

SWITCHED CAPACITOR D/A CONVERTER

This invention relates to digital-to-analog (D/A) converters and, in particular, to a D/A converter of the charge redistribution type.

5 D/A converters of the charge redistribution type normally include an array of binary weighted capacitors which are selectively charged (or discharged) to represent the value of a digital signal. After selected capacitors of the array are charged, the charge stored on the selected capacitors is then redistributed
10 among all the capacitors of the array to produce an analog voltage representative of the digital signal.

This is best explained with reference to the prior art circuit of FIGURE 1 in which 6-bit digital data signals (D1 through D6) are converted into an analog voltage at an output line OL by
15 means of 6 capacitors (C1 through C6) and 6 switching circuits (S1 through S6). The six (6) capacitors C1 through C6 are binary weighted with the smallest capacitor (i.e., C1) having a value equal to one unit of capacitance (C) and the largest capacitor (i.e., C6) having a value equal to 32 units of capacitance (32C). D6, the
20 most significant bit (MSB) of information, is applied to and stored on the largest capacitor (i.e., C6) and D1, the least significant bit (LSB) of information, is applied to and stored on the smallest capacitor (i.e., C1).

As shown in FIGURE 1, one side (X) of each capacitor
25 (C1 through C6) is connected to output line, OL. The output line (OL) is selectively coupled either to Vcc volts via a first metal oxide semiconductor (MOS) transistor switch PL or to ground potential via a second MOS transistor switch NL. The other side (Y) of each capacitor (Ci) is selectively connected either via an
30 MOS transistor switch (PSi) to Vcc volts or via an MOS transistor switch (NSi) to ground potential. Thus two switching transistors are used at each Y side of each capacitor to set each capacitor to a desired condition.

After the digital information is applied to and stored
35 on selected capacitors, all the capacitors are connected in parallel causing the charge stored on selected capacitors to be redistributed among all the capacitors to produce an analog voltage representative of the applied digital input signal.

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The sequence of steps and time periods required to perform digital signal to voltage conversion with the circuit of FIGURE 1 is as follows.

1.) During a first initialization time period, all the capacitors (C_i) are discharged to set them to the same initial condition. This is accomplished, for example, by turning PL OFF and NL ON; and turning all the P S_i transistors OFF and all the N S_i transistors ON.

2.) During a second, subsequent, data loading time period, each digital data signal (D_i) is applied via complementary transistors P S_i or N S_i to the Y side of a C_i capacitor and a charge corresponding to each data signal is stored on a C_i capacitor. This is accomplished, for example, by: (a) turning PL ON and NL OFF whereby OL is held at V_{cc} volts; and (b) each capacitor (C_i) is either charged if the input serial bit, D_i , is "high" or V_{cc} volts, since D_i -high turns ON its N S_i transistor and turns OFF its P S_i transistor; or remains uncharged if D_i is a "low" or "zero" volts, since D_i -low turns ON its transistor P S_i , and turns OFF its transistor N S_i .

3.) During a third, subsequent, recombination or conversion time period, all the C_i capacitors are connected in parallel to produce an analog voltage which is representative of the value of the digital signal. This is accomplished, for example, by: (a) turning PL and NL OFF; and (b) turning all the N S_i transistors ON and all the P S_i transistors OFF.

4.) During a fourth, subsequent, time period, the analog voltage produced across the capacitors is read out via a transfer gate transistor (TR) coupling the output line OL to an amplifier AMP1.

The digital-to-analog converter (DAC) circuit of FIGURE 1 is well suited for many applications. However, a number of problems exist with the DAC circuit of FIGURE 1 where it is desired and/or necessary to form a high density DAC system. In such a system, many capacitors have to be charged quickly during a data load cycle. This is problematic because having to charge the capacitors (C_i) directly and sequentially in a short period of time requires large transistors to handle the large instantaneous currents needed to charge the largest capacitors. On the other



hand where small low conductivity transistors are employed, the charging time becomes long and may exceed the time constraints of the system.

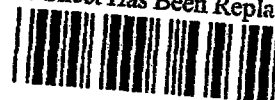
Furthermore, a significant problem exists with the circuit of FIGURE 1 where it is desired to build a high density DAC system employing transistors such as those made of amorphous silicon. These transistors are easy and inexpensive to fabricate and it is therefore desirable to use this type of transistor. This is particularly so where a display panel is formed making use of these types of transistors whereby the display and the control circuitry can be formed using similar technology. Unfortunately, these transistors have low mobility, low gain and high threshold voltages. In addition, these transistors are presently available only in one conductivity type (i.e., N-channel conductivity type). As a result of their low gain and low conductivity and their relatively high threshold voltages (e.g., V_T ranges from 3 to 5 volts), these transistors when operated in the source-follower mode tend to respond very slowly. The slow source-follower mode response presents a problem which is very pronounced in the amorphous silicon technology. However, in general, this problem exists whenever transistors of only one conductivity are available; i.e., the transistors provide good switching action when operated in the common source mode and poor (slow) action when operated in the source follower mode.

