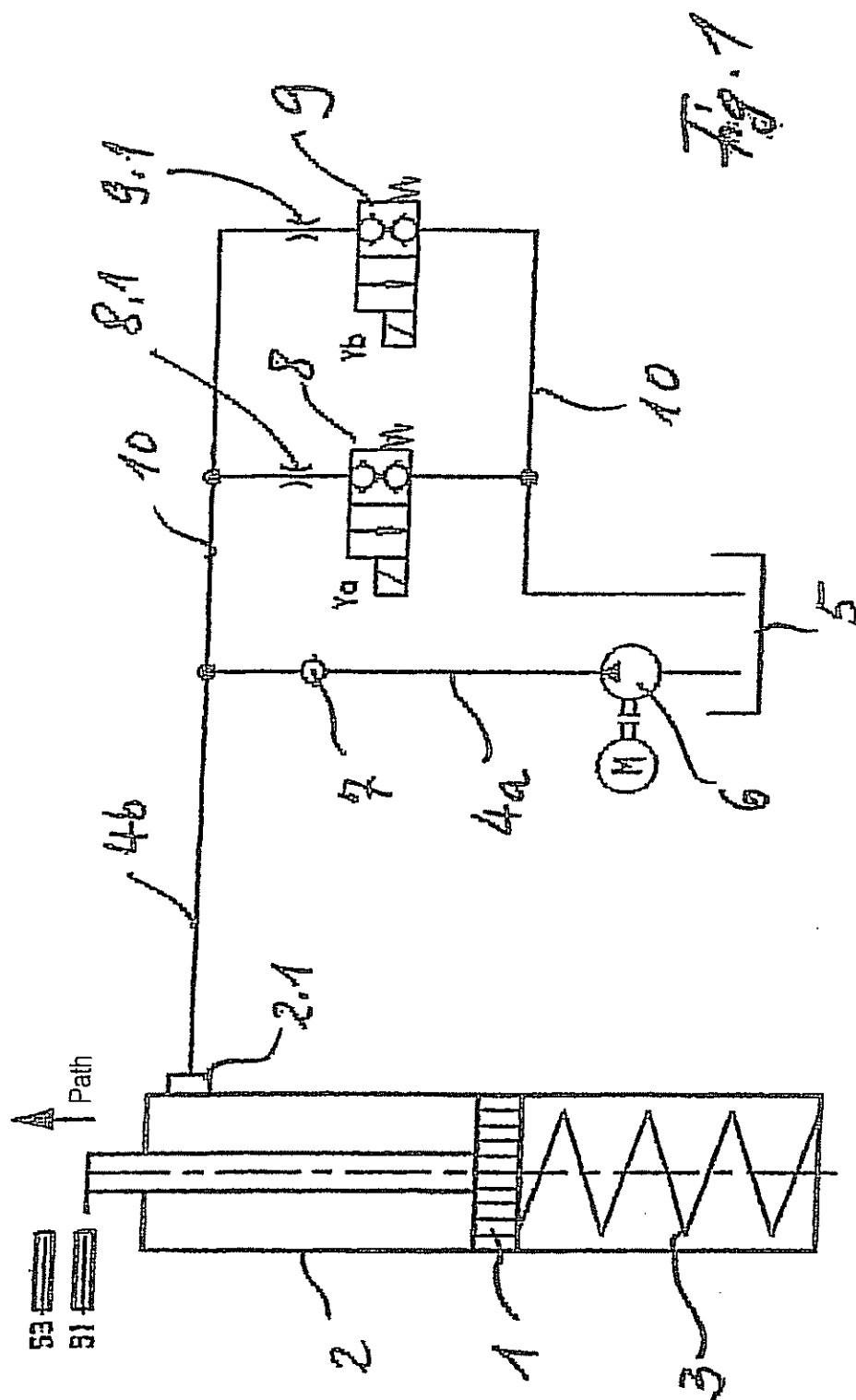




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Drive too quick

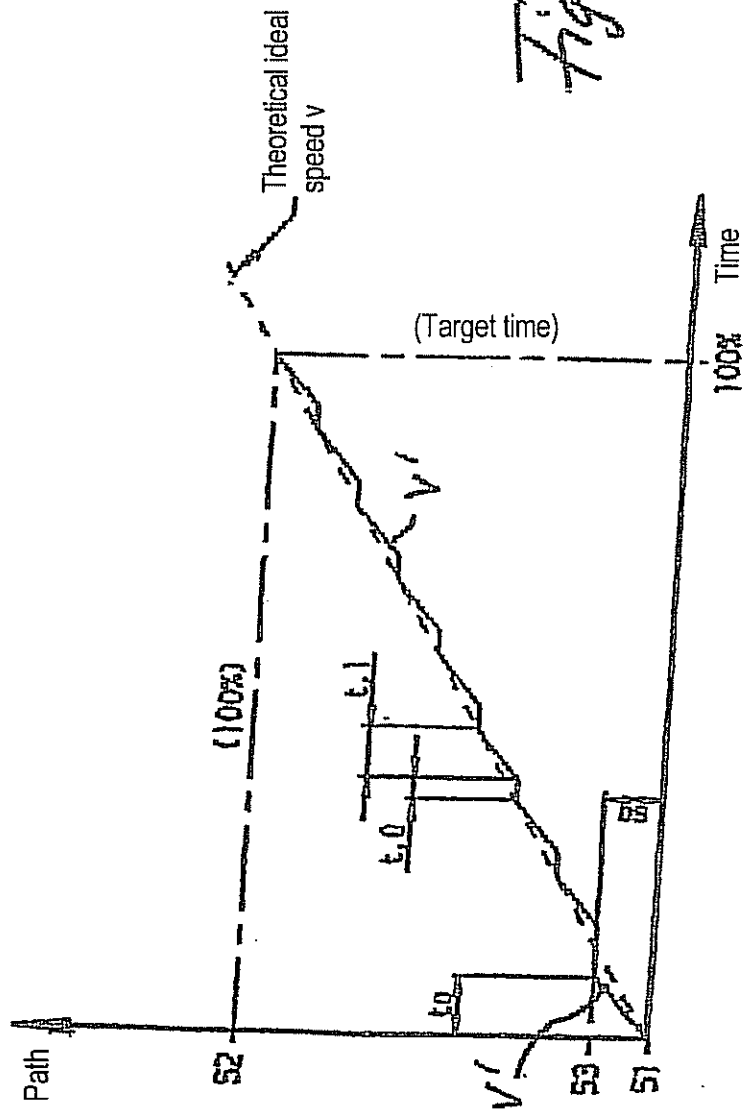


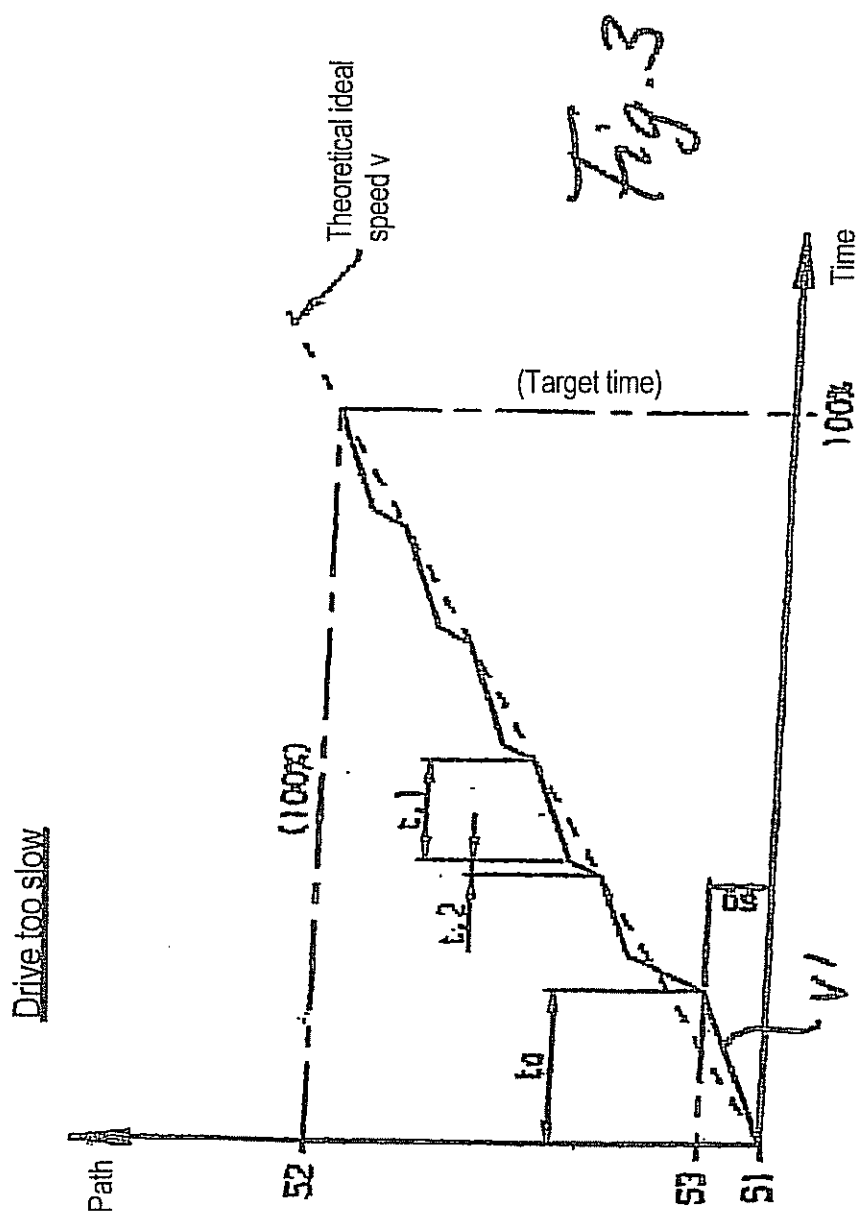
Fig. 2

t_a = time until switch point S3 (intermediate time) $\rightarrow Y_a = 1; Y_b = 0$

s_a = path until switch point S3 (intermediate time)

$t_{1,1} \rightarrow Y_a = 1; Y_b = 0$

$t_{1,0} \rightarrow Y_a = 0; Y_b = 0$



t_a = time until switch point S3 (intermediate time) $\rightarrow Y_a = 1; Y_b = 0$

s_a = path until switch point S3 (intermediate time)

