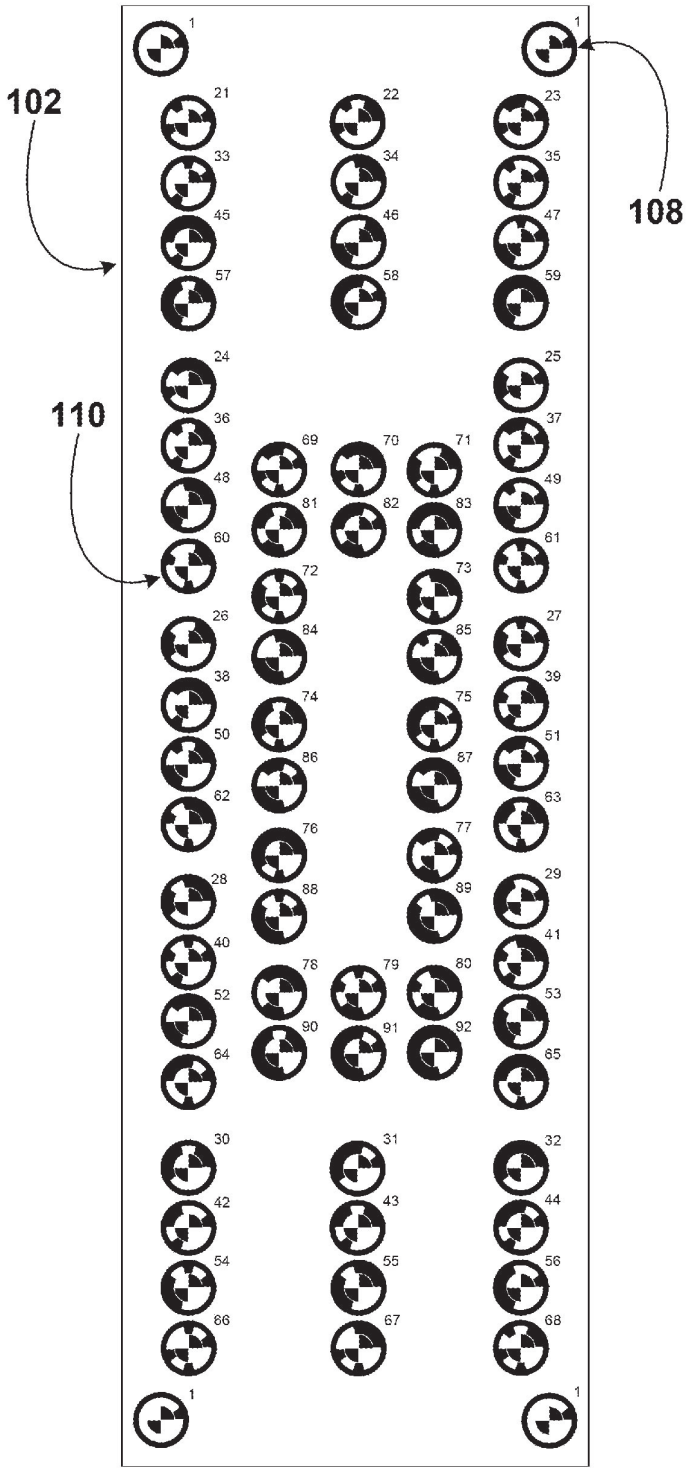

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FIG. 1A

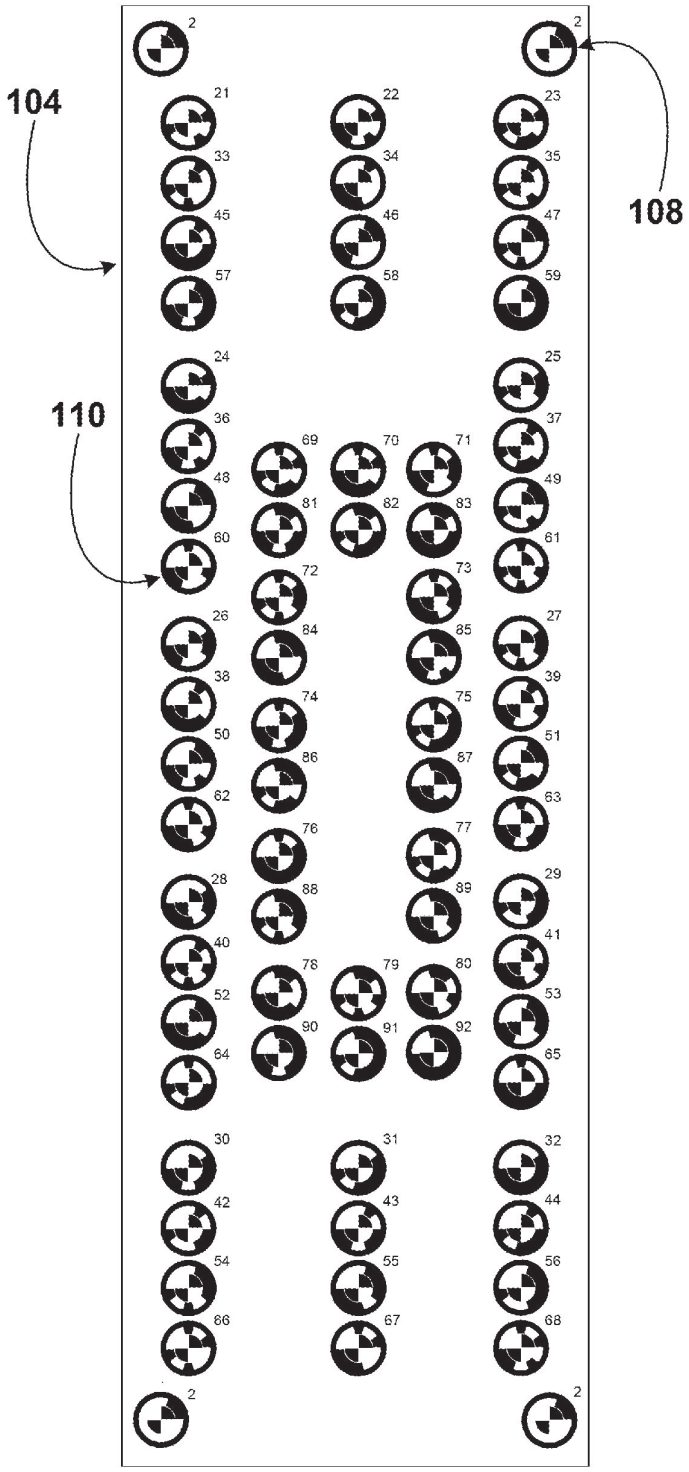

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FIG. 1B

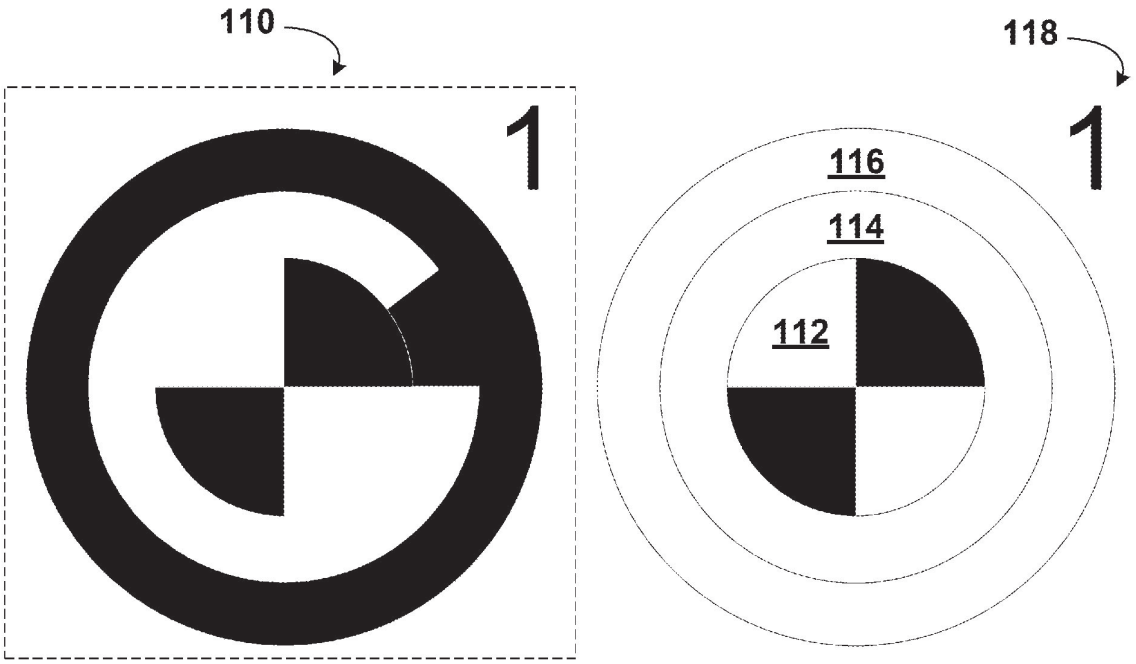


