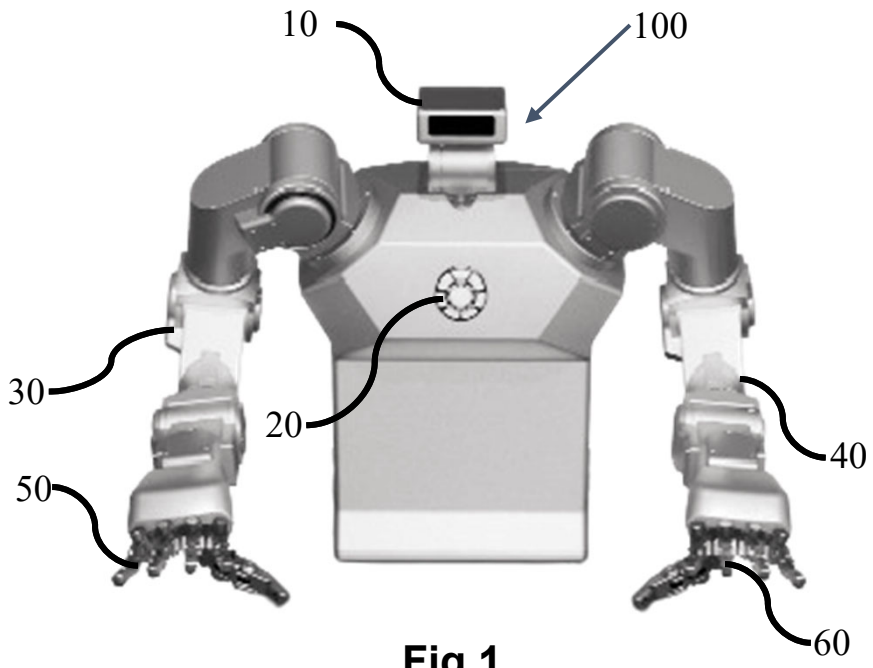


Fig 1

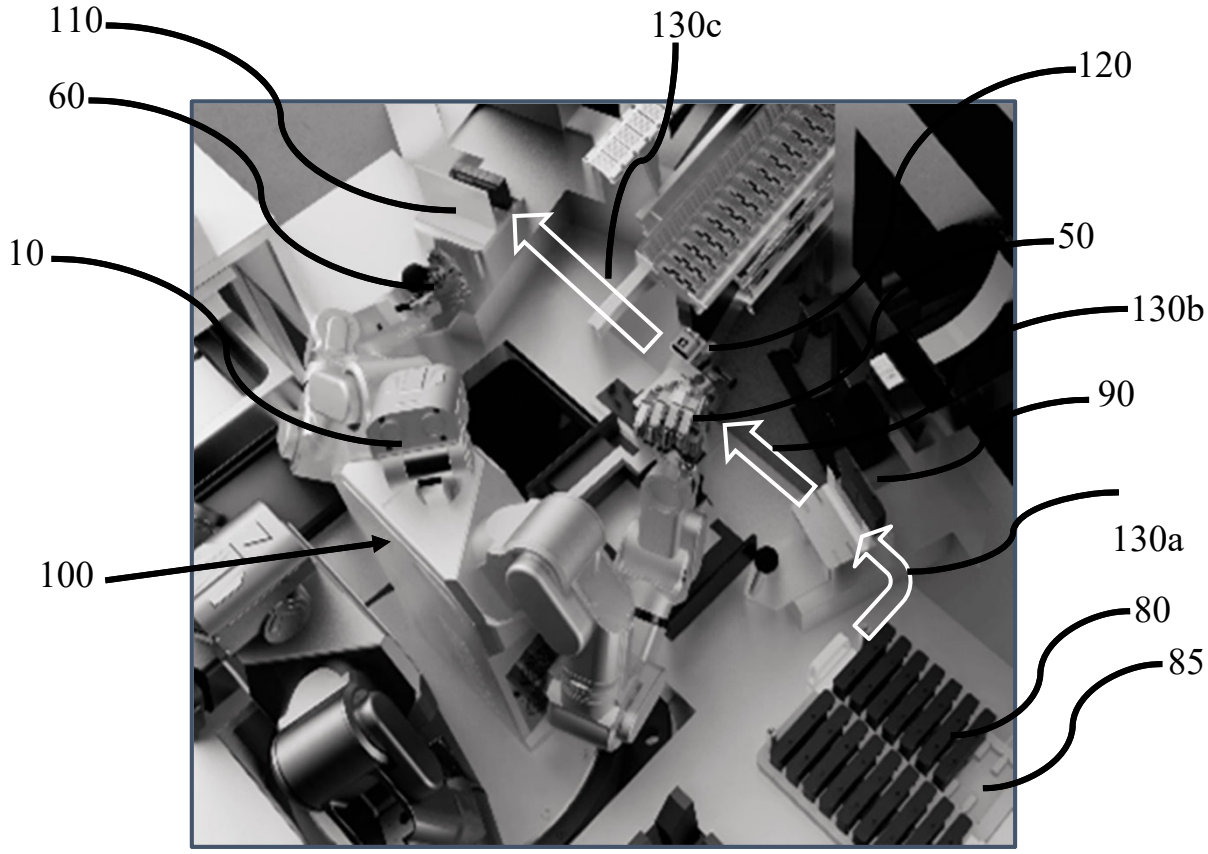


Fig 2

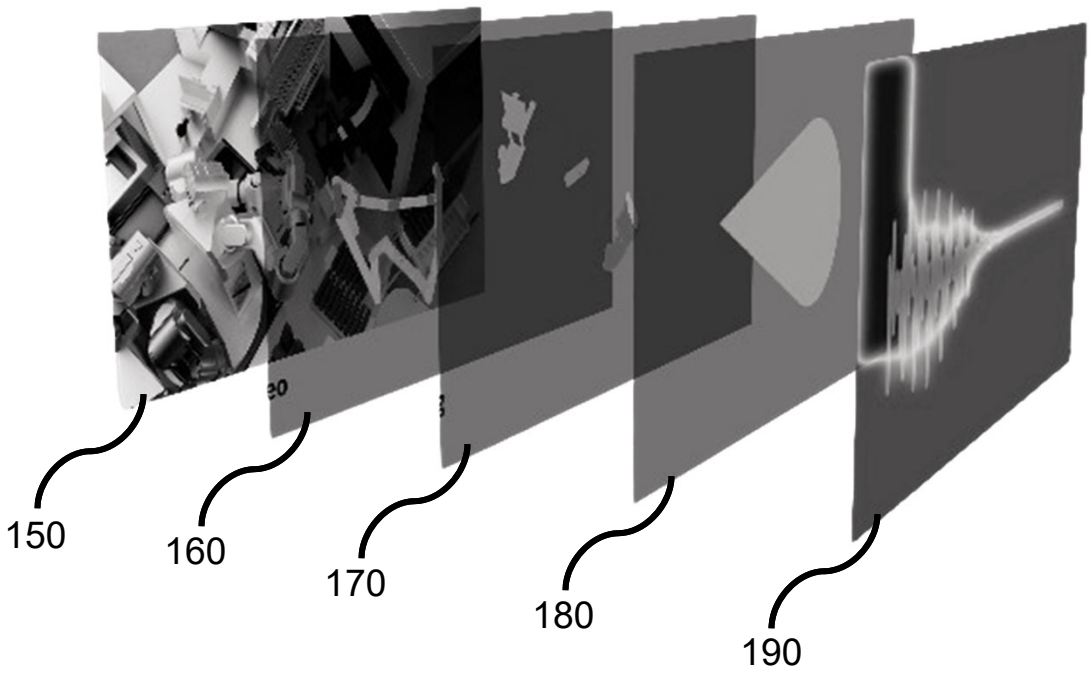


Fig 3

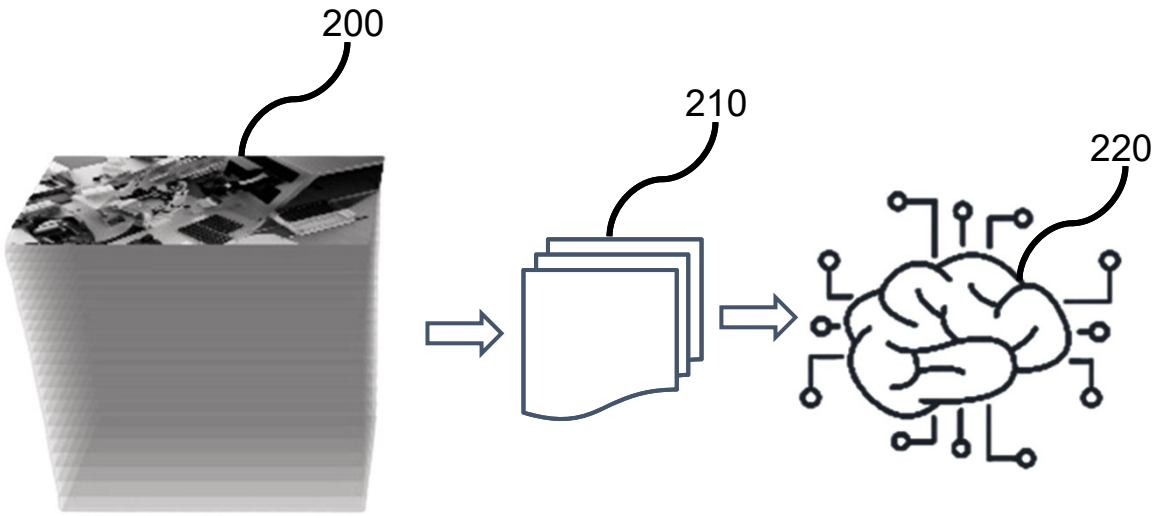


Fig 4

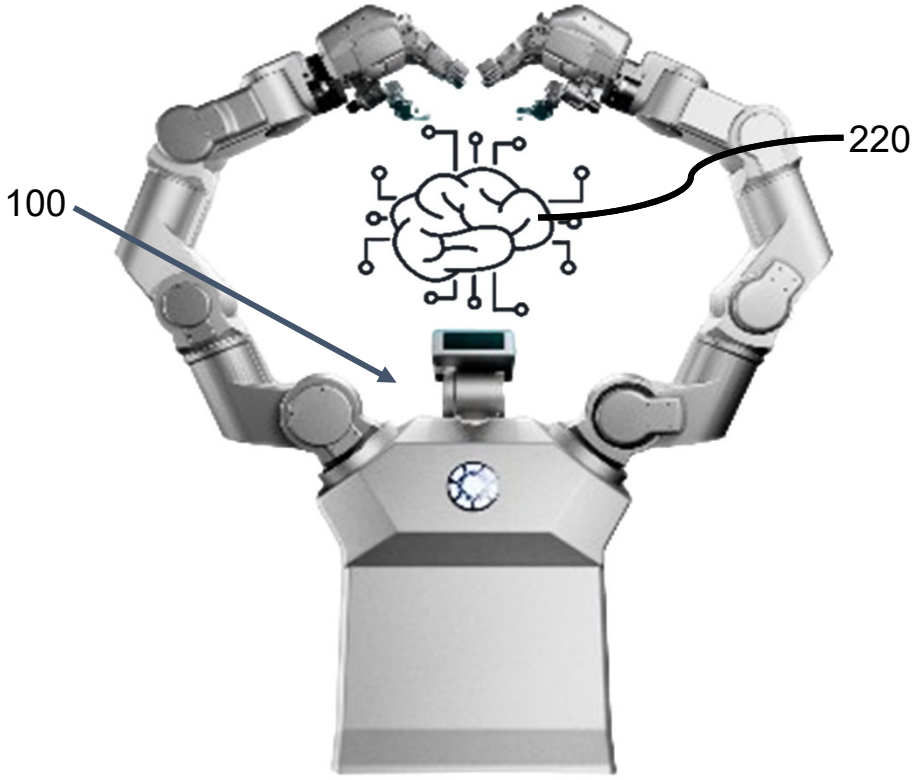


Fig 5

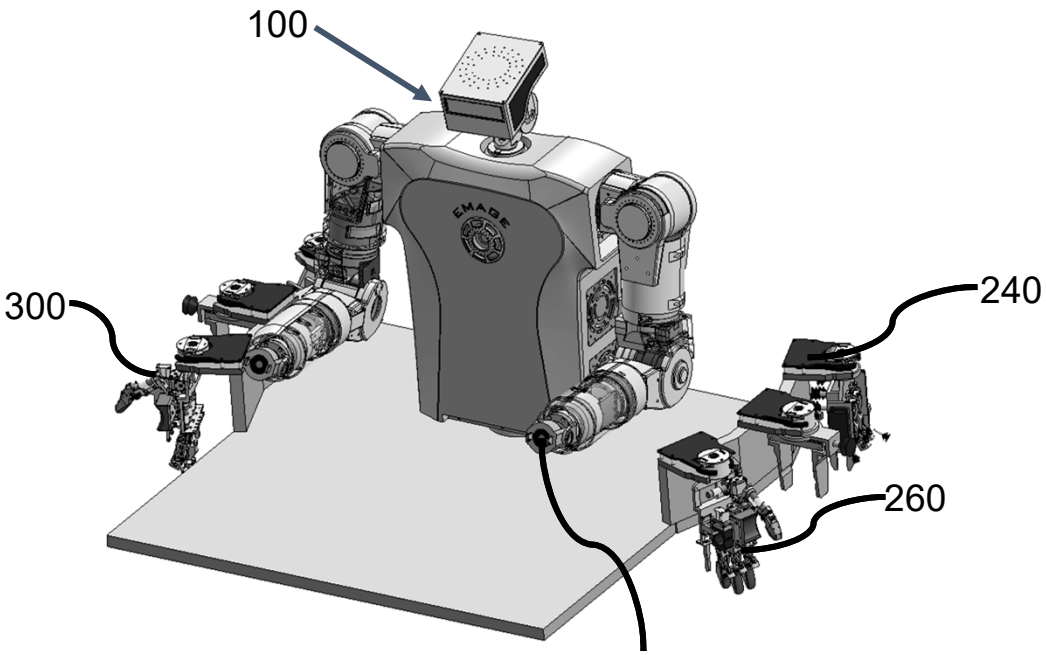
