

Description**1. Field of the Invention**

5 This invention relates to a local data distribution system and in particular to a bus oriented architecture and to the proper biasing of a data distribution bus to optimize the application of priority codes on the bus by individual data processing stations during contention for access activity.

Background of the Invention

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In a bus oriented data distribution architecture a plurality of data processing stations are connected to a common data distribution bus. The distribution system is normally operated in two modes of operation: a data transmission mode and a contention mode. During the data transmission mode any particular station transmits data on that bus by bringing the bus into successively different signal or logic states. Similarly, a data driver at a terminal end of a bus may apply data to the bus to be transmitted to one of the data processing stations. In systems where only one data processing station may transmit data at one time, two or more stations may simultaneously compete for access to the bus. A contention mode of operation is utilized to give a particular station priority should two or more data processing stations attempt to transmit data on the bus at the same time.

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In a contention mode of operation, two or more individual data processing stations simultaneously apply priority codes to the data distribution bus in order for one of them to gain access thereto: It is essential that the bus be maintained at some predetermined and controlled reference logic state during this mode of operation. This predetermined and controlled reference logic state must establish the reference state for the entire length of the bus and simultaneously permit individual data processing stations connected thereto to override the reference state of the bus in order to place its priority code onto the bus where it may be compared with the priority codes of other data processing stations also competing for access to the bus at the same time. European patent EP-A-0030095 discloses a bus transmission system having two or more drive circuits connected to a common transmission line. The drive circuits are provided with three distinct states; a low-level state, a high-level state and a high-impedance state. At the low-level and high-level states the output impedance of the drivers is small and at the high-impedance state their output impedance is very high. The drivers are placed in the high-impedance state when no data is being transmitted over the bus. This arrangement enables the transmission of data without being affected by residual voltage in the transmission line.

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U.S. Patent 4,516,205 discloses a system for controlling access to a bus of a data transmission system by selected ones of a plurality of data stations. To avoid transmission of data by more than one station at a time each data station is assigned a unique address. The addresses of the data stations with data to transmit are compared to assign the stations a priority. The station having the highest priority is granted access to the bus.

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According to the present invention there is provided an arrangement as defined in claim 1. A local area data distribution system having data transmission and contention modes of operation includes an access control system which establishes a controlled logic state on a data distribution bus during a contention interval for allowing a plurality of data processing stations to simultaneously contend with one another in gaining access to the bus. It establishes a controlled state level on the bus that allows each of the contending data processing stations to apply a priority code to the bus to determine which station will gain access to the bus by comparison of the priority codes.

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During a contention interval the bus is held at a predetermined and controlled bias or 'weak' logic state which may be overridden by a priority code bit output of any of the data processing stations. This weak logic state is accomplished through use of a bus biasing system, which holds the bus in an easily overridable logic state during contention activity to allow the priority code bit of any particular work station to control and establish a different logic state on the entire bus.

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Brief Description of the Drawings

55 An appreciation and understanding of the invention may be readily attained by reference to the following specification and the accompanying drawing herein.

FIG. 1 is a block schematic of a data distribution system including its data distribution bus, its bus drivers, the interface circuits and associated data processing stations connected thereto,

FIG. 2 is a schematic showing the bias drive arrangement of the data distribution bus shown in FIG. 1.

FIG. 3 is a schematic showing an alternative embodiment of a bias drive for a data distribution bus, and FIG. 4 is a schematic showing yet another alternative embodiment of a bias drive for a data distribution bus.

5 Detailed Description

A data distribution bus 110 of a local data distribution network and its associated data processing devices is shown in FIG. 1. The data distribution bus 110 is intended to transmit data bidirectionally from any one of a plurality of data processing stations connected to the bus 110 to a bus termination interface unit 100. A plurality of data processing devices 120 are each coupled, via individual station interface circuits 121 to bus 110. These data processing devices 120 (two are shown) may be distributed along the length of the bus, but need not be distributed in any structured dimensional configuration. The data distribution bus 110 may be a two wire pair or other suitable broad band cable transmission medium. The far end of the bus is terminated in a resistive termination impedance 113 equal to the resistive characteristic transmission impedance of the bus 110. The near end of the bus 110 is also terminated by a resistive termination impedance 115 which is selected to be greater than the characteristic impedance of the bus 110.

