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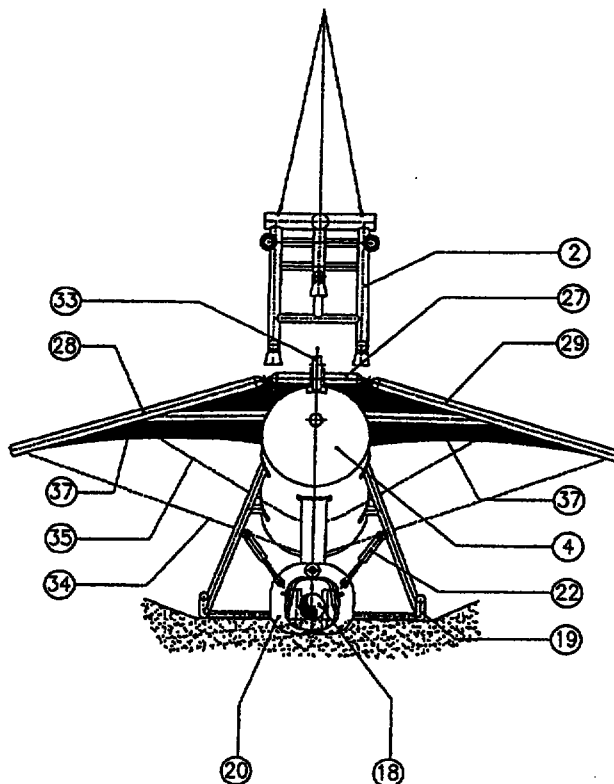
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(54) Title: DEVICE FOR APPLYING AN UPWARD FORCE TO A BODY AND METHOD OF TOWING A BODY**(57) Abstract**

The invention relates to a device and a method of towing new or used pipeline below water-level and sinking it on location, said device having first means for adjusting the collective floating capacity of the device and the portion of the pipeline engaged by the device, and second means which, depending on a velocity in relation to the water to be applied to the assembly of the device and the pipeline coupled to it, supply an additional upward force.



Device for applying an upward force to a body and method of towing a body

The invention relates to a device for exerting an upward force to a body situated in a medium, said device
5 having one or more coupling members by which the device can be coupled to said body.

In particular, the invention relates to a device for exerting an upward force to a body situated on the bottom of a water, such as a pipeline or a part thereof, with the
10 ultimate aim of being able to tow the body through the water.

It is known per se to tow relatively short lengths of pipeline newly to be laid, but this always concerns pipe having sufficient floating power of its own, if it is sealed
15 and completely filled with air. Mostly, such lengths of pipe to be towed are additionally provided with towing weights by which the pipe can be kept at a predetermined distance from the bottom.

The object of the invention is to provide a device and
20 a method by which it is possible to tow new pipeline, but also pipeline already laid and used, to a new location, either in its entirety or in large lengths. This is especially important for pipeline used for a relatively short period, which will increasingly occur with exploitation of
25 the smaller oil and gas reservoirs, since they are often still of sufficient quality to be used anew.

It will be obvious that from an economical point of view, only towing largest possible lengths is justified. A first condition for being able to tow large lengths of
30 pipeline from a bottom is that a composed floating power of the pipeline and the device or devices to be coupled to it can be arranged in the best possible way.

Accordingly, according to the invention it is provided for, that the device has first means to adjust the floating
35 power of the device, and second means that supply an additi-

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onal upward force, depending on a speed in relation to the medium, which is to be applied to the assembly of the device and the body coupled to it.

With said first means, the floating power of the device
5 can be adjusted such, that the collective floating power of the device and the part of the pipeline engaged by the device at the relevant depth of the bottom is a predetermined degree smaller than the weight of the device and the part of the pipeline engaged by the device. The second means
10 then provide for that already at some speed of the assembly of pipeline and devices in relation to the water or seawater the total floating power is large enough to be able to pull the pipeline loose from the bottom.

This has the great advantage that the pipeline will
15 only come loose from the bottom of the sea at the moment when towing is started and that the pipeline at the place of destination can simply be sunk by removing the speed in relation to the seawater. Furthermore, a further advantage is that e.g. with changing weather conditions during towing
20 the pipeline can be brought to a safer depth by simply reducing the towing speed.

A further elaboration of the invention provides for that said first means comprise at least one floating member being provided with an inlet and an outlet, intended for
25 feeding a medium of a first density and discharging a medium of a second density, respectively, the density of said second medium being larger than the density of said first medium, and said second medium being displaced by said first medium.

30 Since the device should be coupled to a body being situated under water, it is important that the floating power of the device is so small, that said device can be easily sunk and be brought into the proper position in relation to the body, before the desired floating power at
35 rest is adjusted. According to a further development, the floating member or floating members are filled with (sea)wa-

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ter before being sunk, and once the device is coupled to the body, the water is expelled by compressed air.

The second means mounted on the device substantially consist of a wing structure connected to the floating member, said structure comprising a wing supporting frame with wing canvas fixed to it, further means having been provided for keeping parts of the wing in a non-operating position or an operating position.

A preferred embodiment of the device according to the invention has a wing supporting frame with a central shaft pivotably mounted in longitudinal direction on top of said floating member, with swinging arms being attached at both sides near an outer end of the central shaft, in which extending arms consisting of one or more parts are provided for bringing the swinging arms from a non-operating position to an operating position and back, said arms engaging the swinging arms at one outer end and engaging a sliding member movable across the central shaft at the other outer end, and locking means being provided for locking the extension arms in predetermined positions on the central shaft.

This construction of the device has the advantage that the device with the wing occupies a relatively small space in a non-operating position, as a consequence of which a large number of such devices can be taken along in one transport, e.g. in the hold and on the deck of a ship. Further, the pivoting wing makes it considerably easier to manoeuvre the device into position under water, since no upward force exerted by the wing as a consequence of flow or advancement need be compensated.

The central shaft of the wing structure is pivotably mounted, so that the wing can be aligned independently of the position of the floating member of the device, which is coupled to the pipeline to be transported. In this way, the wings of a series of successive devices coupled to a pipeline can take up an identical position, and the upward forces



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on the several locations are exerted in corresponding directions.

A second embodiment of the device according to the invention is characterized in that the wing supporting frame
5 comprises a ring rotatable around the floating member, a substantially U-shaped portion longitudinally extending across at least a part of the floating member and having its outer ends connected to the rotatable ring and having a pivoting connection with the rear side of said floating
10 member, with swinging arms being mounted near the outer ends of the legs of the U-shaped portion, and in which extending arms consisting of one or more parts have been provided for bringing the swinging arms from a non-operating position to an operating position and back, said extending arms at one
15 end engaging the swinging arms and at the other end engaging a sliding member movable across a leg of the U-shaped portion, locking means being provided for locking the extending arms on predetermined positions on a leg of the U-shaped portion.

20 With this embodiment, the wing is divided into two halves situated next to the floating member or floating members, whereby it is prevented that due to a floating member being situated under it, a part of the wing surface may not contribute to the upward force to be supplied by the
25 wing. This embodiment is especially meant for those situations in which the floating members should supply a relatively large upward force and also have a considerable surface.

Here, the wing can change its position in relation to the floating member or floating members, to wit by means of
30 the mounted rotatable ring. Since especially with such a larger embodiment, it can be important to be able to adjust the upward force to be realized exactly, considering the ultimate transport speed in relation to the water, according to another elaboration it has been provided for, that the U-
35 shaped portion is pivotably connected to the rotatable ring, and that the rotatable connection of the U-shaped portion

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can be adjusted relative to the rear side of the floating member in such a way, that the U-shaped portion can take up various angular positions in relation to the plane in which the rotatable ring is situated.

5 Basically, such a measure can be applied with the first embodiment as well; however, we chose a design as economically as possible, which can be used within a predetermined range, and in which additional adjusting possibilities were therefore left out.

10 The device is meant to be positioned straight above the pipeline to transported and subsequently be coupled to it. In order to be able to take up the correct position in relation to the pipeline and the bottom (of the sea), the device is provided with a supporting frame connected to one
15 or more floating members and standing on at least two parallel sliding legs, that enclose a sharp angle in relation to the central shaft or the U-shaped portion of the wing supporting frame, in which further at least two clamping members situated between the sliding legs and spaced apart have
20 been provided, their points of application being at the same height in relation to the sliding legs.

In order to move a device according to the invention from e.g. a ship's deck into the vicinity of the pipeline to be transported, a mounting frame has been provided, which is
25 meant to be coupled to the device at one side, and that has fastening points at the other side for being connected to the cables of a crane or winch, by which mounting frame and device can be brought to the desired depth.

The mounting frame is further provided with at least
30 three coupling members, which are meant to cooperate with complementary coupling members on the device, a pipe and/or cable work system having at least connecting points for which complementary connecting points have been mounted on the device, at least one hydraulic cylinder having one end
35 meant to engage (or engage in the vicinity of) an outer end

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or ends of the extending arms and locking means for them mounted on the device.

For accurately positioning, coupling and adjusting the device, after the device has been brought to a predetermined distance over the bottom (of the sea) at the mounting frame, a preferably remotely controlled instrument is employed. Such an instrument is provided with propelling and control means and can be coupled to the mounting frame, in such a way that they take up a fixed position in relation to each other, and in which the piping and cable work system of the mounting frame is coupled to that of the instrument, or directly to a piping and cable work system of the control system onboard the ship from where mounting takes place.

