

DEVICE FOR REMOTE STATUS READINGS AND APPLICATIONS

The present invention relates, generally speaking, to the field of information technologies.

More precisely, according to one of its first aspects, the invention relates to a device for remote
5 status readings, comprising a communication network, a central controller linked to the communication network, and a plurality of peripheral devices linked to the controller through the intermediary of the network, each peripheral device adopting, at each instant, an
10 instantaneous status belonging to a plurality of possible statuses, and the controller periodically scanning the peripheral devices to read their instantaneous status.

Even though many known devices fulfil this definition, these devices usually involve using
15 sophisticated means, leading to a relatively high structural complexity.

Within this context, the device according to the invention has the aim of proposing a technique making it possible to offer the same functions as these known
20 devices, but by implementing simple means that are widespread these days.

In order to do this, the device according to the invention, moreover complying with the generic definition given in the above preamble, is essentially characterised
25 in that the communication network links the peripheral devices to the controller by electromagnetic means, and in that the peripheral devices are supplied with

electrical energy through the intermediary of the communication network.

As a result of this layout, all the connector technology problems are significantly reduced.

5 For example, the communication network can simply comprise a series circuit supplied by the controller and including a plurality of electromagnetic induction loops.

The device according to the invention can be adapted to localised remote status readings by ensuring that each
10 peripheral device has an identification code of its own, that the controller has a configuration memory in which, for each peripheral device, the identification code of this peripheral device and a localisation parameter are stored correlatively, identifying the location of this
15 peripheral device in the network, and that, for each peripheral device, the controller reads the instantaneous status of this peripheral device and its identification code, as a result of which each instantaneous status reading is correlated by the controller with a location
20 on the network.

Whatsoever the intended application, each peripheral device can include, apart from a transmitter-receiver circuit, at least one status encoder adopting an instantaneous status constituting or participating in
25 building up the instantaneous status of this peripheral device, this status encoder being linked to the transmitter-receiver circuit to enable this peripheral device to transmit the instantaneous status of the encoder to the controller.

30 In a possible embodiment of the invention, each peripheral device comprises an electronic tag provided with a memory containing the identification code

attributed to this peripheral device, a local antenna coupled to an induction loop of the communication network to receive the electrical energy transmitted by this induction loop, and from the transmitter-receiver circuit, this transmitter-receiver circuit being linked to the local antenna at least to receive a transmission order from the controller and for transmitting to the controller, apart from the instantaneous status of the encoder, the identification code of this tag.

10 The electronic tags, still called "radio tags", "clever tags" or "smart cards", are widely used these days in many applications for automatic identification, and particularly in anti-theft systems, protection against counterfeiting, the management of handling supports, control of dispatching or reception, etc.

By proposing the use of such tags to obtain remote status readings spread over different locations, the invention thus proposes extending the widespread and proven technique of identification by radio-frequency, or RFTD (Radio Frequency Identification) to localisation in space, thus avoiding the inherent complexities of addressing techniques.

For example, each peripheral device includes, as status encoder, at least one appropriate element such as an electrical contact.

However, each peripheral device can also include, as status encoder, at least one sensor sensitive to the influence of a physical parameter to which this peripheral device is subject.

30 The utility of the device according to the invention can further be increased by providing each peripheral device with a tagging element.

This device is applicable, in general, to remote control management, each peripheral device forming a command terminal able to transmit a determined order to the controller, coded by the instantaneous status adopted
5 by this peripheral device.

When it is adapted to localised remote status readings, this device is applicable to management of remote calls, each peripheral device forming a calling terminal.

10 In particular, each peripheral device can be installed at a specific location, such as a floor of a building, and form a calling terminal for a means of transport, such as a lift.

Finally, in the case where the status encoder for
15 each peripheral device comprises a plurality of appropriate elements, such as electrical contacts, each of these elements can identify a destination assigned to the means of transport from a departure position represented by the specific location.