The near end of bus 110 is connected via common mode choke 117 to a data driver/receiver interface unit 130 which during the data transmission mode transmits data to and receives data from the data transmission bus 110, and it is in turn connected to a data switch 131. The data switch 131 interconnects the bus 110 via interface unit 130 to a host computer and/or to other data distribution bus networks. A data direction and interval control 133 is connected to the data driver/receiver unit 130 and is operative to determine if the data driver/receiver unit 130 is operative to transmit data from the switch 131 to the bus 110 or from the bus 110 to the switch 131. In one particular embodiment data is transmitted as data packets and switch 131 is embodied as a packet switch. The data driver/receiver unit 130 and the station interface circuits 121 are all connected to the bus 110 via common mode choke filter 117.

The direction of data transmission on the bus 110 is controlled by the data direction and interval control 133. The data direction and interval control 133 repeatedly applies a synchronization signal to the data driver/receiver 130 which in turn broadcasts it to the station interfaces 121. This synchronization signal is followed by a direction signal indicating the direction of data transmission. When the data switch 131 does not have data to send to the data processing stations 120 the direction signal is sent out onto the data distribution bus 110 having a code designation indicating to each station interface 121 that if it desires it may now contend for access to the bus in order that it may send data to the data driver/receiver unit 130.

When data flow is from a data processing device 120 to the data driver/receiver unit 130 the individual data processing station with data to transmit must first gain access to the bus 110 for transmitting the data. If two or more data processing devices 120 simultaneously have data to transmit, they must contend with each other to gain access to the bus. Each individual data processing device 120 utilizes a particular priority code assigned to the station interface 121 connecting it to the bus. The station interface compares its code with the code placed on the bus by station interfaces 121 of other contending data processing devices 120 when access to the bus 110 is desired. The contention interval is established under control of the data direction and interval control 133 which biases the bus 110 at a predetermined logic state that station interfaces may override.

During a contention interval each station interface transmits its priority code to the bus 110 bit by bit. It applies a positive voltage to the bus to indicate a logic one and tristates (i.e. - its output is disabled to a high impedance) to represent a logic zero value. Each station interface 121 compares successive ones and zeros appearing on the bus with the bit values of its own station priority code until it detects a logic one on the bus at the same time it transmits a logic zero. That particular station interface then drops out of contention. This process continues until the station interface with the highest priority code wins contention and gains access to the bus 110.

During the contention interval the data driver/receiver unit 130 is inactive (tristated) and the near end bus termination impedance is significantly altered from its value that exists during the data transmission mode of operation when the data driver/receiver 130 is transmitting to bus 110. A contention driver 135 is activated and in concert with a resistive network comprising resistors 115, 136 and 137 provides for a termination impedance equal to the characteristic impedance of the bus 110 during the contention interval. For the duration of the contention interval the data transmission bus 110 must be primarily biased to a logic zero state and yet be readily overridable for the entire length of the bus by application of a logic state of any of the station interface circuits 121 that wishes to change the bus bias level to a logic one state. This override function is facilitated by the contention driver 135 which is enabled by the data direction and interval control 133 to provide the proper bus impedance termination and biasing during a contention

interval prior to data transmission by a data processing device 120.

The contention driver 135 is similar in circuitry to the data driver/receiver 130 but is coupled to the bus 110, via a pair of balanced resistors 136 and 137, and bypasses the common mode choke filter 117. The output of the contention driver 135 places the bus 110 in a weak zero logic state at a controlled level that may be easily overridden by any of the station interface circuits 121 to change a state of the bus 110 to a logic 'one' state so that the bus is driven by the station interface 121 to a logic 'one' state for its entire length.

