

Description

BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates to a connector for an electric part for moving a moving plate in the horizontal direction along the upper surface of a connector body in order to realize a contacted state and a released state, and particularly to a moving mechanism of the moving plate.

2. Brief Description of the Prior Art

Japanese Utility Model Early Laid-open Publication No. Sho 57-115388 discloses a connector for an electric part comprising a connector body, a moving plate, pins disposed in projecting in vertical relation from both side surfaces of the moving plate and the connector body and adapted as means for moving the moving plate in the horizontal direction along the upper surface of the connector body in order to realize a contacted state and a released state, a U-shaped groove formed in an end portion of an operating lever and adapted to removably receiving the pins therein, the operating lever being uprighted astride the connector body while removably catching the pins in the U-shaped groove, and the pins disposed on the side of the movable plate and snugly fitted in the U-shaped groove being exerted a lateral force when the lever is pivoted rightward or leftward from its state uprighted astride the connector body, thereby to realize the contacted state and the released state.

Another connector of this type is disclosed in Japanese Patent Publication No. Sho 60-52547, in which a crank lever is pivotably mounted on one end of the overlapped portion between a moving plate and a connector body, and an eccentric shaft portion disposed on a crank shaft portion, the crank lever being pivoted to cause the eccentric shaft portion to act on the moving plate, thereby to realize the contacted state and the released state.

In the former, however, the operating lever uprighted astride the connector body became an obstacle for an electric part such as IC when the electric part is attached to and removed from the connector. Therefore, it had not only such an inconvenience as that the lever must be mounted on and removed from the connector body every time the moving plate is operated to move or every time the IC is attached to and removed from the connector body, but also had such trouble as that the lever must be kept always.

Furthermore, as this conventional connector was designed such that the operating lever is pivoted rightwards or leftwards in order to moved the moving plate, there cannot be employed a method for realizing the pivotal operation of the operating lever by sim-

ply vertically moving a manipulator of a robot. Therefore, this connector was not suitable for automating the moving operation of the moving plate.

On the other hand, in the crank lever system disclosed in the latter, there were such problems as that the crank shaft portion disposed between the connector body and the moving plate is twisted to make it impossible to transmit the motion caused by its eccentric shaft portion and, as a result, moving distance of the moving plate becomes irregular and an unsatisfactory contacting relation is resulted.

Furthermore, it had the following problems. In order to obtain a sufficient moving distance of the moving plate, if bending is provided to make it possible to obtain a long eccentric distance of the eccentric shaft portion, the above-mentioned twist is increased. On the other hand, if the bending amount is reduced, the pivoting angle of the lever must be increased and if the pivoting angle is increased, the lever is brought to be in its uprighted state. As a result, like the preceding prior art, this cannot be operated by vertical motion using a robot, etc. and if an obstacle is present above the connector, operation becomes difficult.

Also, in any of the above-mentioned conventional contacts, the construction is such that a lateral force is exerted to one place of the moving plate, i.e., either one end or a central portion of the moving plate. Accordingly, there is such a fear as that one-sided force is exerted to the moving plate and a smooth and stable horizontal movement is unobtainable and the operation becomes heavy.

US-A-4,744,768 illustrates also a coupling connector of this type, having the features of the preamble of Claim 1.

SUMMARY OF THE INVENTION

It is therefore an object of the present invention to provide a connector for an electric part which is capable of stably moving a moving plate in the horizontal direction with a reduced force and without generating the above-mentioned problems, so that a proper contacted state and a released state can be obtained.

The invention provides a connector for an electric part, in accordance with Claim 1.

When the first and second operating levers are simultaneously pushed downward, a lateral force directing in the same direction is exerted to both end portions of the moving plate through the pair of transmission shafts, and the moving plate is stably and smoothly moved in the horizontal direction. As a result, a proper contacted state (or released state) can be obtained by the horizontal movement of the moving plate. On the contrary, in order to release the contacted state (or to realize the contacted state), the first and second operating levers are likewise simultaneously pushed upwards. As a result, a lateral force directing in the same direction is exerted to both end

portions of the moving plate by the pair of transmission shafts and the moving plate is stably and smoothly moved in the horizontal direction. By exerting the lateral force to the both end portions of the moving plate, the operation force can be reduced.

