

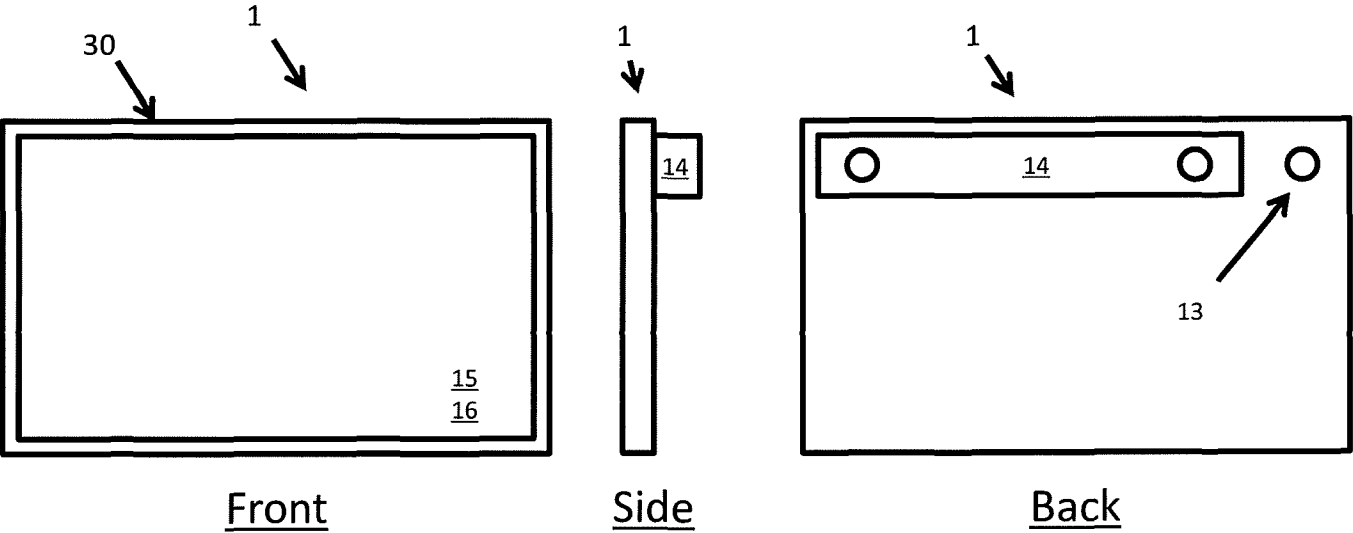


FIG. 1

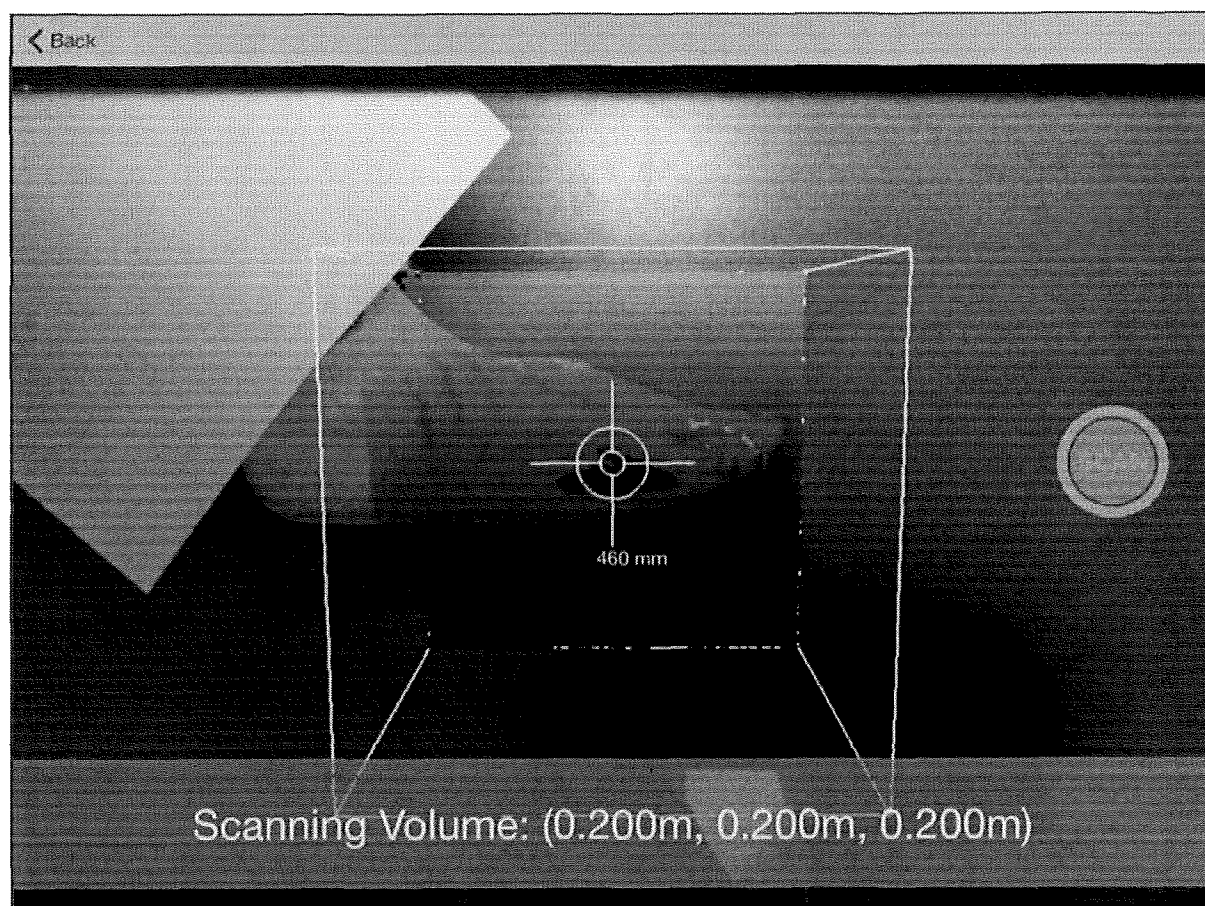


FIG. 2A

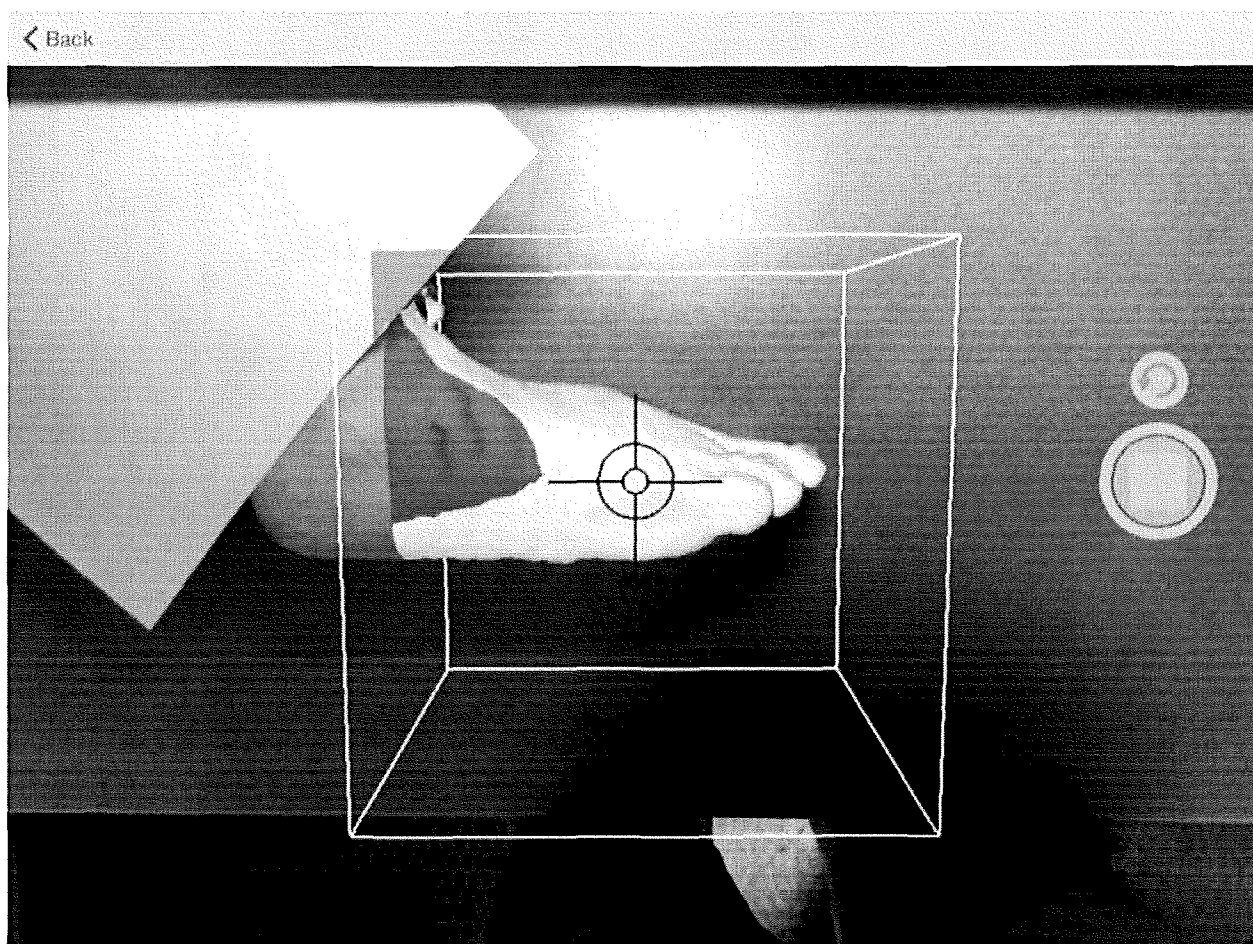


FIG. 2B

