

Abstract

The invention relates to a robot container (1) having a computer housing (10) and a protective housing (20), wherein a plurality of rollers (11) and a first computer housing interface (15A) are arranged on a first outer side of the computer housing (10) and wherein a robot manipulator (12) and a second computer housing interface (15B) are arranged on a second outer side of the computer housing (10) opposite to the first outer side, and wherein a control unit (13) connected to the robot manipulator (12) is arranged in the interior of the computer housing (10), wherein at least one setup element (21) for mounting the protective housing (20) on a floor is arranged on a first outer side of the protective housing (20) and an opening to a cavity enclosed by the protective housing (20) and protective housing interface (25) are arranged on a second outer side of the protective housing (20) opposite to the first outer side, wherein the protective housing interface (25) is reversibly connectable alternately to the first computer housing interface (15A) or to the second computer housing interface (15B), having the following steps, so that by introducing the robot manipulator (12) into the cavity of the protective housing (20) and by joining the protective housing interface (25) to the second computer housing interface (15B), the protective housing (20) and the computer housing (10) form a transport container displaceable via the rollers (11), and so that by joining the protective housing interface (25) to the first computer housing interface (15A), the protective housing (20) forms a base for the computer housing (10) which is non-displaceable due to the at least one setup element (21).

FIG. 1-B