Still further it is desirable and or necessary to reduce the time to perform the digital-to-analog conversion, particularly in high density systems where a multiplicity of conversions must be performed in a very limited time.

Still further, it is desirable to reduce the number of components such as the use of two transistors per Y side of each capacitor. Reducing the number of components increases the yield and reliability of the circuit and enables the circuit to be laid out such that the circuit can be built more easily on pitch with the column and row conductors of a display panel intended for use with the DAC system.

The problems discussed above and others, discussed below, are resolved in circuits and systems embodying the invention.

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In circuits embodying the invention a set of N digital data bits supplied to an input node are converted to an analog voltage by means of N weighted capacitors and N switching transistors, one capacitor being associated with one switching transistor for each one of the N digital data bits. Each capacitor has first and second plates, with the first plate of each capacitor being connected to an output line. Each switching transistor has a conduction path and a gate electrode with which there is associated a gate capacitance which is relatively small compared to the value of the largest binary weighted capacitors. The conduction path of each switching transistor is connected between the other side of its associated capacitor and a reference potential. The N digital data bits are coupled to the gates of the N switching transistors via N selectively enabled data transfer paths, one data transfer path per switching transistor, each data transfer path being connected between the input node and the gate electrode of its corresponding switching transistor.

During a data load period, voltage levels corresponding to the N data bits are selectively sampled via the N data transfer paths and stored on the gates of the switching transistors. Thus, during a data load period data signals are sampled and stored on the gate capacitance of the switching transistors. Due to the small gate capacitance of the switching transistors the loading of the data onto their gates is accomplished very quickly. The data stored on the gates of the switching transistors subsequently determine which binary weighted capacitors get charged and which remain uncharged when a charging voltage is applied across the capacitors.

In a preferred embodiment a precharge pulse having a polarity and amplitude to turn on the switching transistors is applied to the input node and is coupled via the N selectively enabled data transfer paths to all of the switching transistors. The precharge pulse functions to precharge the gate capacitance of the N switching transistors with a turn-on voltage in preparation for the subsequent application of the N digital data bits. The precharge pulse also functions to turn-on all the N switching transistors, in parallel, whereby the N binary weighted capacitors are connected in parallel and redistribute the charge previously



stored on selected ones of the N capacitors thereby producing an analog voltage representative of the previously supplied N digital data bits.

5 Following the precharge of the gates of the N switching transistors, a data load period is initiated and the N selectively enabled data transfer paths are enabled to couple the respective data bits to the gate of its corresponding switching transistor so as to discharge the gate capacitance for one input signal condition or to maintain it charged for another input signal condition. This
10 establishes a voltage corresponding to the value of each one of the N digital data bits on the gate of a corresponding switching transistor.

In the accompanying drawings like reference characters denote like components; and

15 FIGURE 1 is a schematic diagram of a prior art digital-to-analog (D/A) converter circuit;

FIGURE 2 is a schematic diagram of a digital-to-analog converter (DAC) circuit embodying the invention;

20 FIGURE 3 is a diagram of waveforms useful for describing the operation of the circuit of FIGURE 2;

FIGURE 4A is a schematic diagram of a portion of the circuit of FIGURE 2 detailing various capacitances associated with the transistors of the circuit of FIGURE 2;

25 FIGURE 4B is a waveform diagram useful for describing the FIGURE 4A circuit.

FIGURE 5 is a block diagram of a DAC embodying the invention coupled to a data scanner for driving a column conductor of a liquid crystal display (LCD) panel;

30 FIGURE 6 is a block diagram of a system embodying the invention;

FIGURE 7 is an idealized representation of part of the signal and control lines for use in the system of FIGURE 6;

35 FIGURE 8 is a partial schematic diagram of a subranging capacitive network suitable for use in circuits embodying the invention; and

FIGURES 9A and 9B show a simplified circuit arrangement and waveforms for use in circuits embodying the invention.

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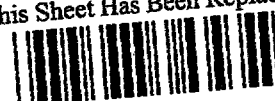
Insulated-gate field-effect transistors (IGFET's) are the active devices preferred for use in practicing the invention. For this reason, the circuits are illustrated in the drawing as employing such transistors and will be so described hereinafter.

5 However, this is not intended to preclude the use of other suitable devices and to this end, the term "transistor" when used without limitation in the appended claims is used in a generic sense.

In the figures, enhancement type IGFET's of n-conductivity type are identified by the letter N followed by a
10 particular reference character. The characteristics of IGFET's are well known and need not be described in detail. But, for a clearer understanding of the description to follow, definition and characteristics of IGFET's pertinent to the invention are set forth below.