$t_{1,1} \rightarrow Y_a = 1; Y_b = 0$

$t_{1,2} \rightarrow Y_a = 1; Y_b = 1$

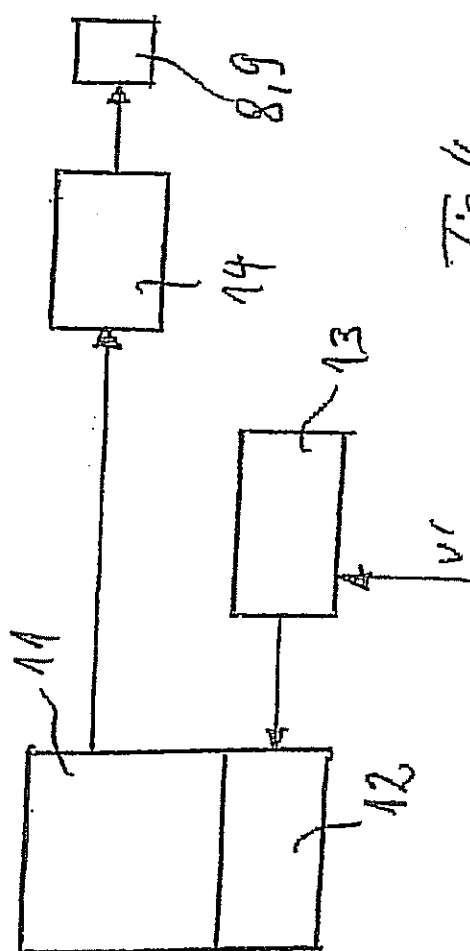