FIG. 1C

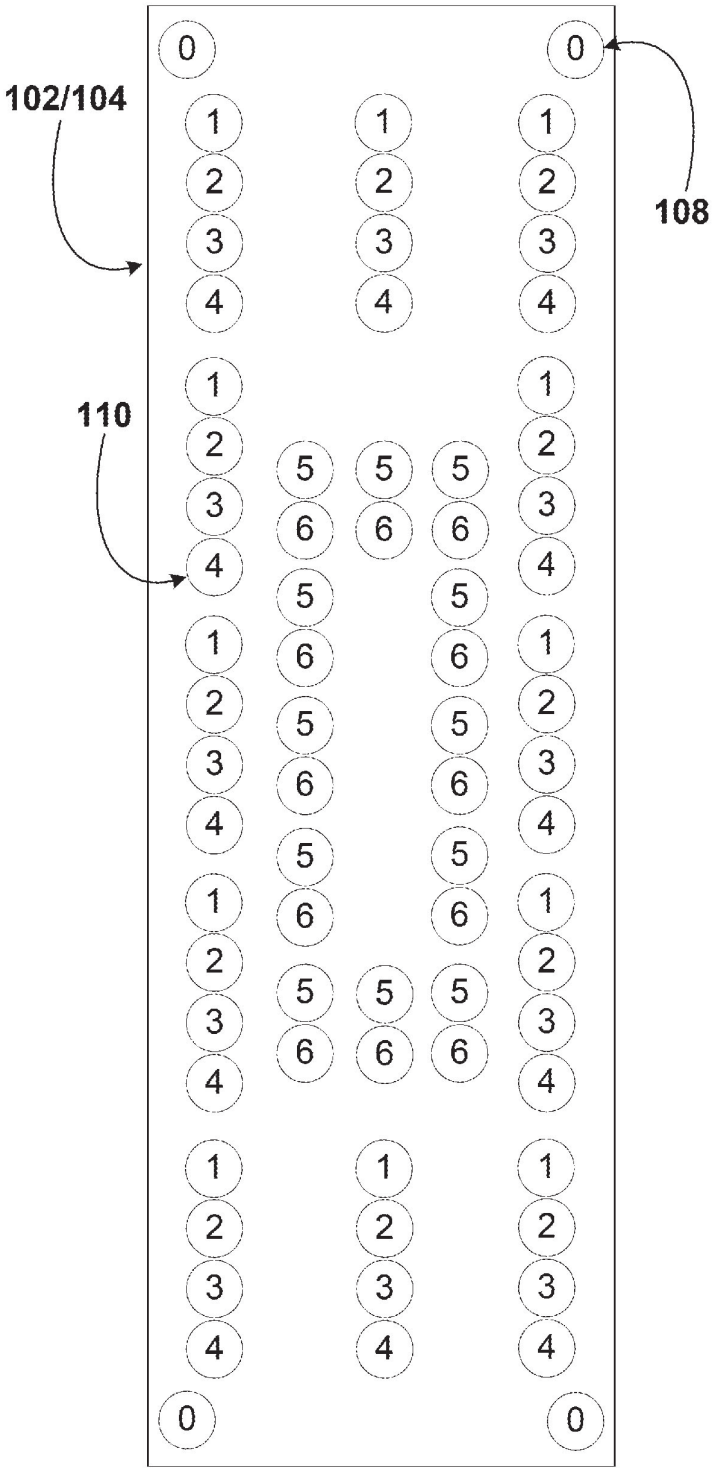


FIG. 1D

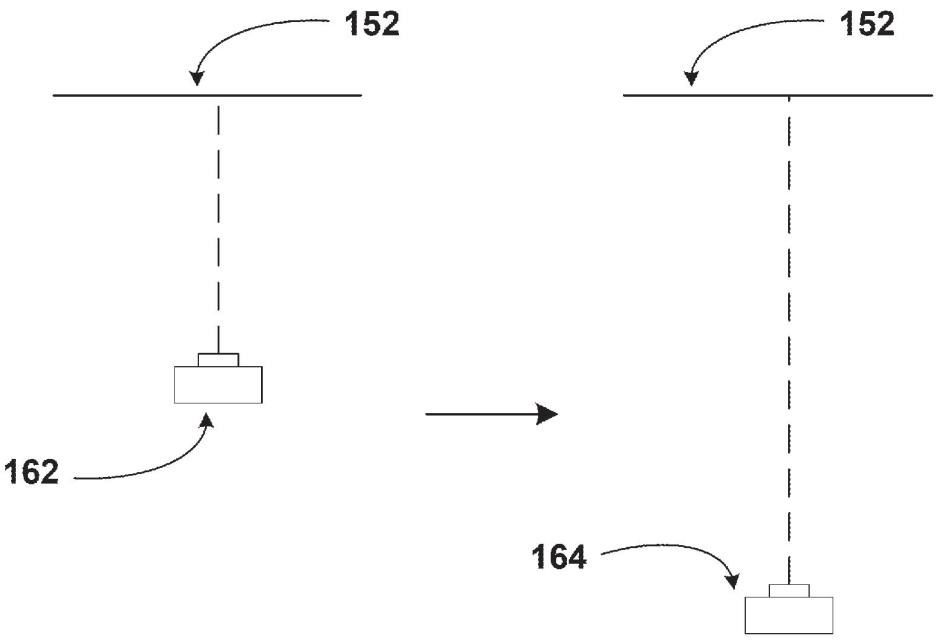


FIG. 1E FIG. 1F

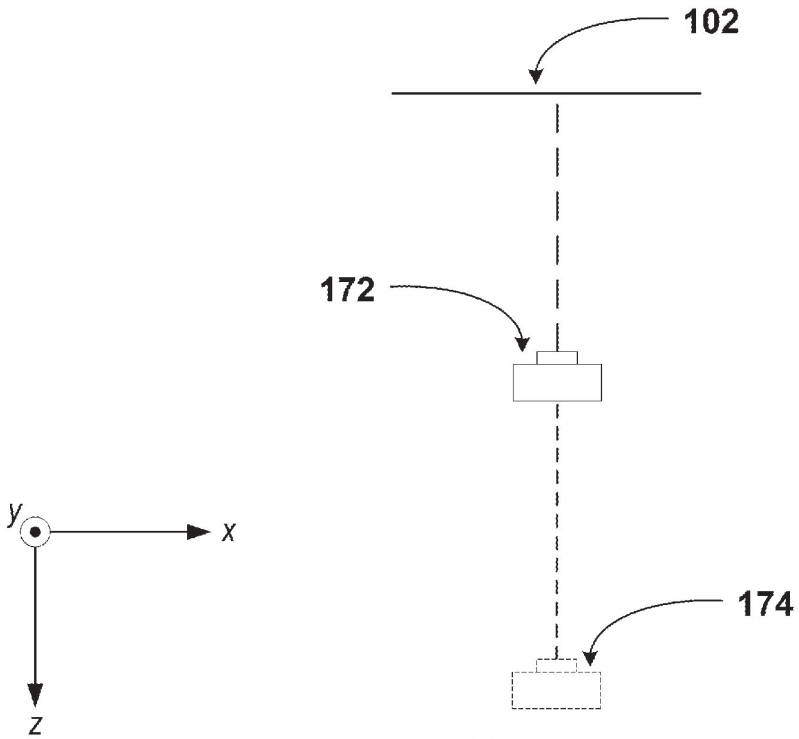


FIG. 1G

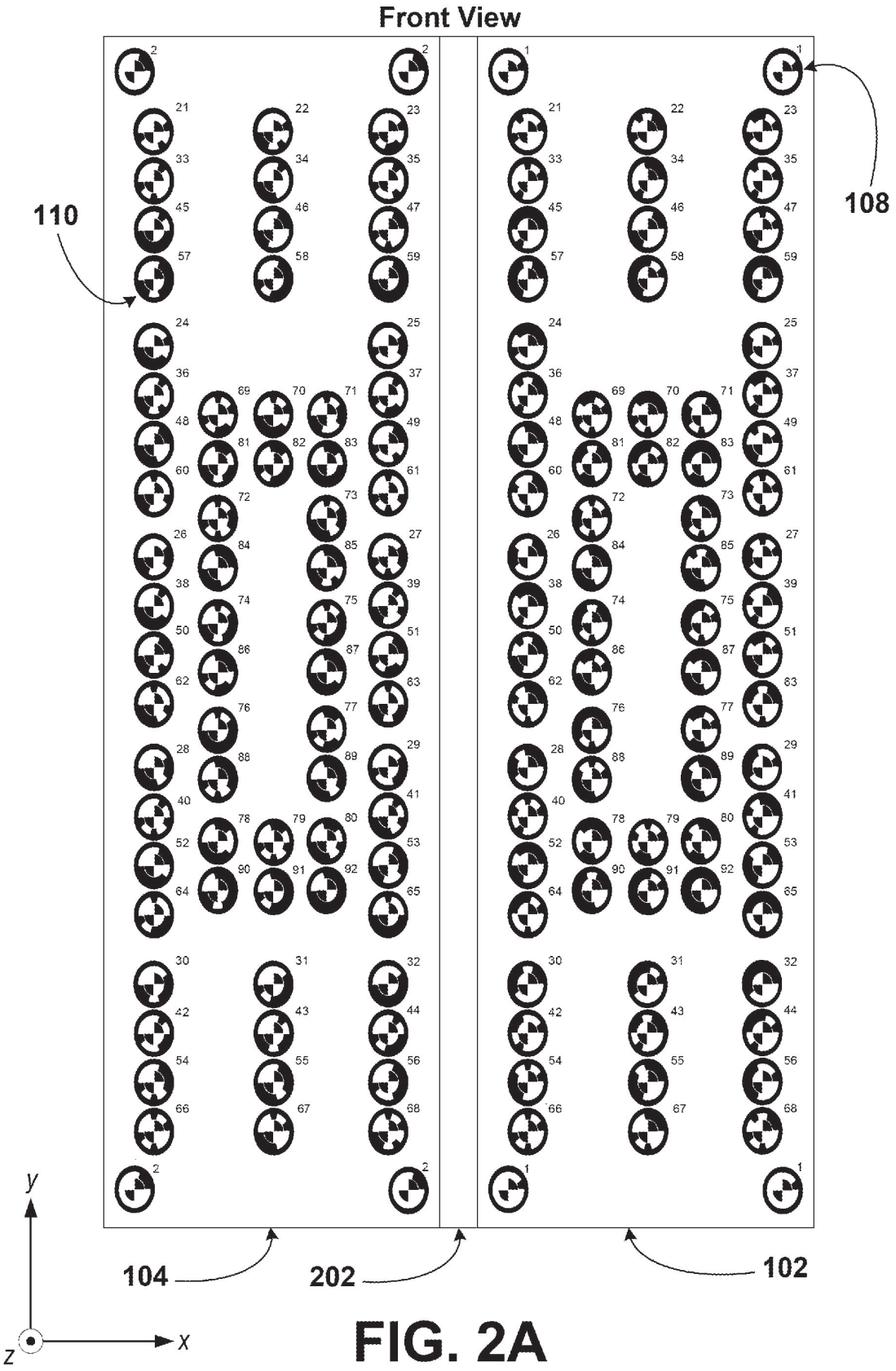


FIG. 2A