The above and other objects and characteristic features and advantages of the present invention will become more apparent to those skilled in the art as the disclosure is made in the following description of preferred embodiments of the invention, as illustrated in the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a plan view of a connector according to one embodiment of the present invention;

Figs. 2 and 3 are side views thereof, Fig. 2 is a view in which first and second operating levers are already pulled upward, and Fig. 3 is a view in which the levers are already pushed downwards;

Fig. 4A is a sectional view of the connector corresponding to Fig. 2;

Fig. 4B is a plan view showing the relation between a contact and a lead when the connector is in the state of Fig. 4A;

Fig. 5A is a sectional view of the connector corresponding to Fig. 3;

Fig. 5B is a plan view showing the relation between the contact and the lead when the connector is in the state of Fig. 5A;

Figs. 6 through 8 are several views showing another embodiment of the present invention;

Fig. 6A is a sectional view of a connector in which an operating lever is already pulled upwards;

Fig. 6B is a plan view showing the relation between a contact and a lead when the connector is in the state of Fig. 6A;

Fig. 7A is a sectional view of the connector in which the operating lever is already pushed downwards;

Fig. 7B is a plan view showing the relation between the contact and the lead when the connector is in the state of Fig. 7A;

Fig. 8A is a sectional view of the connector which is in a contacted state; and

Fig. 8B is a plan view showing the relation between the contact and the lead when the connector is in the state of Fig. 8A.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The preferred embodiments of the present invention will now be described with reference to Figs. 1 through 8.

The numeral 1 denotes a connector body for an electric part which is to be attached to a wiring board, etc. The connector body 1 has a moving plate 2 which

is moved along the upper surface thereof.

When the moving plate 2 is moved in one horizontal direction along the upper surface of the connector body 1, a contacted state is realized with respect to an electric part 3 such as IC, etc. placed on the connector body 1 through the moving plate 2, and when the moving plate 2 is moved in the other horizontal direction, the contacted state with respect to the electric part is released.

The illustrated connector is constructed as follows. the moving plate 2 is superposed on the upper surface of the square connector body 1 formed of an insulator material. The moving plate 2 is provided with a number of holes 5 arranged in a lattice shape consisting of vertical rows and lateral rows and allowing terminals of the electric part 3 to penetrate there-through. While placing the electric part 3 on the upper surface of the moving plate 2, the terminals 4 are thrust into the holes 5 and the leading ends of the terminals 4 are received in a contact accommodating chamber of the connector body 1 which is formed in such a manner as to correspond to the holes 5. Then, as is shown in Figs. 4 and 5, by moving the moving plate 2 in one horizontal direction, the terminals 4 caught in the holes 5 are brought to a contacted position (Fig. 5) from released position (Fig. 4) both with respect to normally closed contacts 12, and by moving the moving plate 2 in the other horizontal direction, the terminals 4 are brought to the released position (Fig. 4) from the contacted position (Fig. 5).

As is shown in Figs. 6 through 8, one contact element 12a of the contact 12 for pinching the terminal 4 of the electric part is placed on the moving plate 2 in its closed state, so that when the moving plate 2 is moved in one horizontal direction, the contact element 12a is displaced against its elasticity to open the contact and the restoring force of the contact element 12a is exerted to the moving plate 2 to move it in the other horizontal direction, and upon the horizontal movement of the moving plate 2 in the other direction, the contact 12 is closed and the terminal 4 of the electric part is pinched.

As for a means for moving the moving plate 2 in the horizontal direction, a first operating lever 6 and a second operating lever 7 are provided.

