CLAIMS

1. A drug delivery device (2, 2A, 2B, 2C) for oral administration, the drug delivery device having a central axis and comprising:

a first body part (4);

a first attachment part (36) attached to the first body part (4) and having a first distal end (40); and

a second attachment part (44) having a second distal end (48); and

an actuator mechanism (16) configured to move the first distal end (40) towards the second distal end (48),

characterized in that the drug delivery device comprising a second body part (10), wherein the second attachment part (44) is attached to the second body part (10), and the actuator mechanism (16) is configured to rotate the first body part (4) in relation to the second body part (10) about a primary axis (A) of the drug delivery device.

2. Drug delivery device according to claim 1, wherein the actuator mechanism (16) comprises a resilient part (16A) configured to apply force to the first body part (4) and/or the second body part (10).

3. Drug delivery device according to claim 2, wherein a first part (18) of the resilient part (16A) is connected to the first body part (4) and a second part (20) of the resilient part (16A) is connected to the second body part (10).

4. Drug delivery device according to any of claims 1-3, wherein the first attachment part (36) extends in a direction away from the first body part (4).

5. Drug delivery device according to any of claims 1-4, wherein the second attachment part (44) extends in a direction away from the second body part (10).

6. Drug delivery device according to any of claims 1-5, wherein the first attachment part (36) has a first attachment axis (X_1), and wherein a distance between the first attachment axis (X_1) and the primary axis (A) is larger than 0.5 mm.

7. Drug delivery device according to any of claims 1-6, wherein the second attachment part (44) has a second attachment axis (X_2), and wherein a distance between the second attachment axis (X_2) and the primary axis (A) is larger than 0.5 mm.

8. Drug delivery according to any of claims 1-7, wherein the first body part (4) is configured to rotate in a first direction and the second body part (10) is configured to rotate in a second direction opposite to the first direction.

9. Drug delivery device according to any of claims 1-8, wherein the first distal end of the first attachment part and/or the second distal end of the second attachment part is provided with a tip (52) configured to penetrate a biological tissue.

10. Drug delivery device according to any of claims 1-9, wherein the first distal end of the first attachment part and/or the second distal end of the second attachment part is provided with a gripping part configured to grip a biological tissue.

11. Drug delivery device according to any of claims 1-10, wherein the drug delivery device comprises a first compartment (68), the drug delivery device being configured to deliver an active drug substance from the first compartment (68) to the surroundings of the drug delivery device.

12. Drug delivery according to any of claims 1-11, wherein the first attachment part and the second attachment part form an angle when the first distal end and the second distal end are in a plane that includes the primary axis.

13. Drug delivery device according to any of claims 1-12, wherein the drug delivery device has a first state where the first body part (4) and the second body part (10) are rotationally stationary relative to each other and a second state where the first body part and the second body part are rotationally mobile relative to each other.

14. Drug delivery device according to any of claims 2 and 3-13 as dependent on claim 2, wherein the drug delivery device has a first state where the resilient part (16A) has a constant resilient force load and a second state where the resilient part at least partly releases the resilient force load.

15. Drug delivery device according to any of claims 1-14, wherein the actuator mechanism (16) is configured to move the first distal end from a first primary position with a first primary radial distance from the central axis of the delivery device to a first secondary position with a first secondary radial distance from the central axis, wherein the first secondary radial distance is larger than the first primary radial distance.

16. Drug delivery device according to any of claims 1-15, wherein the actuator mechanism is configured to move the first distal end from a first primary angular position of first primary position to a first secondary angular position of first secondary position in relation to a first proximal end of the first attachment part, wherein an angle between the first primary angular position and the first secondary angular position is larger than 10 degrees.

17. Drug delivery device according to any of the preceding claims, wherein the drug delivery device comprises a locking mechanism (70) configured to lock the first body part (4) in relation to the second body part (10) in a first state of the drug delivery device.

18. Drug delivery device according to claim 17, wherein the locking mechanism (70) is configured to lock the first attachment part in a first primary position when the drug delivery device is in the first state.

19. Drug delivery device according to any of claim 1-18, wherein the first attachment part is rotationally attached to the first body part and configured to rotate about a first rotation axis perpendicular or parallel to the primary axis.

20. Drug delivery device according to any of claim 1-19, wherein the second attachment part is rotationally attached to the second body part and configured to rotate about a second rotation axis perpendicular or parallel to the primary axis.

21. Pharmaceutical composition (100) comprising a drug delivery device according to any of claims 1-20 and an active drug substance.