The balanced resistors 136 and 137 coupling the output of the contention driver 135 to the bus 110 combine with the terminating impedance 115 at the near end to terminate bus 110 at its real or resistive characteristic impedance. The output of contention driver 135 produces a zero logic state on the data distribution bus 110 over its entire length but at a bias level such that any one station interface 121 can readily override it and apply a different logic state to the entire length of the bus. An understanding of this operation may be readily attained by referring to FIG. 2 which discloses a schematic of the overall bus level drive scheme.

A bus drive scheme for both data transmission and contention between data processing stations is disclosed in FIG. 2. A data distribution bus 210 is shown terminated at its near end and far end by resistive terminations 215 and 213, respectively. The resistive termination 213 is selected to equal the resistive value of the characteristic impedance of bus 210. The resistive termination 215 is selected to equal the resistive value of the characteristic impedance of the bus when it is connected in parallel with resistors 236 and 237 which in turn are in series with the output impedance of contention driver 235. As shown there is a data driver amplifier 214 and a data receiver amplifier 275 connected to the near end of the bus 210. These amplifiers are embodied as tristate devices. A contention driver amplifier 235, also a tristate device, is connected via the balanced resistors 236 and 237 to the near end of the bus 210. The contention driver amplifier 235 is shown connected to ground level (or zero voltage) to indicate that contention driver 235 must have a zero state input and must be separately enabled by the direction and interval control (shown in FIG. 1) during a contention interval. A plurality of data transmission amplifiers 225 and data receiver amplifier 226 are connected along the length of the bus 210 each of which interconnect it to individual data processing devices.

During a contention interval the contention driver 235 is enabled by closing of switch 219 and a zero state is applied to drive bus 210 to a 'weak' zero logic state. The contention driver's low impedance output connects resistors 236 and 237 in series with each other and with the driver output impedance; with the series connection thereof being connected in parallel with the near end terminating impedance 215. The overall terminating impedance presented to the bus 210 by this parallel network during the contention interval equals the combined impedance of the two balanced resistors in series with the output impedance of contention driver 235, which in turn are in parallel with the near end termination impedance 215 of the bus. This combined impedance includes individual values selected to optimize the termination impedance for contention activity and suitably equals the resistive part of the buses' characteristic impedance. With this resistive network terminating bus 210 the contention driver 235 is enabled to apply a weak logic signal to bus 210 that is sufficiently powerful so that the most distant data processing station will detect this logic zero state, and yet permit any one of the amplifiers 225 to drive the entire bus to a logic 'one' state. Accordingly, the resistive network that terminates the near end of the bus 210 must sufficiently attenuate the logic zero signal V_0 present at the output of the contention driver to provide the optimum amplitude of a weak logic zero signal V_B on bus 210. These two quantities are related by the equation:

$$V_B = BV_0$$

where B is the transmission parameter of the resistive network including resistors 215, 236 and 237 and the output impedance R_{DO} of the contention driver 235. Furthermore, the resistive network terminates the bus 210 with an impedance optimized to minimize signal reflection when a data station places a logic 'one' state on the bus. The value B is related to these values by the equation:

$$B_{network} = \frac{R_{215} (R_o)}{R_{215} (R_o + R_{236} + R_{237}) + (R_{236} + R_{237}) R_o}$$

where B is the resistive network transmission parameter seen by the contention driver 235. R_{236} and R_{237} are the values of the balanced coupling resistors 236 and 237, and R_o is the resistive portion of the

characteristic impedance, bus 210.

Since this resistive network must present a near end bus terminating impedance equal to the resistive portion of its characteristic impedance R_o , the following requirement must be met:

$$R_{215} = \frac{R_o (R_{236} + R_{237} + R_{DO})}{R_{236} + R_{237} + R_{DO} - R_o}$$

where R_{215} is the near end terminating impedance 215 of the bus, and R_{236} and R_{237} are the values of the balanced coupling resistors 236 and 237 and R_{DO} is the output impedance of the contention driver 235. R_o is the resistive portion of the characteristic bus impedance.