Fig. 4

52  ——— 100%
 54 

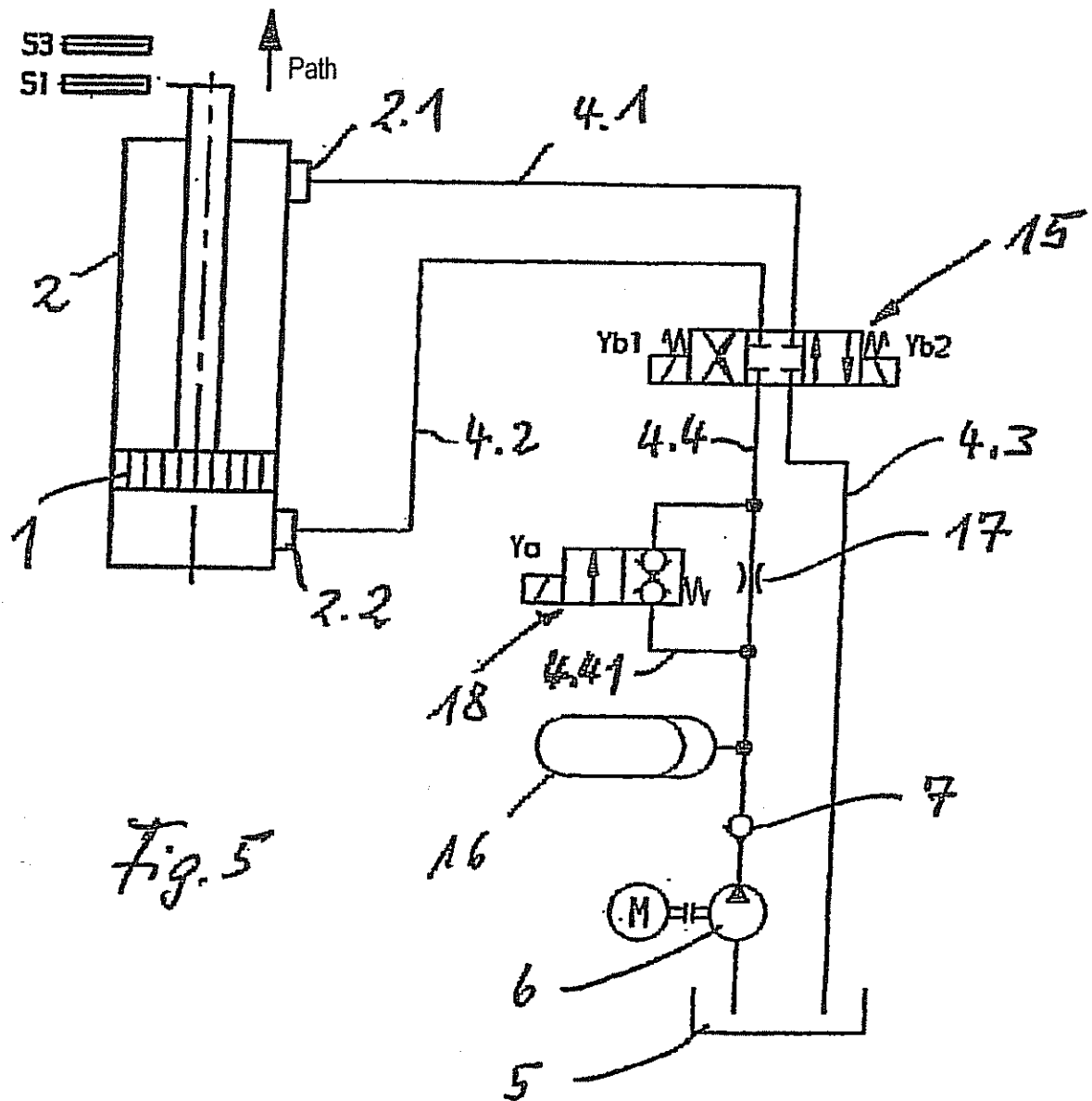
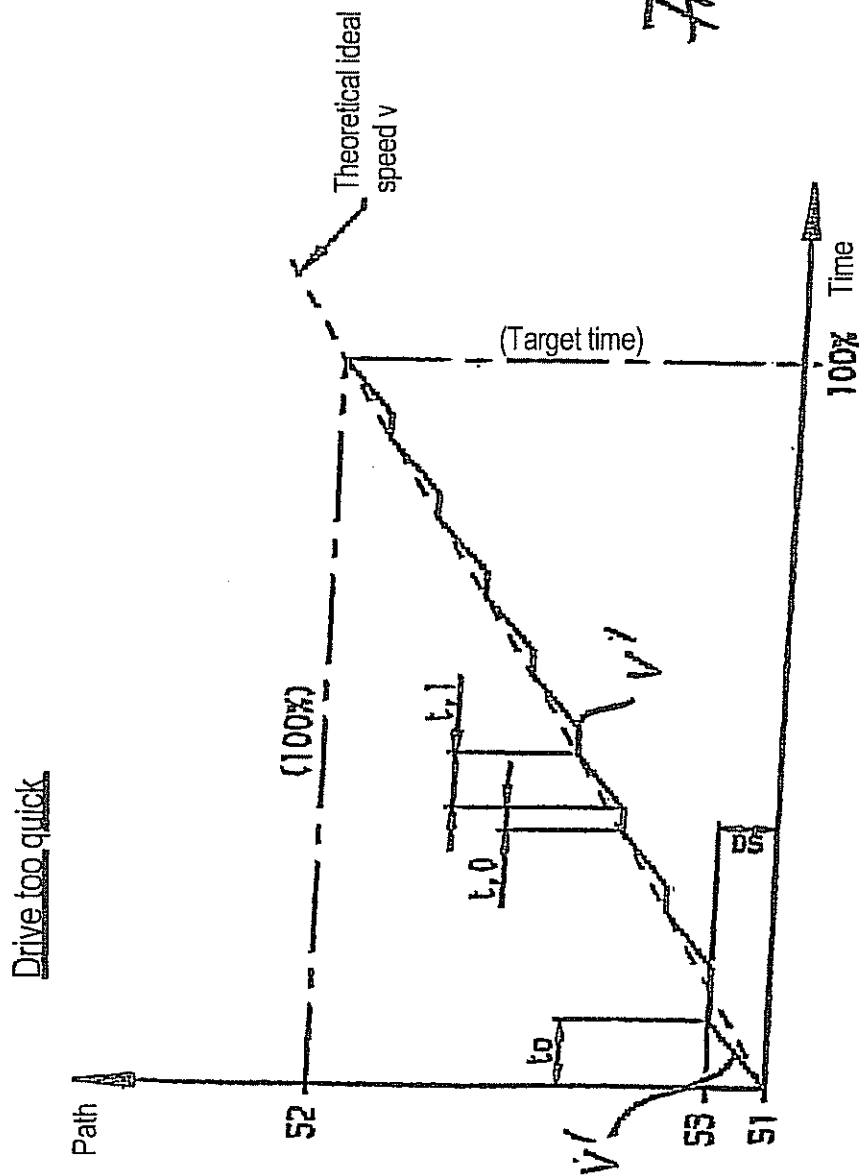


