of a head of the care receiver in the initial sitting posture and behind the head of the care receiver in the standing posture.

7. The assisting robot according to any one of claims 1 to 6, wherein a distance L between a line and the pivot axis of the arm is 230 to 290 mm, the line passing through the shoulder position of the care receiver held by the holder, with being parallel to a trunk holding surface defined by the holder for the care receiver.

8. The assisting robot according to any one of claims 1 to 7, wherein at the predetermined intermediate posture, a buttocks of the care receiver starts rising from a seat surface.

9. The assisting robot according to any one of claims 1 to 7, wherein at the predetermined intermediate posture, the position in the front-rear direction of the center of gravity of the care receiver enters a front-rear span of a ground surface in contact with feet of the care receiver.

10. The assisting robot according to any one of claims 1 to 7, wherein at the predetermined intermediate posture a mass supported by the holder reaches a value that is equal

to or greater than a predetermined percentage of an upper body mass of the care receiver.

11. The assisting robot according to any one of claims 1 to 7, wherein the predetermined intermediate posture is one upon a rear load on the assisting robot from the care receiver reaching a value that is equal to or less than a predetermined value.

12. The assisting robot according to any one of claims 1 to 7, wherein the predetermined intermediate posture is one upon an inclination of an upper body of the care receiver reaches a value that is equal to or greater than a predetermined value.