20 For example, a user of a lift can not only call the latter to the floor where the user situated but can, besides this, indicate which floor he wishes to go to.

Other characteristics and advantages of the invention will become clear from the description given
25 below, as an indicative and in no way limiting example, with reference to the attached drawings, in which:

- figure 1 is a diagrammatic view of a peripheral device applied in a device according to the invention, and using an electronic tag as principal component;

30 - figure 2 is a diagrammatic view of a central controller able to co-operate with the peripheral device of figure 1 in a device according to the invention;

- figure 3 is an overall diagrammatic view of a device according to the invention;

- figure 4 is a diagrammatic view in transparent perspective of a building equipped with a lift managed by
5 a device according to the invention, and

- figure 5 is a cross-section of the same building, seen following the incidence defined by the arrows V-V of figure 4.

As mentioned above, the invention relates to a
10 device (fig. 3) for remote status readings of the type comprising a communication network 1, a central controller 2 linked to the communication network 1, and a plurality of peripheral devices, such as 31 to 33, linked to the controller 2 through the intermediary of the
15 network 1.

At any instant, each of the peripheral devices 31 to 33 takes, from amongst a group of a priori possible statuses, an instantaneous status respectively named STAT_1, STAT_2 and STAT_3 for the different peripheral
20 devices 31 to 33, the controller 2 periodically scanning these peripheral devices 31 to 33 to read the respective instantaneous statuses.

The device according to the invention is distinctive from known devices of this type first of all through the
25 fact that the communication network 1 links the peripheral devices, such as 31 to 33, to the controller 2 by electromagnetic means, and that the peripheral devices are supplied with electrical energy through the intermediary of this communication network 1.

30 As a result of this layout, the very presence of the communication network makes it possible to eliminate both the need for providing a separate electrical supply

network, and the need for ensuring point to point electrical connection for each of the peripheral devices.

For example, the communication network 1 includes a series circuit that itself is supplied by the controller 2 and which includes a plurality of electromagnetic induction loops such as 11, 12 and 13 (figs. 2 and 3), the electric power signal circulating in this series circuit having a frequency typically lower than 500 kHz, and being modulated, for example, at 125 kHz.

Moreover, each peripheral device 31, 32 or 33 is provided with a status encoder 61, 62 or 63, and a transmitter-receiver circuit 421, 422 or 423, the status encoder 61, 62 or 63 being able to produce the instantaneous status STAT_1, STAT_2 or STAT_3 of this peripheral device, and being linked to the transmitter-receiver circuit 421, 422 or 423 of this peripheral device to allow it to transmit this instantaneous status STAT_1, STAT_2 or STAT_3 to the controller 2.

In these conditions, each of the peripheral devices 31 to 33 can form a command terminal in the network 1, able to transmit an order to the controller 2 coded by the instantaneous status adopted by this peripheral device.

In an advanced embodiment of the device according to the invention, allowing localised remote reading of statuses, each of the peripheral devices such as 31 to 33 furthermore possesses its own identification code, called KID_1, KID_2 or KID_3 respectively, for the different peripheral devices 31 to 33.

In order to do this, each peripheral device 31 to 33 preferably includes an electronic tag such as reference 4 (fig. 1).

An electronic tag is typically provided with a memory such as 411, a local antenna such as 401, and a transmitter-receiver circuit such as 421, the latter in this case being capable of constituting the transmitter-receiver circuit mentioned above of the peripheral device
5 equipped with this tag.

The tags of the different peripheral devices 31, 32 and 33 thus comprise, respectively, (fig. 3), memories 411, 412 and 413 for local antennae 401, 402 and 403, and
10 transmitter-receiver circuits 421, 422 and 423.

Each memory 411, 412 or 413 contains the identification code KID_1, KID_2 or KID_3 attributed to the corresponding peripheral device 31, 32 or 33.

Each local antenna 401, 402 or 403 is coupled to one
15 the induction loops 11, 12 or 13 of the communication network 1 to receive the electrical energy transmitted by this induction loop.