Fig. 5

Fig. 6



t_a = time until switch point S3 (intermediate time) $\rightarrow Y_a = 0; Y_{b2} = 1$

s_a = path until switch point S3 (intermediate time)

$t_{1,1} \rightarrow Y_a = 0; Y_{b2} = 1$

$t_{1,0} \rightarrow Y_a = 0; Y_{b2} = 0$

Drive too slow

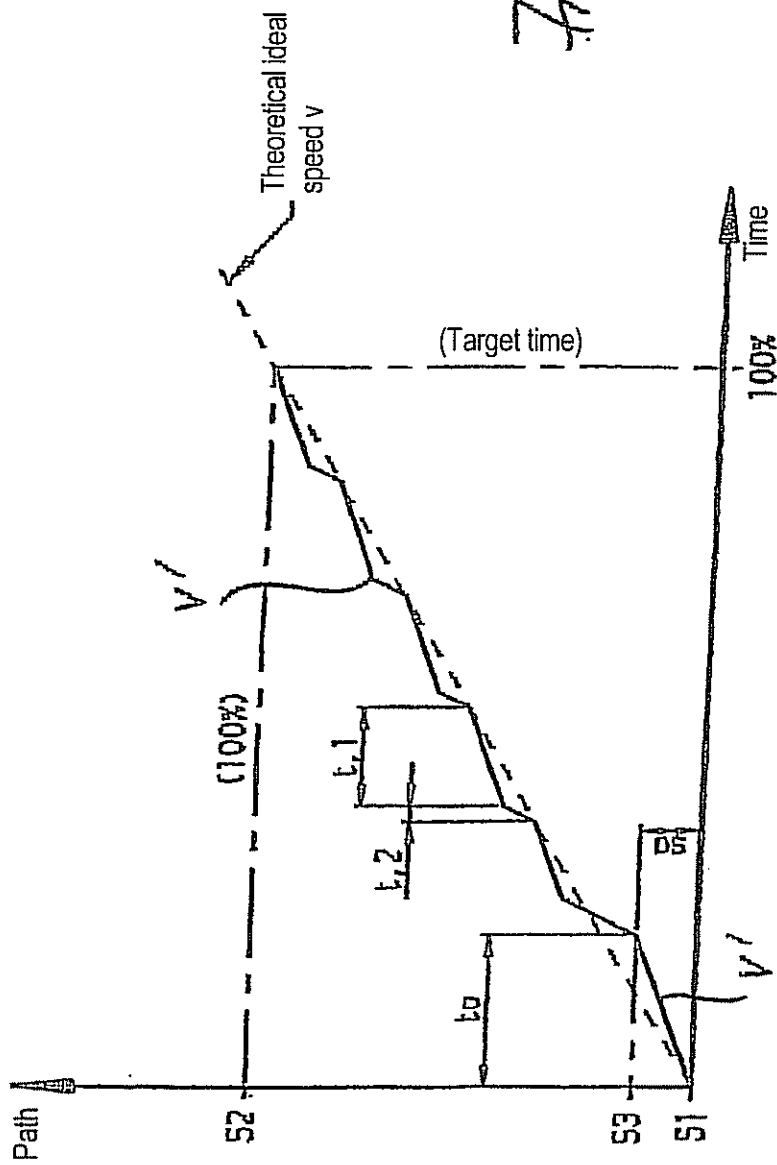


Fig. 7

t_a = time until switch point S3 (intermediate time) $\rightarrow Y_a = 0; Y_{b2} = 1$

s_a = path until switch point S3 (intermediate time)

$t_{1,1} \rightarrow Y_a = 0; Y_{b2} = 1$

$t_{1,2} \rightarrow Y_a = 1; Y_{b2} = 1$

S2  — 100%
S4 