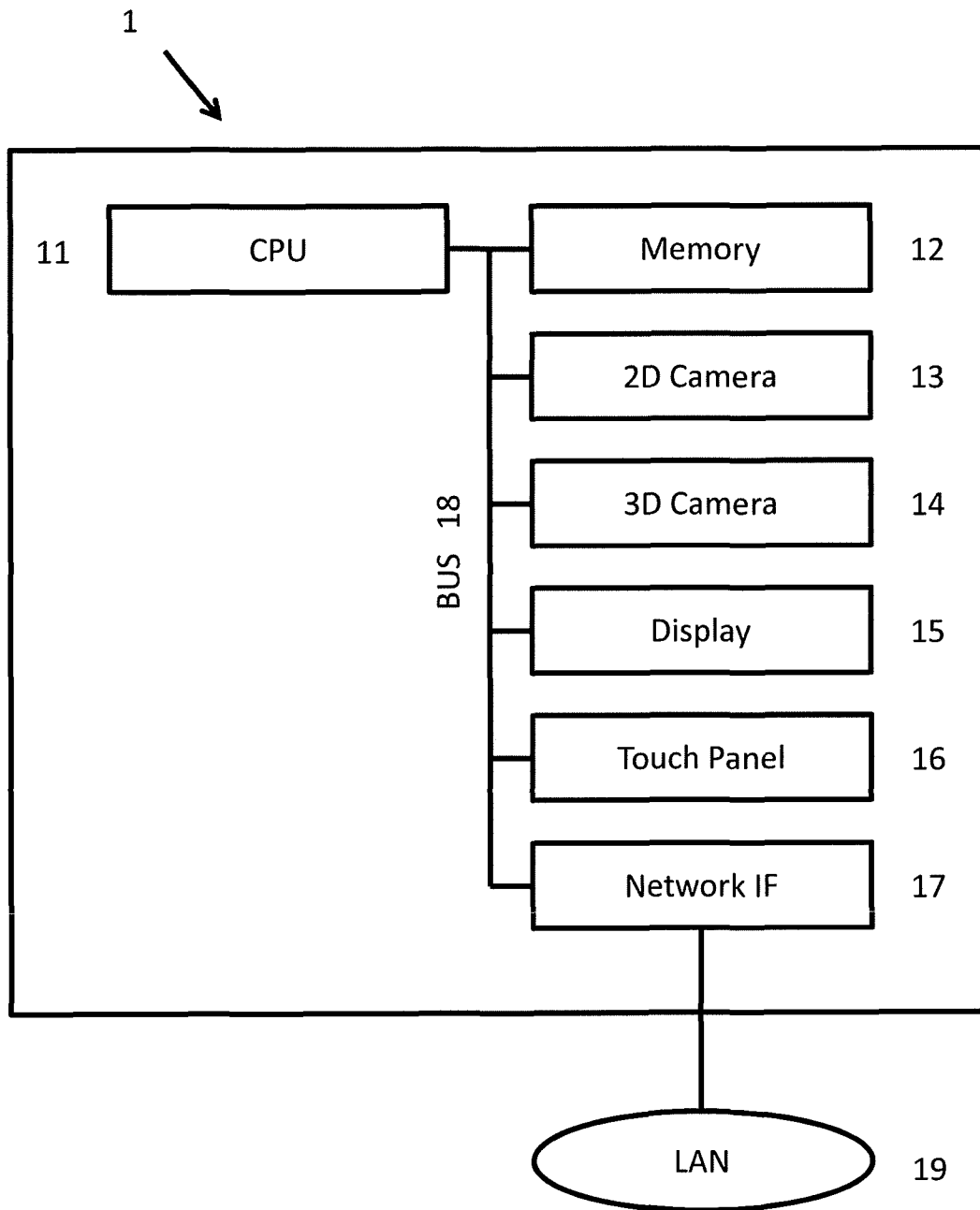


FIG. 3

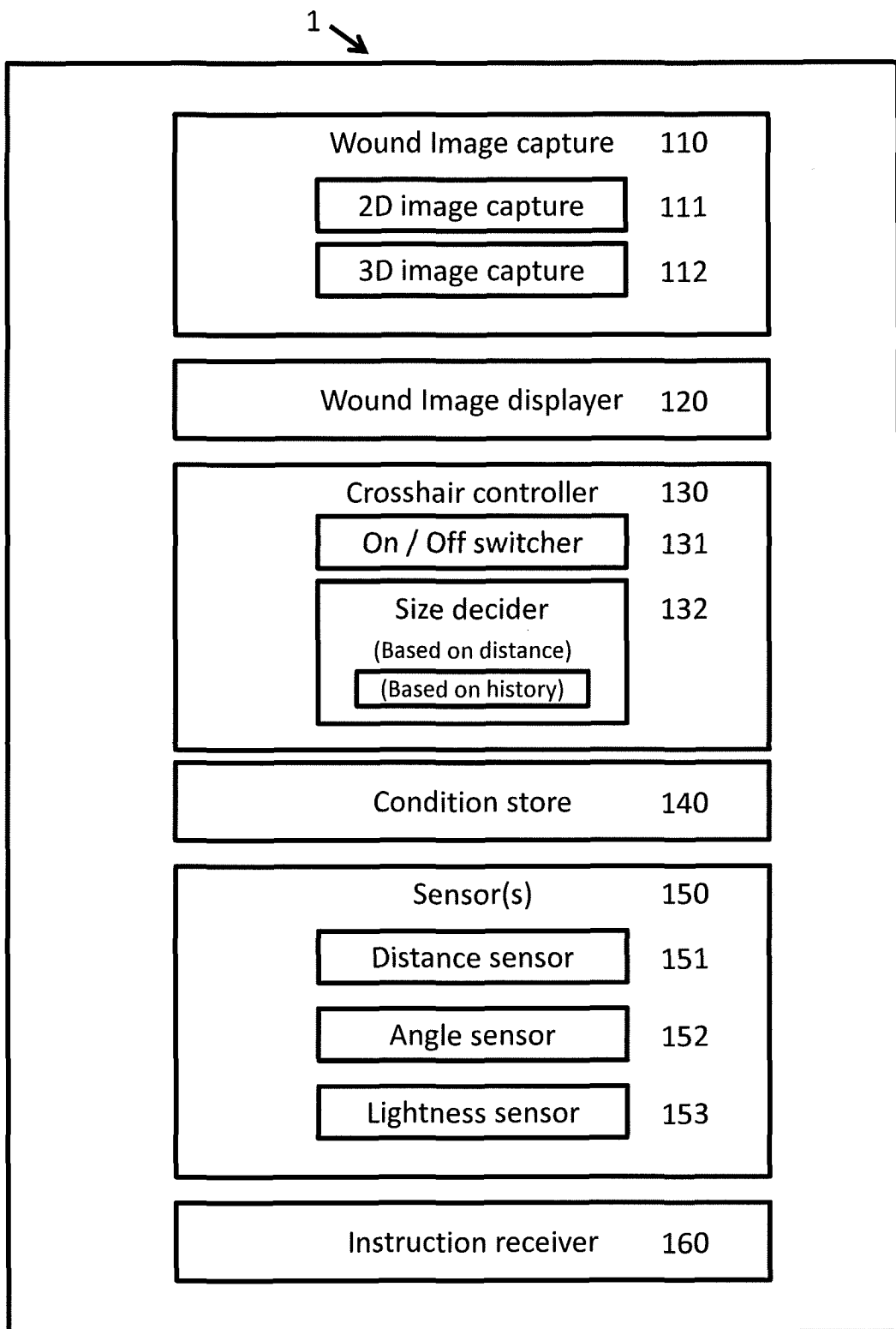
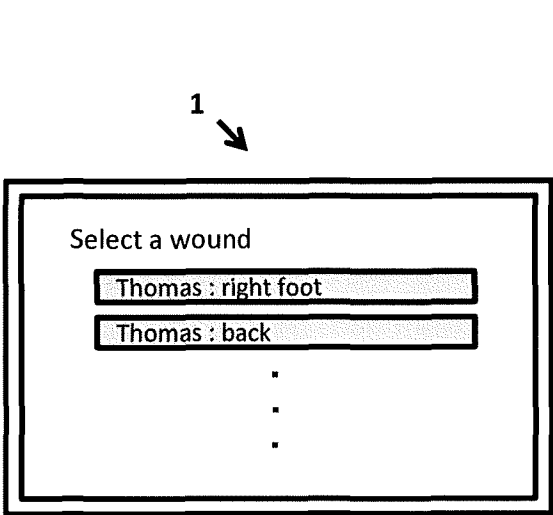
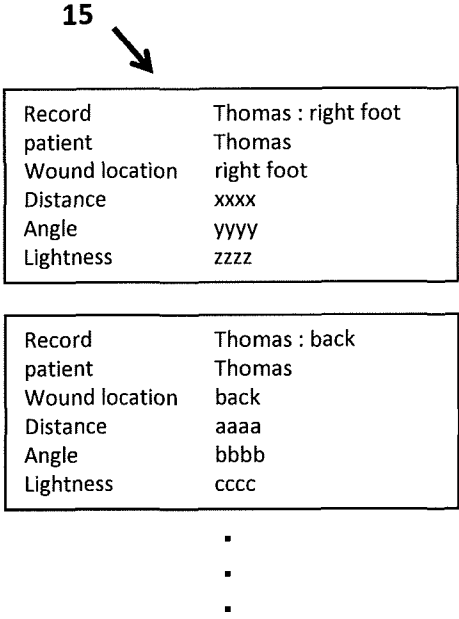


