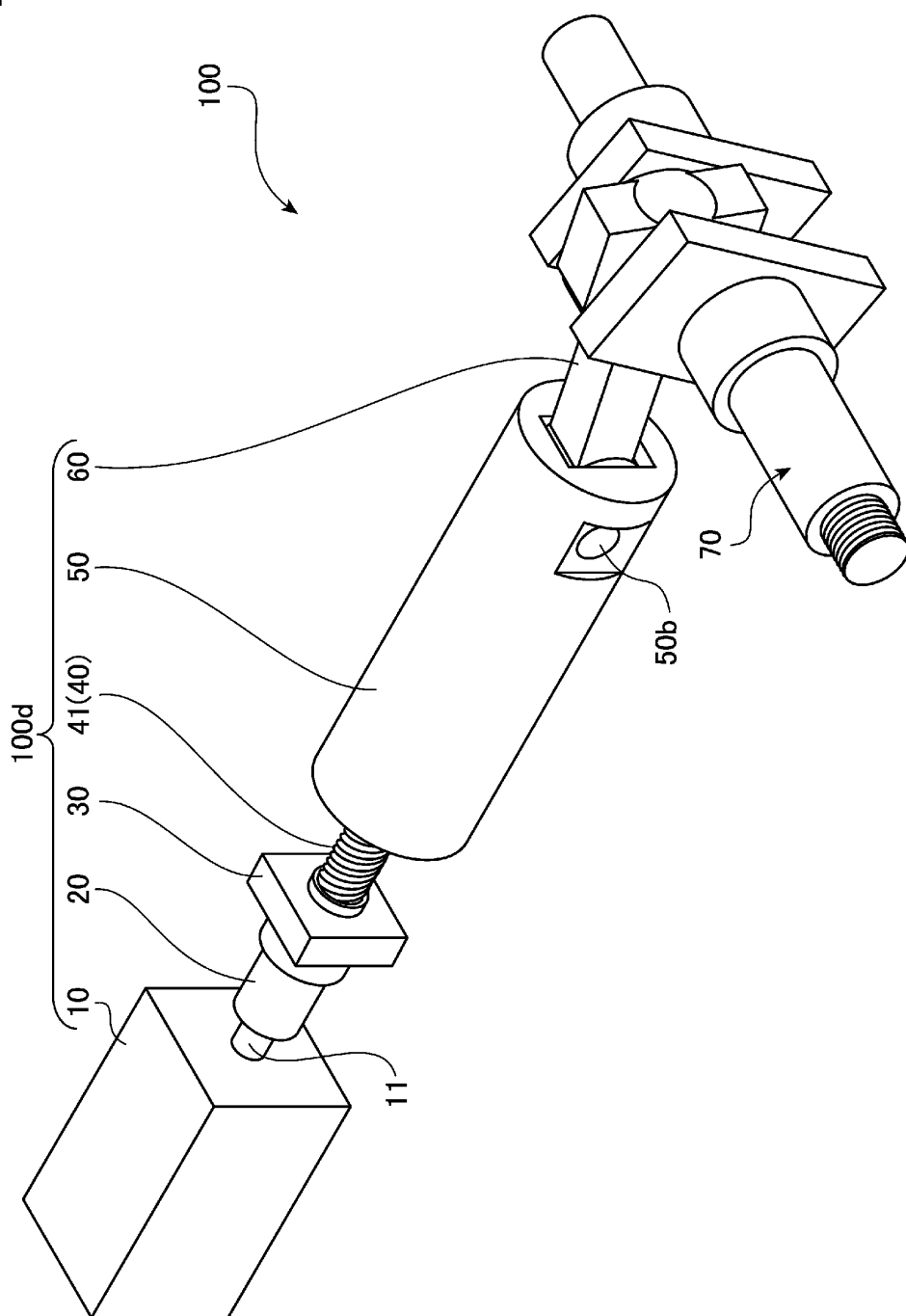
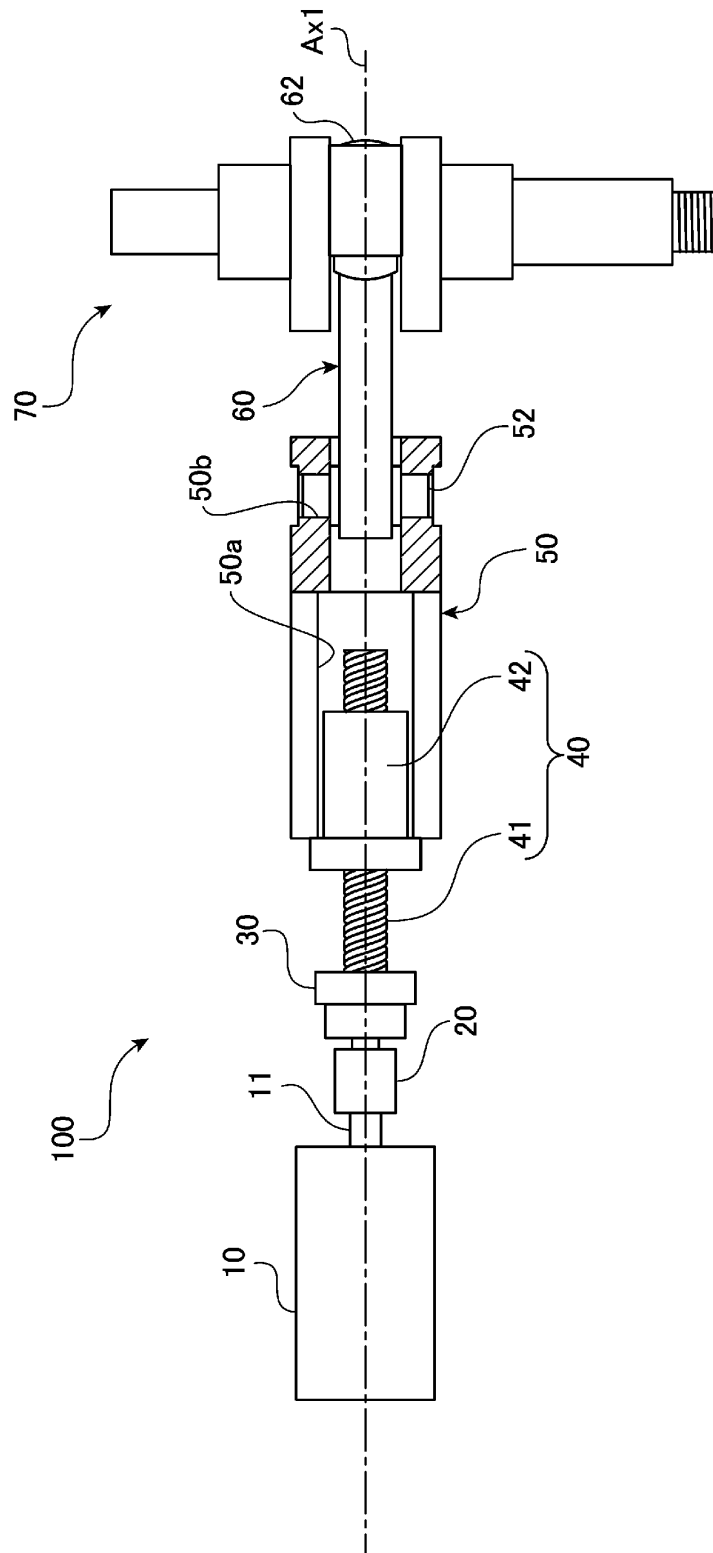


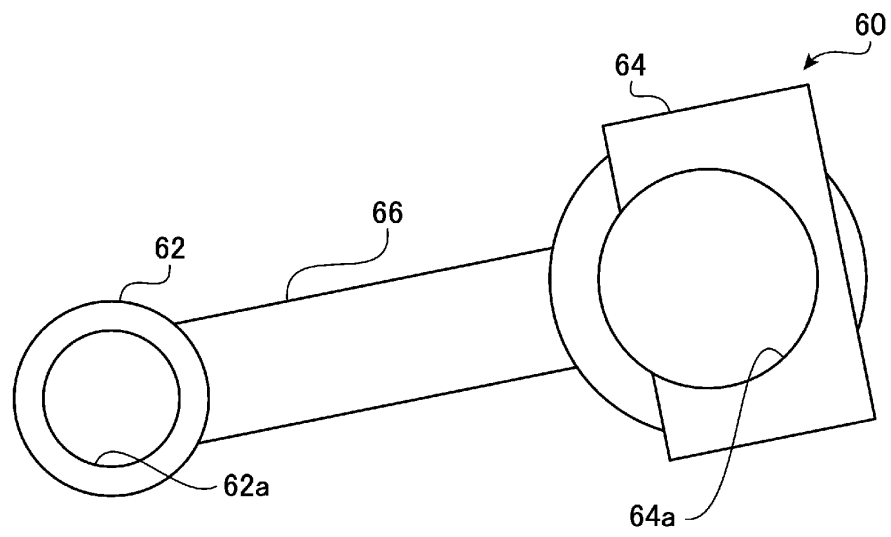
[図1]



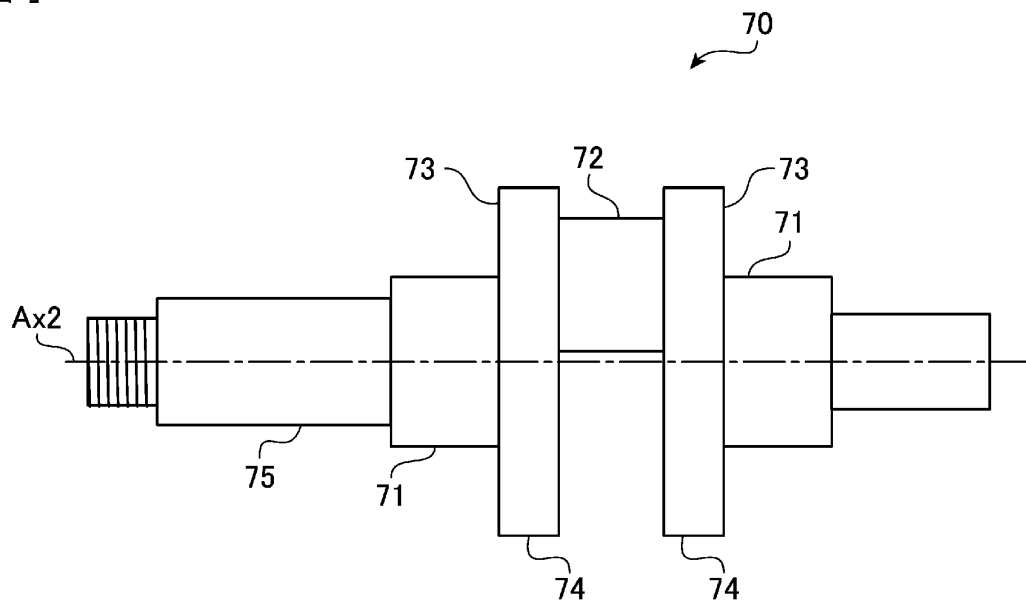
[図2]



