

Abstract

The invention relates to a robot system comprising at least one robot arm and a control unit which is designed such that it can pre-set at least one pre-defined operation that can be carried out by the robot system. The robot system also comprises a display device and at least one input device applied to the robot arm, which is designed such that the sequence of operations of the robot system can be set and/or the pre-defined operations of the robot system can be parameterised by means of the input device, and which is also designed such that it allows the user to control, on a graphic user interface, represented by the control unit on the display device, the setting of the pre-defined operations of the robot system, the setting of the sequence of operations and/or the parameterisation of the pre-defined operations for the robot system.

Fig. 1