15 IGFET's have a first electrode and a second electrode referred to as the source and drain defining the ends of a conduction path, and a control electrode (gate) whose applied potential determines the conductivity of the conduction path. For an N-type IGFET, the source electrode is defined as that electrode
20 of the first and second electrodes having the lowest potential applied thereto. The devices used are bidirectional in the sense that when an enabling signal is applied to the control electrode, current can flow in either direction in the conduction path defined by the first and second electrodes. For conduction to occur, the
25 applied gate-to-source potential (V_g s) must be in a direction to forward bias the gate with respect to the source and must be greater in magnitude than a given value which is defined as the threshold voltage (V_t). When used as a source follower, the voltage at the source electrode (V_s) "follows" the signal applied at
30 the gate (V_g) but is offset by the threshold voltage (V_t). Circuits and systems embodying the invention may be formed using transistors made of amorphous silicon which have low mobility, low gain and high threshold voltages (e.g., $V_T=5$ volts). Lastly, IGFET's such as those made of amorphous silicon have some
35 capacitance between their gate and source electrodes and between their gate and drain electrodes. The effect and use of this capacitance is discussed below.

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Referring to FIGURE 2, there is shown a circuit 11 which functions to convert data bits (Di) serially applied to a data input terminal 3 to a corresponding analog voltage at output terminal 5. To better understand the structure and operation of the circuit of FIGURE 2 note that the circuit of FIGURE 2 may be incorporated in a DAC system of the type shown in FIGURES 6 and 7. Referring to FIGURE 6, there is shown a serial digital data generator 112 with 40 output data word lines (DWL1 through DWL40), with generator 112 producing serial strings of digital signals in parallel on the 40 data word lines. During a data load cycle, each data word line carries 144 bits of serial information which are distributed onto 24 sublines with each subline carrying 6 data bits to its corresponding DAC 11. In FIGURE 6 there are 40 word lines times 24 sublines per word line for a total of 960 sublines. Each subline being coupled to a DAC for converting 6 digital data bits into a corresponding analog voltage which, in the system of FIGURE 6, is then used to drive a corresponding column conductor which is part of a liquid crystal display (LCD) panel 114.

Where the circuit of FIGURE 2 is part of a DAC system of the type shown in FIGURES 6 AND 7, the data signals applied to terminal 3 may be as shown in waveform designated DATA INPUT in FIGURE 3. The waveform DATA INPUT of FIGURE 3 includes precharge periods followed by six data segments. During the precharge period a precharge data pulse (PDP) is applied to the input terminal 3. The PDP pulse is shown to have an amplitude of +15 volts and its pulse width may be assumed to be 4 microseconds. Following the precharge period there is a data load period during which data bits are serially applied to input terminal 3. For the system of FIGURES 6 and 7, the data load period is broken up into six segments with each segment containing 24 data bits. During the first segment (SEG 1) the 24 most significant bits (MSB) are applied to terminal 3 with each bit being distributed to a different one of 24 DAC circuits 11 of the type shown in FIGURE 2. During the second segment (SEG 2) of the data load period the 24 next less significant bits are distributed to different ones of 24 DAC circuits. The process is repeated until the 24 least significant bits (LSB) are applied to terminal 3 and distributed to their respective DAC circuits. The



data bits are assumed to have either an amplitude of 15 volts representing a "high" or logic "1" or an amplitude at, or close, to zero volts representing a "low" or logic "0". The pulse width of each data bit is assumed to be 160 nanoseconds. Accordingly, for
5 this example, a data load period includes the application of 144 pulses to terminal 3 over a period extending for at least 144 x 160 nanoseconds.

The 144 pulses applied to terminal 3 during a data load cycle are decoded via column select signals (CS_j) and
10 demultiplexing signals (Bi) to produce 24 different sets of 6 pulses. Each set of six pulses is converted via a DAC circuit 11 of the type shown in FIGURE 2 to produce an analog voltage which is then used to drive a corresponding column conductor of a liquid crystal display (LCD) panel 114, as shown in FIGURE 6.

15 The digital-to-analog (DAC) converter of FIGURE 2 includes a binary weighted capacitor network 50, a capacitor switching transistor section 52 and a column select (CS) section 56 coupled between data input 3 and section 54. Binary weighted capacitor network 50 is comprised of six binary weighted storage
20 capacitors, C₀, C₁, C₂, C₃, C₄ and C₅. Each higher numbered capacitor (C_i), going from the lowest numbered (C₀) to the highest (C₅), has twice the capacitance of the preceding, lower numbered, capacitor. By way of example, in this embodiment C₀, C₁, C₂, C₃, C₄ and C₅ have the values of .025 pf, .05 pf, 0.1 pf, 0.2 pf, 0.4 pf
25 and 0.8 pf, respectively.

Each capacitor is connected at one terminal (plate, or side, X) to an output node 5. The conduction path of an N channel IGFET (M_{2i}), which may be made of amorphous silicon, is
30 connected between the other terminal (plate, or side, Y) of each capacitor and ground potential. The gate electrode of each one of the switching transistors M_{2i} is connected to a corresponding terminal 02_i of demultiplexer network 54.