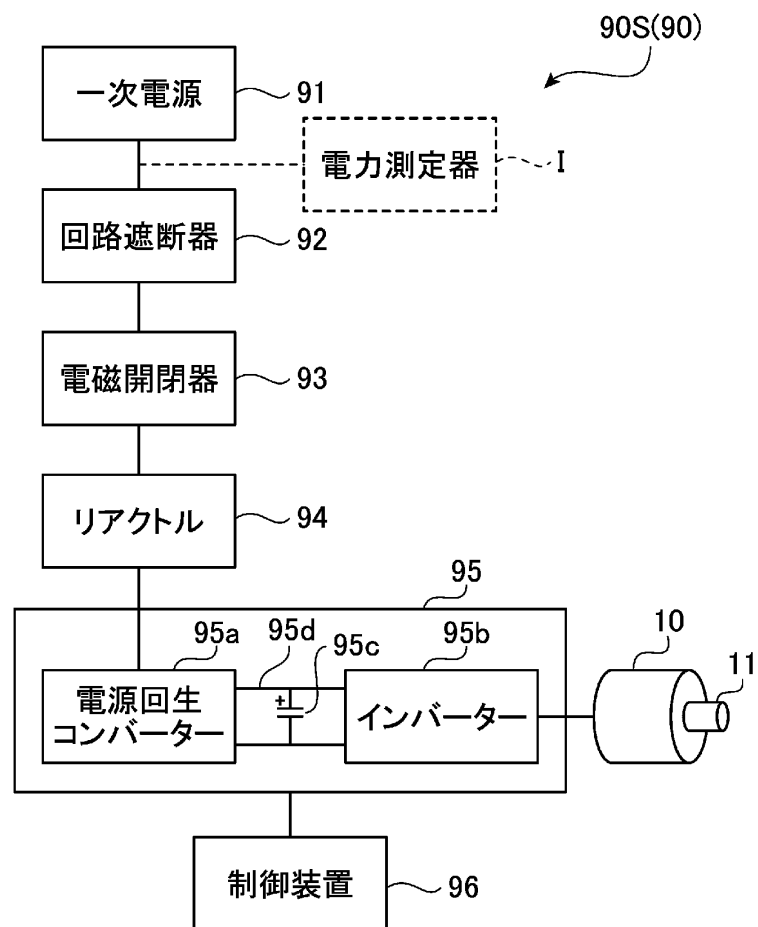
[図3]



[図4]

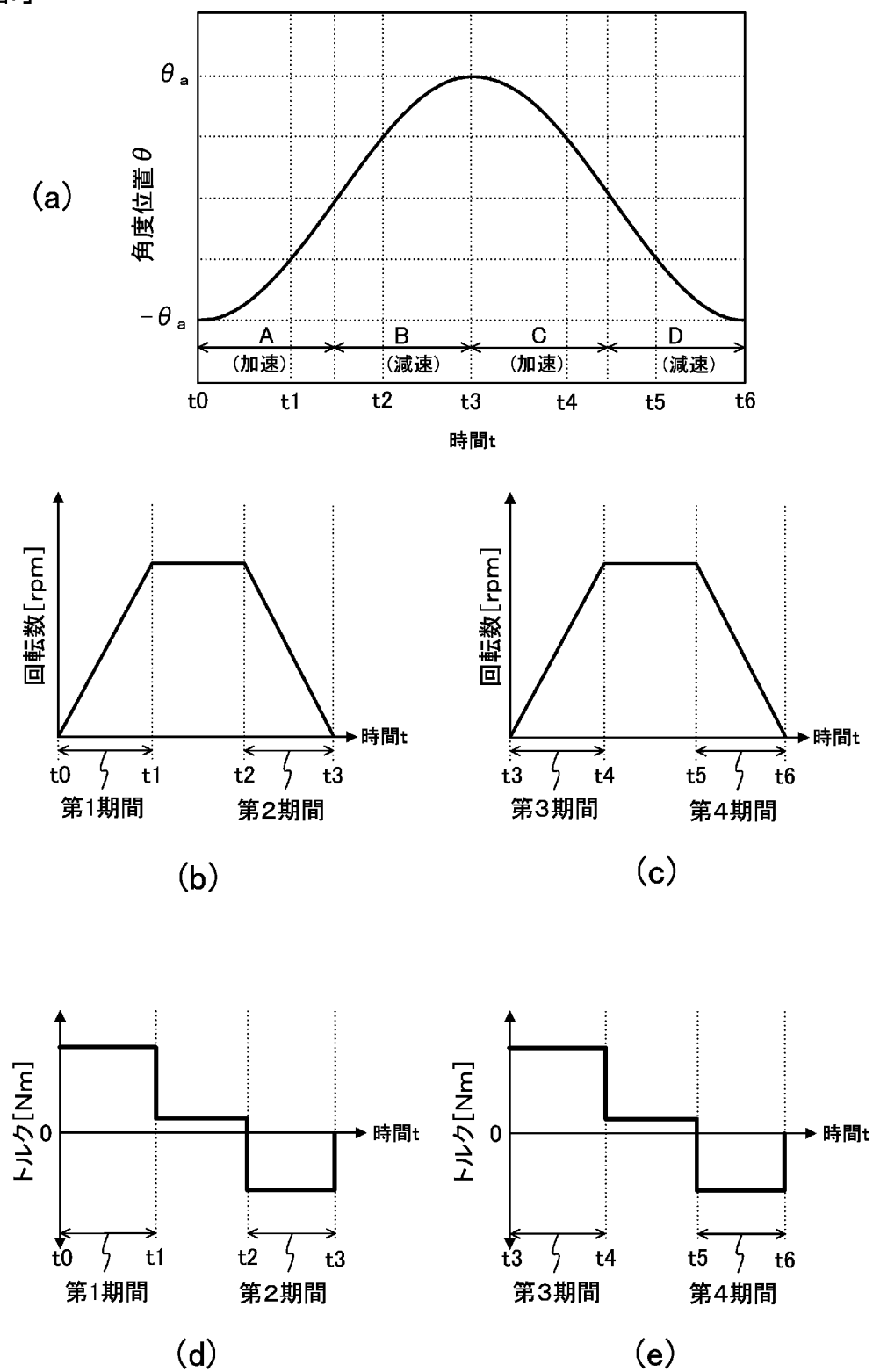


[図5]

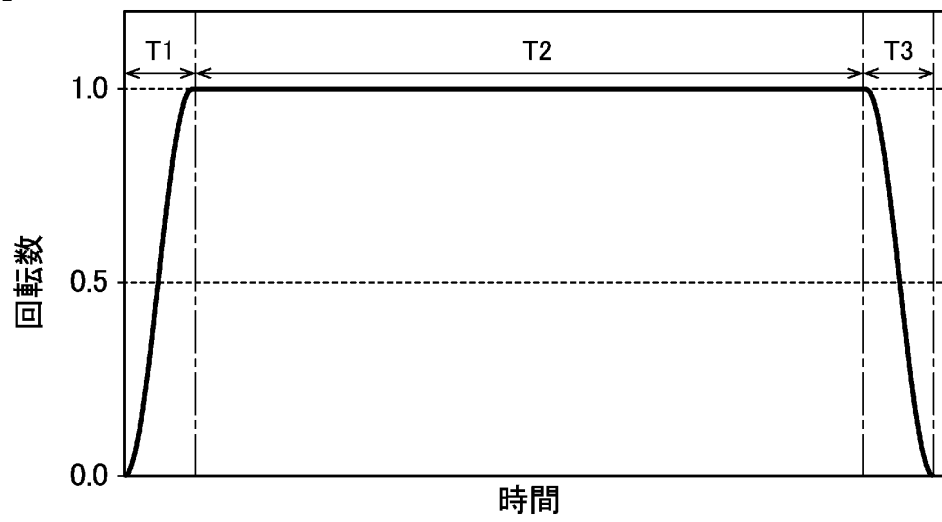




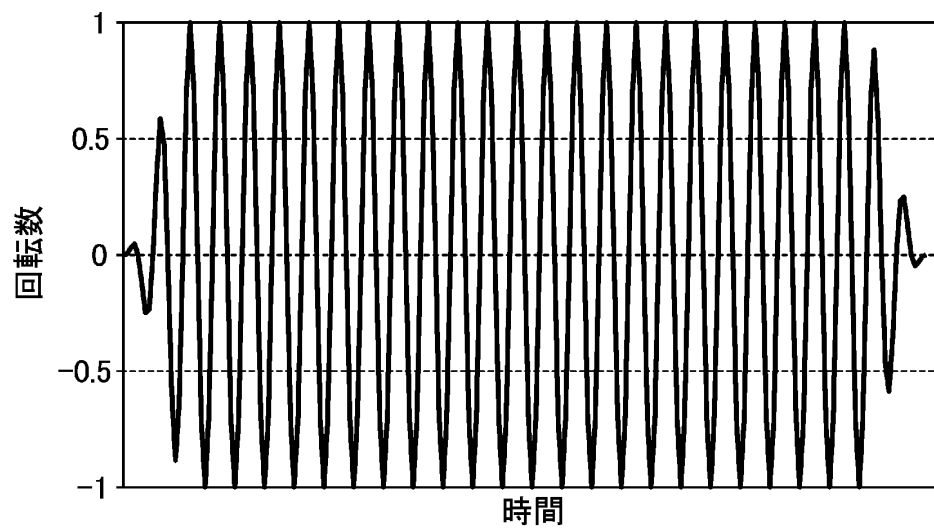
[図7]



[図8]

