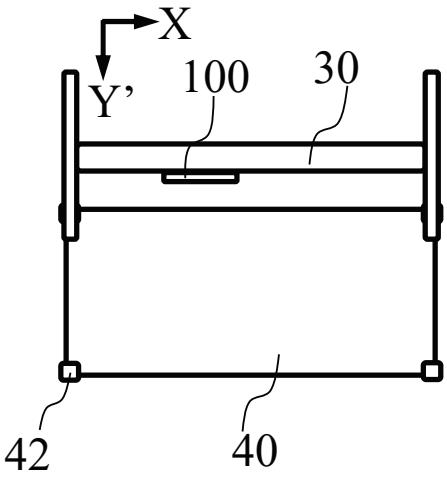


FIG. 7E

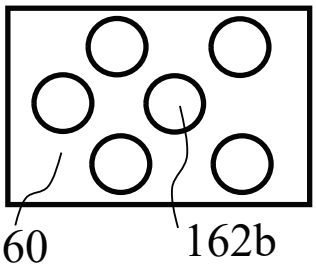


FIG. 7C

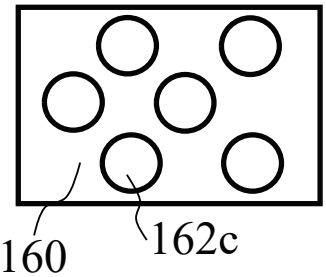


FIG. 7F

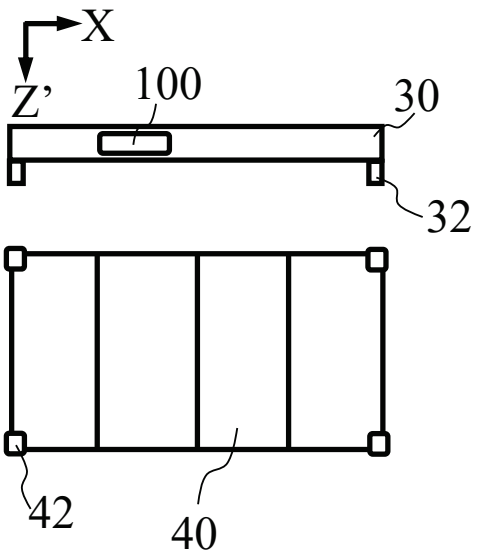


FIG. 7G

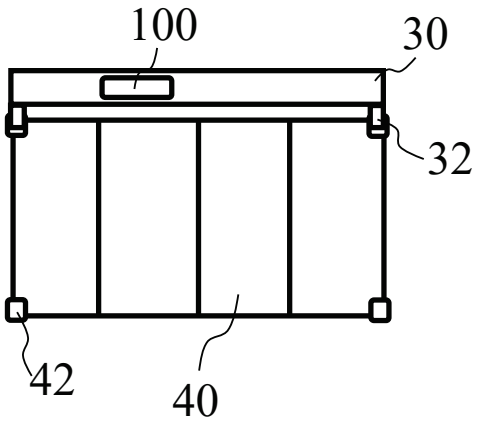


FIG. 7J

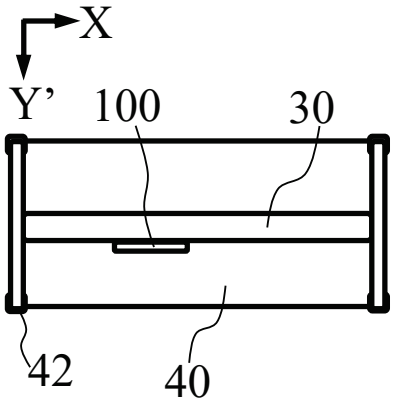


FIG. 7H

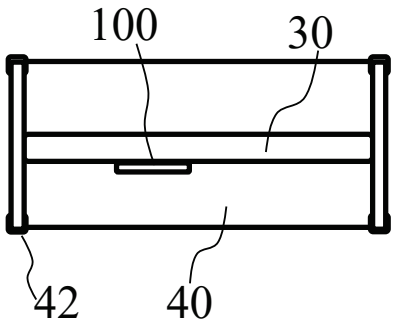


FIG. 7K

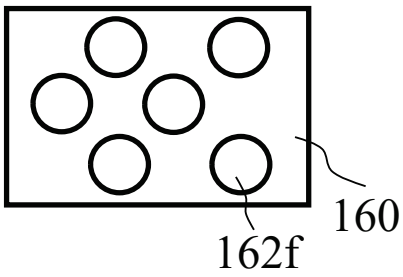


FIG. 7I

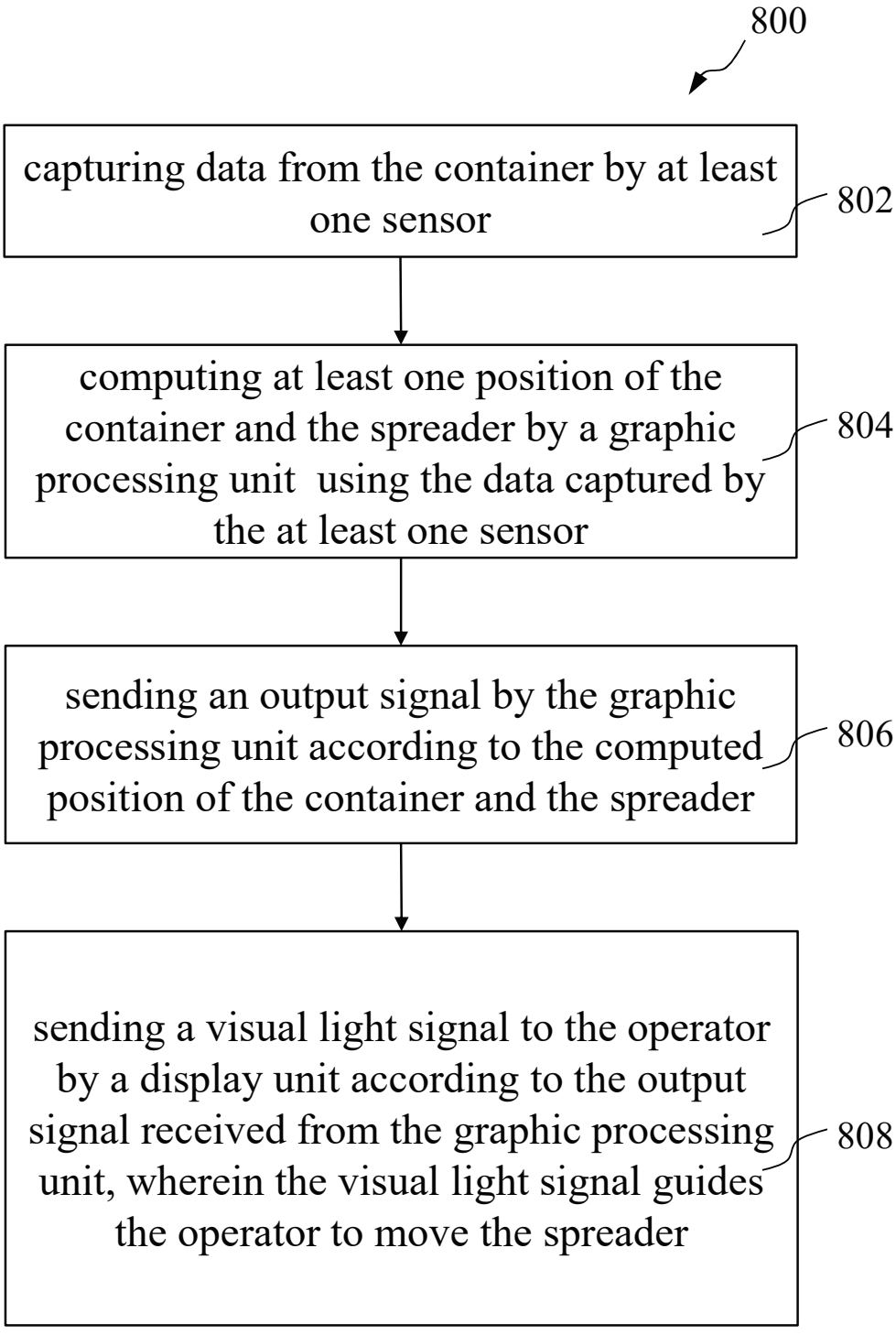

800
capturing data from the container by at least one sensor
802
computing at least one position of the container and the spreader by a graphic processing unit using the data captured by the at least one sensor
804
sending an output signal by the graphic processing unit according to the computed position of the container and the spreader
806
sending a visual light signal to the operator by a display unit according to the output signal received from the graphic processing unit, wherein the visual light signal guides the operator to move the spreader
808

FIG. 8