Furthermore, each transmitter-receiver circuit 421, 422 or 423 is linked to the corresponding local antenna
20 401, 402 or 403 to be able to receive, from the corresponding induction loop, the electrical energy needed to supply the peripheral device concerned, to receive a transmission command from the controller 2, and to transmit to this controller 2 the instantaneous status
25 STAT_1, STAT_2 or STAT_3 of the corresponding peripheral device 31, 32 or 33, together with the identification code KID_1, KID_2 or KID_3 of the tag concerned, in the advanced embodiment of the invention.

Figures 1 and 3 show an embodiment in which each
30 status encoder comprises two appropriate elements formed by electrical contacts activated manually by a user, that is contacts 611 and 612 for the status encoder 61, 621

and 622 for the status encoder 62, and 631, 632 for the status encoder 63.

Nonetheless, each status encoder can include, as well as or instead of such appropriate elements, one or
5 several sensors sensitive to the influence of one or several physical parameters to which this peripheral device is subject.

Each peripheral device 31, 32 or 33, is provided with a processing unit 51, 52 or 53, internal or external
10 to the electronic tag equipping this peripheral device, linked to the transmitter-receiver circuit 421, 422 or 423 of this peripheral device, and in charge of collecting, coding and/or formatting the instantaneous status STAT_1, STAT_2 or STAT_3 so that this status is
15 taken into account by the transmitter-receiver circuit.

According to another aspect of the invention, essential in the case of a localised remote reading of statuses, the controller 2 is provided with a configuration memory 21 in which, for each peripheral
20 device 31, 32 or 33, are stored the identification code KID_1, KID_2 or KID_3 of this peripheral device, and a localisation parameter such as LOC_1, LOC_2 or LOC_3, that identifies the location of this peripheral device in the network 1, the localisation parameter of each
25 peripheral device being correlated, meaning associated, with the identification code of this same peripheral device.

As those skilled in the art will easily understand from reading the present description, the association, in
30 the configuration memory 21 of the controller 2, of the localisation parameter of each peripheral device with the identification code of this same peripheral device, can

be produced by implementing known means, during an installation phase of the device according to the invention.

As a result of this arrangement, the controller 2
5 can thus, by reading at the same time both the instantaneous status STAT_1, STAT_2 or STAT_3 and the identification code KID_1, KID_2 or KID_3 of each peripheral device 31, 32 or 33 it scans, associate each of the read instantaneous statuses to a determined
10 location of the network 1.

In these conditions, each of the peripheral devices 31 to 33 can form a call terminal in the network 1, the controller 2 itself ensuring the management of remote calls through the intermediary of these peripheral
15 devices or call terminals 31 to 33.

Figures 3 to 5 show an application of the device according to the invention for management of a lift.

In this application, the communication network 1 to which the controller 2 is linked includes induction loops
20 such as 11, 12 and 13, set in regular fashion on one side of the vertical partition CL that closes the front face of the lift column, for example on the right-hand side of each lift door, PT_1, PT_2, and PT_3.

The peripheral devices 31, 32 and 33 are set on the
25 other side of the partition CL, on the different corresponding floors ETG_1, ETG_2 and ETG_3.

Since the different peripheral devices 31, 32 and 33 communicate with the controller 2 on the network 1 thanks to the electromagnetic influence that the loops 11, 12
30 and 13 can exert through the partition CL, these peripheral devices can simply, for example, be attached

onto the partition CL, close to the corresponding door PT_1, PT_2 or PT_3

In this case, the localisation parameters, such as LOC_1, LOC_2 and LOC_3, stored in the configuration memory 21 of the controller 2 are representative of the different floors, the identification code KID_1 of the peripheral device 31 thus being associated with the localisation parameter ETG_1, representing the first floor where this peripheral device is installed, the identification code KID_2 of the peripheral device 32 being associated with the localisation parameter ETG_2, representing the second floor where this peripheral device is installed, etc.