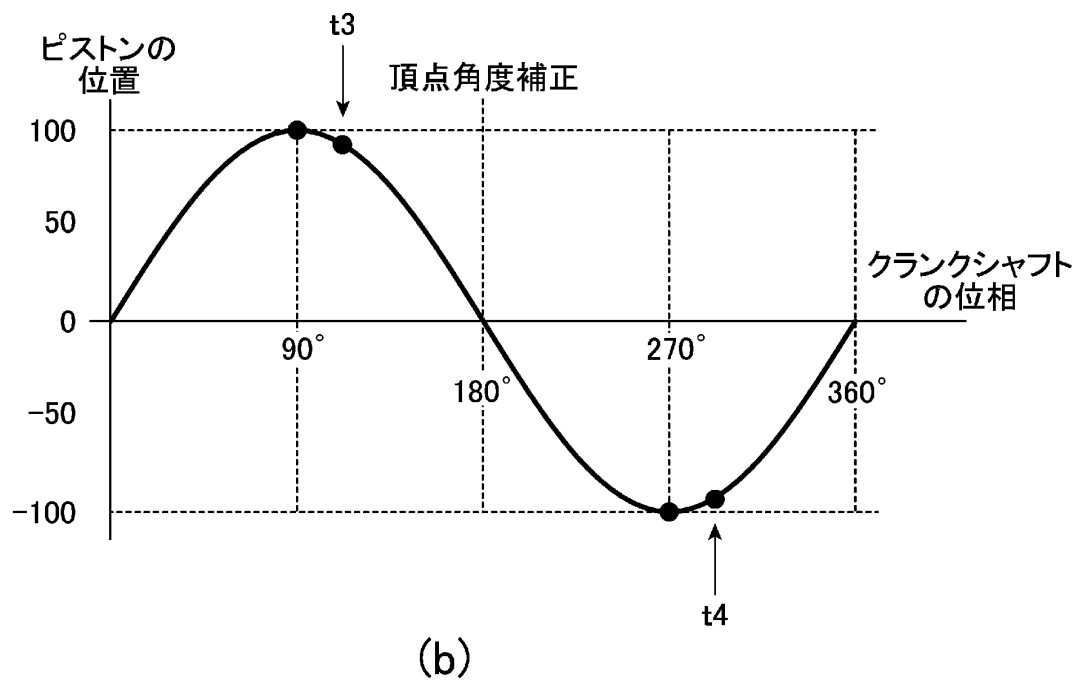
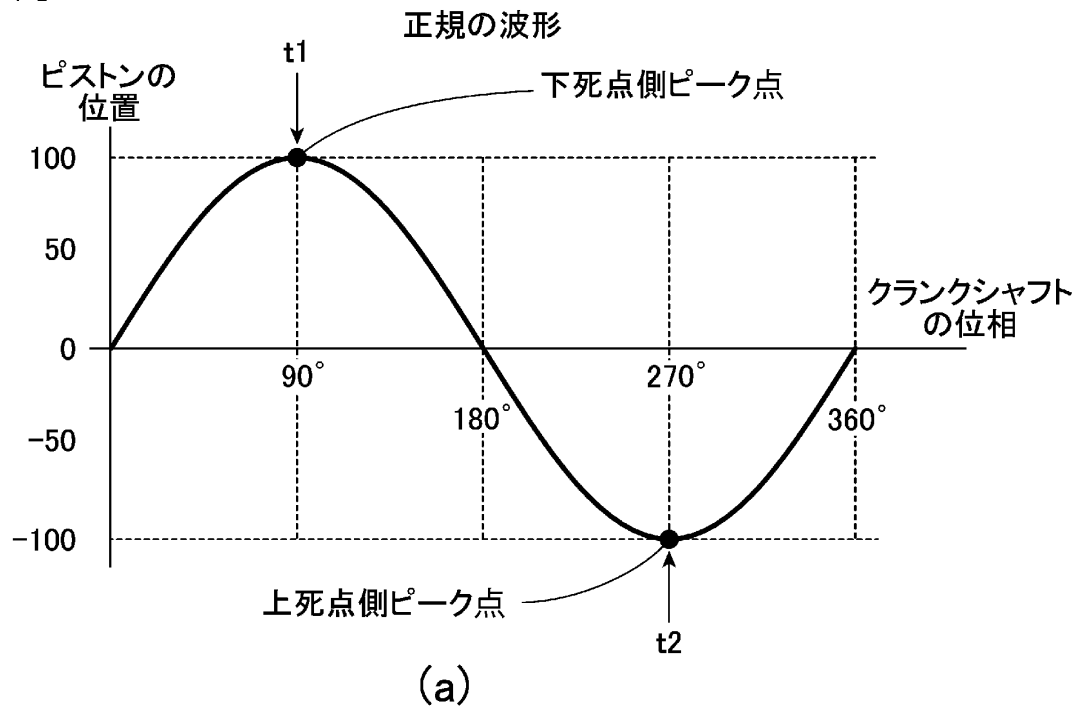


(a)

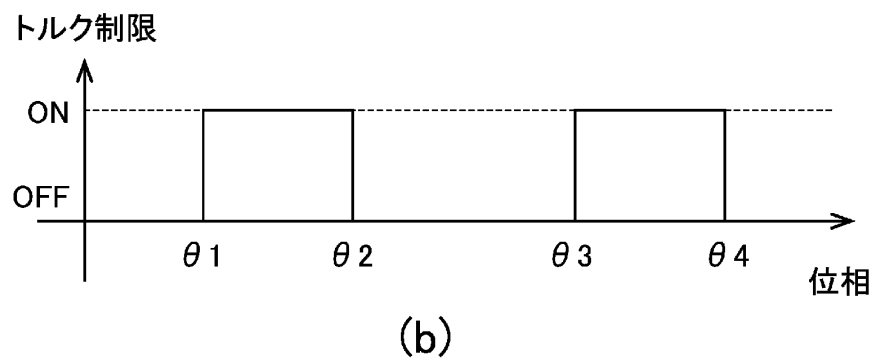
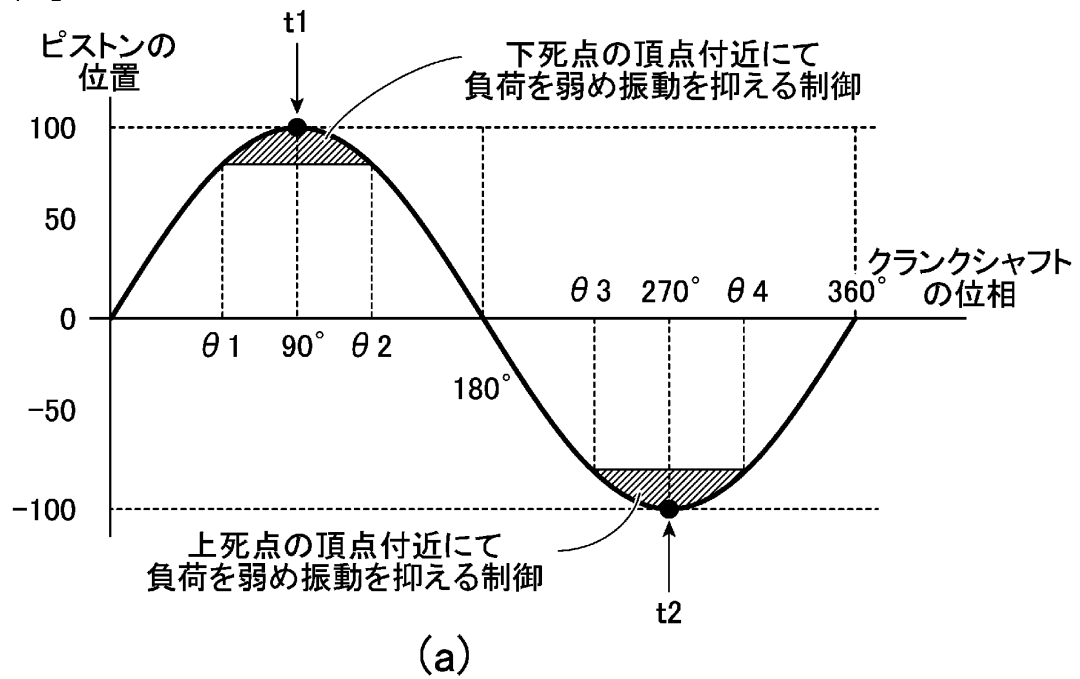


(b)