Each transistor M_{2i}, functions as an ON-OFF switch, and has its conduction path connected between the Y terminal of
35 its associated capacitor C_i and ground potential. Specifically, the M_{2i} transistors are identified in FIGURE 2 as M₂₀, M₂₁, M₂₂, M₂₃, M₂₄ and M₂₅. When a capacitor switching transistor M_{2i} is turned on it clamps the Y side of its associated capacitor C_i to



ground. When a capacitor switching transistor $M2i$ is turned off, the Y side of its associated capacitor is connected to an open switch and the Y side of that capacitor may be assumed to be floating.

5 As discussed below a significant aspect of the invention is the use of the gate capacitance of transistors $M2i$ to store the precharge and data signals. The turn-on and turn-off of each one of switching transistors $M2i$ is controlled by means of two series connected transistors $M1i$ and $M3i$ in bit demultiplexer
10 network 54 and column select network 56. Specifically, the control (gate) electrode of each $M2i$ transistor is connected via the series connected conduction path of a bit demultiplexing transistor $M1i$ and a column select transistor $M3i$ to serial data input terminal 3. Each bit demultiplexer transistor $M1i$ is turned-on or
15 off by means of a bit demultiplexer control pulse signal (B_i) applied to its gate electrode. All the column select transistors $M3i$ are turned on or off at the same time by means of a column select signal, CS_j , applied to all their gate electrodes, in parallel.

A selectively enabled transistor $M2$ which functions to
20 clamp terminal 5 to ground has its conduction path connected between output terminal 5 and ground with a control signal C_z applied to its gate at terminal 4.

A selectively enabled transistor $M3$ has its conduction path connected between a terminal 7 to which is applied an
25 operating potential of 15 volts and the output line 5. A charge control signal CHG is applied to the gate electrode of $M3$ at terminal 6. Transistor $M3$ functions to selectively charge terminal 5 and selected storage capacitors (C_i) to the voltage (e.g., 15 volts) at terminal 7.

30 A selectively enabled transfer transistor $M4$ has its conduction path connected between terminal 5 and a terminal 65. A transfer (XFER) signal applied to the gate of $M4$ functions to transfer the analog signal at terminal 5 to a succeeding stage coupled to terminal 65. A capacitance CP which may be in the
35 range of 0.5 pf is assumed to be present at output 65.

A typical cycle of the circuit of FIGURE 2 will now be described with the aid of the waveform diagram of FIGURES 3. A cycle will be examined going through a sequence which include:



(1) a precharge (initialization) period; (2) a data load period during which data signals are transferred to the gate capacitance of the switching transistors; (3) a capacitor charge period; and (4) a charge redistribution and output signal period. It will be shown that, in circuits embodying the invention, this latter period also functions as and occurs during the precharge initialization period. Thus in circuits embodying the invention there need be only three periods (or phases).

The Precharge Period which lasts from a time t_0 to a time t_1 is initiated, as shown on FIGURE 3, at a time t_0 when:

- (a) The column select (CS_j) signal goes high (20 volts) as shown in the waveform designated CS in FIGURE 3, whereby all the $M3_i$ transistors are turned-on;
- (b) The demultiplexer signals (Bi) are also pulled high (at 20 volts) as shown for waveforms B0-B5 in FIGURE 3, whereby all the demultiplexing transistors $M1_i$ are turned-on; and
- (c) A precharge data pulse (PDP) applied to node 3 is high (at 15 volts) as shown in waveform DATA INPUT of FIGURE 3, applying a voltage of +15V volts to node 3.

Since a voltage of +20 volts is applied to the gate electrodes of all the $M1_i$ and $M3_i$ transistors, they are turned-on hard (overdriven) and couple the PDP voltage of +15V volts via their conduction paths to the gate electrodes of all the switching transistors $M2_i$. The gate capacitance (C_{gi}) of each one of the $M2_i$ transistors which may be assumed to be in the order of 0.1 pf is then charged to +15V volts.

The precharge period terminates at a time t_1 when the Bi signals go low (i.e., from 20 volts to zero volts). Shortly thereafter the column select signal (CS) goes low after which the precharge data pulse (PDP) goes low. The sequence in which the Bi signals, the CS signal, and the precharge data pulse (PDP) go low ensures that the gate capacitance of all the $M2_i$ transistors remain charged to a high voltage. This is best explained with reference to FIGURE 4A which shows the gate-to-drain and gate-to-source capacitances of transistors $M3_i$ and $M1_i$. That is, transistor $M1_i$ has a capacitance $C11$ between its gate and source and a capacitance $C12$ between its gate and drain and transistor $M3_i$ has



a capacitance C21 between its gate and source and a capacitance C22 between its gate and drain.

