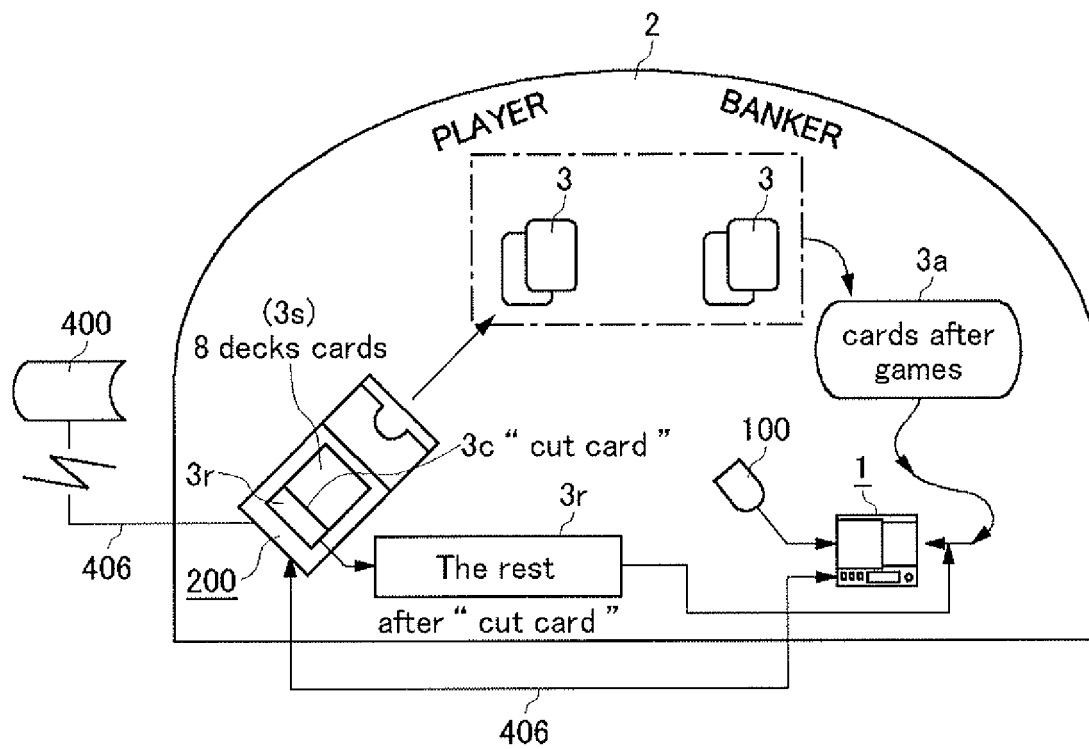
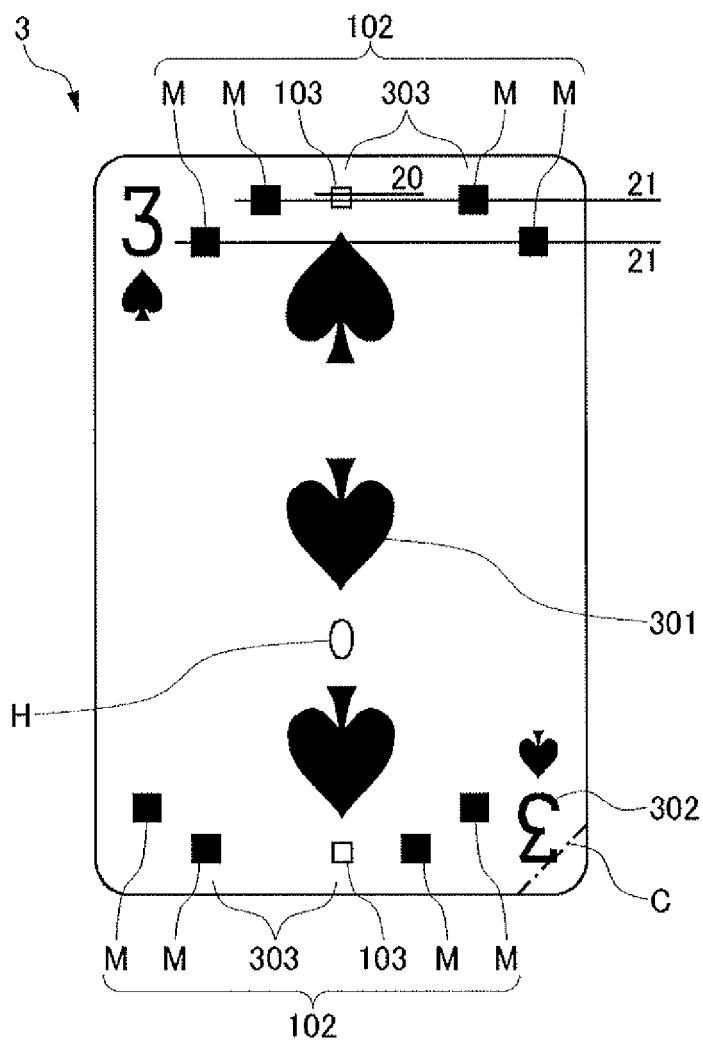