After the controllable instrument has been coupled to mounting frame and device, with the help of the controllable instrument the device is positioned across the pipeline, the clamping members are brought around the pipeline, the liquid medium present in the floating member is completely or partly displaced, the wing supporting frame is brought into operative position by the hydraulic cylinder on the mounting frame, the coupling of the mounting frame to the device is unlocked, and the controllable instrument is uncoupled from the mounting frame at the predetermined height.

In most cases, the pipeline will have been concealed in the bottom (of the sea) in order to make the pipeline heavier and/or to prevent the pipeline from getting damaged by towing nets used in fishing, and prevent the towing nets from getting damaged by the pipeline. Clearing the pipeline in e.g. the area of the North Sea takes place by blowing away the sand lying on and immediately near the pipeline. The cleared parts of the bottom immediately next to the pipeline will not always be situated in a horizontal plane, as a consequence of which the device, which will come to bear on said non-horizontale plane with its sliding legs, will enclose a small angle with the vertical. This is no problem, since the wing is able to tilt in relation to the

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device. Due to the engagement of the two spaced apart clamping members of the device on the device, the position of the device as a whole in relation to the longitudinal direction of the pipeline will always correspond to the predetermined angle.

The invention further provides for a method of transporting a length of pipeline. Preceding the transport, the length of pipeline to be transported is uncoupled, closed off at the ends and partly or completely emptied, whereupon the devices are mounted at predetermined distances and are adjusted. The mutual distance between the devices is determined by, among other things, the total upward force to be produced by each of the devices, stiffness and weight of the pipeline and the resistance of pipeline and the devices coupled to it, that can be expected during transport in the water.

For transport, tugs are coupled at least to the ends of the length of pipeline, the control of the tugs being arranged such, that the forces engaging the pipeline are distributed as uniformly as possible. To that end, according to the invention it has been provided for, that for arranging the control of the tugs, signals are generated by signalling members mounted at least on each of the devices, said signals indicating the absolute position or the position in relation to a certain point of at least the individual devices, said signals being received and processed by a signal processing unit being situated at a distance from the length of pipeline being towed, or moving along with it, and the signal processing unit sends out the control signals intended for the tugs.

Since the pipelines to be transported can have a length of many kilometres, it is very important that except for the horizontal position, the vertical position of each of the devices is known as well, so that oscillations in the pipeline in all directions can be identified and the control can be adjusted to them. Obviously, this means that by changing

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weather conditions, the entity can be sunk to wait for more favourable conditions, or that e.g. yet another one or more tugs can be coupled to the pipeline along its length.

Besides for transporting large lengths of pipeline, the device according to the invention can also be used for releasing other objects from the bottom of the sea and transporting them through the water. Here, one can think of e.g. wrecked ships, for which one or more devices should be coupled to the object, depending on its size.

10 In the following, the invention is further explained by means of the drawing, in which:

Fig. 1 shows a first embodiment of the device as well as a mounting frame and a remotely controlled instrument;

15 Fig. 2A shows schematically a plan view of a first embodiment of the device;

Fig. 2B shows schematically a front view of a first embodiment of the device;

Fig. 2C shows schematically a lateral view of a first embodiment of the device;

20 Fig. 3 shows a front view of the device according to Fig. 1, with the wing in a non-operating position;

Fig. 4 shows a front view according to Fig. 3, with the wing having been brought into the operating position;

25 Fig. 5 shows a second embodiment of the device as well as a mounting frame;

Fig. 6 shows schematically a plan view of the second embodiment; and

Fig. 7A, B, C, D, E show successive stages of positioning and adjusting a device according to the invention.

30 In fig. 1, a first embodiment of the device is indicated by 1, the mounting frame by 2 and the instrument required for precise positioning and adjustment of the device by 3. The device 1 has a floating member 4 being provided with a supporting frame 5 and a wing structure 6.

35 The floating member 4 is provided with an inlet 7 and an outlet 8, said inlet being connected to a compressed air

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connection of the mounting frame 2 in a way not further indicated. Preferably, the inlet 7 is a hydraulically operated valve which is normally in closed position. The outlet 8 can be executed simply as a pressure-relief valve.

5 At the top side of the floating member 4, a number of pins 9 have been mounted, in the given example three, which are intended for cooperation with the legs 10 of the mounting frame 2. The legs 10 extend conically at their ends, as a consequence of which the mounting frame can be positioned
10 on the device more easily. Hydraulically operated locking members 11 are mounted on the legs 10, said members preferably having a protrusion for falling into holes or recessions mounted in the pins 9.

 The mounting frame is further provided with a hydraulic
15 cylinder 12, which, in case of a mounting frame fixed to the device, engages an operating member 13 by which the wing structure 6 can be brought from a non-operating position to an operating position.

 The supporting frame 5 is provided with two pairs of
20 legs 14, 15, with connections 16 with an arched portion 17 being mounted between each pair of legs. The arched portions 17 are intended to fall across a pipeline 18 to be transported, which facilitates positioning the device in relation to pipeline. Further, the pairs of legs 14, 15 are connected to
25 each other by sliding legs 19 at both sides of the arched portions 17. The front ends of the sliding legs protrude slightly upwards in order to prevent them from becoming stuck in the bottom at the beginning of transport of a length of pipeline.

30 Between the legs of the pairs 14, 15, clamping members 20, 21 have been mounted, by which the pipeline can be clamped. The clamping members can be operated by hydraulic cylinders 22 (see Fig. 3). Preferably, the clamping members 20, 21 have their insides provided with elastic pads 23 that
35 can be made of rubber or a plastic and can be provided with more or less elastic compartments or air chambers.

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Such pads serve to prevent damage to the pipeline and possible secondary pipes. Although possible secondary pipes having a much smaller diameter than the main pipe are mostly mounted on top of the main pipe, they can end up at the side
5 of the main pipe due to rotation of the main pipe, or the secondary pipe coming loose from the main pipe.

The device is provided with pipes - not further indicated in the drawing - for hydraulically operating the cylinders 22 for the clamping members 20, 21, the inlet 7 and
10 possibly outlet 8, and a compressed air duct connecting to the inlet 7. When positioning the mounting frame 2 onto the device 1, these pipes connect to a pipe system of the mounting frame 2. Connection can take place through a quick-action coupling system, for example, in which hydraulical
15 means for coupling and uncoupling are situated on the mounting frame.

The pipe system of the mounting frame can have a direct connection to the ship from where the mounting is arranged. However, it is preferred to use a remotely controlled instrument 3, which is kept at depth near the pipeline during
20 subsequent mounting of a number of devices, and to connect the pipes to the mounting ship through said instrument.

For this purpose, a second coupling system 24 is mounted serving for coupling the pipes of the mounting frame 2
25 to the corresponding pipes of the instrument 3. The lines for hydraulically operating the cylinder 12 and the locking members 11 mounted on the mounting frame connect to said coupling system 24 as well.

Apart from the pipe coupling system, the mounting frame
30 is further provided with a mechanical coupling 25, by which mounting frame 2 and instrument 3 can be secured in relation to each other.

Besides hydraulical and compressed air lines, possibly a cable system can be provided for temporarily connecting
35 electrical instruments mounted on the device to the mounting ship.

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Fig. 2A shows a plan view of the device with the various parts of the wing structure 6. The structure has a central pipe being rotatably mounted around the longitudinal axis on the driving member 4. At the front end, a cross-piece 27 has been mounted, to which the pivoting arms 28, 29 have been fastened. The pivoting arms 28, 29 are further connected to expanding arms 30, 31, and the expanding arms 30, 31 are in turn connected to a sliding member 32 slidable across the central pipe 26.

10 The view according to Fig. 2B further shows stay ropes 34, 35 connecting the expanding arms 28, 29 to each other, and for which one or more guides 36 are mounted underneath the drive member. In this way, the pivoting arms 28, 29 and the central pipe 26 can always remain in one plane during
15 load on the wing.

Fig. 2C shows the sliding member 32 slidable across the pipe 26. Said sliding member mounts a protruding portion 33 serving as point of engagement for a complementary portion at the outer end of the hydraulic cylinder 12 on the mounting frame 2. Further, the sliding member is provided with locking means for securing the sliding member 32 on the central pipe 26 in the two outer positions; the operating and the non-operating position. Said locking means can be controlled in a simple way by engagement or removal of the
20 complementary portion of the hydraulic cylinder on the protruding portion 33 of the sliding member 32.

The canvas 37 (see Figs. 3, 4) carried by the wing structure 6 is fixed to the pivoting arms 28, 29 and the cross-piece 27. Further, the canvas is secured by two cables
30 extending along the central pipe and a recession for the sliding member 32 with the protruding portion 33 is made between the cables.

The canvas 37 is mounted in such a way, that a delta wing is formed in the operating position. Due to this, one
35 not only achieves a very stable wing, but also a very well controllable wing.

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Figs. 3 and 4 show a device 1 with mounting frame 2, with the entity placed only across a pipe 18 in Fig. 3, and with the clamping members 20, 21 clamping the pipe 18 in Fig. 4, the wing having been brought in its operating position and the mounting frame having been uncoupled. Here, the water brought into the floating member preceding the mounting is completely or partly expelled by compressed air, which can occur after clamping the pipe to the device and before or after bringing the wing into its operating position.

Figs. 5, 6 show a second embodiment of the device, distinguishing itself from the first embodiment by a wing structure having two wing parts mounted at both sides of the floating member.

The wing structure consists of a ring 38 rotatably mounted around the floating member 4, to which a U-shaped portion 39, extending around the portion of the drive member situated behind the rotatable ring, is pivotably connected. At its rear side, the U-shaped portion 39 is connected to the drive member through an adjustable connecting part 40, by which it is possible to adjust the angle of the wing to the horizontal.