FIG. 4



Condition select menu

FIG. 5



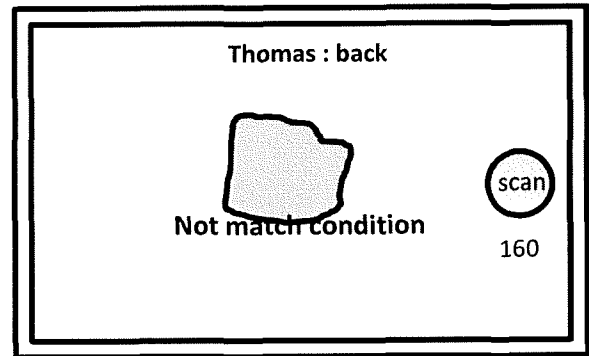
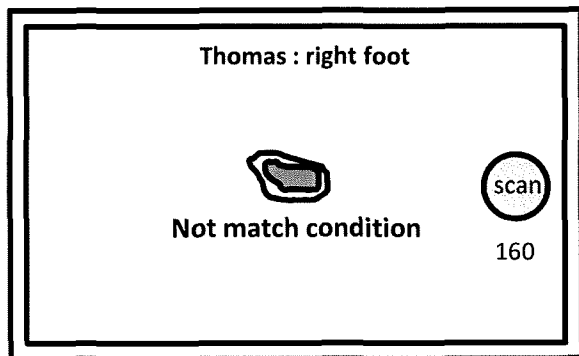
Stored condition data