[Fig. 1]



[Fig. 3]



[Fig. 4]

Combination	Arrangement of marking	Outputs of sensors
1	 Blank Blank	21 OFF 21 OFF
2	 Blank M	21 OFF 21 ON OFF
3	 M Blank	21 ON OFF 21 OFF
4	 M M	21 ON OFF 21 ON OFF

[Fig. 5]

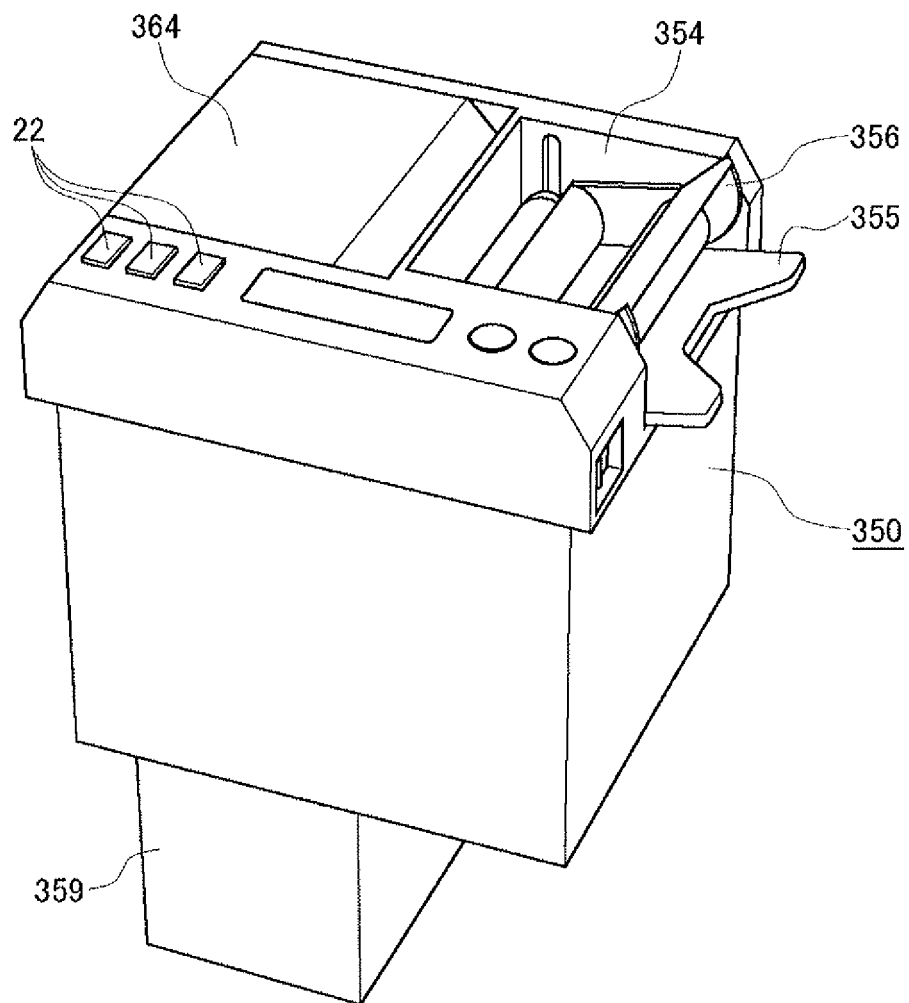
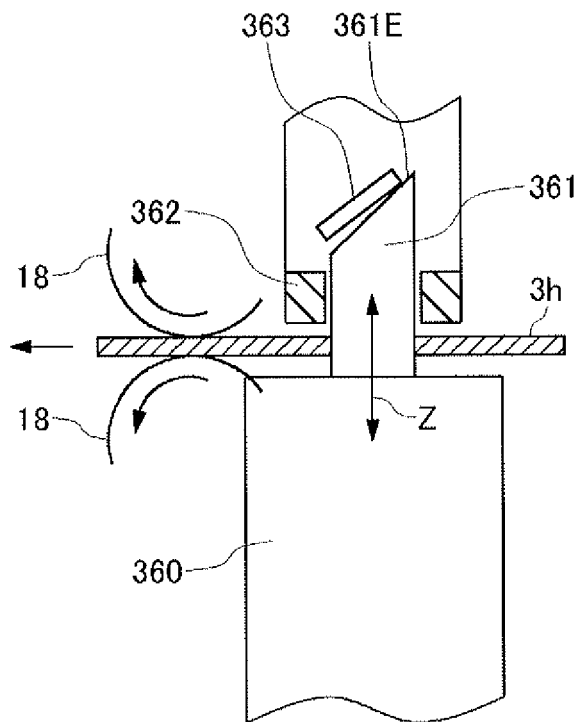
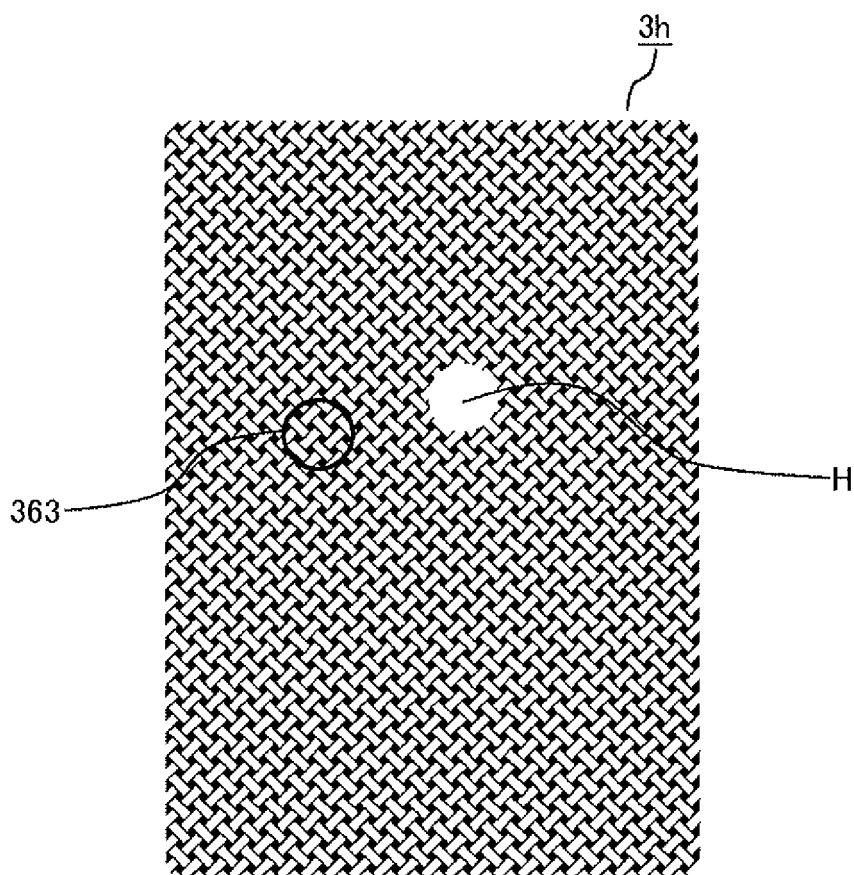