Pivoting arms 41, 42 are mounted at the outer ends of the U-shaped portion 39, near the rotatable ring 38. With the help of expanding arms 43, 44 and sliding members 45, 46 mounted on the U-shaped portion, the pivoting arms can be brought into the operating or the non-operating position. The sliding members 45, 46 are mutually connected to a connecting part 47 which is provided with a protruding portion 48 which is meant to cooperate with a complementary part 49 fixed to the hydraulic cylinder 12 on the mounting frame.

Although not indicated in the drawing, in this embodiment too, the pivoting arms 41, 42 are connected to one or more of the stay ropes extending underneath the floating member.

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Figs. 7A through 7E show the successive stages of installing a device according to the invention.

Fig. 7A shows sinking a remotely controlled instrument to a desired depth from a ship 51. A line and cable supply system 50, necessary for controlling the instrument and for installing the device, is connected to the instrument. At the same time, a mounting frame 2 is coupled to a device 1 by a crane 52, whereupon said device is brought to a predetermined distance above the bottom of the sea (Fig. 7B).

In Fig. 7C, the instrument 3 and the necessary pipes have been coupled to the mounting frame 2. Subsequently, the pipeline is traced with the help of the camera and sonar system on the instrument 3 and, using the propulsion means of the instrument 3, the device is placed across the pipeline 18 (Fig. 7D).

After the device 1 has been placed across the pipeline 18, successively the clamping members are clamped around the pipeline, the water is forced from the floating member and the wing is brought into the operating position. Subsequently, the mounting frame 2 with the instrument 3 are uncoupled from the device by disengaging the locking members 11, and the assembly is brought at a predetermined distance above the bottom of the sea with the help of the propulsion means of the instrument (Fig. 7E).

Finally, the instrument 3 is uncoupled from the mounting frame 2 and the mounting frame can be hauled up and be coupled to a next device. All further devices can be mounted in this way, in which the remote controlled instrument can always be kept in close proximity of the pipeline.

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1. Device for exerting an upward force to a body situated in a medium, said device having one or more coupling members by which the device can be coupled to said
5 body, characterized in that first means have been provided for adjusting the floating power of the device, and second means for supplying an additional upward force, depending on a speed in relation to the medium, which is to be applied to the assembly of the device and the body coupled to it.
- 10 2. Device according to claim 1, characterized in that said first means comprise at least one floating member being provided with an inlet and an outlet, intended for feeding a medium of a first density and discharging a medium of a second density, respectively, the density of said second
15 medium being larger than the density of said first medium, and said second medium being displaced by said first medium.
3. Device according to claim 2, characterized in that said second means substantially consist of a wing structure connected to the floating member.
- 20 4. Device according to claim 3, characterized in that said wing structure comprises a wing supporting frame with wing canvas fixed to it, means having been provided for keeping parts of the wing in a non-operating position or an operating position.
- 25 5. Device according to claim 4, characterized in that said wing supporting frame has a central shaft pivotably mounted in longitudinal direction on top of said floating member, with swinging arms being attached at both sides near an outer end of the central shaft, in which expanding arms
30 consisting of one or more parts are provided for bringing the swinging arms from a non-operating position to an operating position and back, said arms engaging the swinging arms at one outer end and engaging a sliding member movable across the central shaft at the other outer end, and locking

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means being provided for locking the expanding arms in predetermined positions on the central shaft.

6. Device according to claim 4, characterized in that the wing supporting frame comprises a ring rotatable around the floating member, a substantially U-shaped portion longitudinally extending across at least a part of the floating member and having its outer ends connected to the rotatable ring and having a pivoting connection with the rear side of said floating member, with swinging arms being mounted near the outer ends of the legs of the U-shaped portion, and in which extending arms consisting of one or more parts have been provided for bringing the swinging arms from a non-operating position to an operating position and back, said extending arms at one end engaging the swinging arms and at the other end engaging a sliding member movable across a leg of the U-shaped portion, locking means being provided for locking the extending arms on predetermined positions on a leg of the U-shaped portion.

7. Device according to claim 6, characterized in that the U-shaped portion is pivotably connected to the rotatable ring, and that the rotatable connection of the U-shaped portion can be adjusted relative to the rear side of the floating member in such a way, that the U-shaped portion can take up various angular positions in relation to the plane in which the rotatable ring is situated.

8. Device according to claims 2 - 7, characterized in that at the bottom side, the device is provided with a supporting frame connected to one or more floating members and standing on at least two parallel sliding legs, that enclose a sharp angle in relation to the central shaft or the U-shaped portion of the wing supporting frame, in which further at least two clamping members situated between the sliding legs and spaced apart have been provided, their points of application being at the same height in relation to the sliding legs.

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9. Device according to claim 8, characterized in that the clamping members consist of two identical parts, resilient rubber or plastic parts being mounted at the inside.

10. Mounting frame for a device according to one or
5 more of the claims 1 - 9, characterized in that the frame is is provided with at least three coupling members, which are meant to cooperate with complementary coupling members on the device, a pipe and/or cable work system having at least connecting points for which complementary connecting points
10 have been mounted on the device, at least one hydraulic cylinder having one end meant to engage (or engage in the vicinity of) an outer end or ends of the extending arms and locking means for them mounted on the device.

11. Mounting frame according to claim 10, which is
15 meant to be at least partly operated by a controllable instrument, characterized in that the mounting frame has coupling means complementary to coupling means mounted on the controllable instrument, by which instrument and frame can be coupled to each other in a fixed position, and in
20 which the pipe and cable system have a common connecting point complementary to a common connecting point on the controllable instrument.

12. Method of mounting a device according to claims 1 - 9 of a length of pipeline lying on the bottom of the sea,
25 using a mounting frame according to claims 10 - 11 and a controllable instrument, characterized in that it comprises the following steps:

- coupling the mounting frame to the device and lowering the assembly to a predetermined height in relation to
30 the bottom of the sea,
- coupling the controllable instrument to the mounting frame at a predetermined height;
- placing the device across the pipeline with the help of the controllable instrument;
- 35 - have the clamping members engage the pipeline;

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- completely or partly displacing the liquid medium present in the floating member by means of compressed air;
 - driving the hydraulic cylinder on the mounting frame and bringing the wing supporting structure into the operating position;
 - unlocking the coupling of the mounting frame to the device; and
 - uncoupling the controllable instrument from the mounting frame at the predetermined height.
- 10 13. Method of transporting a length of pipeline situated on the bottom of the sea by a number of devices according to claims 1 - 9, characterized in that it comprises the following steps:
- closing off the length of pipeline at its outer ends
 - 15 and completely or partly emptying it;
 - spacing the devices at predetermined mutual intervals on the pipeline and adjusting said devices;
 - coupling the tugs to at least the outer ends of the length of pipeline; and
 - 20 - arranging the control of the tugs.
- 25 14. Method according to claim 13, characterized in that for arranging the control of the tugs, signals are generated by signalling members mounted at least on each of the devices, said signals indicating the absolute position or the position in relation to a certain point of at least the individual devices, said signals being received and processed by a signal processing unit being situated at a distance from the length of pipeline being towed, or moving along with it, and the signal processing unit sends out the control
- 30 signals intended for the tugs.
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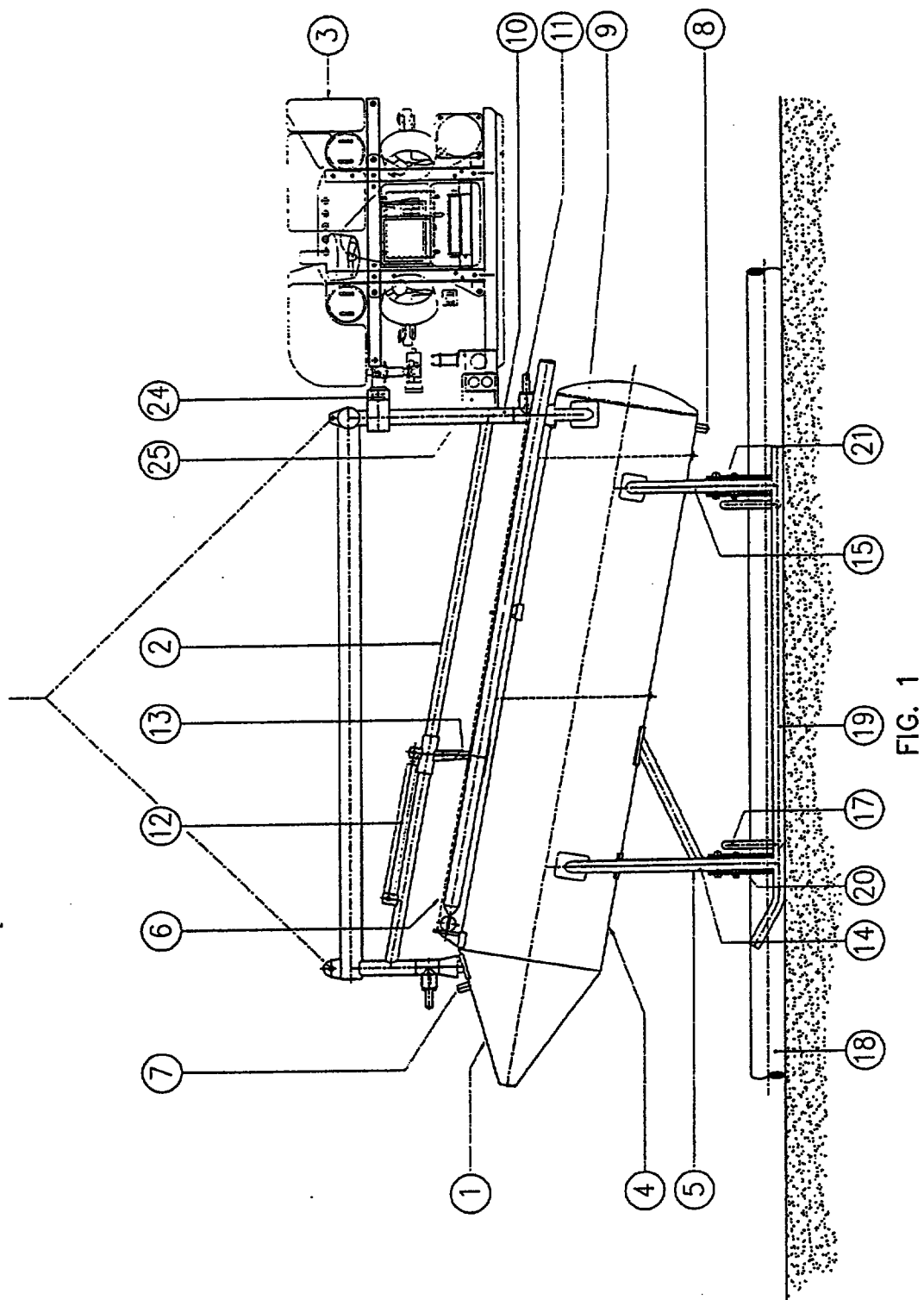


