

ABSTRACT

Embodiments of the present disclosure disclose forward collision control methods and apparatuses, electronic devices, programs, and media, where the forward collision control method includes: detecting a forward suspected collision object on a road where a current traveling object is located on the basis of a neural network; predicting the collision time between the current traveling object and the suspected collision object; and performing forward collision control on the current traveling object according to the collision time, where the forward collision control includes forward collision warning and/or driving control. The embodiments of the present disclosure improve the accuracy and the precision of the detection result of a target object, improves the precision of collision warning, and facilitates reducing road traffic events.

[Figure 1]