Figure 1 consists of three perspective views of a mechanical assembly, labeled (a), (b), and (c). The assembly includes a base 15 and a plate 3. In view (a), a force P is applied to the plate 3, moving it towards the base 15. In view (b), the plate 3 is moved away from the base 15. In view (c), the plate 3 is moved horizontally relative to the base 15. The views illustrate the movement of the plate 3 relative to the base 15, with labels 3, 15, 354, 355, 356, 357, and 358 indicating various components and features.

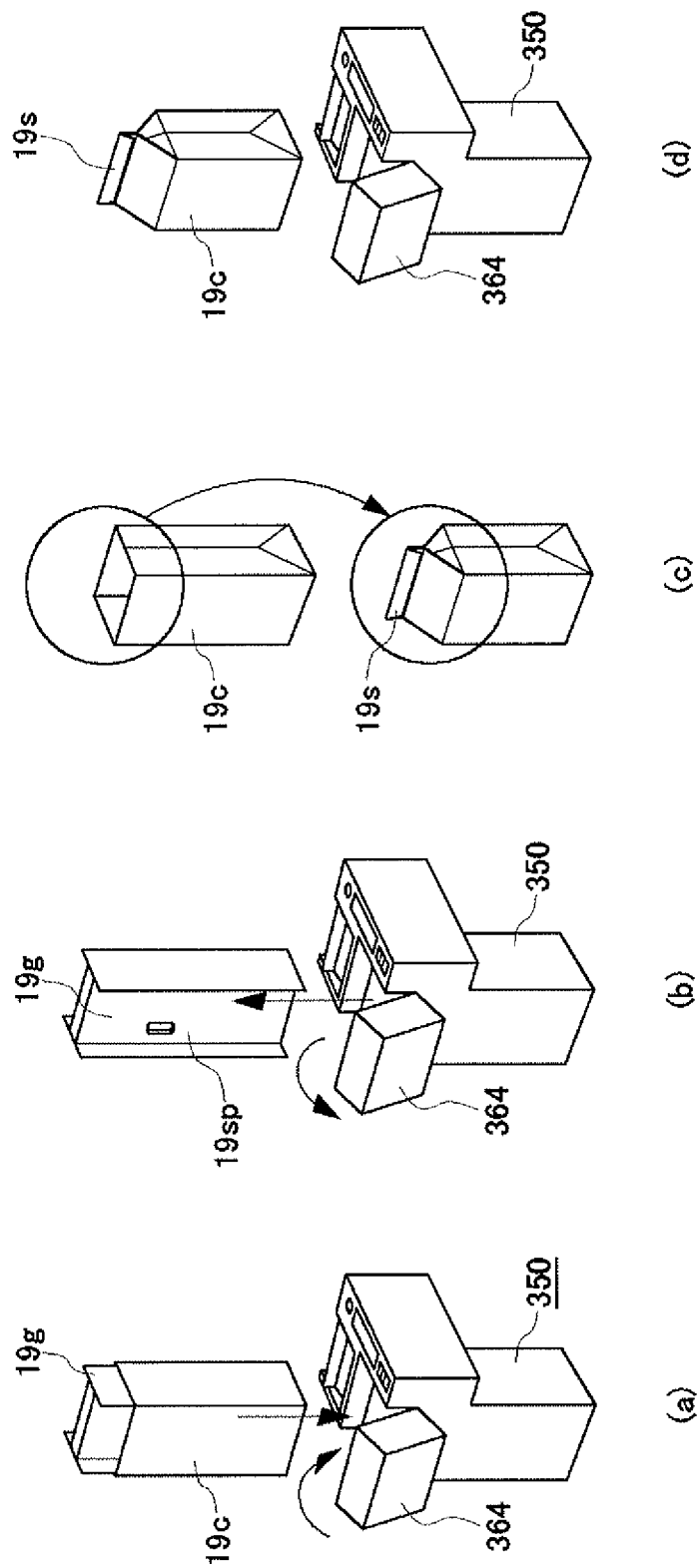
[Fig. 8]