FIG. 1

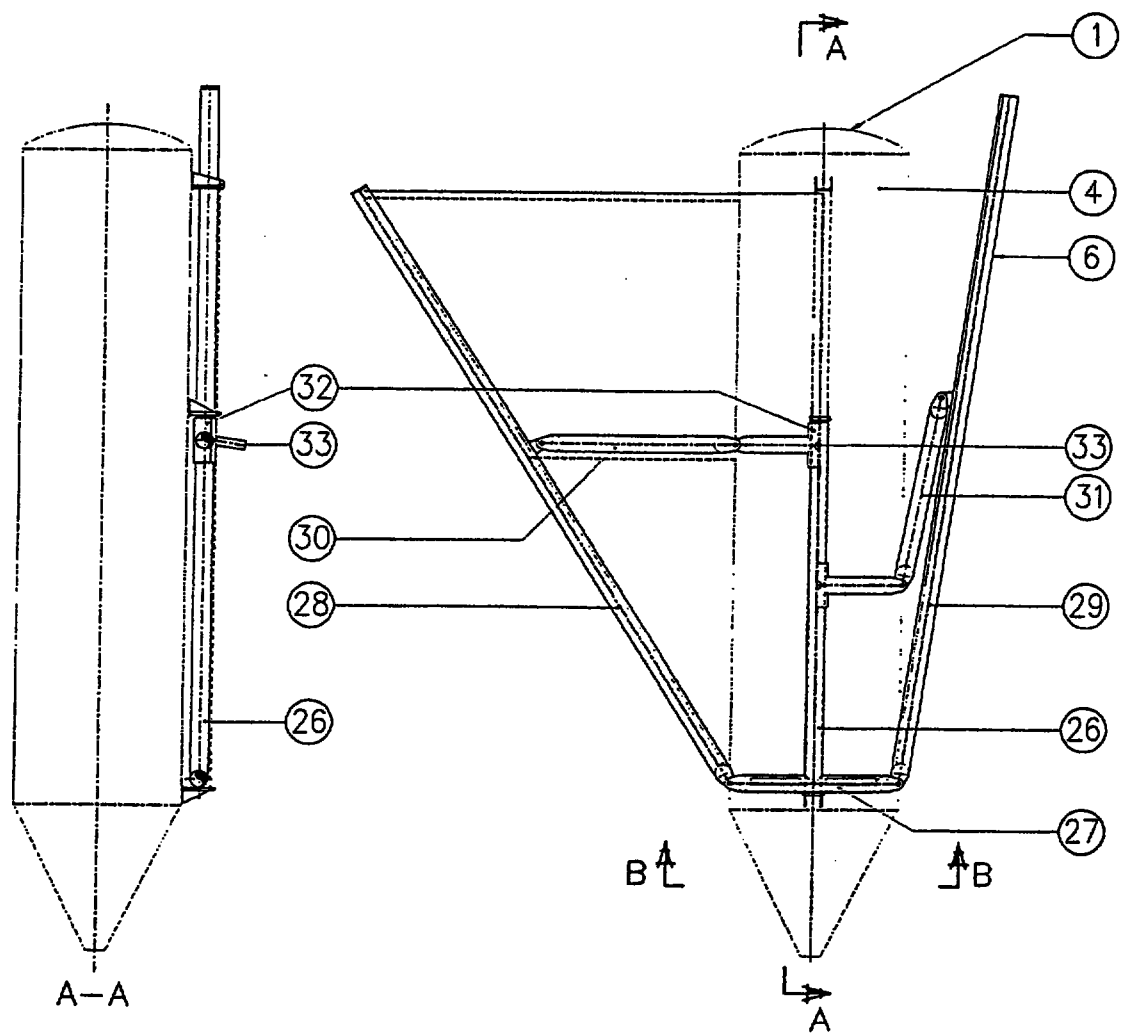


FIG. 2C

FIG. 2A

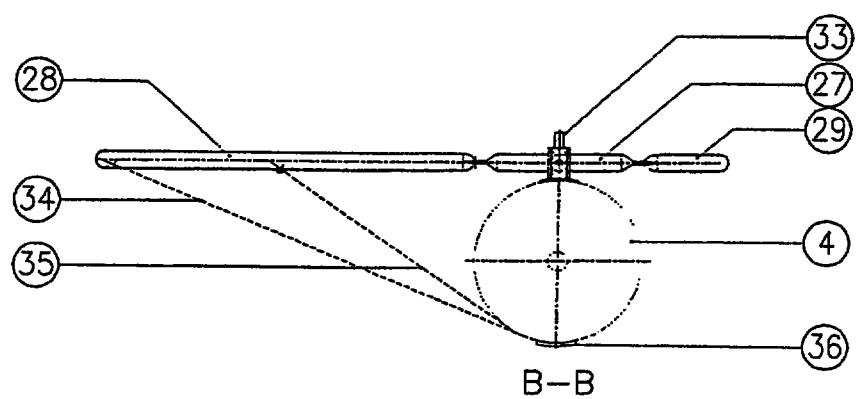


FIG. 2B

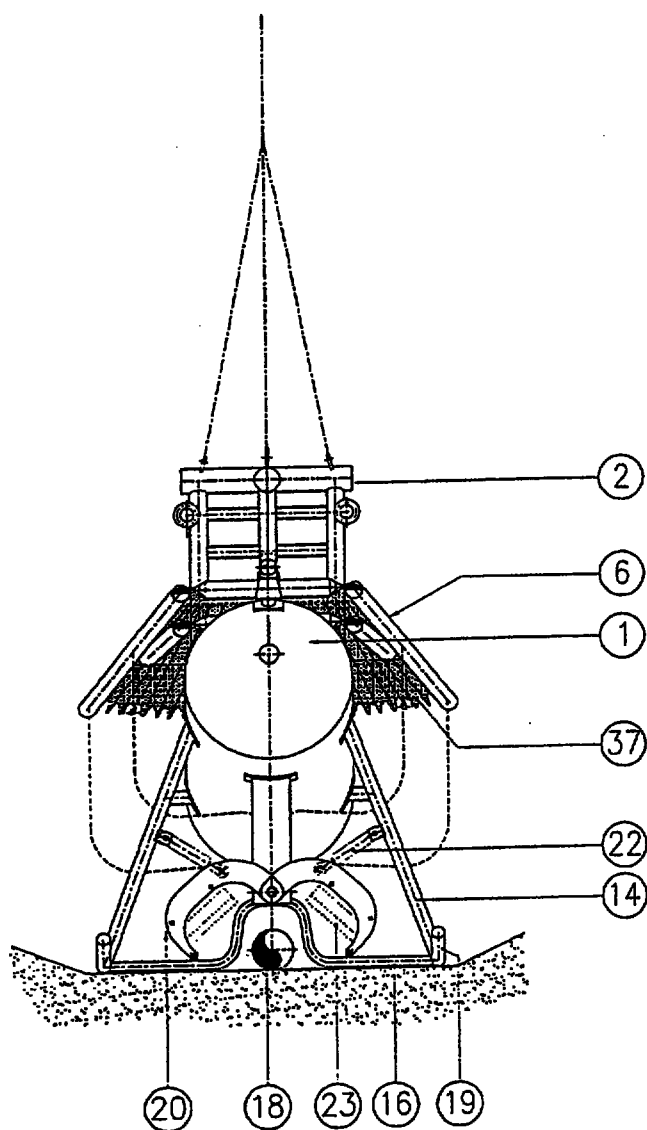


FIG. 3

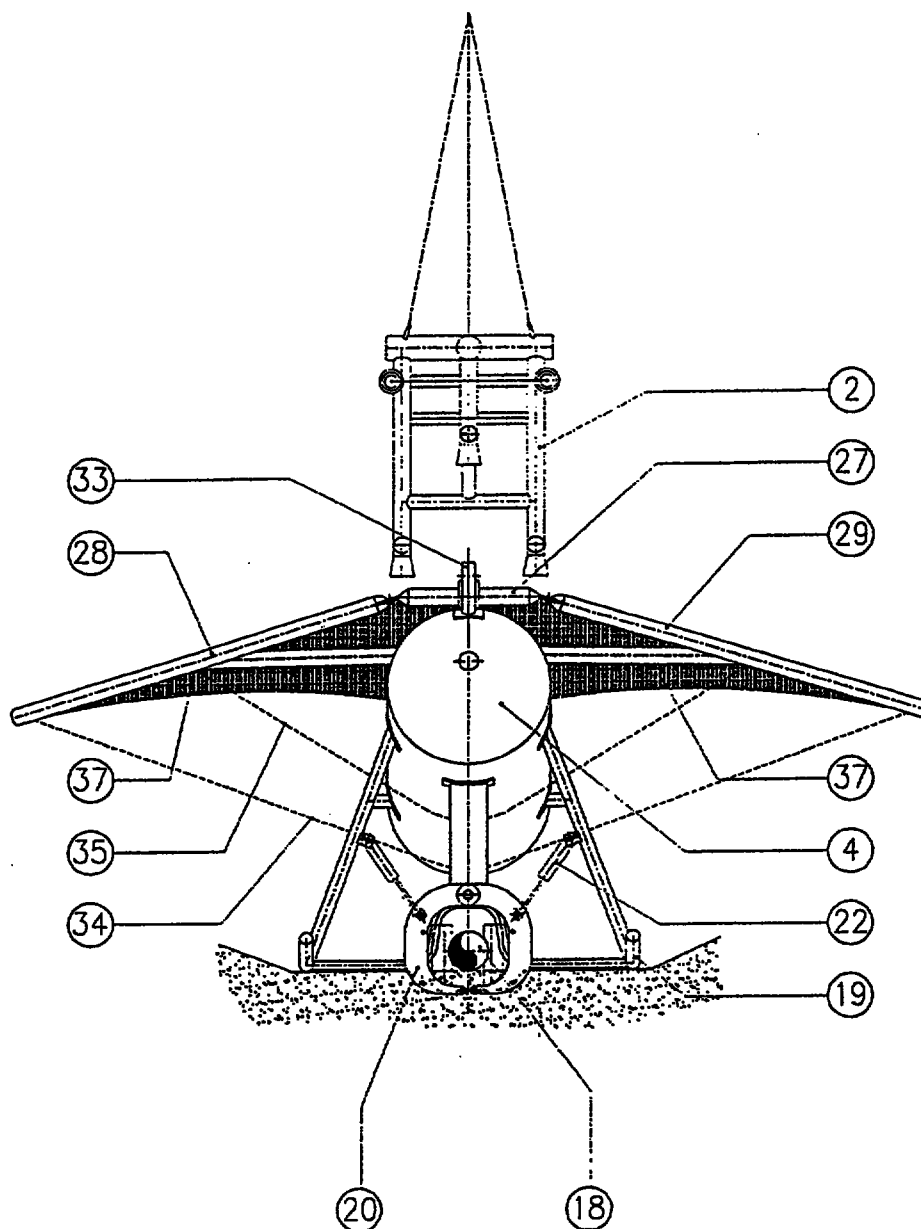


FIG. 4

SUBSTITUTE SHEET (RULE 26)