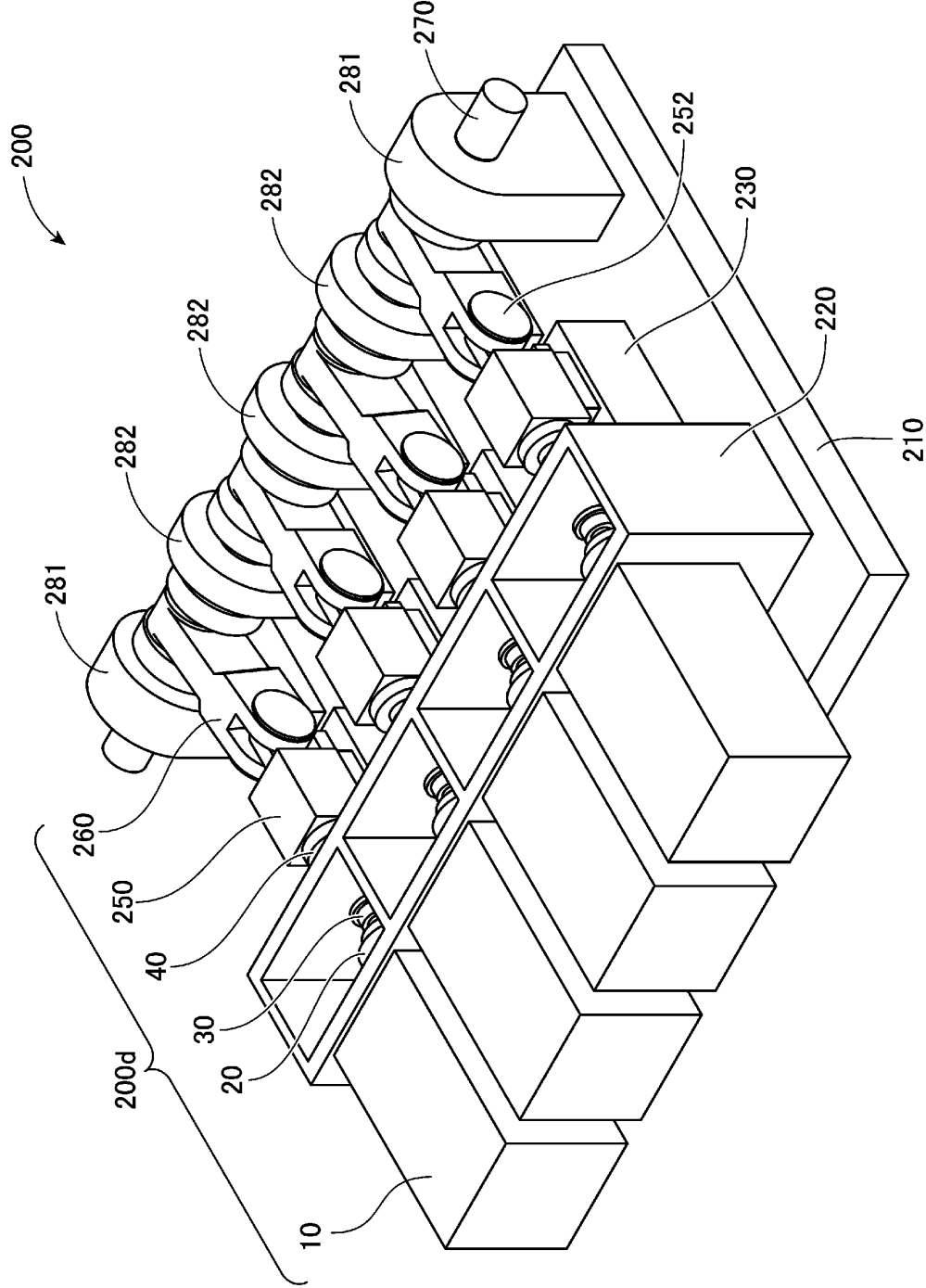
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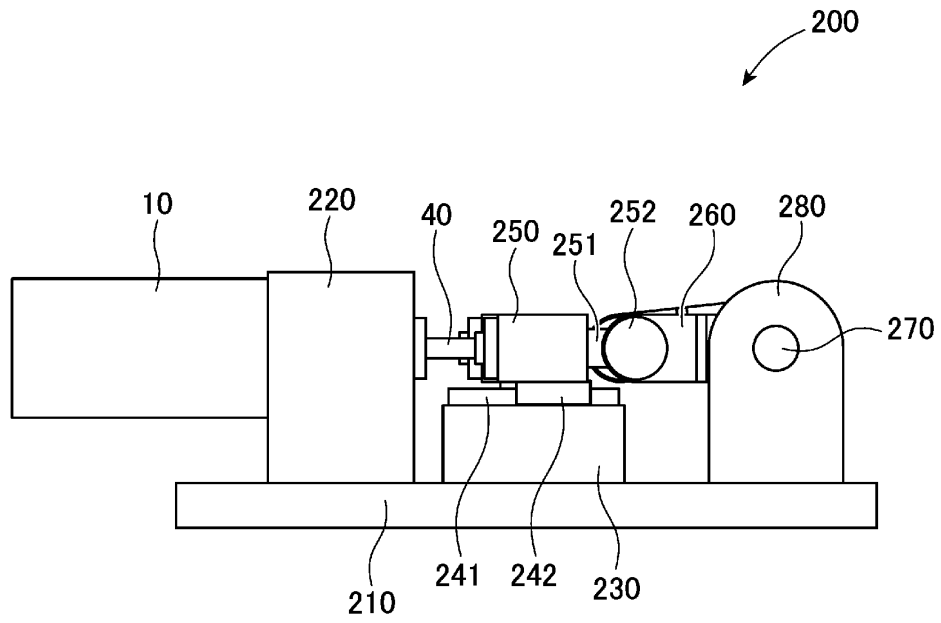
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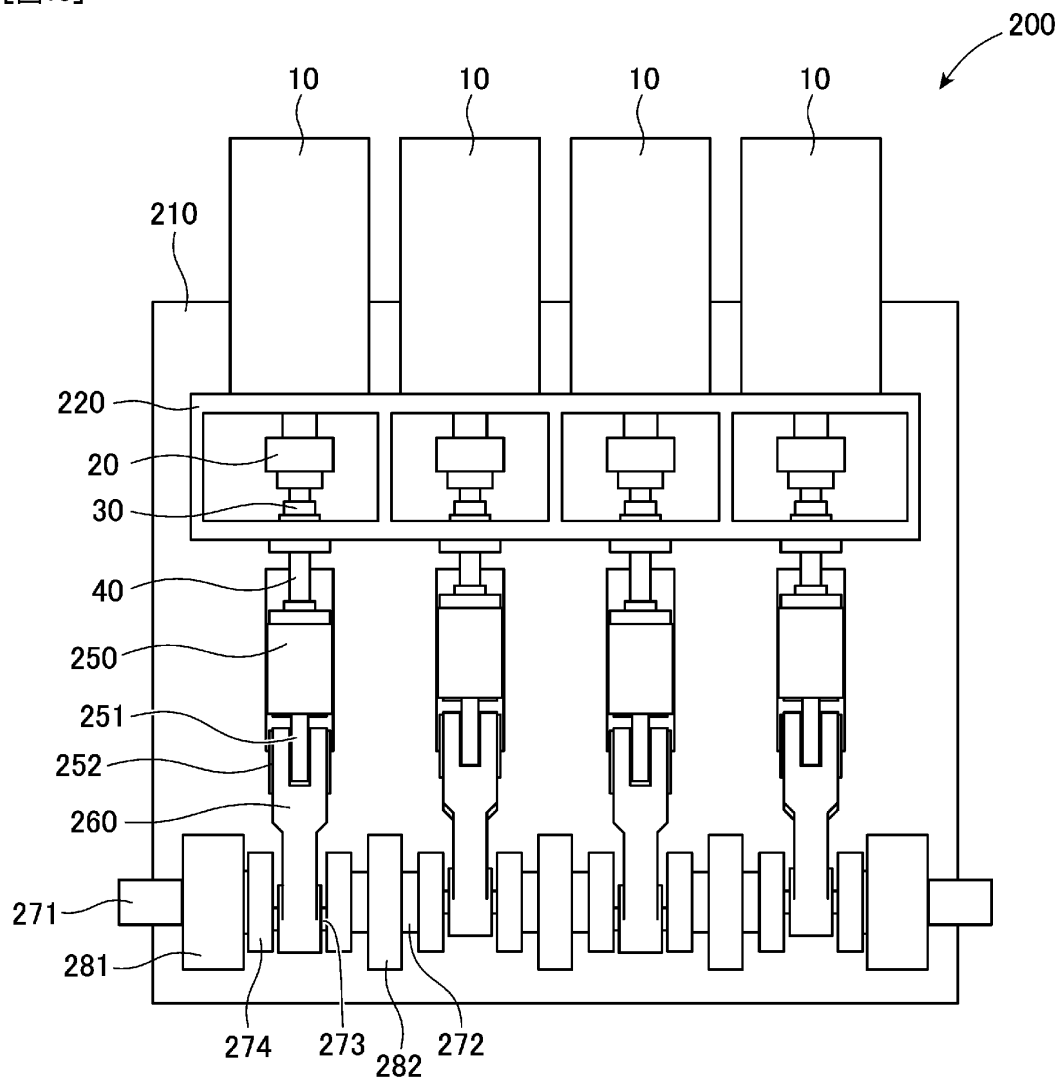
[図11]