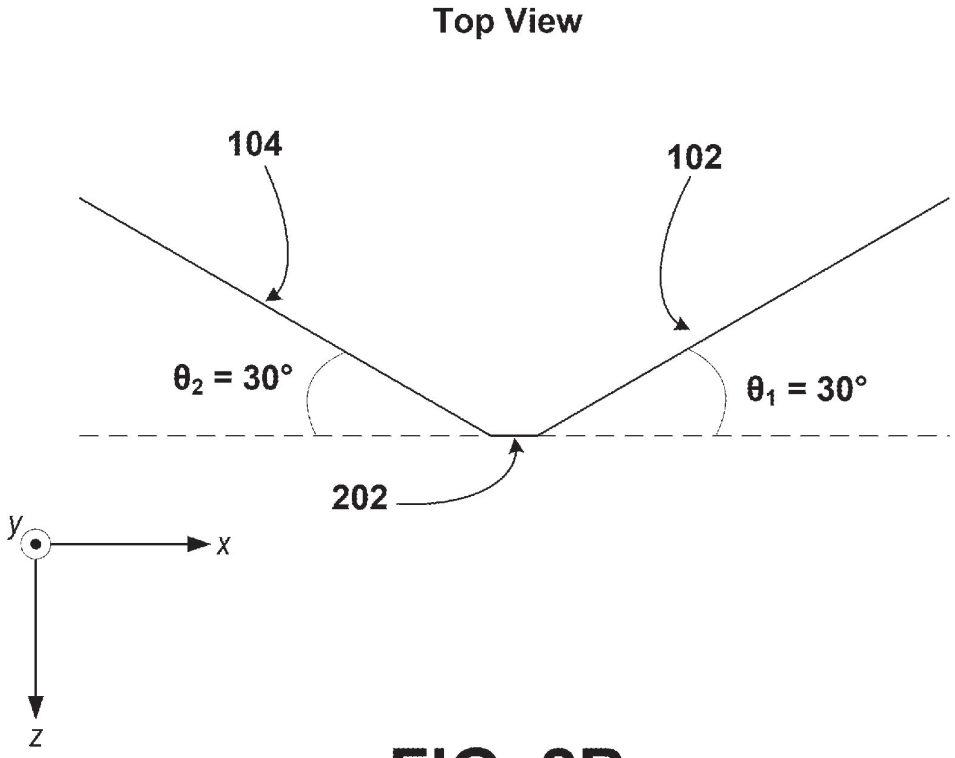


FIG. 2B

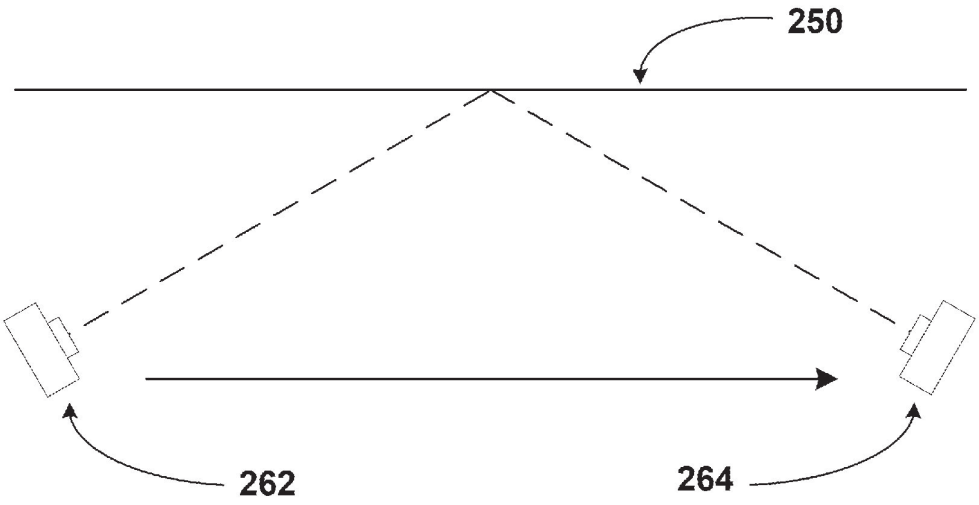


FIG. 2C

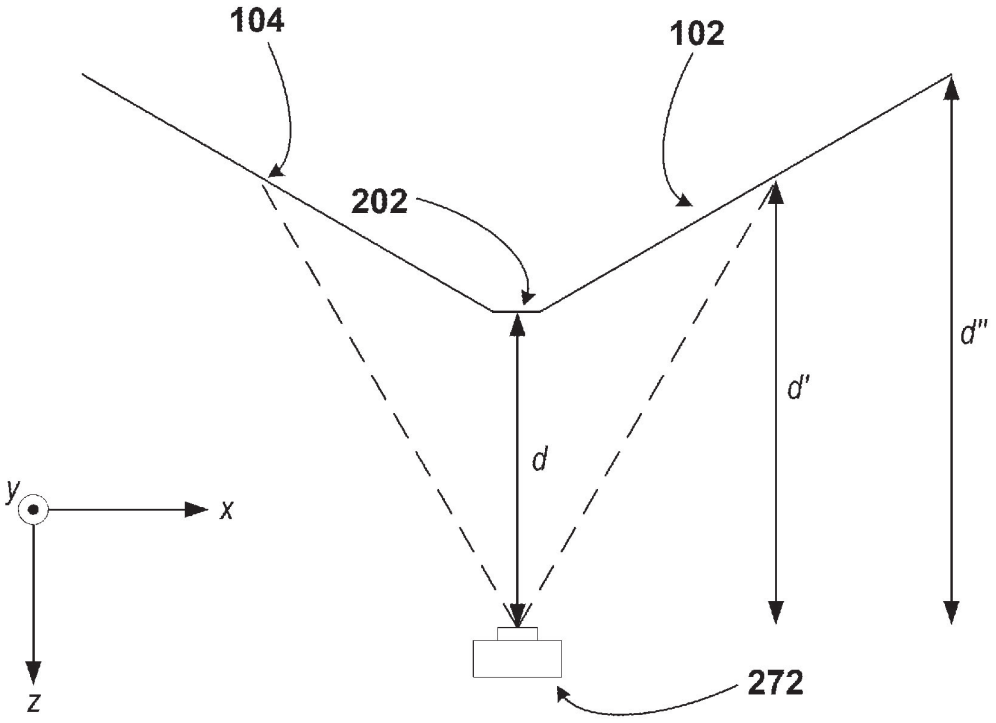


FIG. 2D

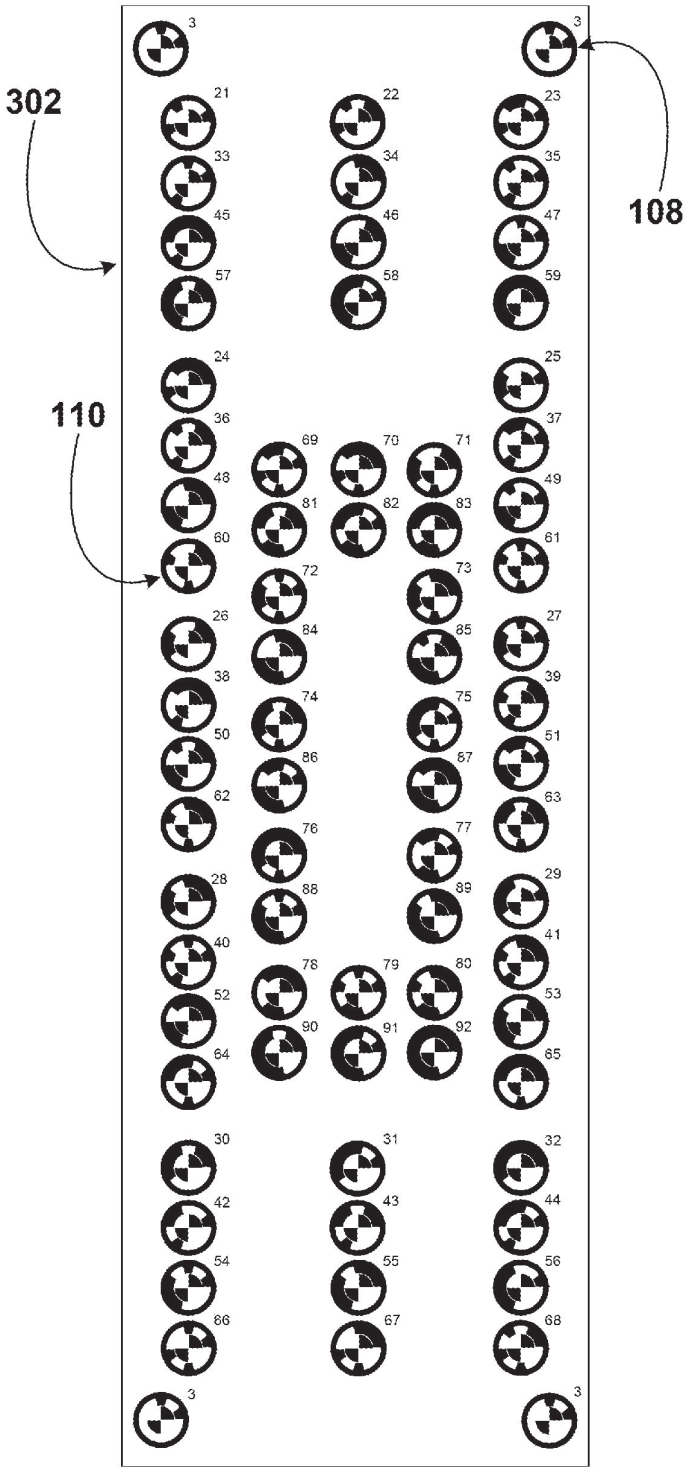

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FIG. 3A

