is expected to be a mainstream method of representing three-dimensional data, a massive amount of data of a point group necessitates compression of the amount of three-dimensional data by encoding for accumulation and transmission, as in the case of a two-dimensional moving picture (examples include MPEG-4 AVC and HEVC standardized by MPEG).

[0004]

Meanwhile, point cloud compression is partially supported by, for example, an open-source library (Point Cloud Library) for point cloud-related processing.

[0005]

Furthermore, a technique for searching for and displaying a facility located in the surroundings of the vehicle is known (for example, see Patent Literature (PTL) 1).

Citation List

Patent Literature

[0006]

PTL 1: International Publication WO 2014/020663

SUMMARY OF THE INVENTION

TECHNICAL PROBLEM

[0007]

There has been a demand for reducing an amount of processing in encoding and decoding of three-dimensional data.

[0008]

Embodiments of the present disclosure provide a three-dimensional data encoding method, a three-dimensional data decoding method, a three-dimensional data encoding device, or a three-dimensional data decoding device that is capable of reducing the amount of processing.

SOLUTIONS TO PROBLEM

[0009]

According to a first aspect of the present disclosure, there is provided a three-dimensional data encoding method, including: generating an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2; encoding a first parameter; determining a value indicated by the first parameter; when the first parameter is determined as indicating a first value, (i) selecting a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic encoding on information of the current node using the selected contexts; and when the first parameter is determined as indicating a second value different from the

first value, (i) selecting a group from M groups according to the occupancy states of neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic encoding on information of the current node using the selected contexts.

[0009a]

According to a second aspect of the present disclosure, there is provided a three-dimensional data encoding device that encodes three-dimensional points each including attribute information, the three-dimensional data encoding device including: a processor; and memory, wherein using the memory, the processor: generates an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2; encodes a first parameter; determines a value indicated by the first parameter; when the first parameter is determined as indicating a first value, (i) selects a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic encoding on information of the current node using the selected contexts; and when the first parameter is determined as indicating a second value different from the first value, (i) selects a group from M groups according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic encoding on information of the current node using the selected contexts.

[0010]

According to a third aspect of the present disclosure, there is provided a three-dimensional data decoding method, including: obtaining an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2; obtaining a first parameter; determining a value indicated by the first parameter; when the first parameter is determined as indicating a first value, (i) selecting a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic decoding on information of the current node using the selected contexts; when the first parameter is determined as indicating a second value different from the first value, (i) selecting a group from M groups according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic decoding on information of the current node using the selected contexts.

[0010a]

According to a fourth aspect of the present disclosure, there is provided a three-dimensional data decoding device that decodes three-dimensional points each including attribute information, the three-dimensional data decoding device including: a processor; and memory, wherein using the memory, the processor: obtains an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2; obtains a first parameter; determines a value indicated by the first parameter; when the first parameter is determined as indicating a first value, (i) selects a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic decoding on information of the current node using the selected contexts; when the first parameter is determined as indicating a second value different from the first value, (i) selects a group from M groups according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic decoding on information of the current node using the selected contexts.

ADVANTAGEOUS EFFECT OF INVENTION

[0011]

Embodiments of the present disclosure provide a three-dimensional data encoding method, a three-dimensional data decoding method, a three-dimensional data encoding device, or a three-dimensional data decoding device that is capable of reducing an amount of processing.

BRIEF DESCRIPTION OF DRAWINGS

[0012]

FIG. 1 is a diagram showing the structure of encoded three-dimensional data according to Embodiment 1.

FIG. 2 is a diagram showing an example of prediction structures among SPCs that belong to the lowermost layer in a GOS according to Embodiment 1.

FIG. 3 is a diagram showing an example of prediction structures among layers according to Embodiment 1.

FIG. 4 is a diagram showing an example order of encoding GOSs according to Embodiment 1.

FIG. 5 is a diagram showing an example order of encoding GOSs according to Embodiment 1.

FIG. 6 is a block diagram of a three-dimensional data encoding device according to Embodiment 1.

FIG. 7 is a flowchart of encoding processes according to Embodiment 1.

FIG. 8 is a block diagram of a three-dimensional data decoding device according to Embodiment 1.

Claims

1. A three-dimensional data encoding method, comprising:

generating an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2;

encoding a first parameter;

determining a value indicated by the first parameter;

when the first parameter is determined as indicating a first value, (i) selecting a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic encoding on information of the current node using the selected contexts; and

when the first parameter is determined as indicating a second value different from the first value, (i) selecting a group from M groups according to the occupancy states of neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic encoding on information of the current node using the selected contexts.

