

## INSERTION TOOL WITH GRIP MECHANISM

### Abstract of the Disclosure

An insertion tool with an implement gripping mechanism is provided. The insertion tool includes an elongated section defining an implement path extending from a proximal end to a distal end, a handle coupled to the proximal end of the elongated section, a grip mechanism coupled to the handle and configured to selectively secure an implement inserted into the implement path through the handle, and a grip actuator operable to cause the grip mechanism to secure the implement to the handle.

[Figure 2]