Suitable values for these resistive components for the terminating and balanced resistors may be readily derived from these two equations in view of anticipated worst case operating conditions, and the level of power input.

Since the 'zero' state is nominally held on the data transmission bus 210 by the contention driver 235, the individual station interfaces amplifiers 225 need only disable their tristate output devices in order to output a logic zero. If any one station applies a logic 'one' to the bus, the contention process is such that stations outputting a logic 'zero' at that time drop out of contention.

When data is being prepared to be sent by any of the data processing devices during the data transmission mode, the transmit and contention drivers 214 and 235 are disabled to their tristate state and the line termination value is determined solely by the termination resistances 215 and 213.

The bus drive scheme shown in FIG. 3 is an alternative embodiment suitable for application in situations where the length of the data distribution bus 310 is relatively short as compared with the system disclosed in FIG. 2. In the bias drive scheme shown in FIG. 3 the data driver and contention driver function are combined into a single driver amplifier 335 which is connected to the data transmission bus 310 via a resistive network including termination resistor 315 and the balanced resistors 336 and 337. When data is applied to the bus 310, the data driver amplifier 335 is enabled and the data is applied to the bus via the resistive network. While the resistive network will attenuate the data signal, this is not critical if the length of the bus 310 is kept within a length that will provide a sufficient signal amplitude at the far end of the bus 310. During a contention interval, the driver circuit is also enabled and an input logic zero signal applied to lead 345 holds the bus 310 at a weak logic "0" state.

Another alternative bias drive arrangement is disclosed in FIG. 4 for application to data distribution buses where minimizing signal reflections due to the slight mismatch in termination impedance is deemed necessary. The drive system includes a data drive amplifier 414, a data receive amplifier 415 and a contention driver 435. The drive scheme further includes the dual termination drivers 444 and 445 which are enabled to be simultaneously operative during data transmission intervals to positively assume a proper line termination at the near end of the data transmission bus 410 and minimize signal reflections. The top termination driver 444 and the lower termination driver 445 are each connected to the bus 410 with opposite polarity to each other so that no logic state is applied to the data transmission bus by the termination drivers when the two termination drivers are enabled. The balanced resistors 446, 447, 448 and 449 are selected with a value such that when the termination drivers are both enabled simultaneously, and the data driver 414 and contention driver 435 are disabled, the near end of the data transmission bus will be terminated by its characteristic impedance.

Claims

1. A local area data distribution bus access arrangement, comprising;

a bus (110) having a far and near end,

a first termination impedance (113) connected at the far end of the bus,

at least one station interface (121) connected to the bus intermediate the far and near end,

a data driver/receiver (130) coupled through a second termination impedance (115) connected to a near end of the bus and operative to transmit and receive data during intervals of non-contention,

CHARACTERIZED BY

a contention driver (135) and an impedance network (136, 137) connecting the contention driver through the second termination impedance to the near end of the bus,

a data direction and interval control (133) connected to the data driver/receiver to synchronize it and to the contention driver to define intervals of contention where the data driver/receiver is inactive

characteristic impedance bus 210.

Since this resistive network must present a near end bus terminating impedance equal to the resistive portion of its characteristic impedance R_0 the following requirement must be met:

$$R_{215} = \frac{R_0 (R_{236} + R_{237} + R_{DO})}{R_{236} + R_{237} + R_{DO} - R_0}$$

where R_{215} is the near end terminating impedance 215 of the bus, and R_{236} and R_{237} are the values of the balanced coupling resistors 236 and 237 and R_{DO} is the output impedance of the contention driver 235. R_0 is the resistive portion of the characteristic bus impedance.

Suitable values for these resistive components for the terminating and balanced resistors may be readily derived from these two equations in view of anticipated worst case operating conditions, and the level of power input.