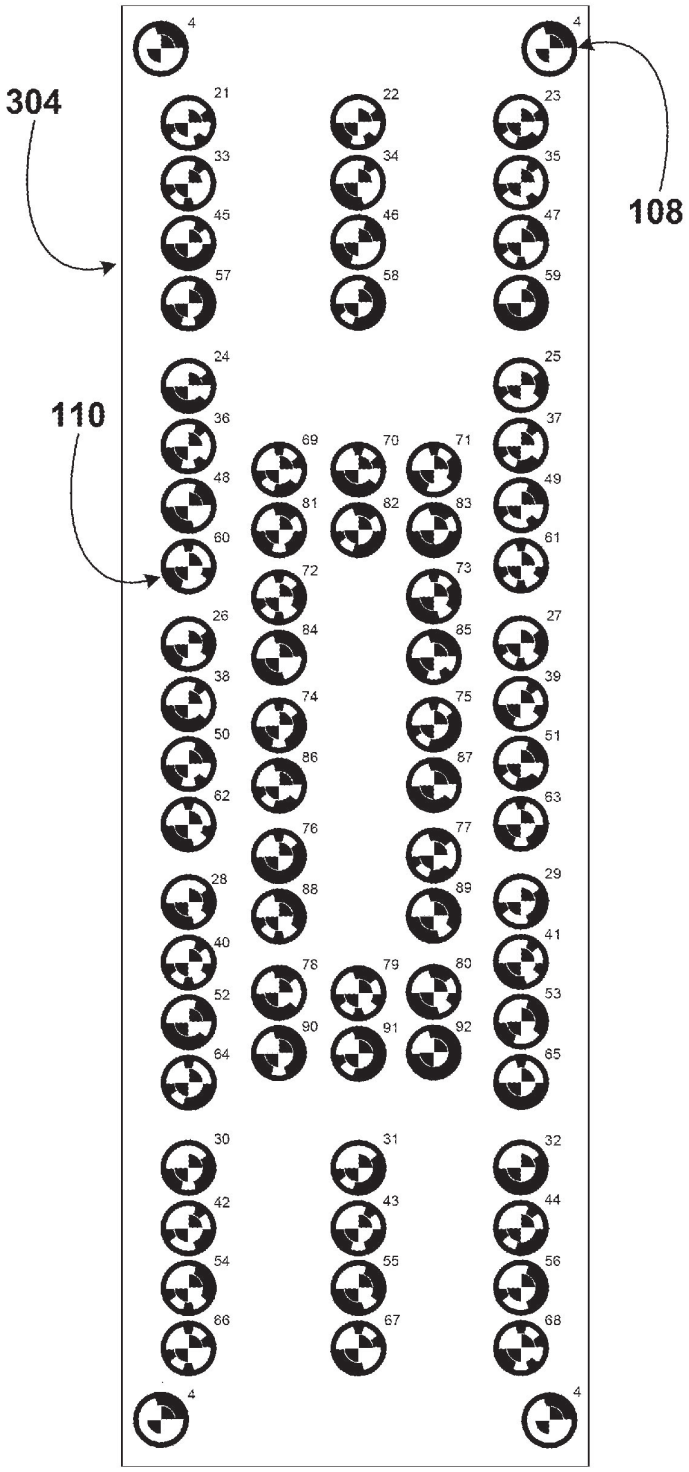

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FIG. 3B

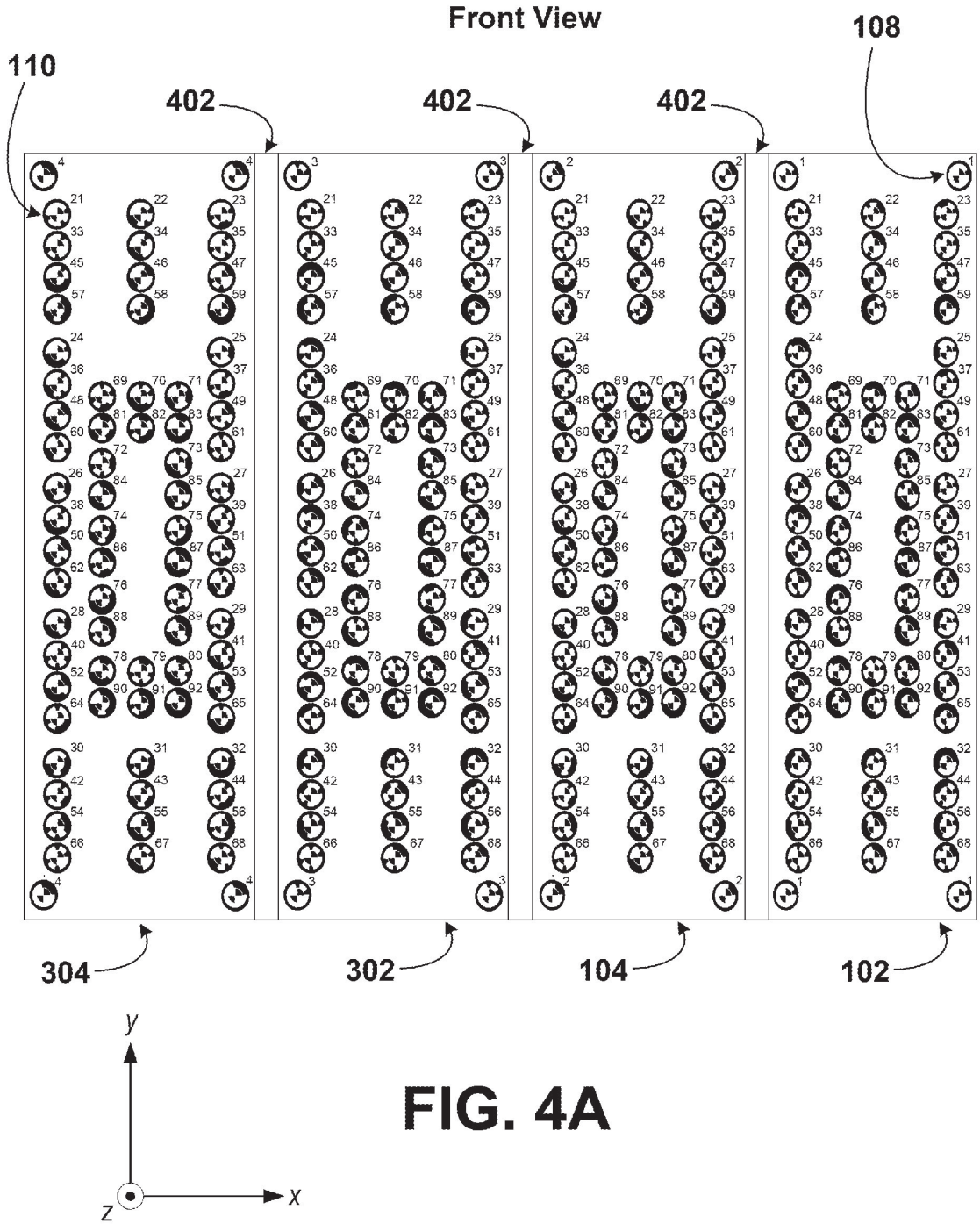


FIG. 4A

Top View

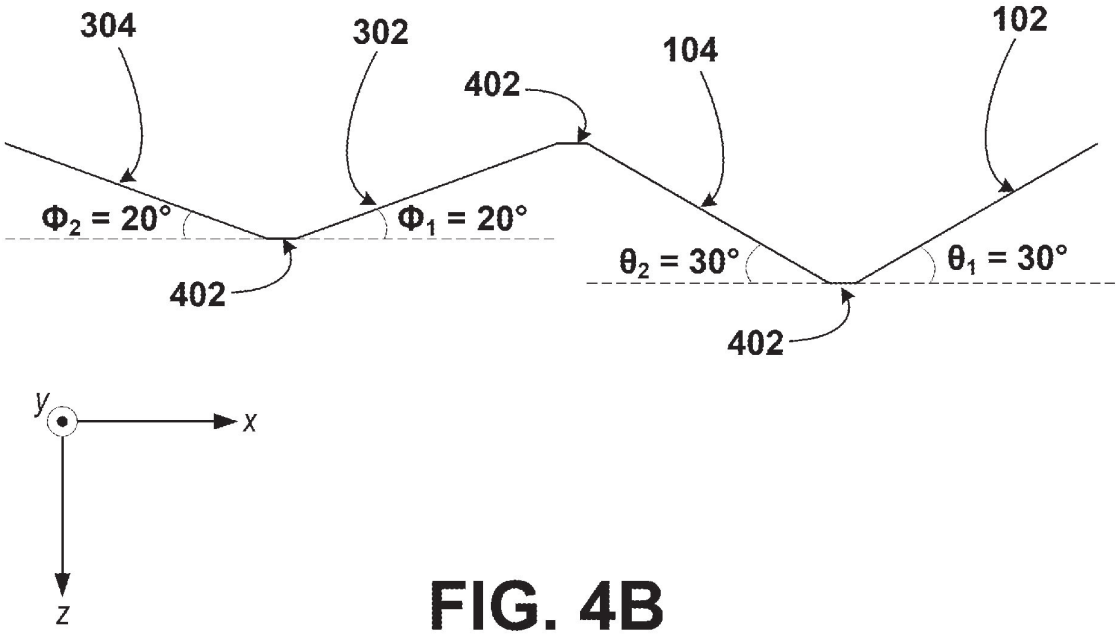


FIG. 4B