A lower portion of one end of the first operating lever 6 is pivotably supported on a side surface of one end of the connector body 1 by a supporting shaft 8 and an upper portion of the operating lever 6 is supported on a side surface of one end of the moving plate 2 by a transmission shaft 9. On the other hand, an upper portion of one end of the second operating lever 7 is pivotably supported on a side surface of the other end of the connector body 1 by a supporting shaft 10 and a lower portion of one end of the operating lever 7 is supported on a side surface of the other end of the moving plate 2.

The transmission shaft 9 is disposed such that

when the first operating lever 6 is pivoted about the supporting shaft 8, a lateral force directing in the same direction as the transmission shaft 11 is exerted to the one end of the moving plate 2. On the other hand, the transmission shaft is disposed such that when the second operating lever 7 is pivoted about the supporting shaft 10, a lateral force direction in the same direction as the transmission shaft 9 is exerted to the other end of the moving plate 2.

That is, the operating lever 6 and the second operating lever 7 are supported on the connector body 1 and the moving plate 2 such that the vertical arrangement of the supporting shaft 8 and transmission shaft 9 of the one end of the operating lever 6 and the vertical arrangement of the supporting shaft 10 and transmission shaft 11 of the second operating lever 7 are reversed with respect to each other.

This embodiment will be described in more detail with reference to the drawings. A pair of bearings 15 also acting as means for regulating corners of the electric part 3 are integrally provided to right and left corner portions of the one end of the moving plate 2, and both ends of the transmission shaft 9 are carried on the bearings 15. At the same time, a moving plate portion between the pair of bearings 15 are downed between a pair of bearings 16 formed on the right and left corner portions of the one end of the connector body 1 and a stopper 17 is formed by the downed portion, so that when the moving plate 2 is moved in the horizontal direction from the released position to the contacted position, the stopper 17 is brought into abutment engagement with one end face of a socket board to hold the contacted position as shown in Fig. 5A. The both ends of the supporting shaft 8 are carried on the bearing 16, the stopper 17 is formed with a hollow interior in order not to interfere with the supporting shaft 8, and the supporting shaft 8 is allowed to be laid long therein. Likewise, a pair of bearings 18 also acting as means for regulating the corners of the electric part 3 are integrally provided to right and left corner portions of the other end of the moving plate 2 and the other end of the connector body 1 is interposed between the inner side and outer side of the bearings 18. The interposed portion forms bearings 19 and a central portion and both ends of the supporting shaft 10 are carried on the bearings 19. At the same time, the bearings 18 are downed along the bearings 19 and both ends of the transmission shaft 11 are carried thereon.

The first operating lever 6 extends from the both pivotally supporting portions of the first operating lever 6 to the both pivotally supporting portions of the second operating lever 1 along the side surface of the connector body 1, and the free end of the first operating lever 6 is disposed to outside of the both pivotally supporting portions of the second operating lever 7, so that the lever 7 will be moved upward and downward on the side surface. Furthermore, the free

end of the lever 6 forms a push-down operating portion 6a to serve it as a force point. Likewise, the second operating lever 7 extends from the both pivotally supporting portions of the second operating lever 7 to the both pivotally supporting portions of the first operating lever 6 along the side surface of the connector body 1, and the free end of the second operating lever 7 is disposed to outside the both pivotally supporting portions of the first operating lever 6 so that the second operating lever 7 will be moved upward and downward on the side surface. Also, the free end of the second operating lever 7 forms a push-down operating portion 7a to serve it as a force point.

The first and second operating levers 6 and 7 are disposed in such a manner as to extend along opposite two side surfaces of the connector body 1, and the free end of the first operating lever 6 is connected by a connecting plate 13 and the free end of the second operating lever 7 is connected by the connecting plate 14. The connecting plates 13 and 14 extend along the other opposite side surfaces of the connector body 1.

The first and second operating levers 6 and 7 may be connected at the end portions on the side of the pivotally supporting portions.

Next, operation of the invention will be described with reference to Figs. 2 through 5.