As discussed above, during precharge, the precharge data pulse (PDP) applied to input node 3 is equal to +15 volts ("high") and remains "high" from time t_0 to t_3 , as shown in the waveforms of figures 4B. The bit control signal (B_i) applied to the gate of demultiplexer transistor M_{1i} has an amplitude of 20 volts which lasts from time t_0 to t_1 as shown in waveforms B_i of FIGURES 4B. The column select (CS_j) signal applied to the gate of column select transistor M_{3i} has an amplitude of 20 volts and lasts from time t_0 to t_2 as shown in waveforms CS_j of FIGURES 4B. The B_i and CS_j signals of +20 volts amplitude overdrive transistors M_{1i} and M_{3i} , respectively, whereby even though M_{3i} and M_{1i} conduct in the source follower mode the full amplitude (+15 volts) of the data input signal is coupled to the gate of switching transistor M_{2i} and charges their gate capacitances, C_{gi} , to a value of 15 volts. Note that the precharge pulse is also of sufficiently long duration to ensure that the gate capacitance of the switching transistors are fully charged to +15 volts as shown in waveform (V_{cgi}) of FIGURE 4B.

As already noted above the M_{1i} transistors are turned-off before the M_{3i} transistors to preserve the high precharge voltage on the gate capacitance of the switching transistors. The transistors (i.e., M_{1i}) which are closest to the switching transistors (M_{2i}) are turned off first. This occurs when B_i goes from +20 volts to zero at time t_1 . Then, transistor M_{3i} is turned-off with CS_j going from +20 volts to zero volts at time t_2 . The PDP then goes from +15 volts to ground at time t_3 . By turning-off M_{1i} before M_{3i} the precharge level applied to M_{2i} is least affected by the negative termination steps of B_i and CS_j as explained below. When the B_i signal terminates at time t_1 and goes from 20 volts to zero volts, a sharp negative transient step is coupled via C_{11} to the gate of M_{2i} tending to decrease the +15 volts precharge signal previously applied to, and being stored on, the gate of M_{2i} . When CS_j swings from 20 volts to 0 volts at time t_2 a like negative step is coupled via C_{21} from the gate of M_{2i} to its source. If CS_j were to go low followed by B_i going low, the gate of M_{2i} would be subjected to two large negative going steps. By



turning off M1i first, only the negative step due to the termination of Bi has a significant effect on the gate voltage of M2i. Also note that the precharge data pulse goes low after Bi has gone low and M1i has been turned-off to ensure that the gate of M2i remains
 5 precharged to a high level. As noted above, the V_t of transistors made of amorphous silicon may be in the range of 5 volts. Therefore, the system is designed such that the gates of the switching transistors, when intended to be turned-on, will be charged to voltages which range from 8 to 15 volts to ensure that
 10 they are turned-on hard and capable of clamping the y side of the binary weighted capacitors to ground.

During a data load period, which follows the precharge period, six digital input signals (D0-D5), representing the value of an input signal whose digital value is to be converted to a
 15 corresponding analog signal, are serially applied as shown in waveform DATA INPUT of FIGURE 3 to input terminal 3 and transferred on to the gate capacitance of corresponding M2i transistors, as described below.

Referring again to FIGURES 2 and 3, during the Data Load
 20 Period:

- (a) The CZ signal is high, turning on transistor M2 and clamping node 5 to ground potential;
- (b) the charging signal (CHG) applied to the gate of transistor M3 is low, as shown in waveform CHG of FIGURE 3,
 25 whereby transistor M3 is turned-off; and
- (c) the transfer signal (XFER) applied to the gate of transistor M4 is low whereby M4 is turned-off.

In the circuit of FIGURE 2, data load is accomplished by sampling the digital data signals serially applied to input node
 30 3 and applying a corresponding signal onto the gate capacitance of a corresponding selected M2i transistor, as detailed below.

The digital data bits are applied to node 3 in an order (or sequence) with the most significant bit (MSB) being applied first and the least significant bit (LSB) last. The most significant
 35 bit (MSB), also identified as D5, is coupled via transistors M35 and M15 to the gate of M25. The next less significant bit [(M-1)SB], also identified as D4, is coupled via transistors M34 and M14 to the gate of M24. The process is repeated until the least significant



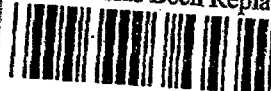
bit (LSB), also identified as D0 is coupled via transistor M30 and M10 to the gate of M20.

At time t_2 as shown in FIGURE 3 the demultiplexing signal B5 goes high (+20 volts) and remains high for an interval T1 until time t_4 . During the interval T1, transistor M15 is enabled, and during this interval 24 MSB digital data signals are applied to node 3. One of these 24 MSB's is selected for a respective DAC_j by conditioning the associated CS_j signal to exhibit a MSB selection or sample pulse during the interval t_1 - t_4 . In this example the column selection pulse (CS_j) occurs at time t_3 and remains high for approximately one MSB bit interval. When CS is high, transistor M35 is turned-on whereby M15 and M35 provide a conduction path or data transfer path between input node 3 and the gate of M25.