FIG. 6

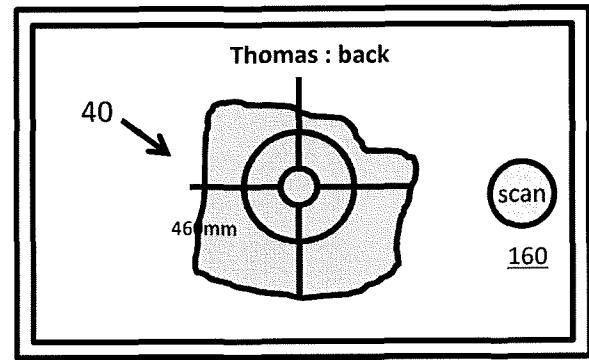
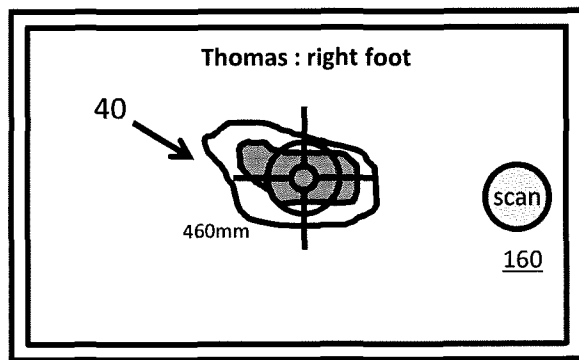
Record	Thomas : right foot1	Record	Thomas : back1
Capture date	2015.m1.d1	Capture date	2015.m4.d4
Patient	Thomas	Patient	Thomas
Wound location	right foot	Wound location	back
Wound width	xxxx1	Wound width	aaaa4
Wound height	yyyy1	Wound height	bbbb4
Wound depth	zzzz1	Wound depth	cccc4
Wound shape	vvvvv1.bmp	Wound shape	dddd4.bmp
Record	Thomas : right foot2	Record	Thomas : back2
Capture date	2015.m2.d2	Capture date	2015.m5.d5
Patient	Thomas	Patient	Thomas
Wound location	right foot	Wound location	back
Wound width	xxxx2	Wound width	aaaa5
Wound height	yyyy2	Wound height	bbbb5
Wound depth	zzzz2	Wound depth	cccc5
Wound shape	vvvvv2.bmp	Wound shape	dddd5.bmp
.		.	
.		.	
.		.	

Wound detection history data

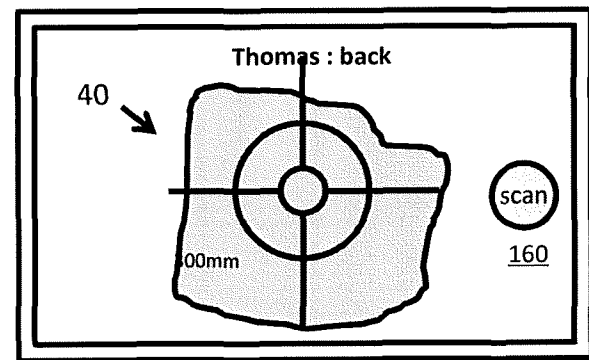
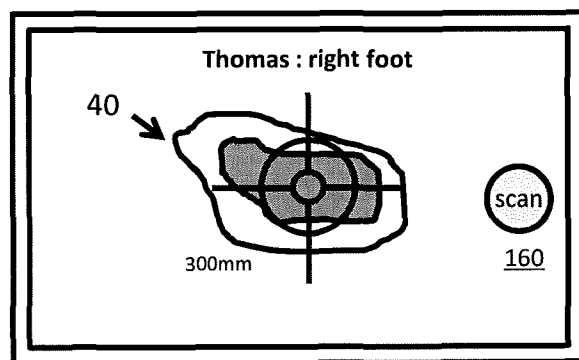
FIG. 7



The crosshair is not displayed if the present capturing environment does not correspond to the stored condition.



The crosshair is displayed if the present capturing environment corresponds to the stored condition. In addition, the distance between the 3D camera and the wound is displayed.



In response to moving the device close to the wound, the wound image is magnified. The size of the crosshair is also magnified so that the size consists with a predetermined actual length.

FIG. 8

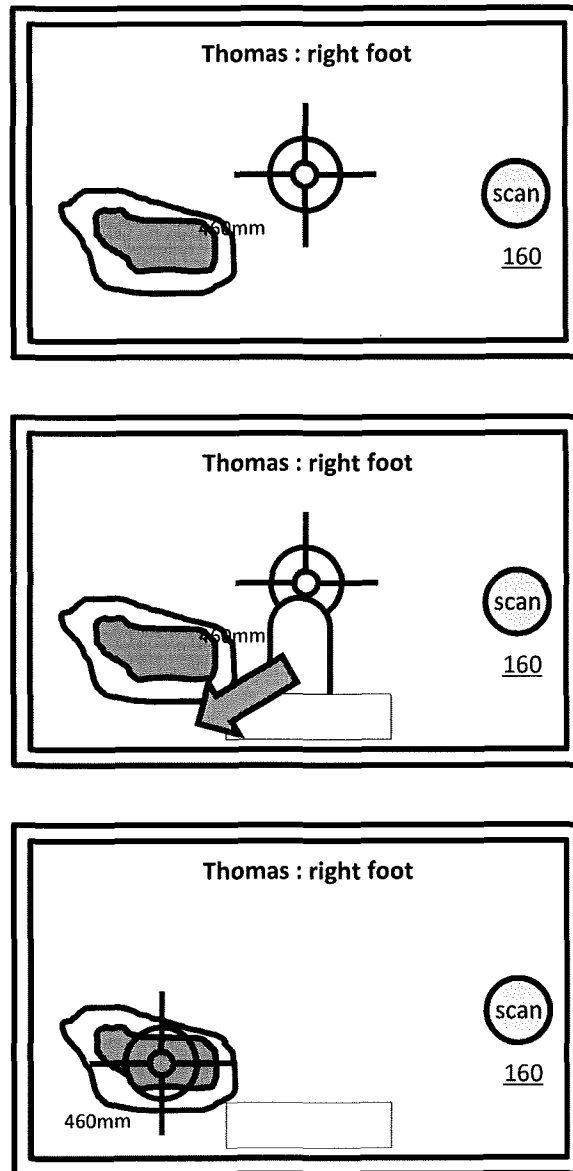
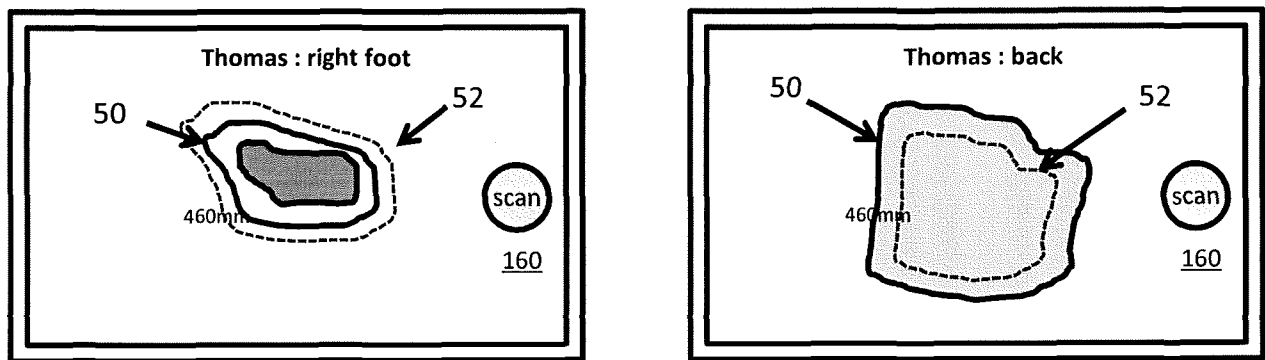