Since the 'zero' state is nominally held on the data transmission bus 210 by the contention driver 235, the individual station interfaces amplifiers 225 need only disable their tristate output devices in order to output a logic zero. If any one station applies a logic 'one' to the bus, the contention process is such that stations outputting a logic 'zero' at that time drop out of contention.

When data is being prepared to be sent by any of the data processing devices during the data transmission mode, the transmit and contention drivers 214 and 235 are disabled to their tristate state and the line termination value is determined solely by the termination resistances 215 and 213.

The bus drive scheme shown in FIG. 3 is an alternative embodiment suitable for application in situations where the length of the data distribution bus 310 is relatively short as compared with the system disclosed in FIG. 2. In the bias drive scheme shown in FIG. 3 the data driver and contention driver function are combined into a single driver amplifier 335 which is connected to the data transmission bus 310 via a resistive network including termination resistor 315 and the balanced resistors 336 and 337. When data is applied to the bus 310, the data driver amplifier 335 is enabled and the data is applied to the bus via the resistive network. While the resistive network will attenuate the data signal, this is not critical if the length of the bus 310 is kept within a length that will provide a sufficient signal amplitude at the far end of the bus 310. During a contention interval, the driver circuit is also enabled and an input logic zero signal applied to lead 345 holds the bus 310 at a weak logic "0"-state.

Another alternative bias drive arrangement is disclosed in FIG. 4 for application to data distribution buses where minimizing signal reflections due to the slight mismatch in termination impedance is deemed necessary. The drive system includes a data drive amplifier 414, a data receive amplifier 415 and a contention driver 435. The drive scheme further includes the dual termination drivers 444 and 445 which are enabled to be simultaneously operative during data transmission intervals to positively assume a proper line termination at the near end of the data transmission bus 410 and minimize signal reflections. The top termination driver 444 and the lower termination driver 445 are each connected to the bus 410 with opposite polarity to each other so that no logic state is applied to the data transmission bus by the termination drivers when the two termination drivers are enabled. The balanced resistors 446, 447, 448 and 449 are selected with a value such that when the termination drivers are both enabled simultaneously, and the data driver 414 and contention driver 435 are disabled, the near end of the data transmission bus will be terminated by its characteristic impedance.

Claims

1. A local area data distribution bus access arrangement, comprising;

- a bus (110) having a far and near end,
- a first termination impedance (113) connected at the far end of the bus,
- at least one station interface (121) connected to the bus intermediate the far and near end,
- a data driver/receiver (130) coupled through a second termination impedance (115) connected to a near end of the bus and operative to transmit and receive data during intervals of non-contention,
- CHARACTERIZED BY
- a contention driver (135) and an impedance network (136, 137) connecting the contention driver through the second termination impedance to the near end of the bus,
- a data direction and interval control (133) connected to the data driver/receiver to synchronize it and to the contention driver to define intervals of contention where the data driver/receiver is inactive

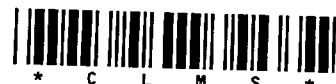


and at which the contention driver is operative to drive the bus to a predetermined and controlled readily overridable weak bias state at which a priority code bit output of a station overrides the weak bias state.

- 5 2. A local area data distribution bus accessing arrangement, as defined in claim 1
 CHARACTERIZED BY
 a termination driver (444, 445) and a second impedance arrangement (446, 447, 448, 449)
 termination driver to the near end of the bus, the termination driver being operative during intervals of
 non-contention to terminate the near end of the bus in its characteristic impedance.
- 10 3. A local area data distribution bus accessing arrangement as defined in claim 2
 CHARACTERIZED IN THAT
 the termination driver includes first and second differential line drivers (235, 275), each connected
 to a near end of the data transmission bus with an opposite polarity orientation so that signal outputs at
 15 the first and second differential line drivers are superimposed on each other so as to provide a null
 signal at the near end of the bus.
4. A local area data distribution bus accessing arrangement as claimed in claim 3,
 CHARACTERIZED BY
 20 a common mode choke (117) coupling the data driver/receiver to the near end of the bus and the
 impedance network (136, 137) comprising a balanced pair of resistors connecting the contention driver
 to the near end of the bus.
5. A local area data distribution bus accessing arrangement as claimed in claim 1,
 25 CHARACTERIZED BY
 the contention driver includes a differential line driver (235) with a low output impedance to facilitate
 the series connection when the differential line driver is active and being coupled to connect the first
 and second resistor and the output impedance in a series connection shunt across the second
 termination impedance.