Recall that the gate capacitance of M25 was precharged to a "high" level which may be in the range of +8 to +15 volts. Note also that transistors M35 and M15 are overdriven with 20 volts applied to their gate electrodes.

If the MSB data signal (D5) is "high", then M35 and M15 tend to conduct in the source follower mode to reestablish the full 15 volts on the gate of M25. The response of M35 and M15 in the source follower mode is slow and they function as a relatively high impedance path to the data signal, even though they are overdriven. However, since the gate capacitance of M25 is already precharged to a "high" value, M35 and M15 are not needed to charge the gate of M25. Hence, M25, whose gate is precharged to a voltage which is substantially greater than the minimum threshold voltage of M25, remains turned-on hard clamping the Y side of capacitance C5 to ground potential. If the MSB data signal (D5) is "low", transistors M35 and M15 conduct in the common source mode and their series connected conduction paths provide a relatively low impedance path capable of quickly discharging the gate capacitance of M25 to ground. Thus, in the circuit of FIGURE 2, when transistors M35 and M15 are turned-on and the MSB data signal is low, they conduct in the common source mode enabling the relatively quick discharge of the gate capacitance of the M25 transistor to ground and the turn-off of transistor M25. In the system of FIGURE 6 following the transfer

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of all the MSB data signals (D5) to the gates of all the respective M25 transistors, transistor M15 is turned-off at a time t_4 just prior to signal B4 going high.

In a like manner, after all the MSB's have been loaded onto the gates of the M25 transistors, the next bits of lower significance are loaded onto the gates of the M24 transistors during a time interval T_2 (i.e., t_4 - t_6) as shown for waveform B4 of FIGURE 3. Similarly to the previous description, B4 goes "high" at time t_4 , turning on transistor M14, and CS goes "high" at time t_5 turning on transistor M34. During the interval that transistor M34 conducts the (M-1)SB is coupled to the gate of M24.

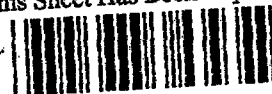
It has therefore been shown that during the data load period a serial data bit (D_i) is applied to data input node 3. The digital data bit (D_i) is, for example, valid for 160 nanoseconds. The CS_j signal turns-on transistor M3_i, for example, for a period of time (e.g., 150 nanoseconds) during which the digital data D_i is valid. Thus the CS_j signal is used to sample the digital data input signal serially applied to node 3 while the demultiplexer transistor M1_i is turned-on. If D_i is high the gate capacitance (C_{gi}) of M2_i remains charged to a high level. If D_i is "low" C_{gi} is discharged via M1_i and M3_i to ground.

It should be appreciated that the gate capacitance, C_{gi} , of the switching transistors M2_i is relatively small (e.g., 0.05 pf to 0.1 pf) whereby the gate capacitance C_{gi} can be charged very quickly.

It should also be appreciated that in circuits embodying the invention, a serial data input signal D_i is captured (or sampled) and stored on the gate capacitance C_{gi} of a switching transistor M2_i. The combination of M1_i and M3_i and the gate capacitance of M2_i function as a sample and hold circuit which can respond very quickly and satisfy the timing requirements of the system, even though the transistors used to practice the invention may be made of amorphous silicon, having low mobility, low gain, and high threshold voltages.

The process of sampling the digital data input signal (D_i) is repeated until the 6 data bits of the serial data are applied to the gate electrodes of the 6 capacitor control switching transistors M25-M20.

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In circuits embodying the invention the gates of the M2i transistors are precharged to the condition (high) which would take the longest time to establish. Consequently the data transfer from node 3 can be done relatively quickly since it only requires discharge of the gate capacitance when the input signal is "low" and the M1i and M3i can operate in the common source node to discharge the gate capacitance node quickly.

The MSB data bits are all loaded prior to the lesser significant bits to allow the MSB switching transistors maximum time to discharge the larger capacitors (C5's). Then the next lesser significant data bits are all loaded to allow the corresponding switching transistors the next longest time interval to discharge the associated transistors, etc. This mode of operation has been determined to be preferable to sequentially loading all to data bits of respective DAC's.

After the data bits have been loaded (applied) to the gates of the capacitor control switching transistors M2i, transistor M2 is turned-off and transistor M3 is turned-on. This is achieved by the signal CHG going high and the signal CZ going low at time t8 as shown in corresponding waveforms in FIGURE 3. The source of transistor M3 is connected to node 5, its drain is connected to node 7 to which +15 volts is applied and its gate is connected to node 6 to which a control charging voltage (CHG) of 20 volts is applied. When M3 is turned-on, a potential of +15 volts is coupled to node 5.

When M3 turns on and +15 volts is applied to node 5, only those capacitors, Ci, whose corresponding switching transistors M2i are turned-on, will be charged. That is, for example, assuming the gate of M24 to be storing a "high" potential, the conduction path of M24 provides a low impedance conduction path for capacitor C4 and clamps the (Y) side of capacitor C4 to ground. Capacitor C4 will have a voltage of +15 volts coupled to its top plate (X) (connected to node 5) and zero volts coupled to its bottom plate (Y). Conversely if the gate of M24 is discharged, then M24 is an open switch and there will be no conduction path to charge capacitor C4.