FIG. 9



Variation of shape of bounding volume

FIG. 10

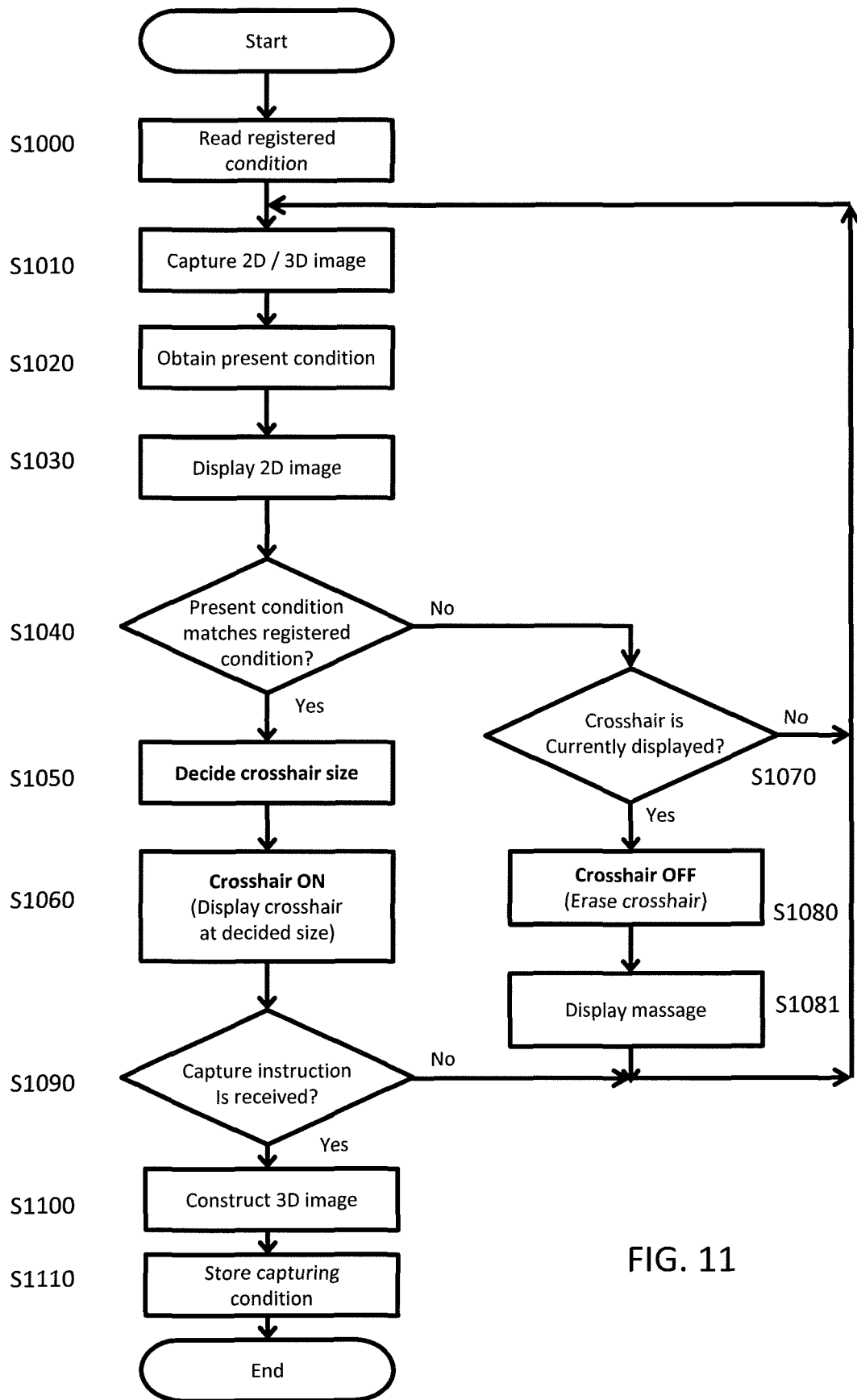


FIG. 11

