

ABSTRACT

Disclosed is a path search system for a robot, wherein the path search system includes a simulation unit, a starting point changing unit, and a data analysis unit, and can set a task-specific starting point for a robot in a smart factory so that the robot can have an efficient movement path. According to the path search system for a robot and the like of the present invention, a task-specific starting point for a robot can be set so that the robot can have an efficient movement path.

FIG.1