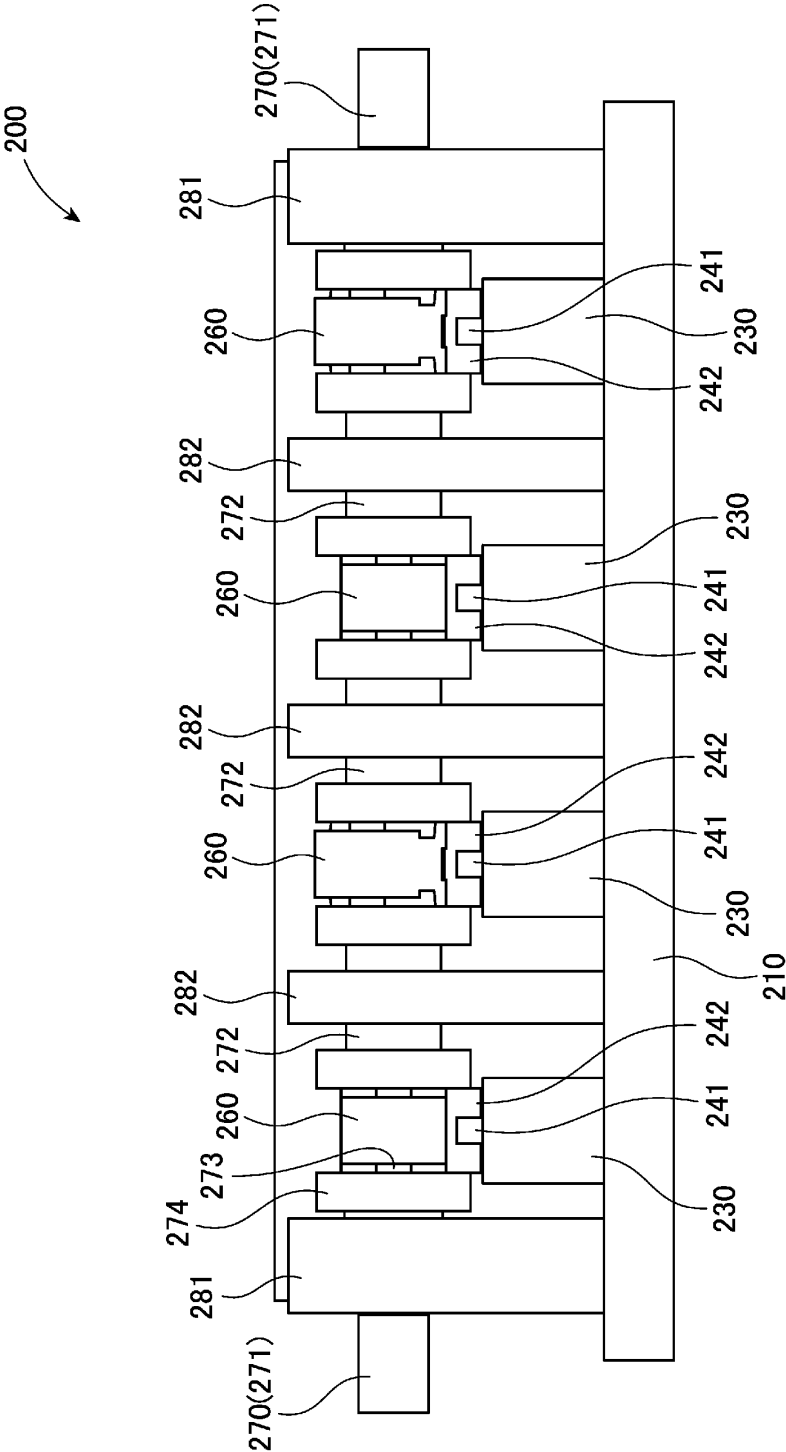
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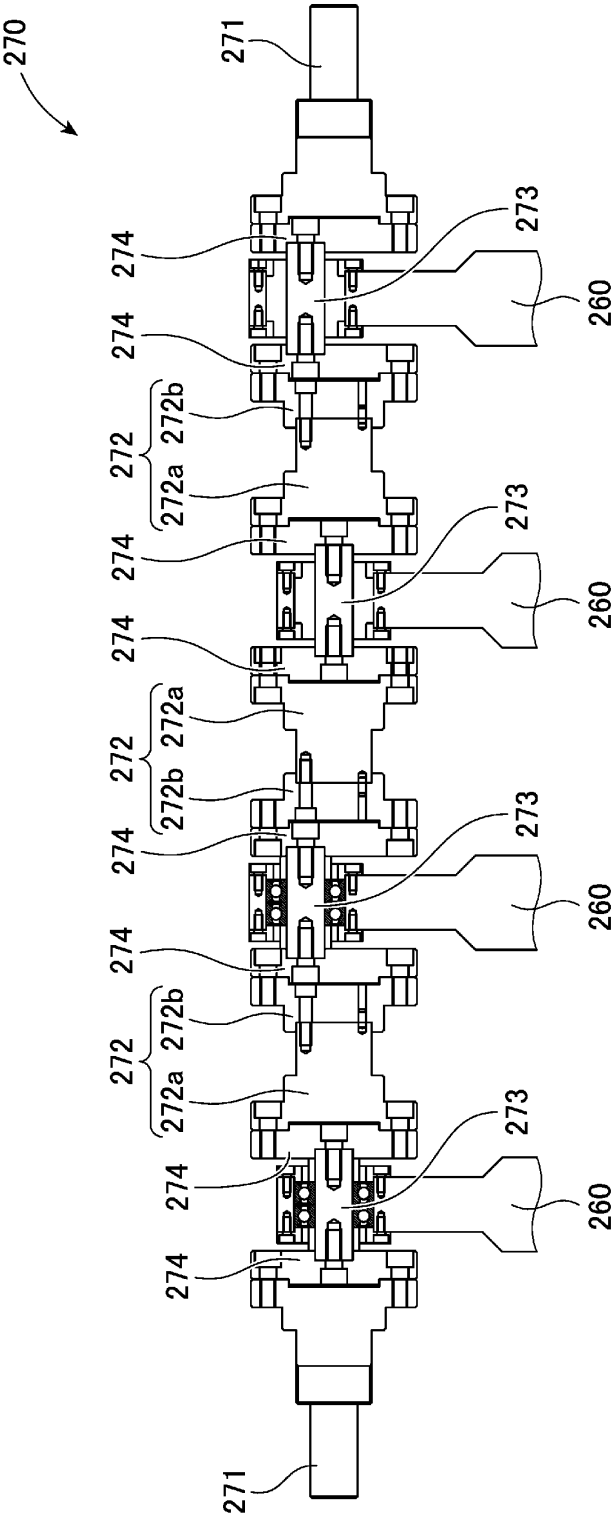
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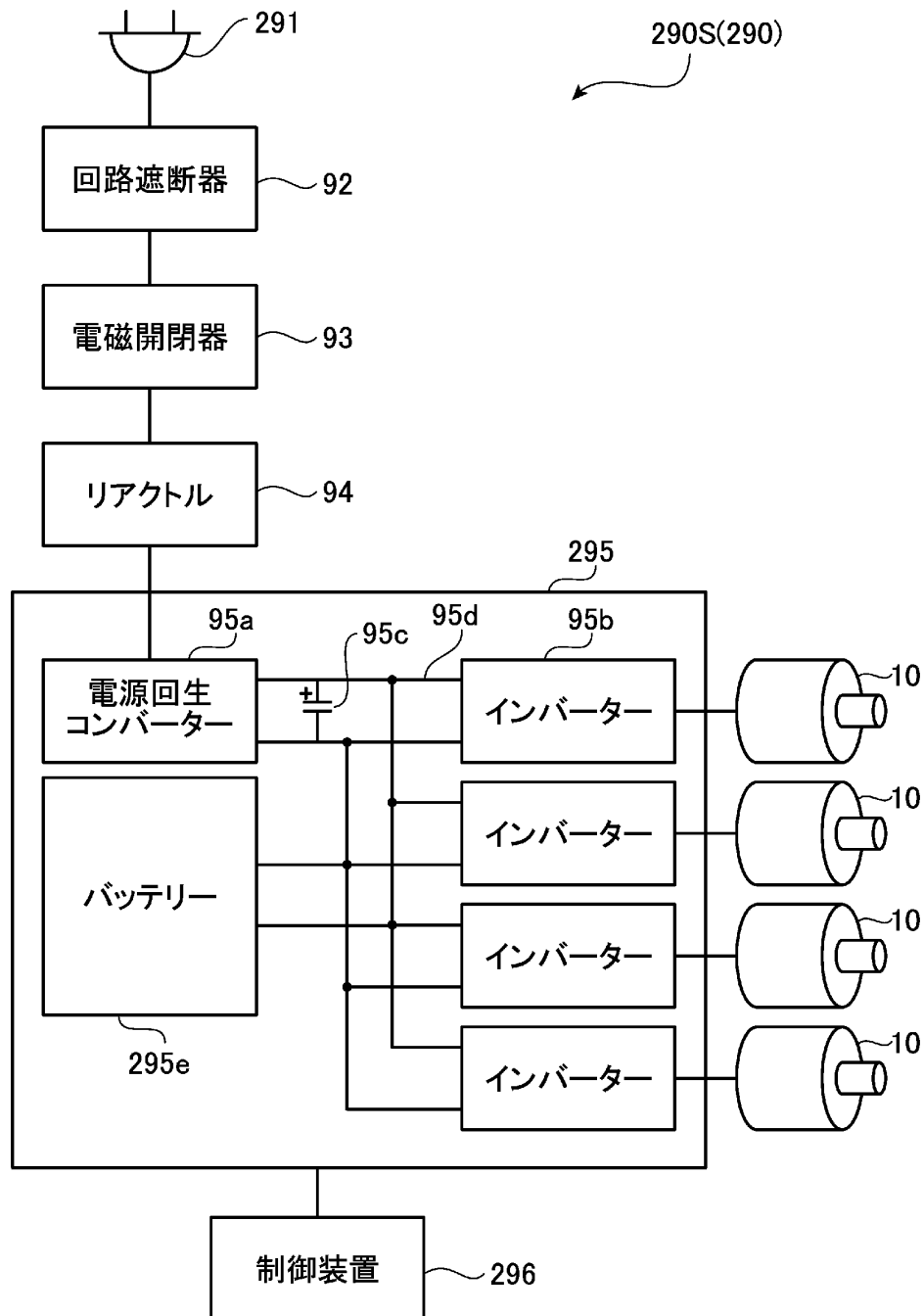
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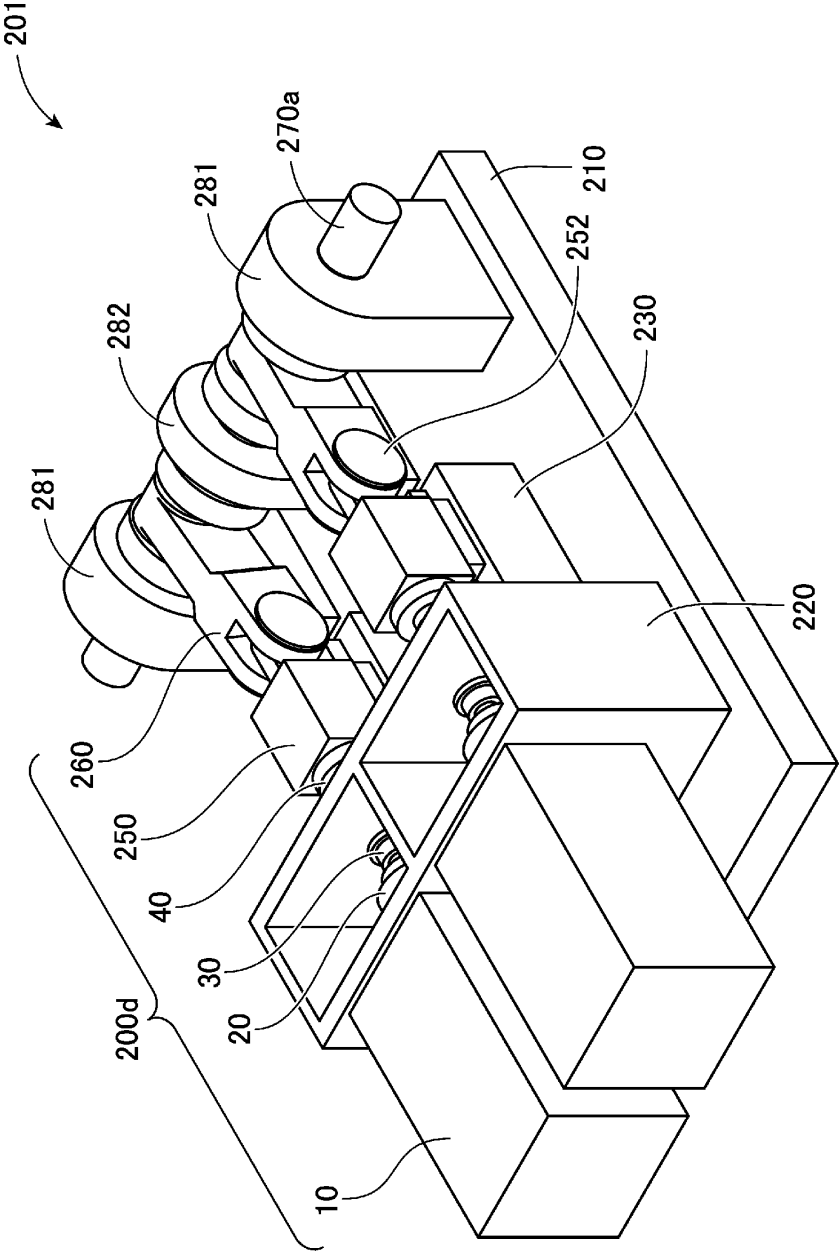
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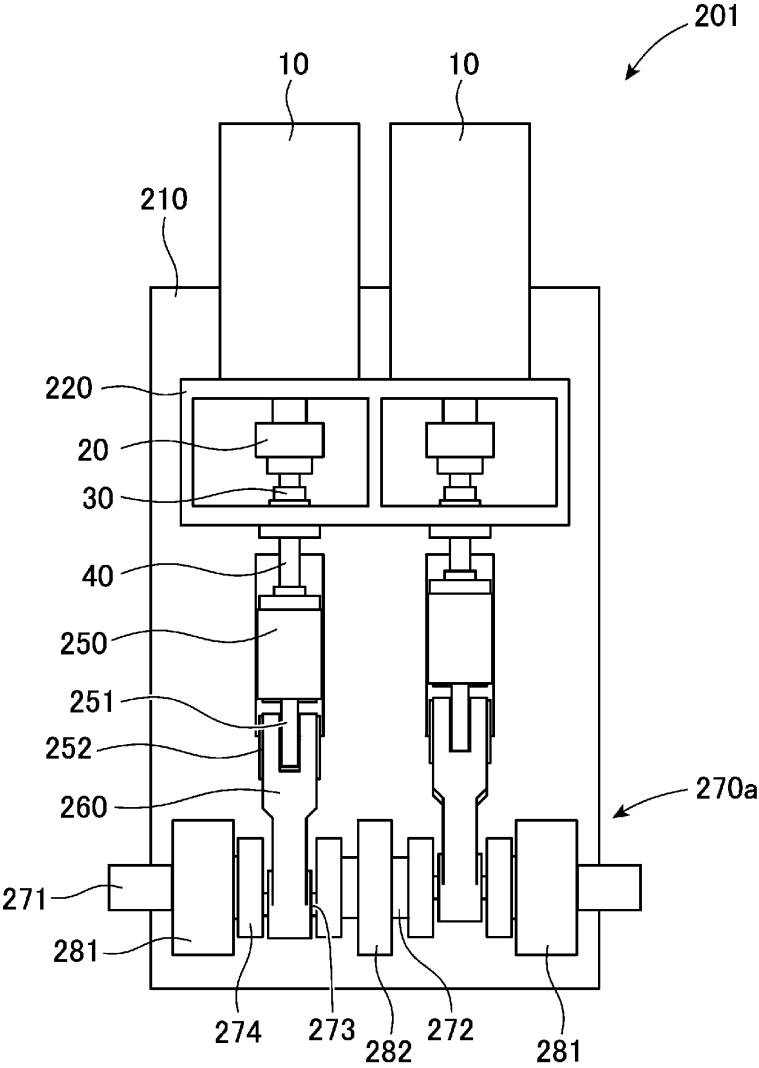