First, when the push-down operating portion 6a of the first operating lever 6 and the push-down operating portion 7a of the second operating lever 7 are simultaneously pushed down from upper positions shown in Figs. 2 and 4A to lower positions shown in Figs. 3 and 5A, the first operating lever 6 is pivoted counterclockwise (downward) about the supporting shaft 8. In association with the foregoing movement, the transmission shaft 9 is pivoted counterclockwise about the supporting point. The afore-mentioned pivotal movement exerts a moving force from the right to the left in the drawings to the moving plate 2. On the other hand, the second operating lever 7 is pivoted clockwise (downward) about the supporting shaft 10. In association with the pivotal movement of the second operating lever 7, the transmission shaft 11 is pivoted clockwise about the supporting point. The foregoing pivotal movement exerts a moving force from the right to the left in the drawings to the moving plate 2 as in the case of the transmission shaft 9. As a result, the moving plate 2 is moved in one horizontal direction.

As a result, the terminals 4 of the electric part 3 placed on the moving plate 2 are horizontally moved from the released position to the contacted position with respect to the contacts 12, and as is shown in Fig. 4B, the normally closed contacts 12 are forcedly interposed by the terminals 4 while opening the contacts 12 against elasticity thereof, thereby to form a pinch-contacted state as shown in Fig. 5b.

On the other hand, when the push-down operat-

ing portion 6a of the first operating lever 6 and the push-down operating portion 7a of the second operating lever 7 are simultaneously pulled upward from lower positions shown in Figs. 3 and 5A to upper positions shown in Figs. 2 and 4A, the first operating lever 6 is pivoted clockwise (upward) about the supporting shaft 8. In association with the foregoing movement, the transmission shaft 9 is pivoted clockwise about the supporting point. The foregoing pivotal movement exerts a moving force from the left to the right in the drawings to the moving plate 2. Similarly, the second operating lever 11 is pivoted counterclockwise (upward) about the supporting shaft 10. In association with the foregoing movement, the transmission shaft 11 is pivoted counterclockwise about the supporting point. The foregoing pivotal movement exerts a moving force from the left to the right in the drawings to the moving plate 2 as in the case with the transmission shaft 9. As a result, the moving plate 2 is horizontally moved in the other direction.

As a result, the terminals 4 of the electric part 3 placed on the moving plate 2 are horizontally moved from a contacted position with respect to the contacts 12 to a released position shown in Fig. 4A. As a result, the terminals 4 are brought out of engagement with the contacts 12 as shown in Fig. 4B.

Another embodiment will be describe with respect to Figs. 6 through 8. As is shown in Figs. 6A and 6B, the electric part 3 is placed on the moving plate 2 and the terminals 4 are thrustured into the terminal insertion holes 5 formed in the moving plate 2, thereby to form a state where the leading ends of the terminals 4 are placed in the vicinity of the inlets of the contacts 12. In the foregoing state, when the push-down operating portion 6a of the first operating lever 6 and the push-down operating portion 7a of the second operating lever 7 are simultaneously pushed down from upper positions shown in Fig. 6A to lower positions shown in Fig. 7A, the moving plate 2 is horizontally moved from the right to the left in the drawings. In association with the foregoing movement, as is shown in Fig. 7B, one contact element 12a of the normally closed contact 12 engaged with a contact engaging portion 20 formed in an inner surface of the terminal insertion hole 5 of the moving plate 2 is opened against elasticity and the terminals 4 of the electric part 3 are guided between elastic elements of the contacts 12 in order to realize a loosely inserted state.

When the push-down force to the first and second operating levers 6 and 7 are canceled, the contact element 12a of the contact 12, as shown in Figs. 8A and 8B, is restored to the closing direction to elastically pinch the terminal 4 and at the same time, the restoring force of the contact element 12a is exerted to the engaging portion 20 of the moving plate 2 to automatically horizontally move the moving plate from the left to the right in the drawings.

The moving force (restoring force) to the moving

plate 2 is exerted to the transmission shafts 9 and 11. As a result, the first and second operating levers 6 and 7 are automatically restored from the lower position to the upper position along the side surface of the connector body 1, thereby to form a push-down waiting state.