At the termination of the capacitor charging period, the capacitors Ci corresponding to which the serial digital data



bits, D_i , are "high," will be charged having +V (e.g., 15) volts across their plates while the capacitors C_i corresponding to which the serial data bits, D_i , are "low," will not be charged. The capacitor charge period is terminated when CHG returns to zero (t_9), and

5 M3 is turned-off.

Following the charge phase, all the column select signals (CS) go high and all the demultiplexer signals (B_i) go high concurrently. All the transistors $M3_i$ are then turned-on and all

10 the transistors $M1_i$ are also turned-on and the voltage at node 3 goes "high" applying a PDP of +15 volts to the gates of the $M2_i$ transistors charging all their gates to the high level and turning-on all the $M2_i$ transistors.

The turn-on of all the $M2_i$ transistors causes all the C_i

15 capacitors to be connected in parallel, which in turn causes a redistribution of the charge stored on the selectively charged capacitors C_i , to all the capacitors C_0 to C_5 . Consequently, after the charge is redistributed, a voltage is produced across the storage capacitors C_i whose amplitude corresponds to the binary (digital)

20 value of the previously applied digital data serial input word; i.e., the data signals applied during the preceding data load.

Charge redistribution is known and need not be discussed in great detail. The following brief example should suffice to explain the operation. Assume, for example, that during

25 the data load, only the gates of $M2_4$ and $M2_3$ are charged to a high condition and the gates of $M2_5$, $M2_2$, $M2_1$ and $M2_0$ are discharged. Then, during the capacitor charging (conversion) period, only capacitors C_4 and C_3 are charged. The charge Q_4 stored across C_4 may be expressed as $Q_4 = (C_4)(V)$ and the charge

30 Q_3 stored across C_3 may be expressed as $Q_3 = (C_3)(V)$. Since C_4 and C_3 are connected in parallel, the total stored charge (Q_T) is equal to $(C_3 + C_4)V$.

When all the capacitors are subsequently connected in parallel, the charge stored on C_3 and C_4 is redistributed among all

35 the capacitors and the voltage (V_f) across the capacitors may be expressed as $V_f = (C_3 + C_4)(V)/C_T$. For this particular example and assuming the capacitors to be binary weighted $C_3=8C_0$, $C_4=16C_0$, $C_T=63C_0$ and, $V_f = (24/63)V$.

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The voltage produced at node 5 may be transferred to a succeeding stage by the application of a positive going transfer (XFR) pulse to the gate of transistor M4 (i.e., when XFR pulse goes high at time t_{10} . The turn-on of M4 functions to couple the capacitance of a succeeding stage (CP) in parallel with the storage capacitors C_i . In practice, the analog voltage at node 5 when transferred to the next stage will be attenuated due to the presence of CP.

Note, as indicated in FIGURE 2, a dither signal may be imposed on the output node 5 if desired to improve the effective resolution of the DAC. The dither signal may be a pulsed signal, with pulses occurring concurrently with the XFR pulses, and having an amplitude corresponding to one half the output potential representing an LSB, for example.

A significant aspect of the invention is that the precharge of the gates of the capacitor control transistors M2i also functions to provide the charge redistribution and the generation of the analog voltage at node 5 which is coupled via M4 to an amplifier 67.

The circuit FIGURE 2 may be used to implement the digital-to-analog conversion (DAC) function in the system outlined in FIGURE 5. Serial digital data signals are applied to a digital-to-analog converter (DAC) 100 of the form shown in FIGURE 2 to produce an analog signal which is applied to a data scanner 101 whose output is applied to the column(s) of a liquid crystal display (LCD) panel.

A block diagram of a DAC system incorporating circuits embodying the invention is shown in FIGURE 6 and was discussed above. A serial video input signal is applied to serial digital data generator 112 which functions to format the incoming information and to produce serial data on 40 output channels or data word lines, DWL1 through DWL40. Each data word line is coupled via 24 sublines to 24 different DAC circuits of the type shown in FIGURE 2. Six data bits of the 144 bits serially produced on each subline are sampled in time via column select and demultiplexer bit select lines and applied to each DAC circuit 11 to produce an analog voltage which is used to drive a corresponding column conductor of LCD panel 114. In FIGURE 6 each column select line



(CS) controls the propagating signals corresponding to every 24th column. In FIGURE 7 each column select line (CS) controls the propagating signals corresponding to a set of 40 consecutive columns. The distribution of data bits from the data word line to some of the DAC circuits is detailed in FIGURE 7. In brief, although they differ in source details, the systems of FIGURES 6 and 7 are similar in that serial bits are propagated in parallel on 40 lines. The serial bits on each data word line are then propagated onto 24 sublimes, each subline corresponding to one column conductor of an LCD panel and each subline carrying 6 serial data bits to be converted to an analog voltage for driving its corresponding column conduction.