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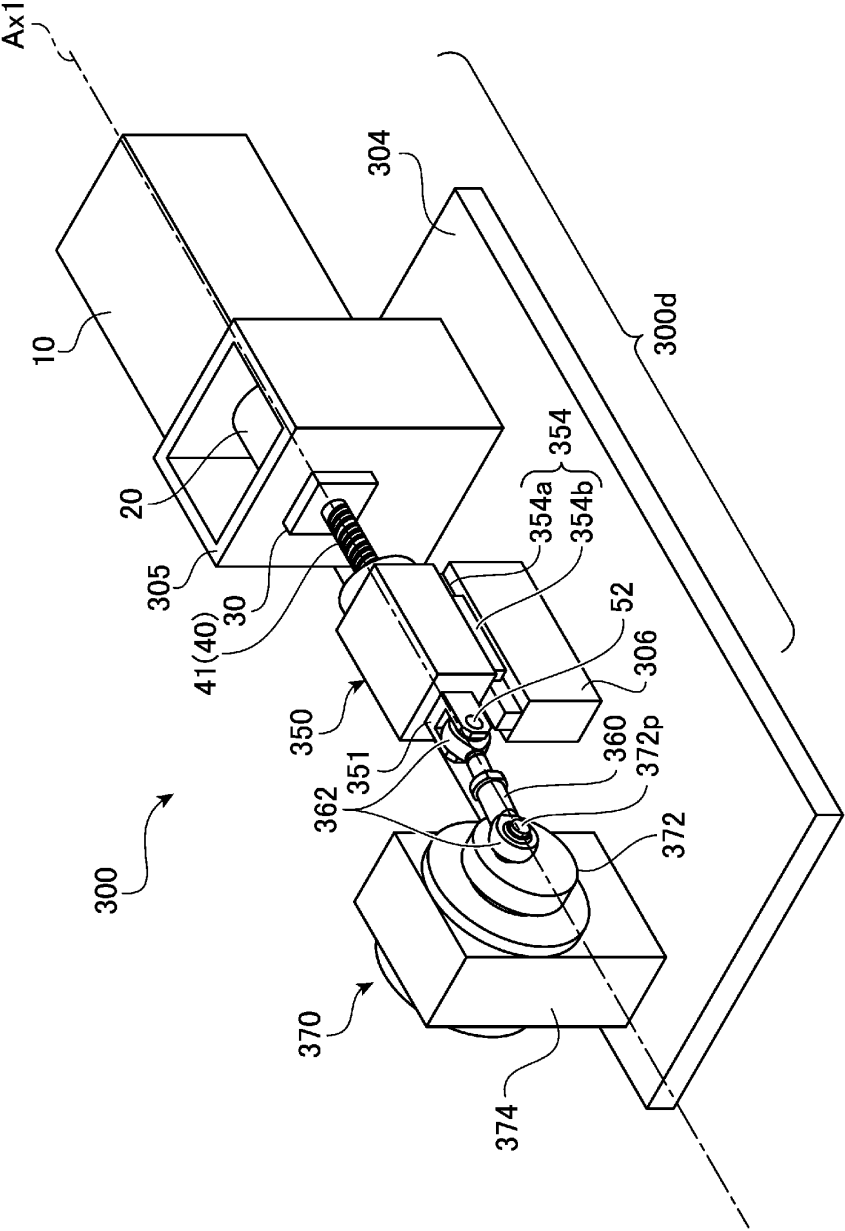
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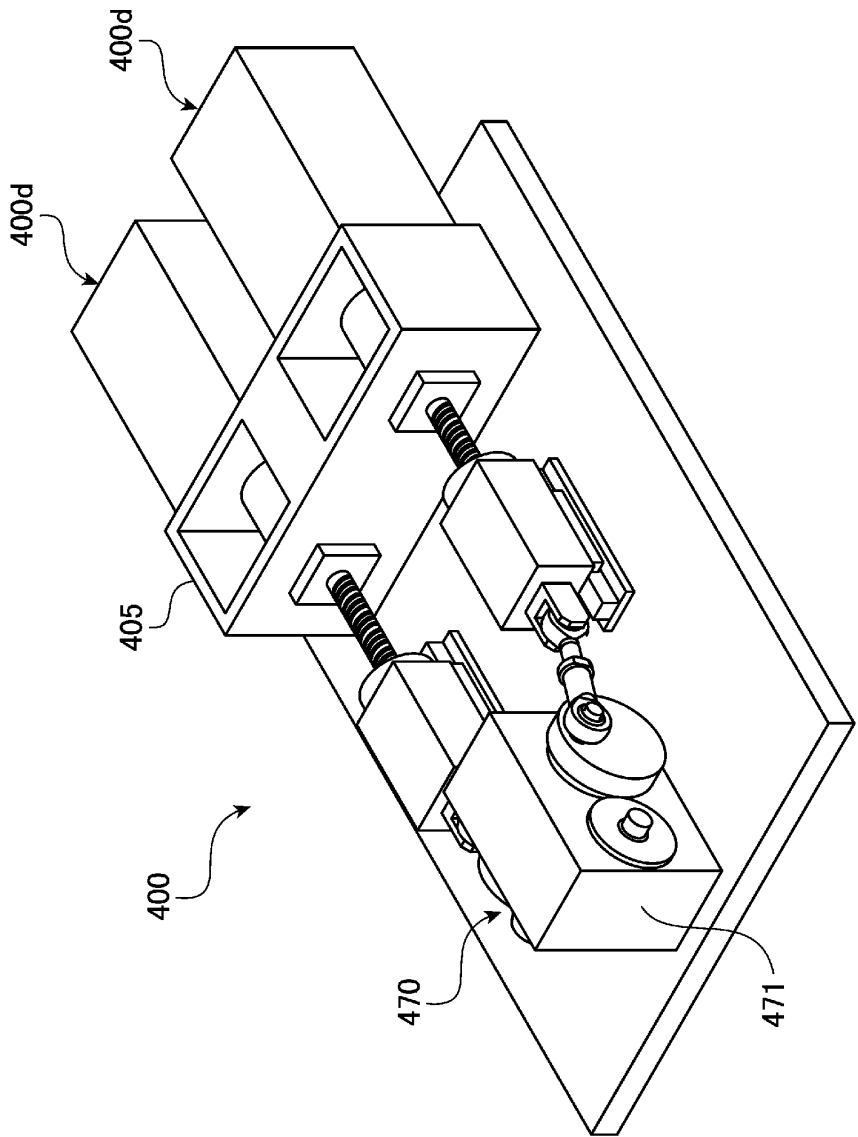
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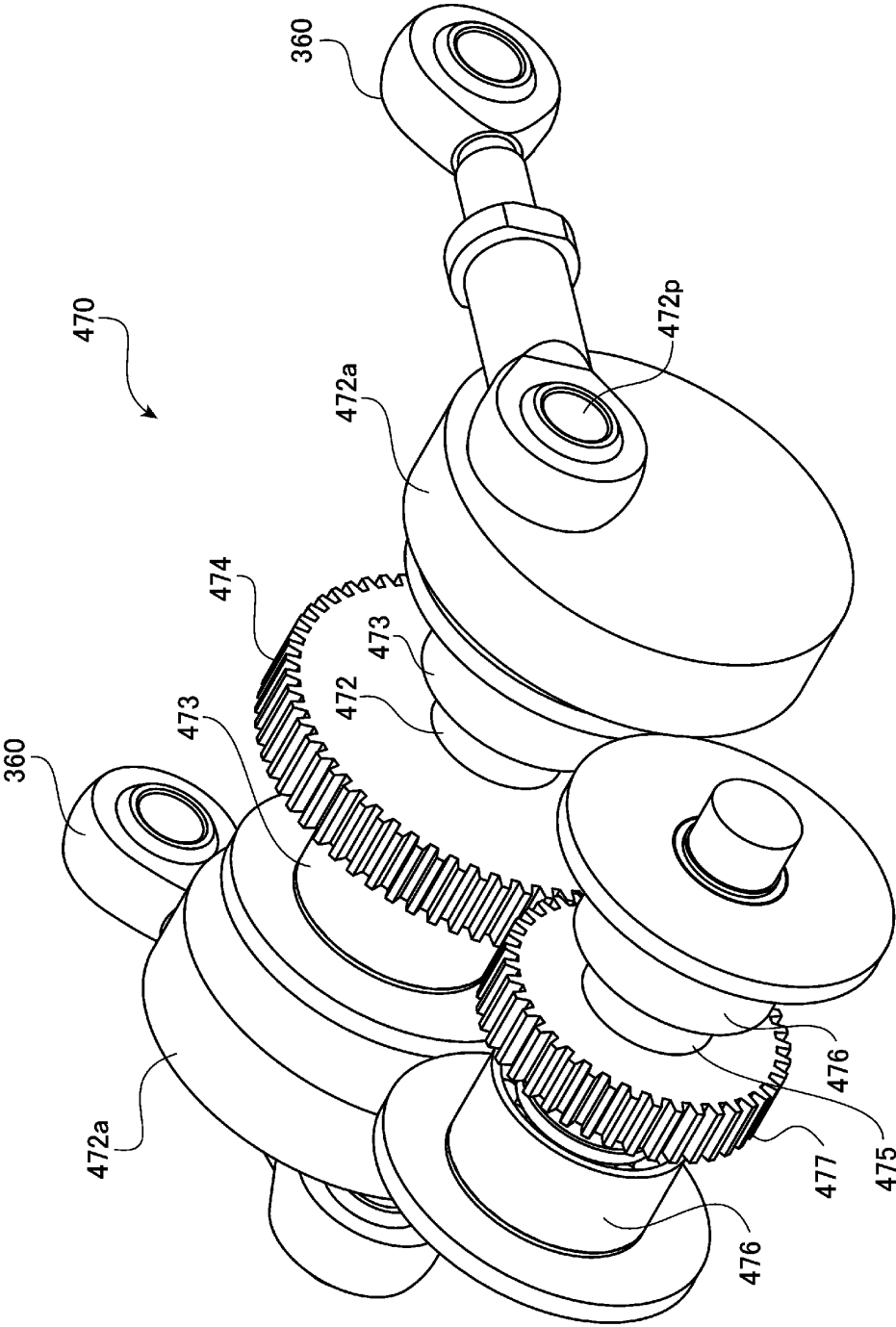
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[図20]