2. The three-dimensional data encoding method according to claim 1, wherein N is greater than M.

3. A three-dimensional data decoding method, comprising:

obtaining an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2;

obtaining a first parameter;

determining a value indicated by the first parameter;

when the first parameter is determined as indicating a first value, (i) selecting a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic decoding on information of the current node using the selected contexts;

when the first parameter is determined as indicating a second value different from the first value, (i) selecting a group from M groups according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selecting contexts based on the selected group, and (iii) performing arithmetic decoding on information of the current node using the selected contexts.

4. The three-dimensional data decoding method according to claim 3, wherein N is greater than M.

5. A three-dimensional data encoding device that encodes three-dimensional points each including attribute information, the three-dimensional data encoding device comprising:

a processor; and

memory,

wherein using the memory, the processor:

generates an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2;

encodes a first parameter;

determines a value indicated by the first parameter;

when the first parameter is determined as indicating a first value, (i) selects a group from N groups according to occupancy states of neighboring nodes neighboring a current node and

located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic encoding on information of the current node using the selected contexts; and

when the first parameter is determined as indicating a second value different from the first value, (i) selects a group from M groups according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic encoding on information of the current node using the selected contexts.

6. A three-dimensional data decoding device that decodes three-dimensional points each including attribute information, the three-dimensional data decoding device comprising:

a processor; and

memory,

wherein using the memory, the processor:

obtains an n-ary tree structure of three-dimensional points included in three-dimensional data, n being an integer greater than or equal to 2;

obtains a first parameter;

determines a value indicated by the first parameter;

when the first parameter is determined as indicating a first value, (i) selects a group from N groups according to occupancy states of neighboring nodes neighboring a current node and located inside or outside a parent node of the current node, N being an integer greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic decoding on information of the current node using the selected contexts;

when the first parameter is determined as indicating a second value different from the first value, (i) selects a group from M groups

according to occupancy states of the neighboring nodes neighboring the current node and located inside the parent node of the current node, M being an integer different from N and greater than 1, (ii) selects contexts based on the selected group, and (iii) performs arithmetic decoding on information of the current node using the selected contexts.

7. The three-dimensional data encoding method according to claim 1, wherein

when the first parameter is determined as indicating the first value, a first pattern of the occupancy states of neighboring nodes is selected as a first group from the N groups,

when the first parameter is determined as indicating the second value, the first pattern of the occupancy states of neighboring nodes is selected as a second group from the M groups, and

the first group and the second group indicate that all of the neighboring nodes neighboring the current node do not include a three-dimensional point.

8. The three-dimensional data encoding method according to claim 7, wherein

the number of patterns of the occupancy states of neighboring nodes assigned to the first group of the N groups is one, and

the number of patterns of the occupancy states of neighboring nodes assigned to the second group of the M groups is one.

9. The three-dimensional data encoding method according to claim 1, wherein

when the first parameter is determined as indicating the first value, a first pattern of the occupancy states of neighboring nodes is selected as a first group from the N groups,

when the first parameter is determined as indicating the second value, the first pattern of the occupancy states of neighboring nodes

is selected as a second group from the M groups, and

the first group and the second group indicate that at least one of the neighboring nodes neighboring the current node includes a three-dimensional point.

10. The three-dimensional data encoding method according to claim 9, wherein

Q patterns of the occupancy states of neighboring nodes are assigned to the first group of the N groups,

P patterns of the occupancy states of neighboring nodes are assigned to the second group of the M groups, and

P is greater than Q.

11. The three-dimensional data decoding method according to claim 3, wherein

when the first parameter is determined as indicating the first value, a first pattern of the occupancy states of neighboring nodes is selected as a first group from the N groups,

when the first parameter is determined as indicating the second value, the first pattern of the occupancy states of neighboring nodes is selected as a second group from the M groups, and

the first group and the second group indicate that all of the neighboring nodes neighboring the current node do not include a three-dimensional point.

12. The three-dimensional data decoding method according to claim 11, wherein

the number of patterns of the occupancy states of neighboring nodes assigned to the first group of the N groups is one, and

the number of patterns of the occupancy states of neighboring nodes assigned to the second group of the M groups is one.

13. The three-dimensional data decoding method according to claim 3, wherein

when the first parameter is determined as indicating the first value, a first pattern of the occupancy states of neighboring nodes is selected as a first group from the N groups,

when the first parameter is determined as indicating the second value, the first pattern of the occupancy states of neighboring nodes is selected as a second group from the M groups, and

the first group and the second group indicate that at least one of the neighboring nodes neighboring the current node includes a three-dimensional point.

14. The three-dimensional data decoding method according to claim 13, wherein

Q patterns of the occupancy states of neighboring nodes are assigned to the first group of the N groups,

P patterns of the occupancy states of neighboring nodes are assigned to the second group of the M groups, and

P is greater than Q.