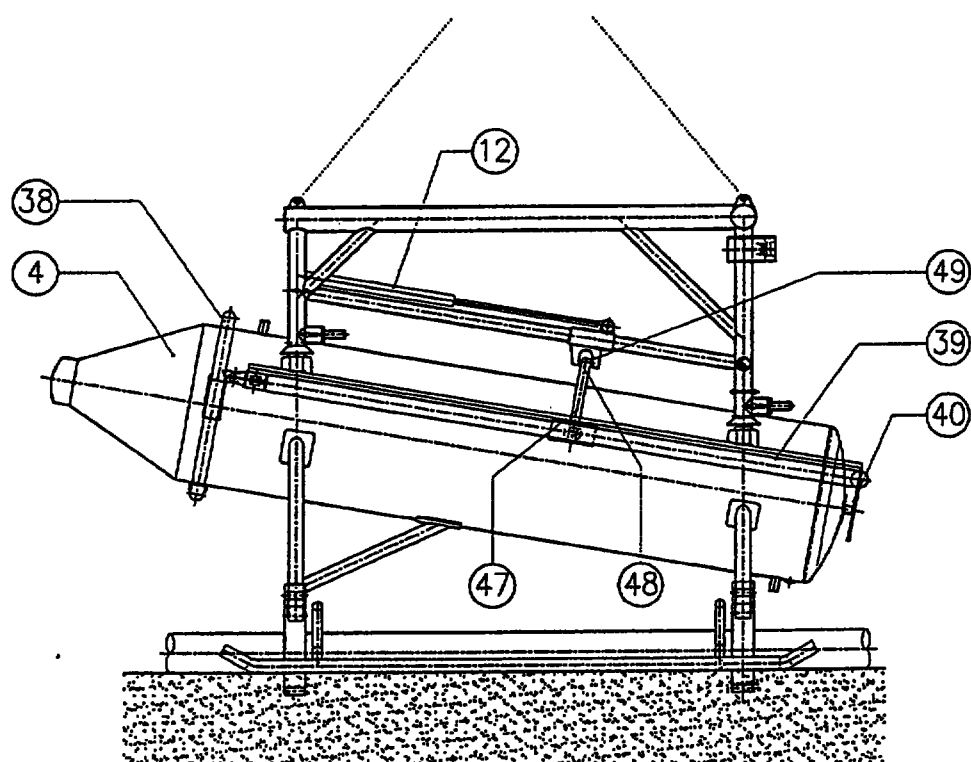


FIG. 5

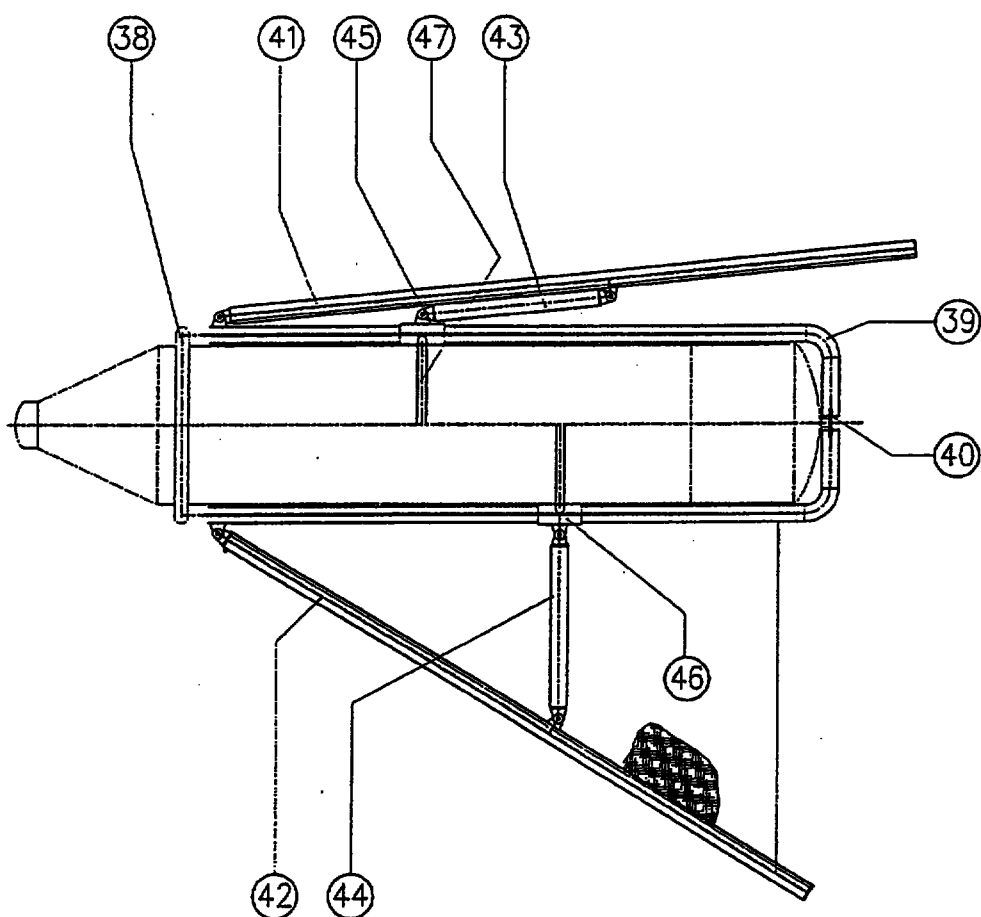


FIG. 6

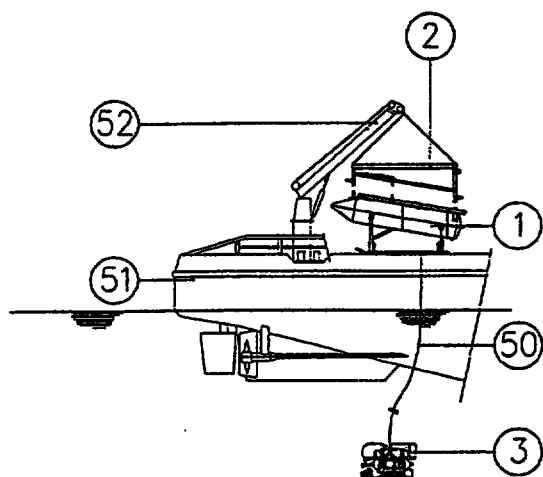


FIG. 7A

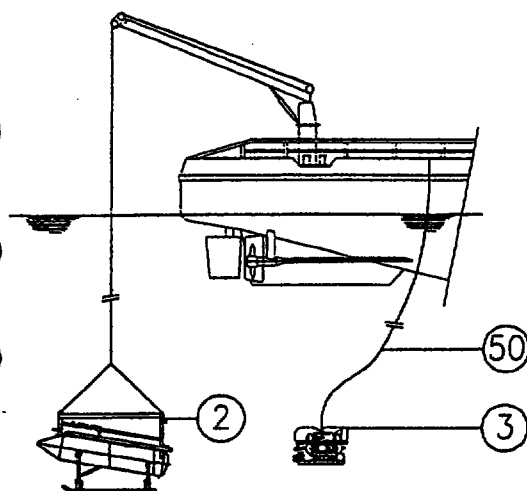


FIG. 7B

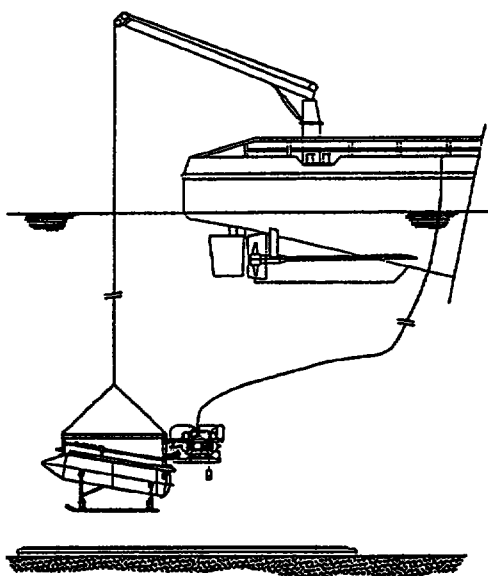


FIG. 7C

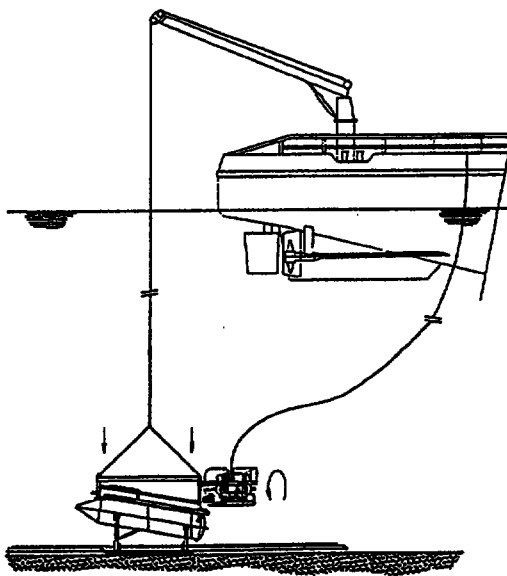


FIG. 7D

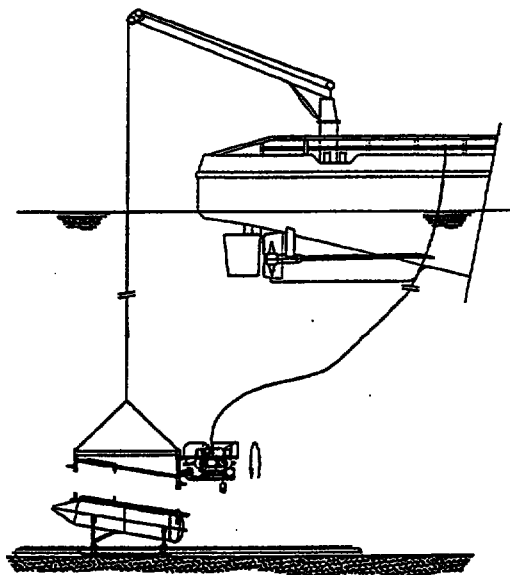


FIG. 7E

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Device for applying an upward force to a body and method of towing a body.

The invention relates to a device for exerting an upward force to a submerged pipeline, said device having one
5 or more coupling members by which the device can be coupled to said pipeline, a floating member for adjusting the floating power of the device, and an adjustable wing structure.

Such a device is known from US-A-4,789,269. This known device is relatively small and in order to give enough lift
10 force to a pipeline a large number of these known devices spaced at closed intervals is needed. The device according to the invention is designed to give a far greater lift force as a result of which only a relatively small number of these devices is needed to exert sufficient lift force on a
15 submerged pipeline. The aim of the invention is to provide a device with a far greater lift force that still can be handled easily when attaching or removing the device from a pipeline.

Accordingly, according to the invention it is provided
20 for, that the floating member, consisting of one or more parts, is a separate floating member, the said wing structure being connected to the floating member and that said wing structure comprises a wing supporting frame with wing canvas fixed to it, means having been provided for keeping parts of
25 the wing in a non-operating position or an operating position.

By being able to put the wing in a non-operating position the effective surface area of the wing is greatly reduced as a result of which the wing component in the total
30 lifting force of the device becomes neglectable small.

With the floating member, the floating power of the device can be adjusted such, that the collective floating power of the device and the part of the pipeline engaged by the device at the relevant depth of the bottom is a predetermined degree smaller than the weight of the device and
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the part of the pipeline engaged by the device. The wing structure provides for that already at some speed of the assembly of pipeline and devices in relation to the water of sea-water the total floating power is large enough to be
5 able to pull the pipeline loose from the bottom.

This has the great advantage that the pipeline will only come loose from the bottom of the sea at the moment when towing is started and that the pipeline at the place of destination can simply be sunk by removing the speed in
10 relation to the seawater. Furthermore, a further advantage is that e.g. with changing weather conditions during towing the pipeline can be brought to a safer depth by simply reducing the towing speed.

The canvas or the like is mounted in such a way to the
15 wing supporting frame that a delta wing is formed when the wing is positioned in the operating position. This has the advantage that a very stable wing is formed and moreover that therewith the wing is very well controllable.

A further elaboration of the invention provides for
20 that the floating member is provided with an inlet and an outlet, intended for feeding a medium of a first density and discharging a medium of a second density, respectively, the density of said second medium being larger than the density of said first medium, and said second medium being displaced
25 by said first medium.

Since the device should be coupled to a body being situated under water, it is important that the floating power of the device is so small, that said device can be easily sunk and be brought into the proper position in
30 relation to the body, before the desired floating power at rest is adjusted. According to a further development, the floating member or floating members are filled with (sea)water before being sunk, and once the device is coupled to the body, the water is expelled by compressed air.