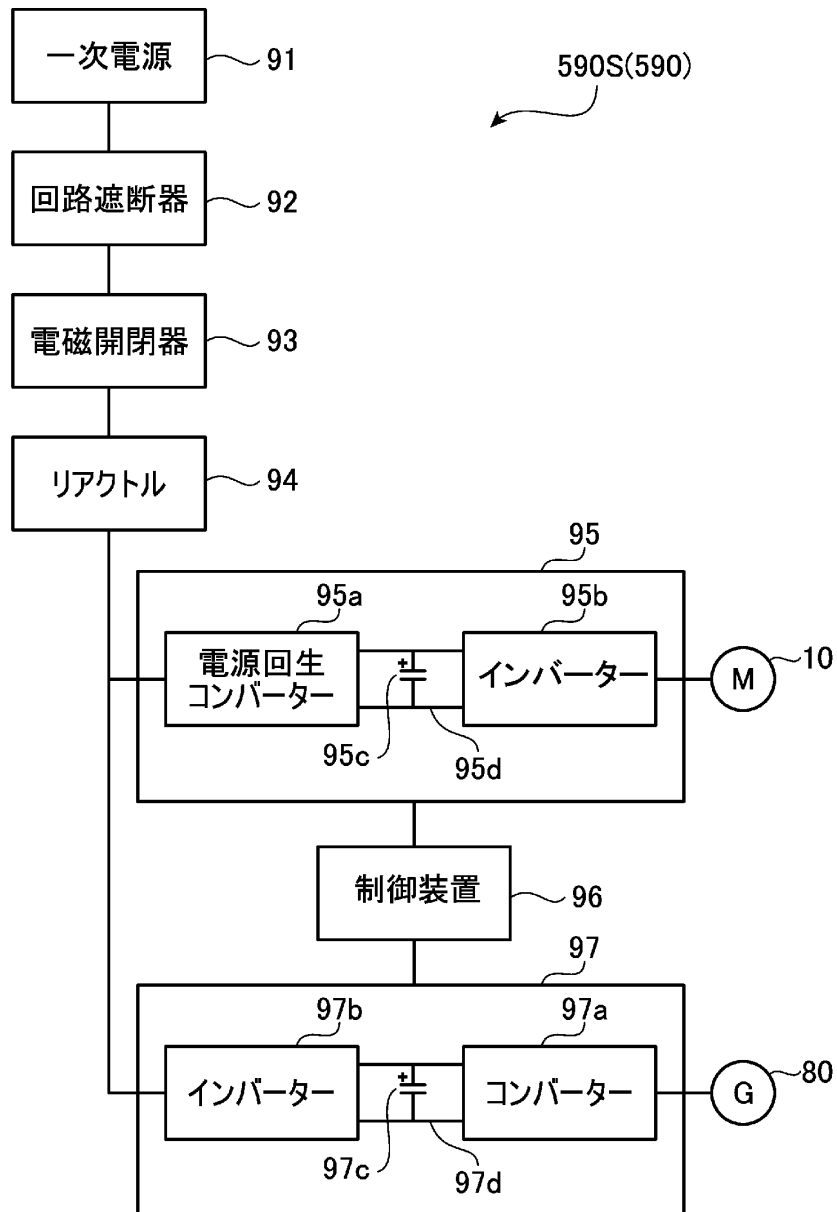


[図21]

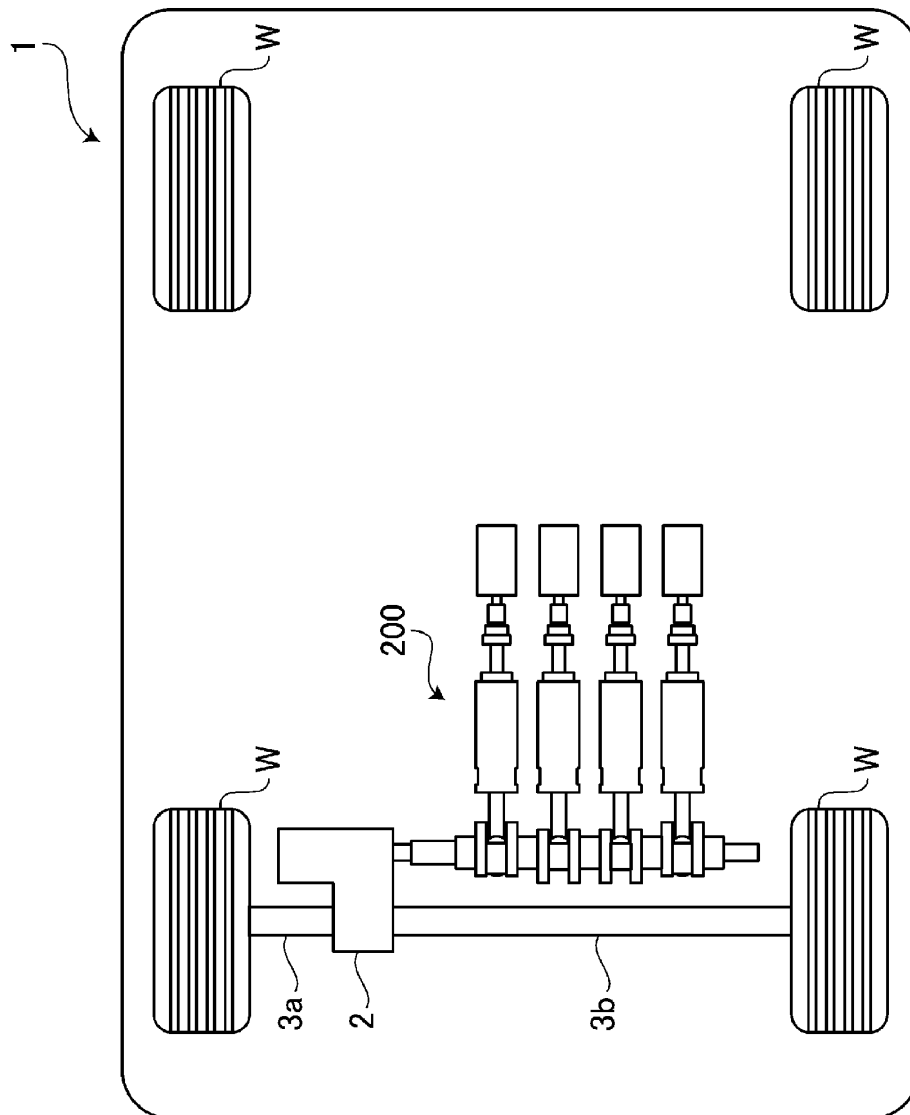




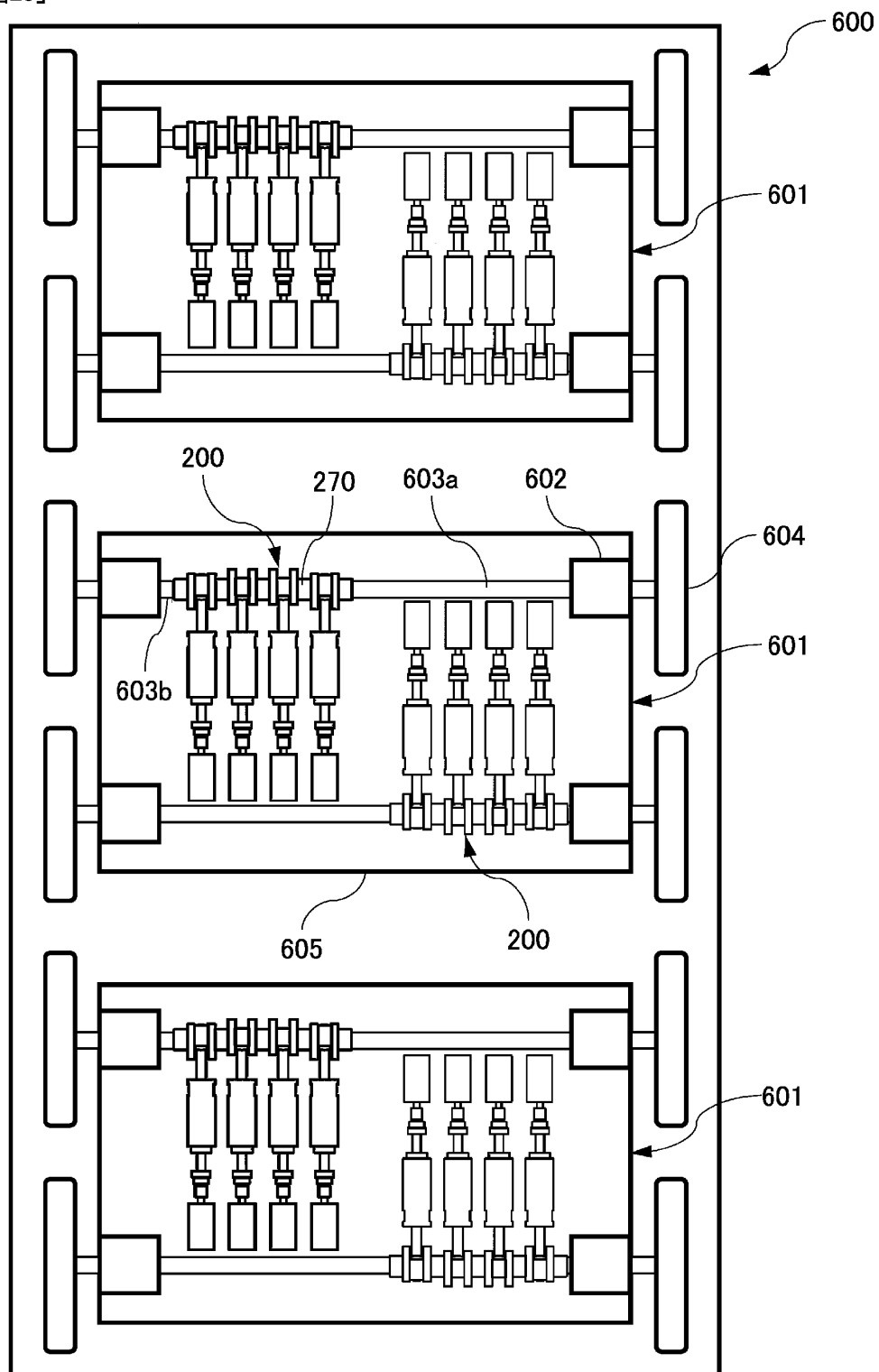
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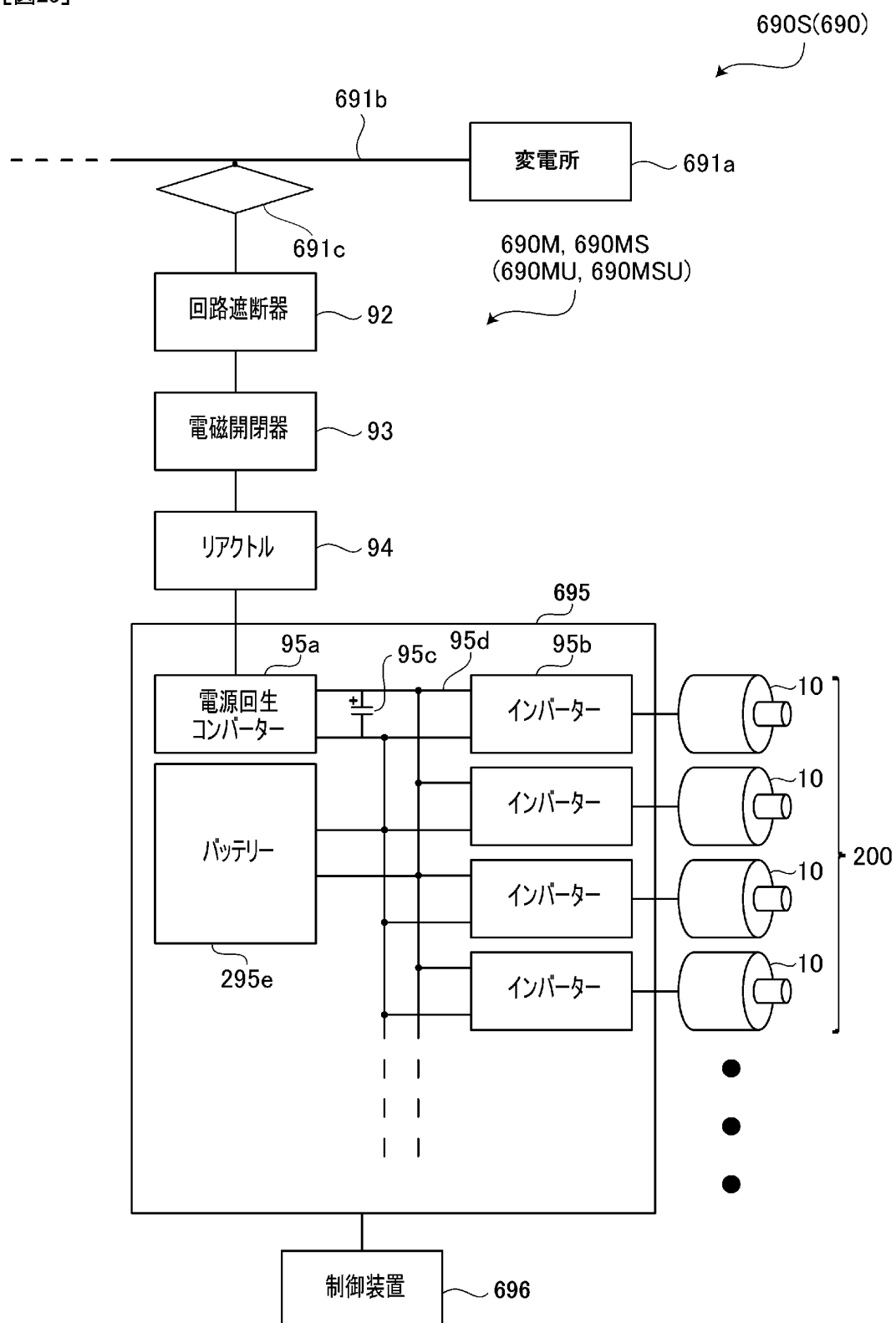
[図24]



