What is claimed is:

1. A control system, applied to a behavioral control device of a home service robot, comprising:

a collection device configured on a preset position of the home service robot to collect operation instructions input by a user, and to form and output collection data;

a communication module including a first communication unit and a second communication unit, the first communication unit being connected to the collection device to receive the collection data, and transforming the collection data into transformed collection data matched to the first communication unit;

a first processing unit connected to the first communication unit and the second communication unit respectively, to receive the transformed collection data, and to recognize and process the transformed collection data, to form a control command and output the control command by the second communication unit;

a second processing unit connected to the second communication unit to receive the control command, and to form and output a control instruction according to the control command;

an execution unit connected to the second processing unit to execute actions under effect of the control instruction, and the actions being matched to the control instruction;

a detecting unit connected to the second processing unit, to detect status information of a present physical environment where the home service robot is located, and to form detection information and output the detection information to the second processing unit;

a memory unit included in the second processing unit, the memory unit comprising a plurality of preset scene modes and matching relations between the plurality of preset scene modes and the status information of the present physical environment;

wherein the second processing unit sends a present scene mode, the control command and the control instruction to the first processing unit, the first processing unit analyzes received data, to form an analysis result to return to the second processing unit, the first processing unit updates the matching relations according to the analysis result.

2. The control system as claimed in Claim 1, wherein the collection device comprises:

a sound capture module connected to the first communication unit to capture a voice message, and to form and output a transformed voice collection data matched to the first communication unit;

an image capture module connected to the first communication unit to capture an image message, and to form and output a transformed image collection data matched to the first communication unit.

3. The control system as claimed in Claim 2, wherein the first processing unit comprises:

a voice recognition unit connected to the sound capture module to recognize a voice control command according to the transformed voice collection data;

an image recognition unit connected to the image capture module to recognize an image control command according to the transformed image collection data.

4. The control system as claimed in Claim 1, wherein the detecting unit comprises:

a temperature sensor connected to the second processing unit, to acquire temperature information of the present physical environment, and to form a temperature signal and output the temperature signal to the second processing unit;

a light sensor connected to the second processing unit, to acquire light information of the present physical environment, and to form a light signal and output the light signal to the second processing unit;

a displacement sensor connected to the second processing unit, to acquire position information of the present physical environment, and to form a position signal and output the position signal to the second processing unit.

5. The control system as claimed in Claim 1, wherein the execution unit comprises:

an audio play unit connected to the second processing unit to execute an action of audio play under the effect of the control instruction which is output by the second processing unit and which is relevant to the audio play unit;

a light regulation unit connected to the second processing unit to execute an action of light regulation under the effect of the control instruction which is output by the second processing unit and which is relevant to the light regulation unit;

a drive unit connected to the second processing unit to execute an action of position movement under the effect of the control instruction which is output by the second processing unit and which is relevant to the drive unit.

6. The control system as claimed in Claim 5, wherein the audio play unit is an audio play device inside the home service robot or an audio play device in the present physical environment where the home service robot is located, whose control end is connected to a corresponding output end of the second processing unit.

7. The control system as claimed in Claim 5, wherein the light regulation unit is a lighting system in the present physical environment where the home service robot is located, whose control end is connected to a corresponding output end of the second processing unit, to regulate light intensity of the present physical environment.