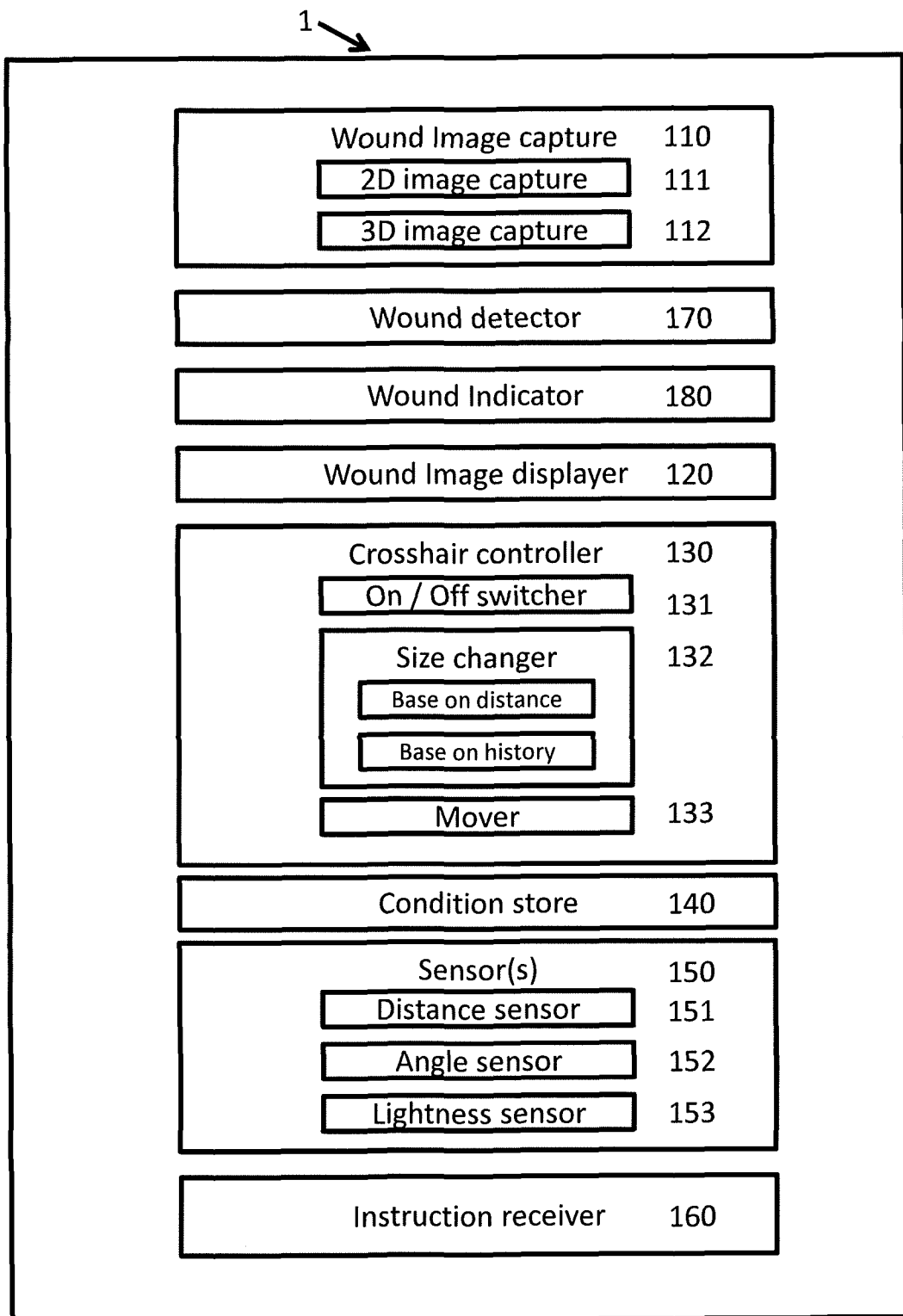


FIG. 12

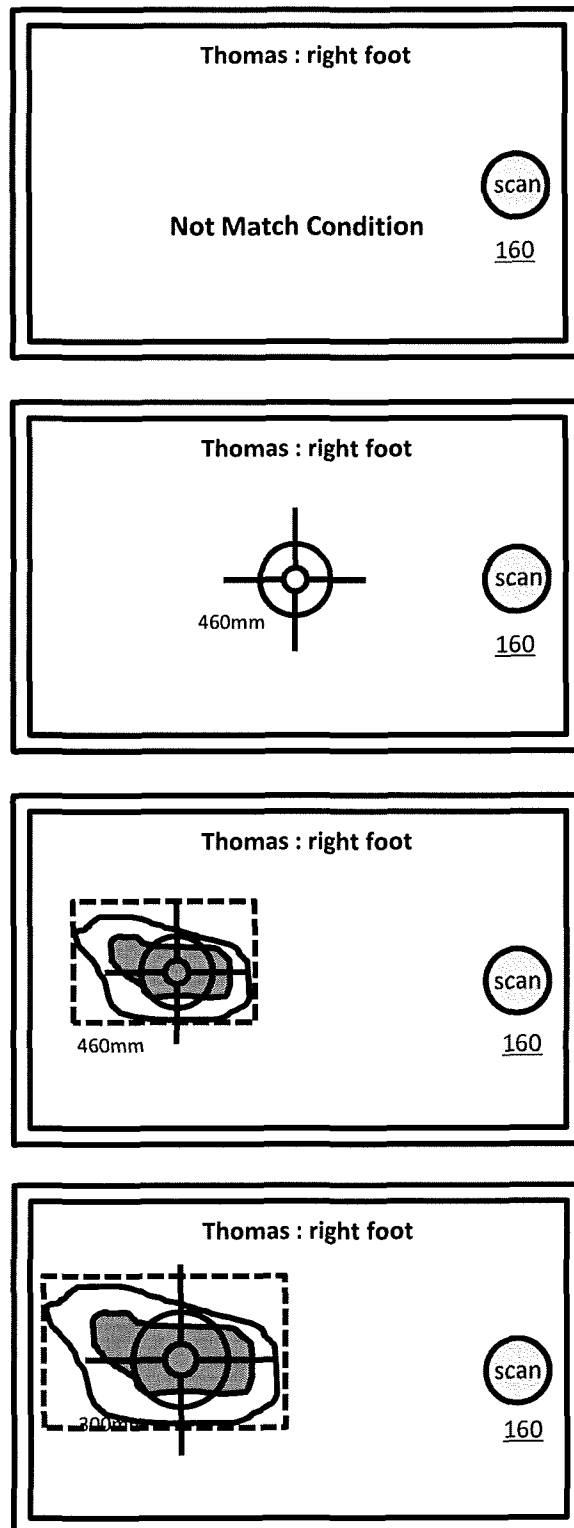
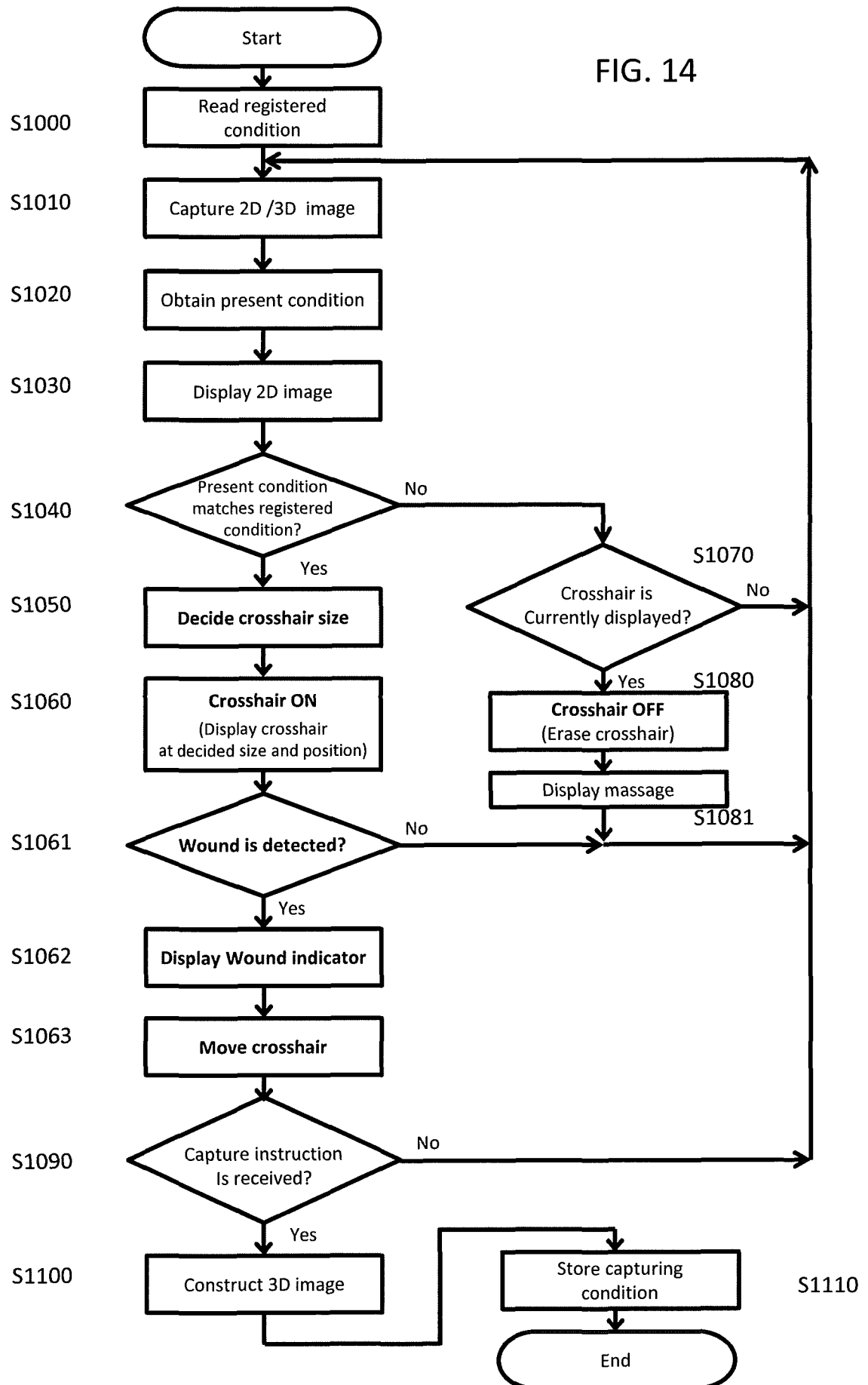