30 Patentansprüche

1. Zugriffsanordnung eines lokalen Datenverteilungsbusses mit folgenden Merkmalen:
 ein Bus (110) mit einem fernen und einem nahen Ende, eine erste Abschlußimpedanz (113), die am
 35 fernen Ende des Busses angeschlossen ist,
 mindestens eine Stationsschnittstelle (121), die zwischen dem fernen und dem nahen Ende an dem
 Bus angeschlossen ist,
 ein Datentreiber/Empfänger (130), der über eine zweite Abschlußimpedanz (115) an einem nahen Ende
 des Busses angeschlossen ist, und der Daten während der Intervalle einer Nicht-Konkurrenzsituation
 40 übertragen und empfangen kann,
gekennzeichnet durch
 einen Konkurrenztreiber (135) und ein Impedanznetzwerk (136, 137), das den Konkurrenztreiber über
 die zweite Abschlußimpedanz mit dem nahen Ende des Busses verbindet, eine Datenrichtungs- und
 Intervallsteuereinheit (133), die zur Synchronisation des Datentreibers/Empfängers mit diesem und mit
 45 dem Konkurrenztreiber verbunden ist, um Konkurrenzintervalle festzulegen, in denen der Datentrei-
 ber/Empfänger inaktiv ist und in denen der Konkurrenztreiber den Bus in einen vorbestimmten,
 gesteuerten und ohne weiteres aufhebbares schwachen Vorspannungszustand treibt, in dem ein
 Prioritätscodebit am Ausgang einer Station den schwachen Vorspannungszustand aufhebt.
- 50 2. Zugriffsanordnung eines lokalen Datenverteilungsbusses nach Anspruch 1, gekennzeichnet durch
 einen Abschlußtreiber (444, 445) und eine zweite Impedanzanordnung (446, 447, 448, 449) des
 Abschlußtreiber am nahen Ende des Busses, wobei der Abschlußtreiber während der Intervalle einer
 Nicht-Konkurrenzsituation das nahe Ende des Busses mit seinem Wellenwiderstand abschließen kann.
- 55 3. Zugriffsanordnung eines lokalen Datenverteilungsbusses nach Anspruch 2, dadurch gekennzeichnet,
 daß
 der Abschlußtreiber einen ersten und zweiten differentiellen Leitungstreiber (235, 275) enthält, die je mit
 einer entgegengesetzten Polarität an einem nahen Ende des Datenübertragungsbusses angeschlossen



sind, so daß sich die Ausgangssignale im ersten und zweiten differentiellen Leitungstreiber gegenseitig derart überlagern, daß ein Null-Signal am nahen Ende des Busses erzeugt wird.

4. Zugriffsanordnung eines lokalen Datenverteilungsbusses nach Anspruch 3,
 5 gekennzeichnet durch
 eine Gleichtakt-Drosselspule (117), die den Datentreiber/Empfänger mit dem nahen Ende des Busses verbindet, und durch das Impedanznetzwerk (136, 137) mit einem symmetrischen Paar von Widerständen, das den Konkurrenztreiber mit dem nahen Ende des Busses verbindet.
- 10 5. Zugriffsanordnung eines lokalen Datenverteilungsbusses nach Anspruch 1, dadurch gekennzeichnet, daß
 der Konkurrenztreiber einen differentiellen Leitungstreiber (235) mit einer niedrigen Ausgangsimpedanz enthält, um die Reihenschaltung möglich zu machen, wenn der differentielle Leitungstreiber aktiv ist, und daß der Konkurrenztreiber derart ausgebildet ist, daß er den ersten und zweiten Widerstand sowie
 15 die Ausgangsimpedanz in einer Reihenschaltung parallel mit der zweiten Abschlußimpedanz verbinden kann.