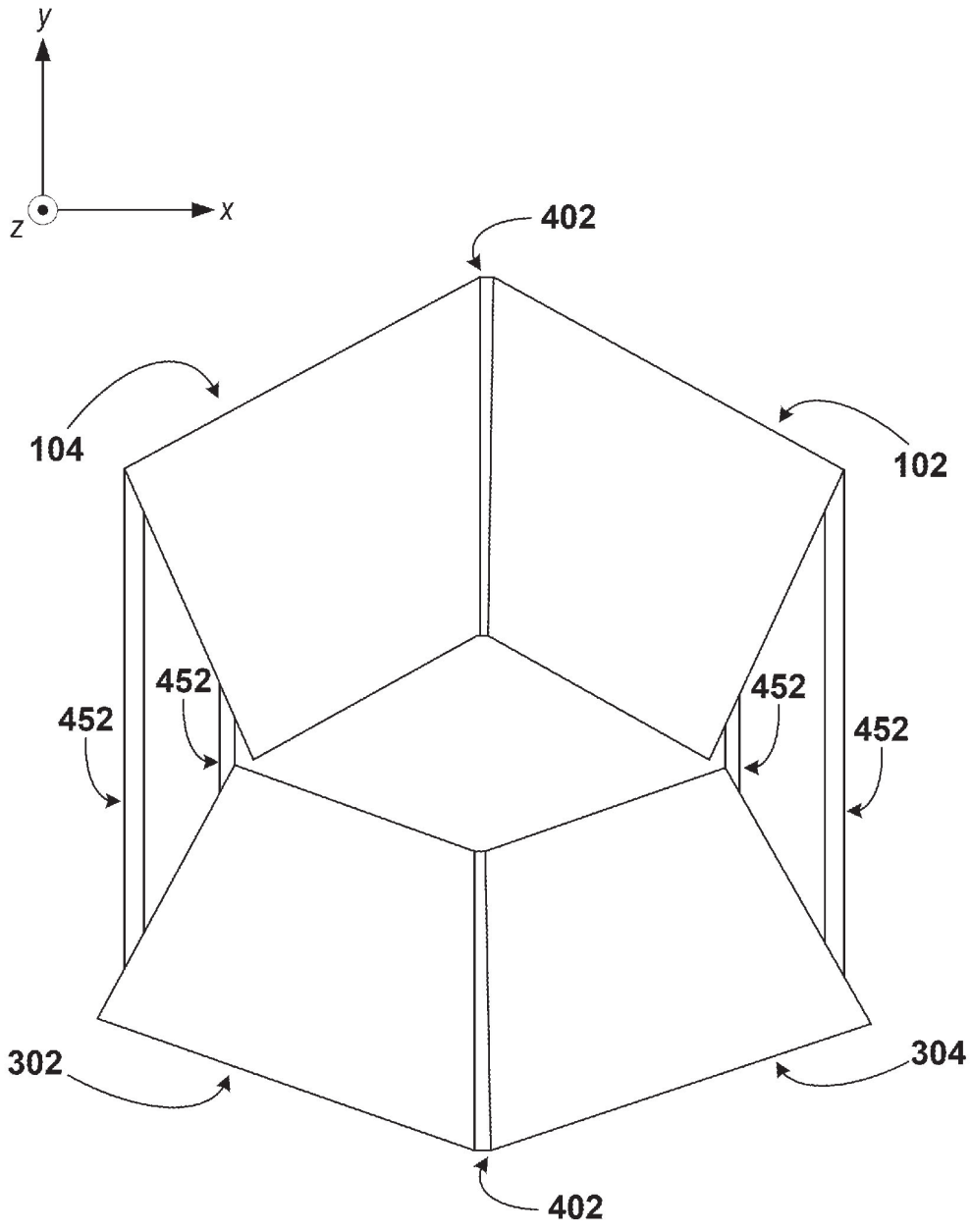


FIG. 4C

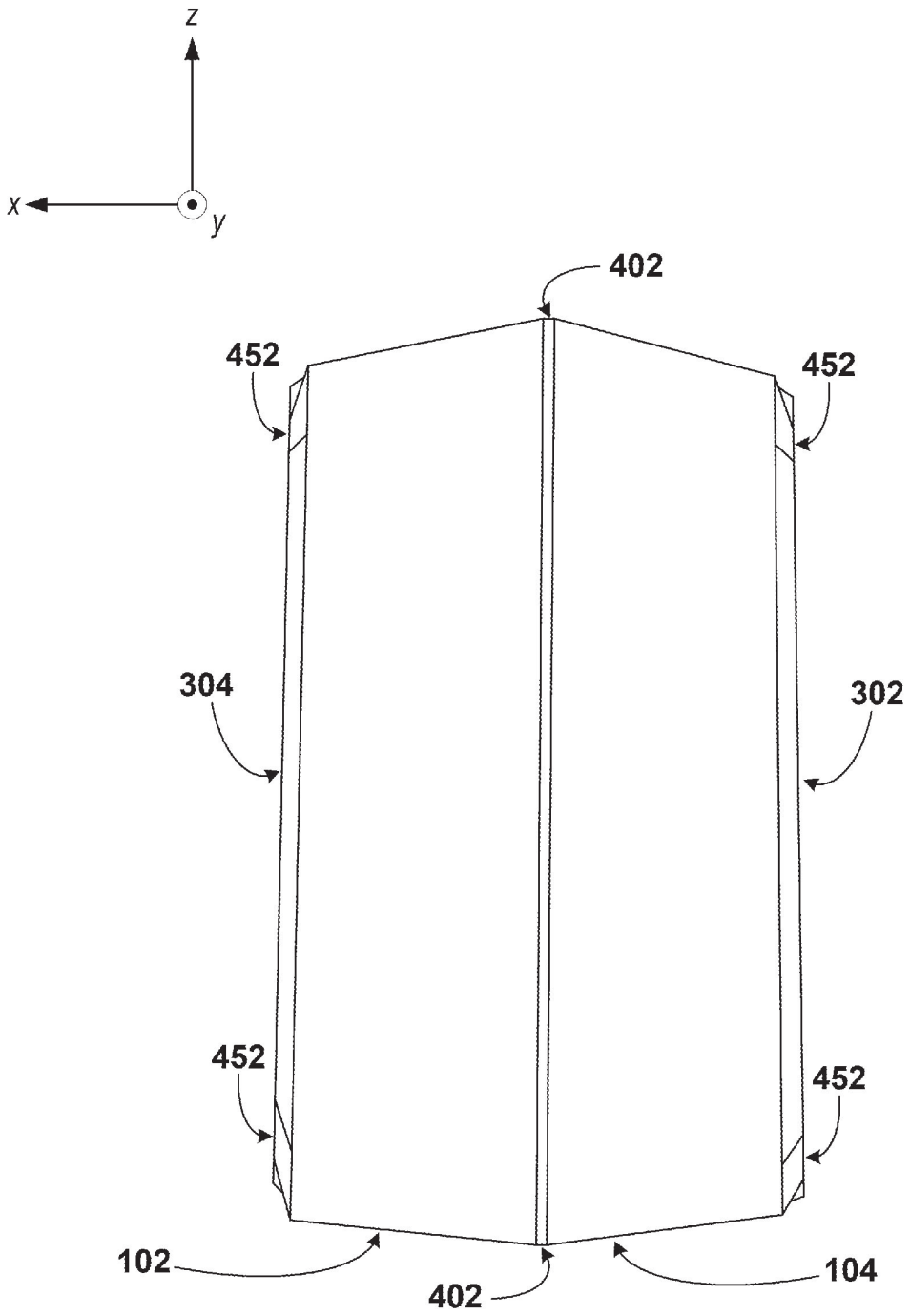


FIG. 4D

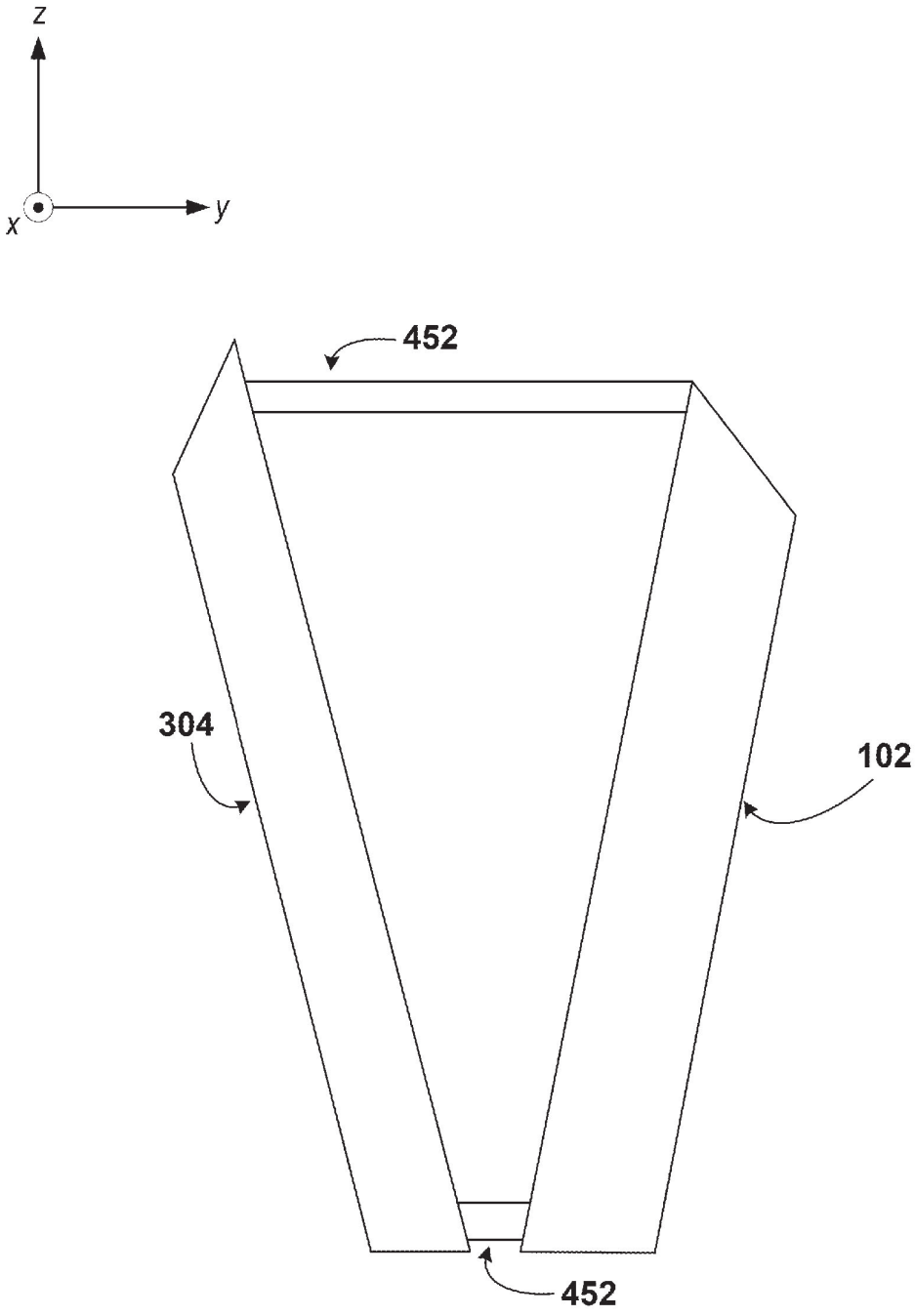


FIG. 4E

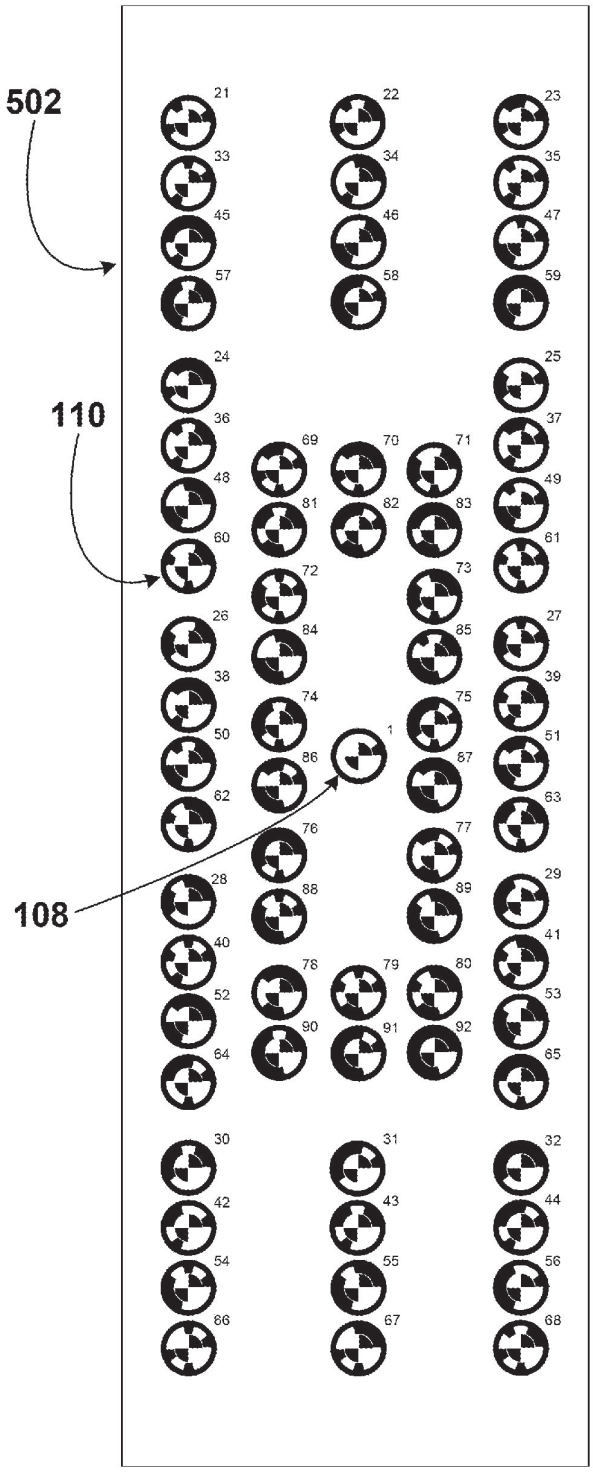

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FIG. 5