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A preferred embodiment of the device according to the invention has a wing supporting frame with a central shaft pivotally mounted in longitudinal direction on top of said floating member, with swinging arms being attached at both
5 sides near an outer end of the central shaft, in which extending arms consisting of one or more parts are provided for bringing the swinging arms from a non-operating position to an operating position and back, said arms engaging the swinging arms at one outer end and engaging a sliding member
10 movable across the central shaft at the other outer end, and locking means being provided for locking the extension arms in predetermined positions on the central shaft.

This construction of the device has the advantage that the device with the wing occupies a relatively small space
15 in a non-operating position, as a consequence of which a large number of such devices can be taken along in one transport, e.g. in the hold and on the deck of a ship. Further, the pivoting wing makes it considerably easier to manoeuvre the device into position under water, since no
20 upward force exerted by the wing as a consequence of flow or advancement need be compensated.

The central shaft of the wing structure is pivotally mounted, so that the wing can be aligned independently of the position of the floating member of the device, which is
25 coupled to the pipeline to be transported. In this way, the wings of a series of successive devices coupled to a pipeline can take up an identical position, and the upward forces on the several locations are exerted in corresponding directions.

30 A second embodiment of the device according to the invention is characterized in that the wing supporting frame comprises a ring rotatable around the floating member, a substantially U-shaped portion longitudinally extending across at least a part of the floating member and having its
35 outer ends connected to the rotatable ring and having a pivoting connection with the rear side of said floating

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member, with swinging arms being mounted near the outer ends of the legs of the U-shaped portion, and in which extending arms consisting of one or more parts have been provided for bringing the swinging arms from a non-operating position to
5 an operating position and back, said extending arms at one end engaging the swinging arms and at the other end engaging a sliding member movable across a leg of the U-shaped portion, locking means being provided for locking the extending arms on predetermined positions on a leg of the U-shaped
10 portion.

With this embodiment, the wing is divided into two halves situated next to the floating member or floating members, whereby it is prevented that due to a floating member being situated under it, a part of the wing surface
15 may not contribute to the upward force to be supplied by the wing. This embodiment is especially meant for those situations in which the floating members should supply a relatively large upward force and also have a considerable surface.

Here, the wing can change its position in relation to
20 the floating member or floating members, to wit by means of the mounted rotatable ring. Since especially with such a larger embodiment, it can be important to be able to adjust the upward force to be realized exactly, considering the ultimate transport speed in relation to the water, according
25 to another elaboration it has been provided for, that the U-shaped portion is pivotally connected to the rotatable ring, and that the rotatable connection of the U-shaped portion can be adjusted relative to the rear side of the floating member in such a way, that the U-shaped portion can take up
30 various angular positions in relation to the plane in which the rotatable ring is situated.

Basically, such a measure can be applied with the first embodiment as well; however, we chose a design as economically as possible, which can be used within a predetermined
35 range, and in which additional adjusting possibilities were therefore left out.