Besides the configuration memory 21, the controller 2 includes a transmitter-receiver circuit 22 in charge of ensuring electrical energy transmission and information transmission on the network 1, a processing unit 23 ensuring information processing as a whole in this controller and having a reading and writing access to the configuration memory 21, and an interface 24 piloted by the processing unit 23 and ensuring the link between the processing unit 23 and a command circuit 8 of the lift.

Each of the peripheral devices 31, 32 and 33 possesses an electric contact 611, 621 and 631, that the user can command with a button to indicate that he wishes to go down to a lower floor, and an electric contact 612, 622 and 632, that the user can command with a button to indicate that he wishes to go up to an upper floor.

If, for example, a user presses on the contact button 622 of the peripheral device 32 situated on the second floor, referenced ETG_2, the controller 2 will receive the identification code KID_2 from this

peripheral device, and the status STAT_2 of the status encoder 62, this STAT_2 status representing the activation of the contact button 622.

By reading its memory 21, the controller 2 will thus
5 be informed that a user, situated on floor ETG_2, that is the second floor, has called the lift and has, more precisely, indicated his wish to go up to an upper floor.

This call can thus be transmitted, through the intermediary of the controller interface 24, to the
10 command circuit 8 of the lift, which will take over to send the most readily available lift cabin to the second floor in order to reach an upper floor.

It is evident that each of the peripheral devices could have a single button only, whose activation would
15 then be taken into account just like a call for the lift for any a priori destination, the user not indicating his destination until inside the lift cabin, by activating the button of the floor required.

On the other hand, each of the peripheral devices
20 31, 32 or 33, instead of having only one single call button for access to an upper floor, and a call button for access to a lower floor, could possess, as status encoder 61, 62 or 63, a keyboard on which the user could specifically indicate the floor of destination, meaning
25 that the status STAT_1, STAT_2 or STAT_3 of each status encoder can a priori be represented by any number of bits whatsoever.

As shown in figures 1 and 3, each peripheral device such as 31, 32 or 33 can furthermore include a display
30 element such as 71, 72 or 73, this element being connected to the processing unit 51, 52 or 53, which in return retransmits the display instructions received from

the controller 2 by the transmitter-receiver circuit 421, 422 or 423.

This display element 71, 72 or 73 thus makes it possible to make available, at the position of each of the peripheral devices, information pertinent for the whole of these peripheral devices, such as the instantaneous movement instruction to the lift cabin, or the floor number this cabin has reached.

As those skilled in the art will have understood by reading the present description, the partition CL of the production mode shown fulfils the function of a support for the peripheral devices 31 to 33 and that of a dielectric separating the induction loops 11 to 13 of the antennae 401 to 403.

These same functions could thus be fulfilled, in other applications of the invention, by materials completely different from those able to constitute a partition of a building.

For example, wallpaper covering the walls of a room could both contain or cover a network of induction loops passing through these walls, and acting as support for a plurality of peripheral devices, for example taking the form of simple tags stuck onto its surface and making remote command possible, in selective manner, for lighting or electrical equipment respectively, distributed throughout the whole room.

In the same way, a fabric for clothing, such as a jacket, could be passed through by a network of induction loops and act as support for a command element for electric equipment, such as a magnetic tape or CD-ROM reader housed in the collar of this clothing, this command element being, for example, fixed onto the

clothing by means of a simple Velcro hook and loop fastener.

CLAIMS

1. System for remote status readings, comprising a communication network (1), a central controller (2) linked to the communication network (1), and a plurality of peripheral devices, (31 to 33), linked to the controller (2) through the intermediary of the network (1), each peripheral device (31 to 33) adopting at each instant an instantaneous status (STAT_1 to STAT_3) belonging to a plurality of possible statuses, and the controller (2) periodically scanning the peripheral devices (31 to 33) to read their instantaneous statuses, characterised in that the communication network (1) links the peripheral devices (31 to 33) to the controller (2) by radio frequency means, and in that the peripheral devices (31 to 33) are supplied in electrical energy through the intermediary of this communication network (1).