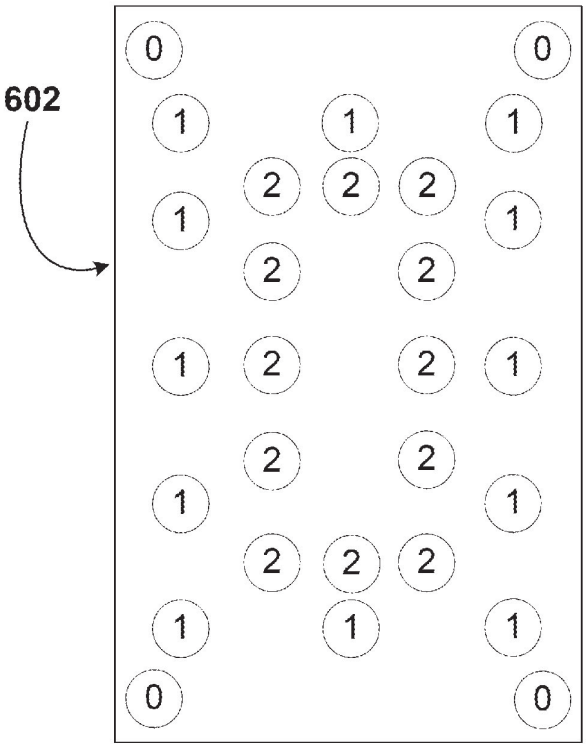


FIG. 6A

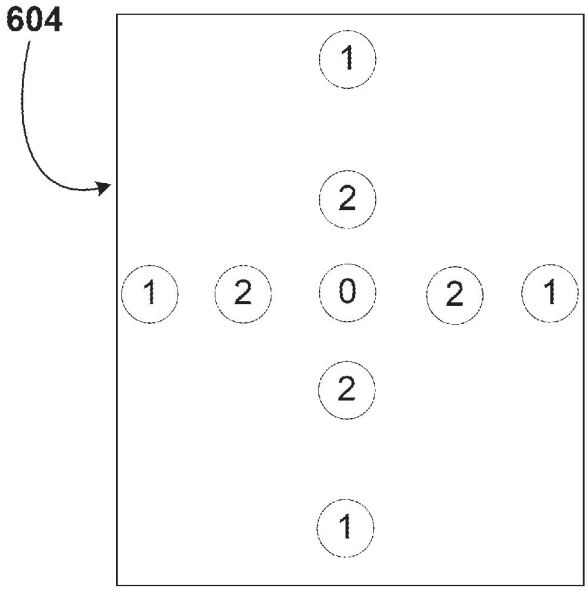


FIG. 6B

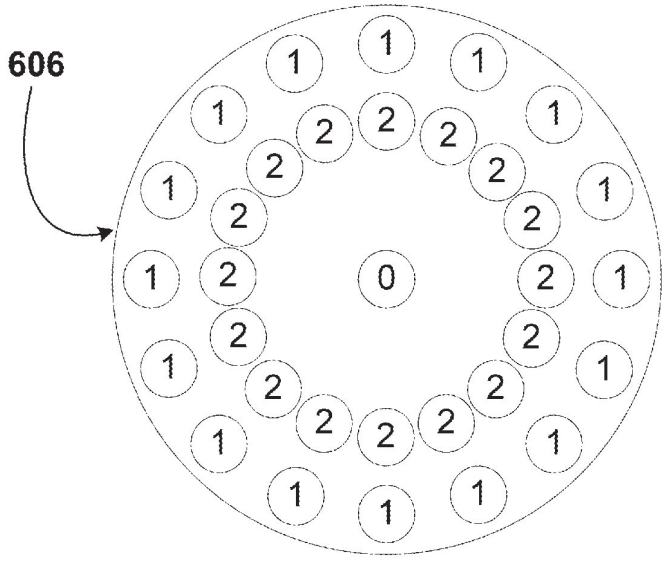


FIG. 6C

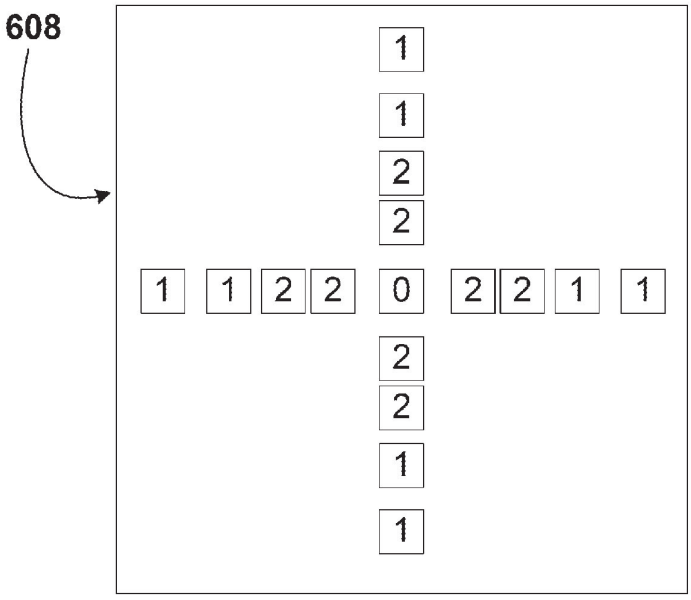


FIG. 6D