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The device is meant to be positioned straight above the pipeline to transported and subsequently be coupled to it. In order to be able to take up the correct position in relation to the pipeline and the bottom (of the sea), the device is provided with a supporting frame connected to one or more floating members and standing on at least two parallel sliding legs, that enclose a sharp angle in relation to the central shaft or the U-shaped portion of the wing supporting frame, in which further at least two clamping members situated between the sliding legs and spaced apart have been provided, their points of application being at the same height in relation to the sliding legs.

In order to move a device according to the invention from e.g. a ship's deck into the vicinity of the pipeline to be transported, a mounting frame has been provided, which is meant to be coupled to the device at one side, and that has fastening points at the other side for being connected to the cables of a crane or winch, by which mounting frame and device can be brought to the desired depth.

The mounting frame is further provided with at least three coupling members, which are meant to cooperate with complementary coupling members on the device, a pipe and/or cable work system having at least connecting points for which complementary connecting points have been mounted on the device, at least one hydraulic cylinder having one end meant to engage (or engage in the vicinity of) an outer end or ends of the extending arms and locking means for them mounted on the device.

For accurately positioning, coupling and adjusting the device, after the device has been brought to a predetermined distance over the bottom (of the sea) at the mounting frame, a preferably remotely controlled instrument is employed. Such an instrument is provided with propelling and control means and can be coupled to the mounting frame, in such a way that they take up a fixed position in relation to each other, and in which the piping and cable work system of the

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mounting frame is coupled to that of the instrument, or directly to a piping and cable work system of the control system onboard the ship from where mounting takes place.

After the controllable instrument has been coupled to
5 mounting frame and device, with the help of the controllable instrument the device is positioned across the pipeline, the clamping members are brought around the pipeline, the liquid medium present in the floating member is completely or partly displaced, the wing supporting frame is brought into
10 operative position by the hydraulic cylinder on the mounting frame, the coupling of the mounting frame to the device is unlocked, and the controllable instrument is uncoupled from the mounting frame at the predetermined height.

In most cases, the pipeline will have been concealed in
15 the bottom (of the sea) in order to make the pipeline heavier and/or to prevent the pipeline from getting damaged by towing nets used in fishing, and prevent the towing nets from getting damaged by the pipeline. Clearing the pipeline in e.g. the area of the North Sea takes place by blowing
20 away the sand lying on and immediately near the pipeline. The cleared parts of the bottom immediately next to the pipeline will not always be situated in a horizontal plane, as a consequence of which the device, which will come to bear on said non-horizontal plane with its sliding legs,
25 will enclose a small angle with the vertical. This is no problem, since the wing is able to tilt in relation to the device. Due to the engagement of the two spaced apart clamping members of the device on the device, the position of the device as a whole in relation to the longitudinal direction of the pipeline will always correspond to the predetermined
30 angle.

The invention further provides for a method of transporting a length of pipeline. Preceding the transport, the length of pipeline to be transported is uncoupled, closed
35 off at the ends and partly or completely emptied, whereupon the devices are mounted at predetermined distances and are

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adjusted. The mutual distance between the devices is determined by, among other things, the total upward force to be produced by each of the devices, stiffness and weight of the pipeline and the resistance of pipeline and the devices
5 coupled to it, that can be expected during transport in the water.

For transport, tugs are coupled at least to the ends of the length of pipeline, the control of the tugs being arranged such, that the forces engaging the pipeline are distributed as uniformly as possible. To that end, according to
10 the invention it has been provided for, that for arranging the control of the tugs, signals are generated by signalling members mounted at least on each of the devices, said signals indicating the absolute position or the position in
15 relation to a certain point of at least the individual devices, said signals being received and processed by a signal processing unit being situated at a distance from the length of pipeline being towed, or moving along with it, and the signal processing unit sends out the control signals
20 intended for the tugs.

Since the pipelines to be transported can have a length of many kilometres, it is very important that except for the horizontal position, the vertical position of each of the devices is known as well, so that oscillations in the pipeline in all directions can be identified and the control can
25 be adjusted to them. Obviously, this means that by changing weather conditions, the entity can be sunk to wait for more favourable conditions, or that e.g. yet another one or more tugs can be coupled to the pipeline along its length.

30 Besides for transporting large lengths of pipeline, the device according to the invention can also be used for releasing other objects from the bottom of the sea and transporting them through the water. Here, one can think of e.g. wrecked ships, for which one or more devices should be
35 coupled to the object, depending on its size.

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In the following, the invention is further explained by means of the drawing, in which:

Fig. 1 shows a first embodiment of the device as well as a mounting frame and a remotely controlled instrument;

5 Fig. 2A shows schematically a plan view of a first embodiment of the device;

Fig. 2B shows schematically a front view of a first embodiment of the device;

10 Fig. 2C shows schematically a lateral view of a first embodiment of the device;

Fig. 3 shows a front view of the device according to Fig. 1, with the wing in a non-operating position;

Fig. 4 shows a front view according to Fig. 3, with the wing having been brought into the operating position;

15 Fig. 5 shows a second embodiment of the device as well as a mounting frame;

Fig. 6 shows schematically a plan view of the second embodiment; and

20 Fig. 7A, B, C, D, E show successive stages of positioning and adjusting a device according to the invention.

In fig. 1, a first embodiment of the device is indicated by 1, the mounting frame by 2 and the instrument required for precise positioning and adjustment of the device by 3. The device 1 has a floating member 4 being provided with
25 a supporting frame 5 and a wing structure 6.

The floating member 4 is provided with an inlet 7 and an outlet 8, said inlet being connected to a compressed air connection of the mounting frame 2 in a way not further indicated. Preferably, the inlet 7 is a hydraulically operated valve which is normally in closed position. The outlet 8
30 can be executed simply as a pressure-relief valve.

At the top side of the floating member 4, a number of pins 9 have been mounted, in the given example three, which are intended for cooperation with the legs 10 of the mounting frame 2. The legs 10 extend conically at their ends, as
35 a consequence of which the mounting frame can be positioned

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on the device more easily. Hydraulically operated locking members 11 are mounted on the legs 10, said members preferably having a protrusion for falling into holes or recessions mounted in the pins 9.

5 The mounting frame is further provided with a hydraulic cylinder 12, which, in case of a mounting frame fixed to the device, engages an operating member 13 by which the wing structure 6 can be brought from a non-operating position to an operating position.

10 The supporting frame 5 is provided with two pairs of legs 14, 15, with connections 16 with an arched portion 17 being mounted between each pair of legs. The arched portions 17 are intended to fall across a pipeline 18 to be transported, which facilitates positioning the device in relation to
15 pipeline. Further, the pairs of legs 14, 15 are connected to each other by sliding legs 19 at both sides of the arched portions 17. The front ends of the sliding legs protrude slightly upwards in order to prevent them from becoming stuck in the bottom at the beginning of transport of a
20 length of pipeline.

Between the legs of the pairs 14, 15, clamping members 20, 21 have been mounted, by which the pipeline can be clamped. The clamping members can be operated by hydraulic cylinders 22 (see Fig. 3). Preferably, the clamping members
25 20, 21 have their insides provided with elastic pads 23 that can be made of rubber or a plastic and can be provided with more or less elastic compartments or air chambers.

Such pads serve to prevent damage to the pipeline and possible secondary pipes. Although possible secondary pipes
30 having a much smaller diameter than the main pipe are mostly mounted on top of the main pipe, they can end up at the side of the main pipe due to rotation of the main pipe, or the secondary pipe coming loose from the main pipe.

The device is provided with pipes - not further indicated in the drawing - for hydraulically operating the cylinders 22 for the clamping members 20, 21, the inlet 7 and
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possibly outlet 8, and a compressed air duct connecting to the inlet 7. When positioning the mounting frame 2 onto the device 1, these pipes connect to a pipe system of the mounting frame 2. Connection can take place through a quick-action coupling system, for example, in which hydraulic means for coupling and uncoupling are situated on the mounting frame.

The pipe system of the mounting frame can have a direct connection to the ship from where the mounting is arranged. However, it is preferred to use a remotely controlled instrument 3, which is kept at depth near the pipeline during subsequent mounting of a number of devices, and to connect the pipes to the mounting ship through said instrument.

For this purpose, a second coupling system 24 is mounted serving for coupling the pipes of the mounting frame 2 to the corresponding pipes of the instrument 3. The lines for hydraulically operating the cylinder 12 and the locking members 11 mounted on the mounting frame connect to said coupling system 24 as well.

Apart from the pipe coupling system, the mounting frame is further provided with a mechanical coupling 25, by which mounting frame 2 and instrument 3 can be secured in relation to each other.

Besides hydraulic and compressed air lines, possibly a cable system can be provided for temporarily connecting electrical instruments mounted on the device to the mounting ship.

Fig. 2A shows a plan view of the device with the various parts of the wing structure 6. The structure has a central pipe being rotatably mounted around the longitudinal axis on the driving member 4. At the front end, a cross-piece 27 has been mounted, to which the pivoting arms 28, 29 have been fastened. The pivoting arms 28, 29 are further connected to expanding arms 30, 31, and the expanding arms 30, 31 are in turn connected to a sliding member 32 slidable across the central pipe 26.

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The view according to Fig. 2B ~~further shows stay~~ ropes 34, 35 connecting the expanding arms 28, 29 to each other, and for which one or more guides 36 are mounted underneath the drive member. In this way, the pivoting arms 28, 29 and the central pipe 26 can always remain in one plane during load on the wing.