As described in the foregoing, according to the present invention, by simultaneously pushing down or pulling upward the first and second operating levers, lateral force directing in the same direction is exerted to one and the other ends of the moving plate in order to reduce the operating force to exerted to the respective operating levers to a half, and an operating force exerted to the connector body can be divided into the both end portions of the connector body. As a result, while avoiding a stress concentration to the connector body and the wiring board supporting thereof, the moving plate can be smoothly and stably moved rightward or leftward with a reduced force, thereby to realize a proper and sure contacted state and released state.

Also, according to the present invention, such problems inherent in the prior art using a crank lever as means for operating the movement of the moving plate as twist of the crank shaft portion, irregularity of moving distance, and inferior contacted state can effectively solved. Furthermore, a sufficient moving distance can be obtained by a small push-down force, and a contacted position and released position can be properly obtained.

Moreover, the first and second operating levers are disposed long along the side surface of the connector body and are subjected to push-down operation or pull-up operation without jeopardizing the attaching and removing operation of the electric part. As the contacted state and released state can be achieved simply by means of the push-down or pull-up operation of the operating levers, this can be suitably used for automation using a robot, etc.

In addition, according to the present invention, according to conditions of use, either the first or the second operating lever may be selectively used to effect the horizontal movement of the moving plate by pushing down operation or pull-up operation of such selected operation lever.

Claims

1. A connector for an electric part including a connector body (1) for the connection with the electric part, and a moving plate (2) movably mounted on said connector body and able to move along the upper surface of said connector body, said moving plate (2), when moved in one direction, being brought into contact with the electric part and brought out of contact when moved in the other direction, said connector comprising an op-



ing portion 6a of the first operating lever 6 and the push-down operating portion 7a of the second operating lever 7 are simultaneously pulled upward from lower positions shown in Figs. 3 and 5A to upper positions shown in Figs. 2 and 4A, the first operating lever 6 is pivoted clockwise (upward) about the supporting shaft 8. In association with the foregoing movement, the transmission shaft 9 is pivoted clockwise about the supporting point. The foregoing pivotal movement exerts a moving force from the left to the right in the drawings to the moving plate 2. Similarly, the second operating lever 1 is pivoted counterclockwise (upward) about the supporting shaft 10. In association with the foregoing movement, the transmission shaft 11 is pivoted counterclockwise about the supporting point. The foregoing pivotal movement exerts a moving force from the left to the right in the drawings to the moving plate 2 as in the case with the transmission shaft 9. As a result, the moving plate 2 is horizontally moved in the other direction.

As a result, the terminals 4 of the electric part 3 placed on the moving plate 2 are horizontally moved from a contacted position with respect to the contacts 12 to a released position shown in Fig. 4A. As a result, the terminals 4 are brought out of engagement with the contacts 12 as shown in Fig. 4B.

Another embodiment will be describe with respect to Figs. 6 through 8. As is shown in Figs. 6A and 6B, the electric part 3 is placed on the moving plate 2 and the terminals 4 are thrust into the terminal insertion holes 5 formed in the moving plate 2, thereby to form a state where the leading ends of the terminals 4 are placed in the vicinity of the inlets of the contacts 12. In the foregoing state, when the push-down operating portion 6a of the first operating lever 6 and the push-down operating portion 7a of the second operating lever 7 are simultaneously pushed down from upper positions shown in Fig. 6A to lower positions shown in Fig. 7A, the moving plate 2 is horizontally moved from the right to the left in the drawings. In association with the foregoing movement, as is shown in Fig. 7B, one contact element 12a of the normally closed contact 12 engaged with a contact engaging portion 20 formed in an inner surface of the terminal insertion hole 5 of the moving plate 2 is opened against elasticity and the terminals 4 of the electric part 3 are guided between elastic elements of the contacts 12 in order to realize a loosely inserted state.

When the push-down force to the first and second operating levers 6 and 7 are canceled, the contact element 12a of the contact 12, as shown in Figs. 8A and 8B, is restored to the closing direction to elastically pinch the terminal 4 and at the same time, the restoring force of the contact element 12a is exerted to the engaging portion 20 of the moving plate 2 to automatically horizontally move the moving plate from the left to the right in the drawings.