Revendications

- 20 1. Dispositif local d'accès à un bus de répartition de données, comprenant:
 un bus (110) possédant une extrémité lointaine et une extrémité proche,
 une première impédance de terminaison (113) reliée à l'extrémité lointaine du bus,
 au moins une interface (121) de station reliée au bus de manière intermédiaire entre l'extrémité
 lointaine et l'extrémité proche,
 25 un dispositif de commande / récepteur (130) de données, couplé au moyen d'une deuxième
 impédance (115) de terminaison reliée à une extrémité proche du bus et agissant pour transmettre et
 recevoir des données pendant des intervalles sans concurrence,
 CARACTERISE PAR
 un dispositif de commande (135) de concurrence et un réseau d'impédance (136, 137) reliant le
 30 dispositif de commande de concurrence à travers la deuxième impédance de terminaison à l'extrémité
 proche du bus,
 une commande (133) de direction et d'intervalle de données reliée au dispositif de commande /
 récepteur de donnée pour le synchroniser et au dispositif de commande de concurrence pour définir
 des intervalles de concurrence où le dispositif de commande / récepteur de donnée est inactif et
 35 auxquels le dispositif de commande de concurrence agit pour amener le bus à un état de faible
 polarisation prédéterminé et auquel on peut déroger facilement de manière commandée, dans lequel
 une priorité peut être immédiatement appliquée et dans lequel une sortie de bit de code de priorité
 d'une station est prioritaire vis-à-vis de l'état de faible polarisation.
- 40 2. Dispositif local d'accès à un bus de répartition de données selon la revendication 1
 CARACTERISE PAR
 un dispositif de commande (444, 445) de terminaison et un deuxième dispositif de commande
 (446, 447, 448, 449) de terminaison d'agencement d'impédance à l'extrémité proche du bus, le
 dispositif de commande de terminaison agissant pendant des intervalles sans concurrence afin que
 45 l'extrémité proche du bus soit terminée par l'impédance caractéristique souhaitée.
3. Dispositif local d'accès à un bus de répartition de données selon la revendication 2
 CARACTERISE EN CE QUE
 le dispositif de commande de terminaison inclut un premier et un deuxième dispositifs de
 50 commande (235, 275) de lignes différentielles, reliés chacun à une extrémité proche du bus de
 transmission de données, selon une orientation à polarités opposées de sorte que des sorties de
 signaux au premier et au deuxième dispositif de commande de lignes différentielles sont superposées
 l'une à l'autre de façon à fournir un signal nul à l'extrémité proche du bus.
- 55 4. Dispositif local d'accès à un bus de répartition de données selon la revendication 3
 CARACTERISE EN CE QUE
 une réactance (117) de mode commun couple le dispositif de commande / récepteur de donnée à
 l'extrémité lointaine du bus, et le réseau d'impédances (136, 137) comprend une paire équilibrée de



résistances reliant le dispositif de commande de concurrence à l'extrémité proche du bus.

5. Dispositif local d'accès à un bus de répartition de données selon la revendication 1,
CARACTERISE EN CE QUE

5 le dispositif de commande de concurrence comporte un dispositif de commande (235) de lignes différentielles à faible impédance de sortie, afin de faciliter la liaison en série lorsque le dispositif de commande de lignes différentielles est actif et est couplé de manière à relier la première et la deuxième résistance et l'impédance de sortie selon un shunt de liaison en série aux bornes de la deuxième impédance de terminaison.

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