FIG. 13

FIG. 14



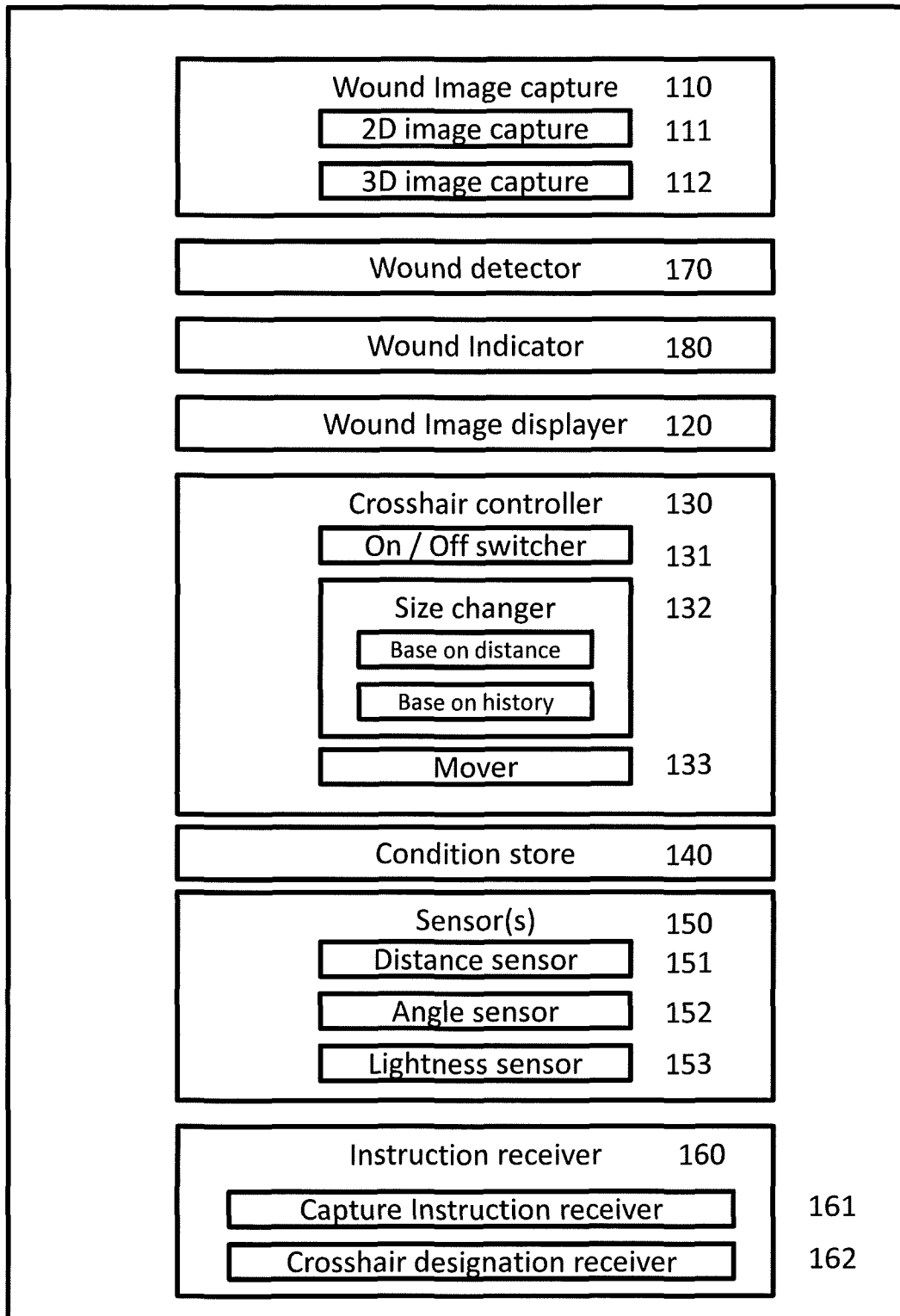
15/18
1 →

FIG. 15

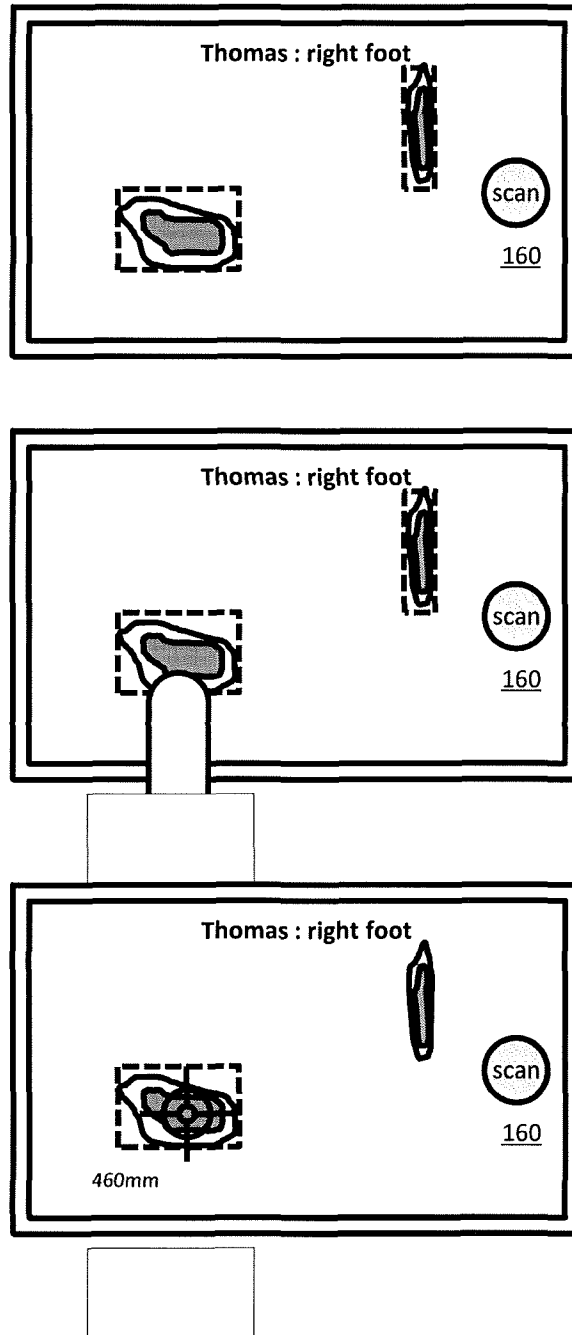