The moving force (restoring force) to the moving

plate 2 is exerted to the transmission shafts 9 and 11. As a result, the first and second operating levers 6 and 7 are automatically restored from the lower position to the upper position along the side surface of the connector body 1, thereby to form a push-down waiting state.

As described in the foregoing, according to the present invention, by simultaneously pushing down or pulling upward the first and second operating levers, lateral force directing in the same direction is exerted to one and the other ends of the moving plate in order to reduce the operating force to exerted to the respective operating levers to a half, and an operating force exerted to the connector body can be divided into the both end portions of the connector body. As a result, while avoiding a stress concentration to the connector body and the wiring board supporting thereof, the moving plate can be smoothly and stably moved rightward or leftward with a reduced force, thereby to realize a proper and sure contacted state and released state.

Also, according to the present invention, such problems inherent in the prior art using a crank lever as means for operating the movement of the moving plate as twist of the crank shaft portion, irregularity of moving distance, and inferior contacted state can effectively solved. Furthermore, a sufficient moving distance can be obtained by a small push-down force, and a contacted position and released position can be properly obtained.

Moreover, the first and second operating levers are disposed long along the side surface of the connector body and are subjected to push-down operation or pull-up operation without jeopardizing the attaching and removing operation of the electric part. As the contacted state and released state can be achieved simply by means of the push-down or pull-up operation of the operating levers, this can be suitably used for automation using a robot, etc.

In addition, according to the present invention, according to conditions of use, either the first or the second operating lever may be selectively used to effect the horizontal movement of the moving plate by pushing down operation or pull-up operation of such selected operation lever.

Claims

1. A connector for an electric part including a connector body (1) for the connection with the electric part, and a moving plate (2) movably mounted on said connector body and able to move along the upper surface of said connector body, said moving plate (2), when moved in one direction, being brought into contact with the electric part and brought out of contact when moved in the other direction, said connector comprising an op-



erating lever (6) operable to move said moving plate (2) with respect of the connector body (1), one end of said operating lever (6) being pivotably supported on a side surface of one end of said connector body (1) through a supporting shaft (8) characterized by:

a second operating lever (7) pivotably supported on a side surface of the other end of said connector body (1) through a supporting shaft (10);

one end of said first-mentioned operating lever (6) being supported on a side surface of one end of said moving plate (2) through a transmission shaft (9) and one end of said second operating lever (7) also being supported on a side surface of the other end of said moving plate (2) through a transmission shaft (11) with said transmission shafts being so positioned in relation to the respective pivotal axes of said levers (6,7) to cause force directed in the same direction to be applied to both ends of said moving plate (2), when said first and second operating levers (6,7) are pivoted in opposite directions about said supporting shafts (8,10).

2. A connector for an electric part as claimed in Claim 1, wherein a free end of said first-mentioned lever (6) is disposed to an external side of the pivotally supporting portion of said second operation lever (7) and a free end of said second operating lever (7) is also disposed to an external side of the pivotally supporting portion of said first-mentioned operating lever (6).

Patentansprüche

1. Verbindungsglied für ein elektrisches Teil, das einen Verbindungskörper (1) für die Verbindung mit dem elektrischen Teil sowie eine bewegbare Platte (2) umfaßt, die bewegbar am genannten Verbindungskörper montiert ist und sich an der Oberfläche des genannten Verbindungskörpers entlang bewegen kann, wobei die genannte bewegbare Platte (2), wenn sie sich in eine Richtung bewegt, in Kontakt mit dem elektrischen Teil gebracht und, wenn sie sich in die andere Richtung bewegt, ihr Kontakt damit aufgehoben wird, wobei das genannte Verbindungsglied einen Betätigungshebel (6) umfaßt, mit dessen Hilfe die genannte bewegbare Platte (2) im Verhältnis zum Verbindungskörper (1) bewegt werden kann, und wobei ein Ende des genannten Betätigungshebels (6) an einer Seitenfläche des einen Endes des genannten Verbindungskörpers (1) schwenkbar über eine Stützwelle (8) abgestützt ist, gekennzeichnet durch:

einen zweiten Betätigungshebel (7), der

an einer Seitenfläche des anderen Endes des genannten Verbindungskörpers (1) schwenkbar über eine Stützwelle (10) abgestützt ist;

ein Ende des genannten ersterwähnten Betätigungshebels (6), das an einer Seitenfläche des einen Endes der genannten bewegbaren Platte (2) über eine Übertragungswelle (9) abgestützt ist, und ein Ende des genannten zweiten Betätigungshebels (7), das außerdem an einer Seitenfläche des anderen Endes der genannten bewegbaren Platte (2) über eine Übertragungswelle (11) abgestützt ist, wobei die genannten Übertragungswellen im Verhältnis zu den entsprechenden Schwenkachsen der genannten Hebel (6, 7) so angeordnet sind, daß in die gleiche Richtung ausgerichtete Kräfte auf die beiden Enden der genannten bewegbaren Platte (2) einwirken, wenn die genannten ersten und zweiten Betätigungshebel (6, 7) in entgegengesetzten Richtungen um die genannten Stützwellen (8, 10) geschwenkt werden.

2. Verbindungsglied für ein elektrisches Teil nach Anspruch 1, wobei ein freies Ende des genannten ersterwähnten Hebels (6) zu einer Außenseite des schwenkbar abstützenden Abschnittes des genannten zweiten Betätigungshebels (7) und außerdem ein freies Ende des genannten zweiten Betätigungshebels (7) zu einer Außenseite des schwenkbar abstützenden Abschnittes des genannten ersterwähnten Betätigungshebels (6) hin angeordnet sind.

Revendications

1. Un connecteur pour une pièce électrique comprenant un corps de connecteur (1) pour la connexion à la pièce électrique, et une plaque en mouvement (2) montée de façon mobile sur ledit corps de connecteur et capable de se déplacer le long de la surface supérieure dudit corps de connecteur, ladite plaque en mouvement (2), quand elle est déplacée dans une première direction, étant mise en contact avec la pièce électrique et le contact étant rompu quand elle est déplacée dans l'autre direction, ledit connecteur comprenant un levier de commande (6) actionnable pour déplacer ladite plaque mobile (2) par rapport au corps de connecteur (1), une extrémité dudit levier de commande (6) étant supportée de façon pivotante sur une surface latérale d'une première extrémité dudit corps de connecteur (1) par l'intermédiaire d'un arbre de support (8), caractérisé par :

un deuxième levier de commande (7) supporté de façon pivotante sur une surface latérale de l'autre extrémité dudit corps de connecteur (1)



par l'intermédiaire d'un arbre de support (10);

une extrémité dudit premier levier de commande mentionné (6) étant supportée sur une surface latérale d'une première extrémité de ladite plaque mobile (2) par l'intermédiaire d'un arbre de transmission (9) et une extrémité dudit deuxième levier de commande (7) étant aussi supportée sur une surface latérale de l'autre extrémité de ladite plaque mobile (2) par l'intermédiaire d'un arbre de transmission (11) avec lesdits arbres de transmission positionnés par rapport aux axes de pivotement respectifs desdits leviers (6, 7) de façon à créer une force dirigée dans la même direction s'exerçant aux deux extrémités de ladite plaque mobile (2), lorsque l'on fait pivoter lesdits premier et deuxième leviers (6, 7) dans des directions opposées autour desdits arbres de support (8, 10).

2. Un connecteur pour une pièce électrique suivant la revendication 1, dans lequel une extrémité libre dudit premier levier mentionné (6) est disposée vers un côté extérieur de la partie de support pivotant dudit deuxième levier de commande (7) et une extrémité libre dudit deuxième levier de commande (7) est aussi disposée vers un côté extérieur de la partie de support pivotant dudit premier levier de commande mentionné (6).

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