The binary weighted capacitive network 50 shown in FIGURE 2 requires that each succeeding capacitor be twice the size of a preceding capacitor. This calls for the manufacture of a wide range of capacitors, and that either very large capacitors or very small capacitors are made. (Note that where more than 6 binary steps are desirable the problem becomes worse.) Very small capacitors are difficult to make accurately and there is an additional problem with stray capacitance. Large capacitors take too much space. These problems may be alleviated by the subranging type circuit shown in FIGURE 8. Binary weighted capacitors C3, C4 and C5 may be made to have a capacitance of, for example, 0.05 pf, 0.1 pf and 0.2 pf, respectively. The top plates of capacitors C0, C1 and C2 are connected in common to a node 81 and a coupling capacitor Cc is connected between node 81 and output node 5 to which one side of C3, C4 and C5 are connected. Capacitor Cc functions to divide down the values of capacitors C0, C1 and C2 and to produce a network equivalent to that of 50 in FIGURE 2.

Using 2 equal ratio sections, with each section having N levels (steps or stages), the coupling capacitor Cc may be calculated as follows:

$$C_c = 1/2 C_3 (2^N/2^{N-1}).$$

for N=3, $C_c = 1/2 C_3 (8/7).$

Thus a capacitor network can be formed with two sets of capacitors and a coupling capacitor. The capacitors in one set can be (but need not be) the same as the capacitors in the other



set and, for example, only three different capacitors are required for each set in addition to the coupling capacitor. Transistors M3A and M3B coupled to nodes 5 and 81, respectively perform the same function as transistor M3 in FIGURE 2.

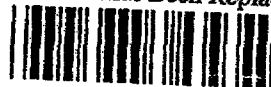
5 In the circuit of FIGURE 2 transistor M3 is used to selectively apply a charging voltage to node 5 and transistor M2 is used to selectively clamp node 5 to ground. Alternatively, a single transistor M3k could be used to perform the functions of transistors M3 and M2 if connected and operated as shown in
10 FIGURES 9A and 9B. Referring to FIGURE 9A, note that transistor M3k would be connected in the circuit of FIGURE 2 instead of transistors M3 and M2 with one electrode (source/drain) 131 connected to output node 5 and another electrode (drain/source) 132 connected to power terminal 7. The gate of transistor M3k
15 would be driven with the CHG/ZERO signal of the type shown in waveform 6 of FIGURE 9B and a potential (charge level) of the type shown in waveform 7 of FIGURE 9B would be applied to power terminal 7. The precharge, data input, column select and bit select signals would be similar to those shown and used in the
20 circuit of FIGURE 2, discussed above.

The circuit of FIGURE 2 is shown to be a six bit Digital to Analog converter. However it should be appreciated that this is only by way of example and more, or less data bits, and a corresponding number of capacitors and transistors would be also
25 used to practice the invention.

A particular switching sequence has been illustrated in the drawings. However it should be evident that other switching sequences and different positioning of the M3i and M1i transistors may be employed without departing from the teachings of the
30 inventors.

Also, the circuit and systems has been shown to have
40 word lines each supplying 24 sublines for producing 960 analog voltages driving 960 columns of a display panel. It should be evident that the total number of outputs could be more or less
35 and the ratio or word lines to sublines may have many different values.

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CLAIMS:

1. A digital-to-analog converter (DAC) for converting a set of N data bits to an analog voltage comprising:

N capacitors (C0-C5), one capacitor for each one of said N data bits;

each capacitor having first and second plates; and

means connecting the first plate of each capacitor to an output node; characterized by:

N switching transistors (M26-M25) one for each one of said N data bits, each one of said N switching transistors having first and second electrodes defining the ends of a conduction path and a gate electrode, each gate electrode having associated therewith a relatively small capacitance;

means connecting the conduction path of each switching transistor between the second plate of its associated capacitor and a first power terminal (ground);

an input node (3) adapted to receive serially supplied digital data signals during a data load interval and a precharge signal during a precharge interval;

N selectively enabled data transfer paths, (M10, M30, ...M15, M35) one data transfer path per each one of said N switching transistors, each data transfer path connected between said input node and the gate electrode of its associated switching transistor;

means (CSj; B0-B5) for selectively turning-on said N data transfer paths, one at time, during said data load interval for selectively sampling the digital data signals and for applying and storing a voltage corresponding to each one of said digital data signals on the gate of a corresponding one of said N switching transistors; and

means (M3) for selectively applying a voltage across said capacitors for charging them in accordance with the data responsive voltage levels present on the gate of their respective switching transistors.

2. A converter in accordance with claim 1 wherein, during each precharge interval, the gate capacitance of each one of said N switching transistors is precharged to a turn-on-level, and said N capacitors are connected in parallel.

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