Fig. 2C shows the sliding member 32 slidable across the pipe 26. Said sliding member mounts a protruding portion 33 serving as point of engagement for a complementary portion at the outer end of the hydraulic cylinder 12 on the mounting frame 2. Further, the sliding member is provided with locking means for securing the sliding member 32 on the central pipe 26 in the two outer positions; the operating and the non-operating position. Said locking means can be controlled in a simple way by engagement or removal of the complementary portion of the hydraulic cylinder on the protruding portion 33 of the sliding member 32.

The canvas 37 (see Figs. 3, 4) carried by the wing structure 6 is fixed to the pivoting arms 28, 29 and the cross-piece 27. Further, the canvas is secured by two cables extending along the central pipe and a recession for the sliding member 32 with the protruding portion 33 is made between the cables.

The canvas 37 is mounted in such a way, that a delta wing is formed in the operating position. Due to this, one not only achieves a very stable wing, but also a very well controllable wing.

Figs. 3 and 4 show a device 1 with mounting frame 2, with the entity placed only across a pipe 18 in Fig. 3, and with the clamping members 20, 21 clamping the pipe 18 in Fig. 4, the wing having been brought in its operating position and the mounting frame having been uncoupled. Here, the water brought into the floating member preceding the mounting is completely or partly expelled by compressed air, which can occur after clamping the pipe to the device and

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before or after bringing the wing into its operating position.

Figs. 5, 6 show a second embodiment of the device, distinguishing itself from the first embodiment by a wing structure having two wing parts mounted at both sides of the floating member.

The wing structure consists of a ring 38 rotatably mounted around the floating member 4, to which a U-shaped portion 39, extending around the portion of the drive member situated behind the rotatable ring, is pivotally connected. At its rear side, the U-shaped portion 39 is connected to the drive member through an adjustable connecting part 40, by which it is possible to adjust the angle of the wing to the horizontal.

Pivoting arms 41, 42 are mounted at the outer ends of the U-shaped portion 39, near the rotatable ring 38. With the help of expanding arms 43, 44 and sliding members 45, 46 mounted on the U-shaped portion, the pivoting arms can be brought into the operating or the non-operating position. The sliding members 45, 46 are mutually connected to a connecting part 47 which is provided with a protruding portion 48 which is meant to cooperate with a complementary part 49 fixed to the hydraulic cylinder 12 on the mounting frame.

Although not indicated in the drawing, in this embodiment too, the pivoting arms 41, 42 are connected to one or more of the stay ropes extending underneath the floating member.

Figs. 7A through 7E show the successive stages of installing a device according to the invention.

Fig. 7A shows sinking a remotely controlled instrument to a desired depth from a ship 51. A line and cable supply system 50, necessary for controlling the instrument and for installing the device, is connected to the instrument. At the same time, a mounting frame 2 is coupled to a device 1

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by a crane 52, whereupon said device is brought to a predetermined distance above the bottom of the sea (Fig. 7B).

5 In Fig. 7C, the instrument 3 and the necessary pipes have been coupled to the mounting frame 2. Subsequently, the pipeline is traced with the help of the camera and sonar system on the instrument 3 and, using the propulsion means of the instrument 3, the device is placed across the pipeline 18 (Fig. 7D).

10 After the device 1 has been placed across the pipeline 18, successively the clamping members are clamped around the pipeline, the water is forced from the floating member and the wing is brought into the operating position. Subsequently, the mounting frame 2 with the instrument 3 are uncoupled from the device by disengaging the locking members 11, and
15 the assembly is brought at a predetermined distance above the bottom of the sea with the help of the propulsion means of the instrument (Fig. 7E).

20 Finally, the instrument 3 is uncoupled from the mounting frame 2 and the mounting frame can be hauled up and be coupled to a next device. All further devices can be mounted in this way, in which the remote controlled instrument can always be kept in close proximity of the pipeline.

- claims -



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1. Device (1) for exerting an upward force to a submerged pipeline, said device (1) having one or more coupling members (20,21) by which the device (1) can be coupled to
5 said pipeline, a floating member (4) for adjusting the floating power of the device (1), and an adjustable wing structure (6), characterized in that the floating member (4), consisting of one or more parts, is a separate floating member (4), the said wing structure (6) being connected to
10 the floating member (4) and that said wing structure (6) comprises a wing supporting frame (26-32;38-47) with wing canvas (37) fixed to it, means (12,31-33;44-47) having been provided for keeping parts of the wing (6) in a non-operating position or an operating position.

15 2. Device according to claim 1, characterized in that said floating member (4) being provided with an inlet (7) and an outlet (8), intended for feeding a medium of a first density and discharging a medium of a second density, respectively, the density of said second medium being larger
20 than the density of said first medium, and said second medium being displaced by said first medium.

3. Device according to claim 1-2, characterized in that said wing supporting frame (26-32) has a central shaft (26) pivotally mounted in longitudinal direction on top of
25 said floating member (4), with swinging arms (28,29) being attached at both sides near an outer end of the central shaft (26), in which extending arms (30,31) consisting of one or more parts are provided for bringing the swinging arms (28,29) from a non-operating position to an operating
30 position and back, said arms (30,31) engaging the swinging arms (28,29) at one outer end and engaging a sliding member (32) movable across the central shaft at the other outer end, and locking means being provided for locking the extending arms (30,31) in predetermined positions on the central
35 shaft (26).



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4. . Device according to claim 1-2, characterized in that the wing supporting frame (38-47) comprises a ring (38) rotatable around the floating member (4), a substantially U-shaped portion (39) longitudinally extending across at least a part of the floating member (4) and having its outer ends connected to the rotatable ring (38) and having a pivoting connection (40) with the rear side of said floating member (4), with swinging arms (41,42) being mounted near the outer ends of the legs of the U-shaped portion, and in which extending arms (43,44) consisting of one or more parts have been provided for bringing the swinging arms (41,42) from a non-operating position to an operating position and back, said extending arms (43,44) at one end engaging the swinging arms (41,42) and at the other end engaging a sliding member (45,46) movable across a leg of the U-shaped portion (39), locking means being provided for locking the extending arms (43,44) on predetermined positions on a leg of the U-shaped portion (39).

5. Device according to claim 4, characterized in that the U-shaped portion (39) is pivotally connected to the rotatable ring (38), and that the rotatable connection (40) of the U-shaped portion (39) can be adjusted relative to the rear side of the floating member (4) in such a way, that the U-shaped portion (39) can take up various angular positions in relation to the plane in which the rotatable ring (38) is situated.

6. Device according to claims 1-5, characterized in that at the bottom side, the device is provided with a supporting frame (5) connected to one or more floating members (4) and standing on at least two parallel sliding legs (19), that enclose a sharp angle in relation to the central shaft (26) or the U-shaped portion (39) of the wing supporting frame (26-32;38-47), in which further at least two clamping members (20,21) situated between the sliding legs (19) and spaced apart have been provided, their points



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of application being at the same height in relation to the sliding legs (19).

7. Device according to claim 6, characterized in that the clamping members (20,21) consist of two identical parts, resilient rubber of plastic parts (23) being mounted at the inside.

8. Mounting frame (2) for a device according to one or more of the claims 1-7, characterized in that the frame (2) is provided with at least three coupling members (10), which are meant to cooperate with complementary coupling members (9) on the device, a pipe and/or cable work system having at least connecting points for which complementary connecting points have been mounted on the device, at least one hydraulic cylinder (12) having one end meant to engage (or engage in the vicinity of) an outer end or ends of the extending arms (30,31;43,44) and locking means for them mounted on the device.

9. Mounting frame according to claim 8, which is meant to be at least partly operated by a controllable instrument (2), characterized in that the mounting frame has coupling means complementary to coupling means mounted on the controllable instrument (3), by which instrument (3) and frame (2) can be coupled to each other in a fixed position, and in which the pipe and cable system have a common connecting point complementary to a common connecting point on the controllable instrument (3).

10. Method of mounting a device according to claims 1-7 of a length of pipeline lying on the bottom of the sea, using a mounting frame (2) according to claims 8-9 and a controllable instrument (3), characterized in that it comprises the following steps:

- coupling the mounting frame (2) to the device (1) and lowering the assembly to a predetermined height in relation to the bottom of the sea,
- coupling the controllable instrument (3) to the mounting frame (2) at a predetermined height;



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- placing the device (1) across the pipeline with the help of the controllable instrument (3);
- have the clamping members (20,21) engage the pipeline;
- 5 - completely or partly displacing the liquid medium present in the floating member (4) by means of compressed air;
- driving the hydraulic cylinder (12) on the mounting frame (2) and bringing the wing supporting structure (26-10 32;38-47) into the operating position;
- unlocking the coupling of the mounting frame (2) to the device (1); and
- uncoupling the controllable instrument (3) from the mounting frame (2) at the predetermined height.
- 15 11. Method of transporting a length of pipeline situated on the bottom of the sea by a number of devices according to claims 1-7, characterized in that it comprises the following steps:
 - closing off the length of pipeline at its outer ends20 and completely or partly emptying it;
 - spacing the devices at predetermined mutual intervals on the pipeline and adjusting said devices;
 - coupling the tugs to at least the outer ends of the length of pipeline; and
 - 25 - arranging the control of the tugs.
- 12. Method according to claim 11, characterized in that for arranging the control of the tugs, signals are generated by signalling members mounted at least on each of the devices, said signals indicating the absolute position or the30 position in relation to a certain point of at least the individual devices, said signals being received and processed by a signal processing unit being situated at a distance from the length of pipeline being towed, or moving along with it, and the signal processing unit sends out the control35 signals intended for the tugs.