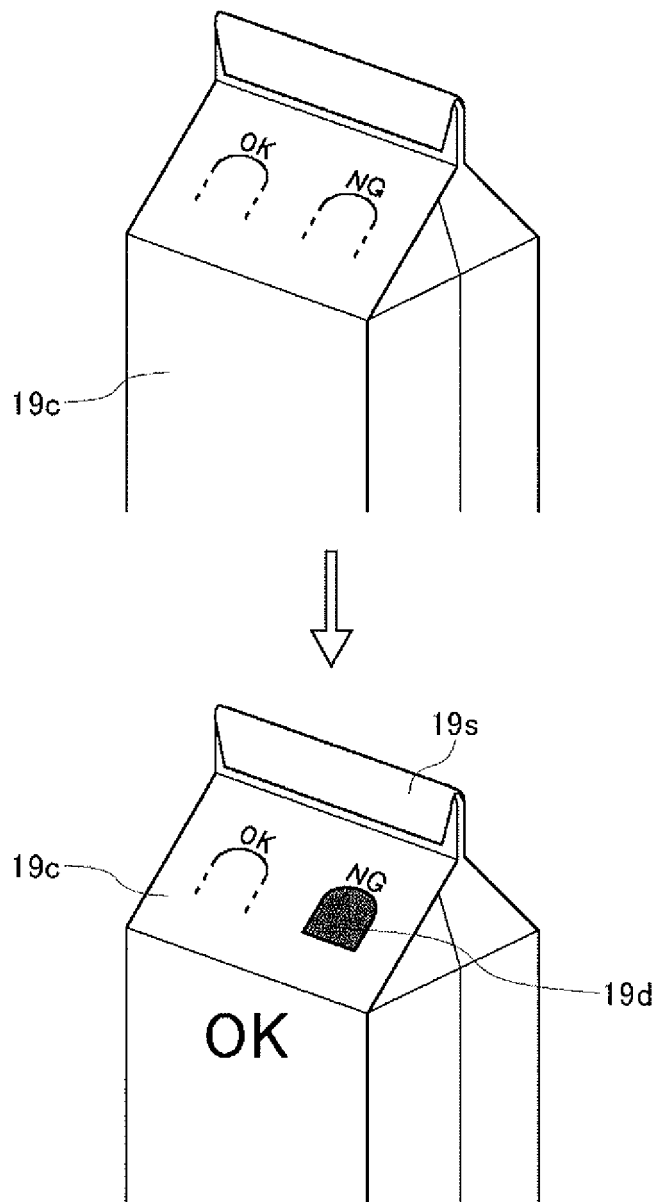
[Fig. 9]