FIG. 16

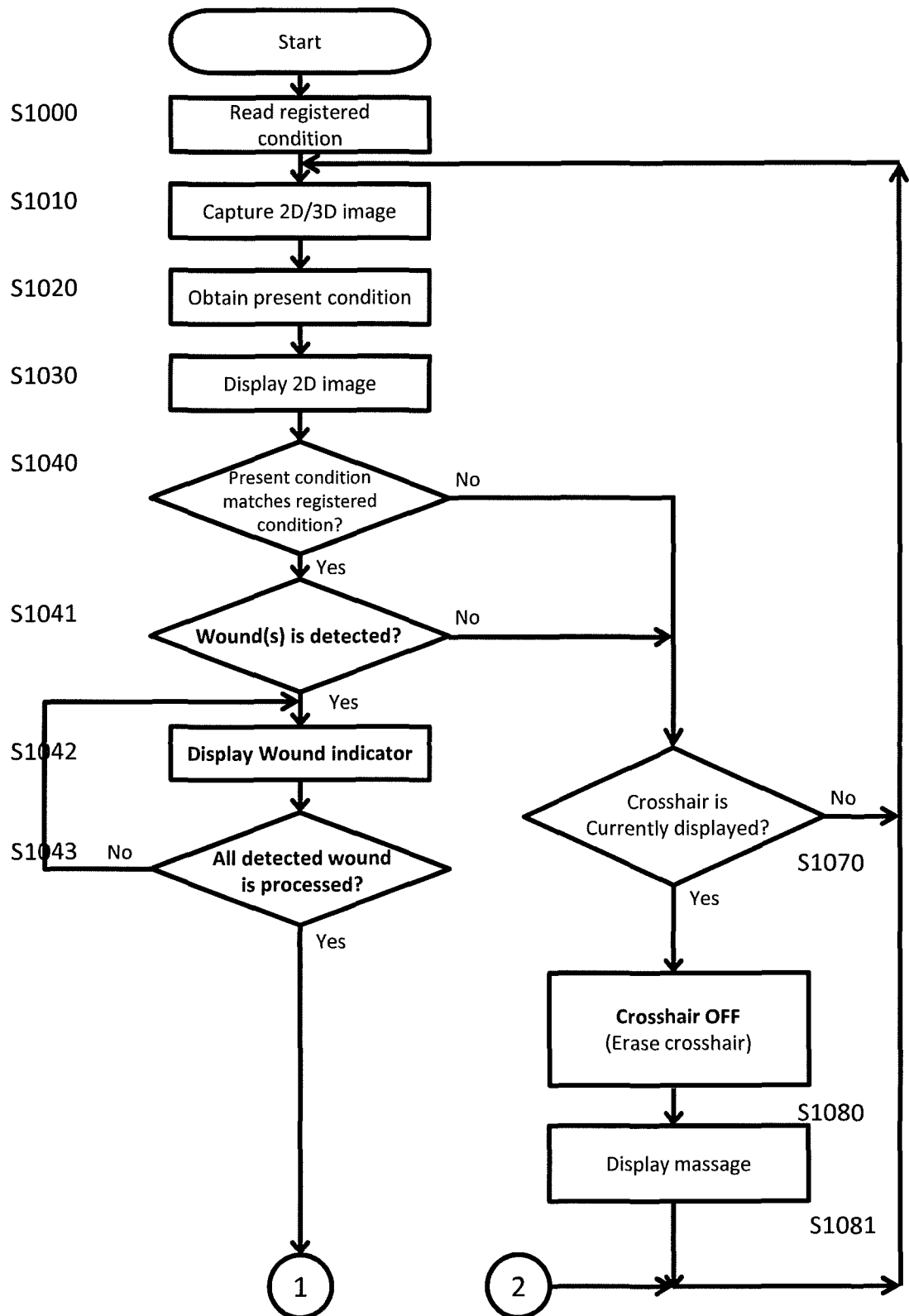


FIG. 17A

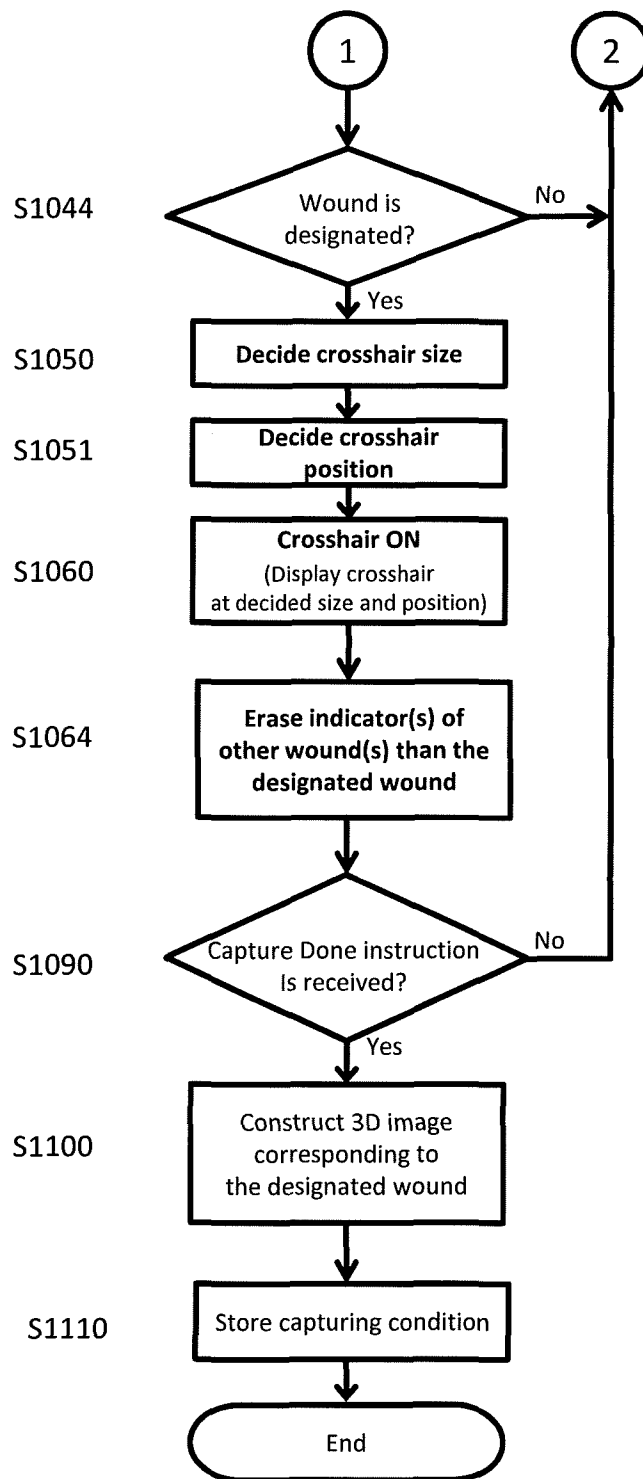


FIG. 17B