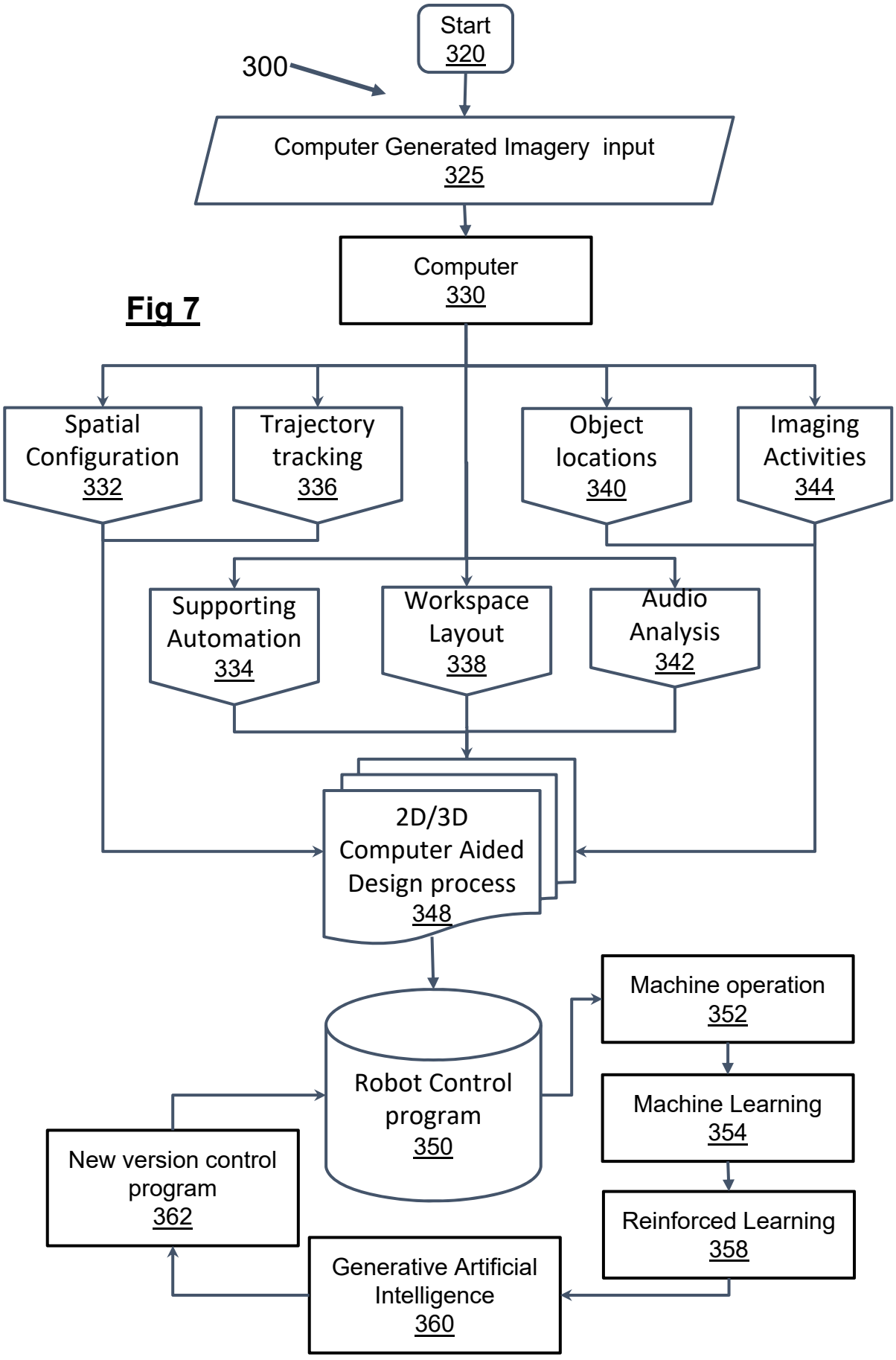


Fig 6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Start
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Computer Generated Imagery input
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Computer
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Spatial Configuration
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Trajectory tracking
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Object locations
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Imaging Activities
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Supporting Automation
334
Workspace Layout
338
Audio Analysis
342
2D/3D Computer Aided Design process
348
Robot Control program
350
Machine operation
352
Machine Learning
354
Reinforced Learning
358
Generative Artificial Intelligence
360
New version control program
362

Fig 7