2. System for remote status readings according to claim 1, characterised in that the communication network (1) comprises a series circuit supplied by the controller (2) and includes a plurality of electromagnetic induction loops (11, 12, 13).

3. System for remote status readings according to either one of claims 1 or 2, characterised in that each peripheral device (31 to 33) possesses its own identification code (KID_1 to KID_3), in that the controller (2) has a configuration memory (21) in which are stored correlatively, for each peripheral device (31 to 33), the identification code (KID_1 to KID_3) of this

peripheral device and a localisation parameter (LOC_1 to LOC_3) identifying the location of this peripheral device (31 to 33) in the network (1), and in that the controller (2) reads, for each peripheral device (31 to 33), the
5 instantaneous status (STAT_1 to STAT_3) of this peripheral device (31 to 33) and its identification code (KID_1 to KID_3), with the result that each instantaneous status read (STAT_1 to STAT_3) is correlated, by the controller (2) to a location in the network (1).

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4. System for remote status readings according to any one of the above claims, characterised in that each peripheral device (31 to 33) includes, apart from a transmitter-receiver circuit (421, 422, 423), at least
15 one status encoder (61, 62, 63) adopting an instantaneous status (STAT_1 to STAT_3) constituting or participating in building up the instantaneous status of this peripheral device, this status encoder (61, 62, 63) being linked to the transmitter-receiver circuit (421, 422,
20 423) to allow this peripheral device (31 to 33) to transmit the instantaneous status (STAT_1 to STAT_3) of the encoder (61, 62, 63) to the controller (2).

5. System for remote status readings according to claims
25 2 to 4, characterised in that each peripheral device (31 to 33) includes an electronic tag (4) equipped with a memory (411, 412, 413) containing the identification code (KID_1 to KID_3) attributed to this peripheral device (31 to 33), a local antenna (401, 402, 403) coupled to an
30 induction loop (11, 12, 13) of the communication network (1) to receive the electrical energy transmitted by this induction loop, and the transmitter-receiver circuit

(421, 422, 423), this transmitter-receiver circuit being linked to the local antenna (401, 402, 403) to be able at least to receive from the controller (2) a transmission order and to be able to transmit to the controller (2),
5 apart from the instantaneous status (STAT_1 to STAT_3) of the encoder (61, 62, 63), the identification code (KID_1 to KID_3) of this tag.

6. System for remote status readings according to claim 4
10 or 5, characterised in that each peripheral device (31 to 33) includes, as status encoder (61, 62, 63), at least one appropriate element (611, 621, 631) such as an electric contact.

15 7. System for remote status readings according to any one of claims 4 to 6, characterised in that each peripheral device (31 to 33) includes, as status encoder, at least one sensor sensitive to the influence of a physical parameter to which this peripheral device is subjected.

20 8. System for remote status readings according to any one of claims 4 to 7, characterised in that each peripheral device (31 to 33) furthermore includes a display element (71, 72, 73).

25 9. System for remote status readings according to any one of the above claims, characterised in that each peripheral device (31 to 33) forms a command terminal for management of remote commands.

30 10. System for remote status readings according to any one of claims 1 to 8, characterised in that each

peripheral device (31 to 33) forms a call terminal for management of remote calls.

11. System for remote status readings according to claim
5 10, characterised in that each peripheral device (31 to 33) is installed at a specific location, such as a floor of a building (ETG_1 to ETG_3), and forms a call terminal for a means of transport, such as a lift.
- 10 12. System for remote status readings according to claim 11, characterised in that the status encoder of each peripheral device (31 to 33) includes a plurality of appropriate elements (611, 612; 621, 622; 631, 632) such as electric contacts, each of which identifies an
15 assigned destination for the means of transport from a departure position represented by the specific location.