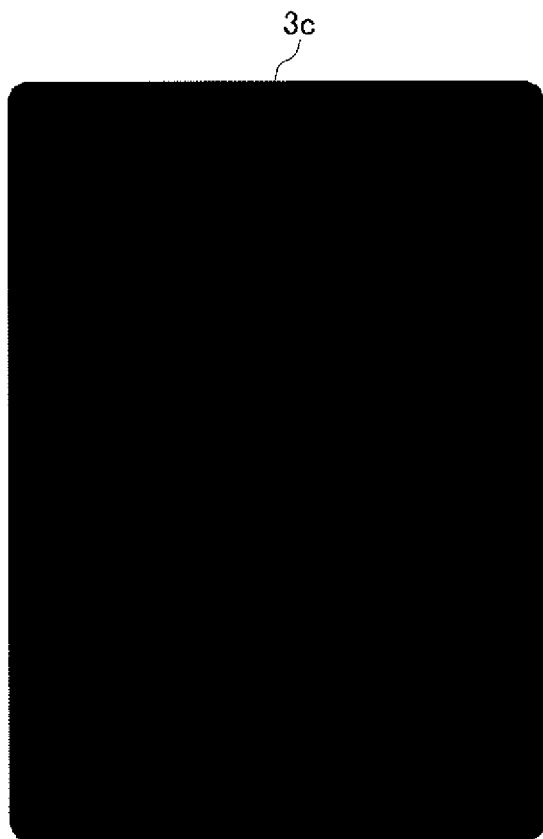
[Fig. 10]



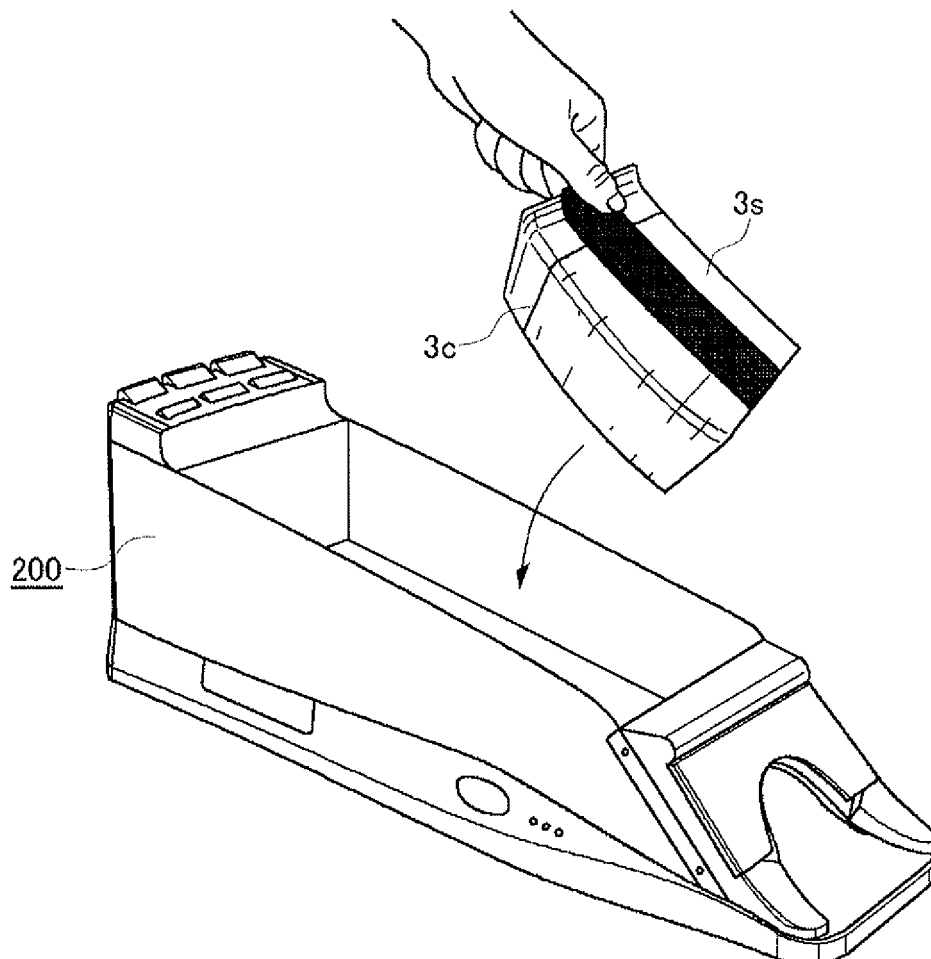
[Fig. 11]



[Fig. 12]



[Fig. 13]



[Fig. 14]