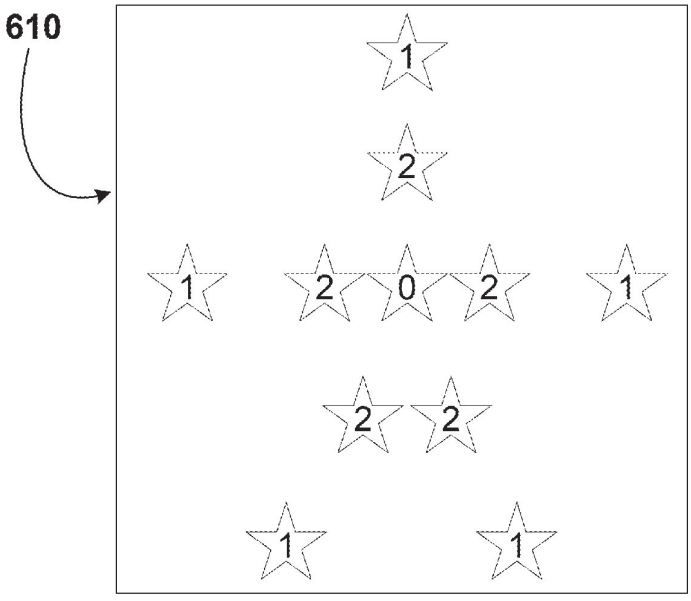


FIG. 6E

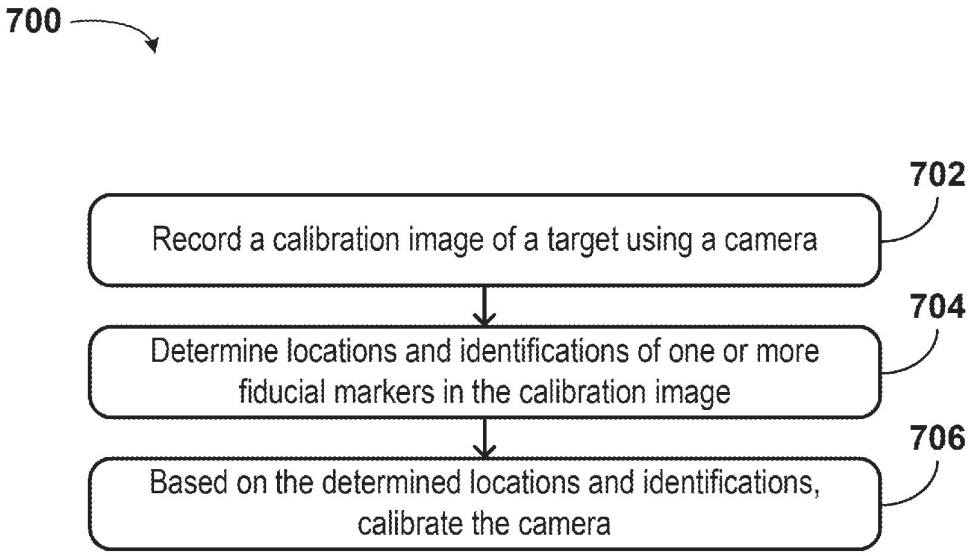

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Record a calibration image of a target using a camera
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Determine locations and identifications of one or more fiducial markers in the calibration image
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Based on the determined locations and identifications, calibrate the camera

FIG. 7