

Abstract

Provided are a gripping device and a method. The gripping device comprises: an upper surface gripping unit having a first suction surface that can be suctioned onto the upper surface of an article; a control unit that controls the movement of the upper surface gripping unit by setting a transport parameter, for actuating the upper surface gripping unit, on the basis of transport target data about the article; and a correction unit that corrects, on the basis of characteristic data about the article, the transport parameter determined by the control unit.