

5. The system of claim 4, wherein said first and second surfaces are on an object of said objects.
6. The system of any one of claims 4-5, wherein said first surface is in spaced relationship with said second surface.
7. The system of claim 4 or 6, wherein said first and second surfaces are on a first and a second object, respectively, and said first and said second objects are in spaced relationship with each other.
8. The system of any one of claims 1-3, wherein said environment is the interior of a vehicle.
9. The system of claim 8, wherein said vehicle is a passenger aircraft.
10. The system of claim 9, wherein said tags are attached to seats in said passenger aircraft.
11. The system of any one of claims 9-10, wherein said sensors are attached to seats in said passenger aircraft.
12. The system of any one of claims 1-3 or 8, wherein said tag stores more than one identity.
13. The system of claim 12, wherein said more than one identify is stored in a preselected arrangement on said tag.
14. The system of claim 13, wherein said more than one identity corresponds to more than one adjacent seat in a row of seats.

15. A method, comprising the steps of:

deploying a plurality of wireless sensors in an environment, a sensor of said plurality of sensors configured to sense a change in said environment and emit a signal related to said change, said sensor having an identity;

deploying a plurality of machine-readable tags in said environment, a tag of said plurality of tags including location-related digital information and said identity of said sensor;

reading said tag to obtain said location-related digital information of said tag and said identity of said sensor; and

outputting location-related digital information and said identity read from said tag to a configuration database, wherein said data stores said location-related digital information and said identity in said database.

16. The method of claim 15, further comprising the step of configuring said environment containing objects and sensors before deploying said sensor and machine-readable tags to said environment.

17. The method of claim 16, further comprising the step of verifying said sensors are deployed in conformance with said configuration.

18. The method of any one of claims 16-17, further comprising the step of attaching said machine-readable tags to objects in said environment.

19. The method of any one of claims 16-18, further comprising the step of confirming said configuration of objects and sensors in said environment.

20. The method of claim 19 further comprising the steps of:

a. confirming said configuration of objects and sensors in said environment by reading information on said machine-readable tags; and

b. uploading said information read from said machine-readable tags to said database.