[図25]

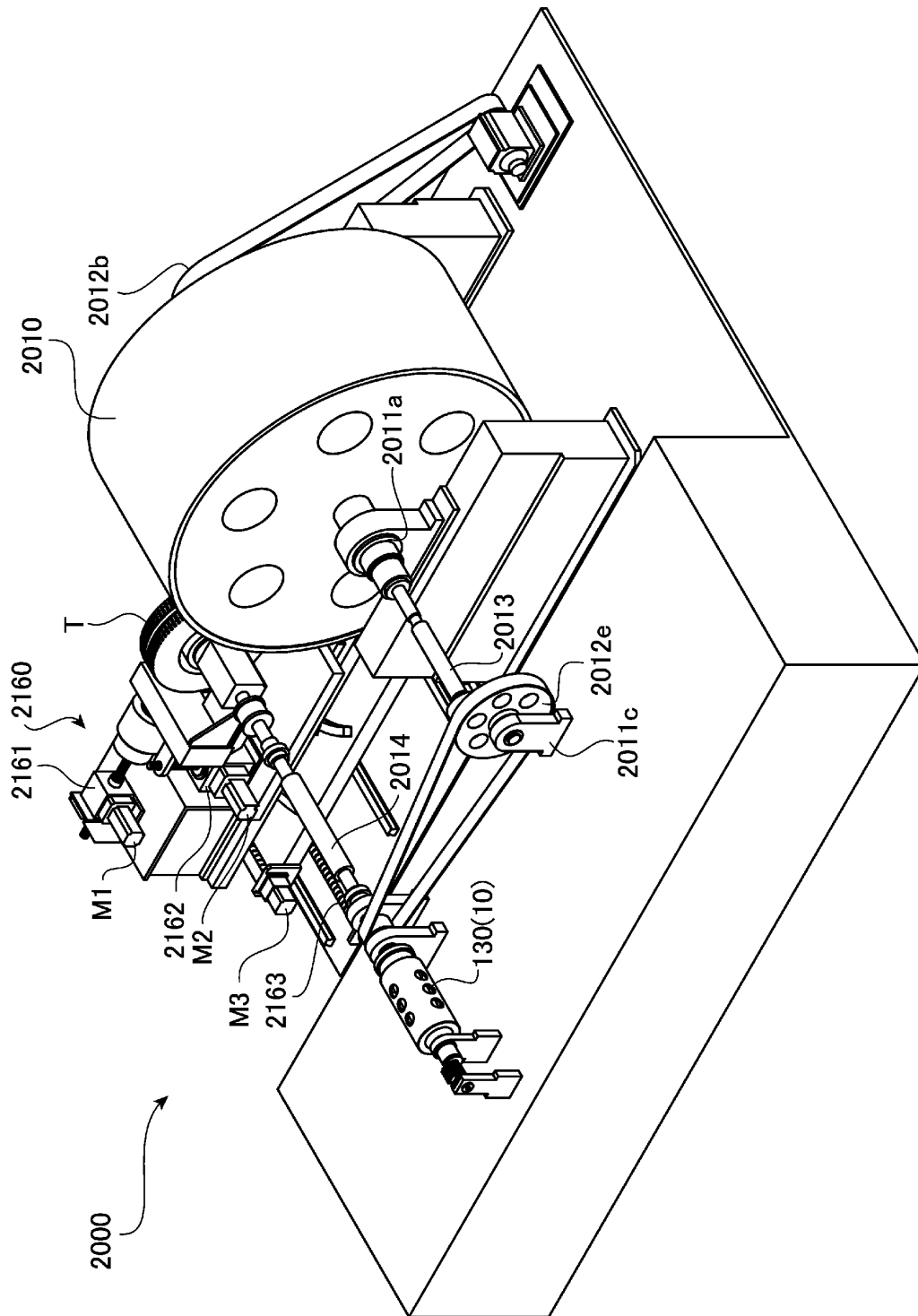


[図26]





[図28]





[図30]

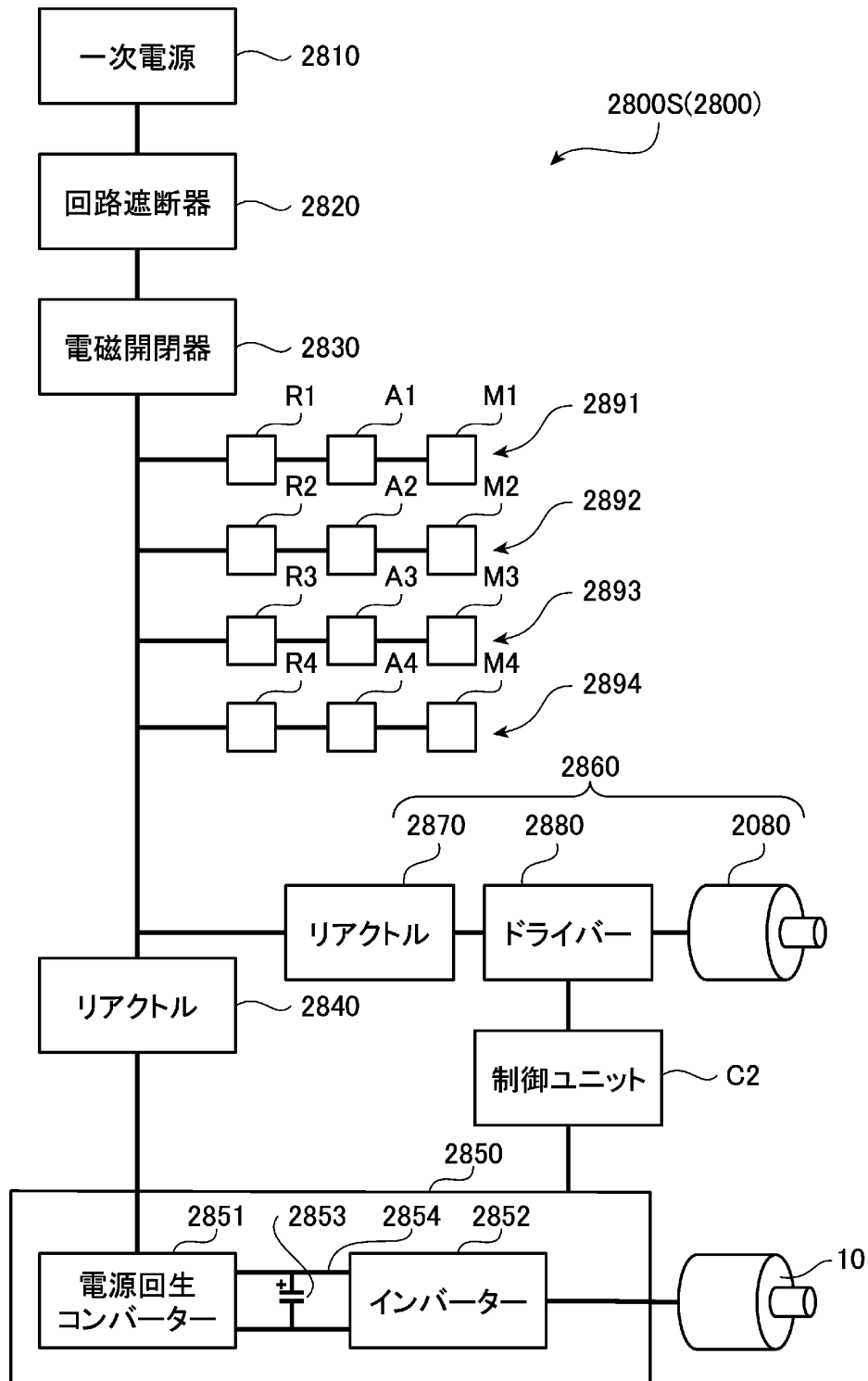
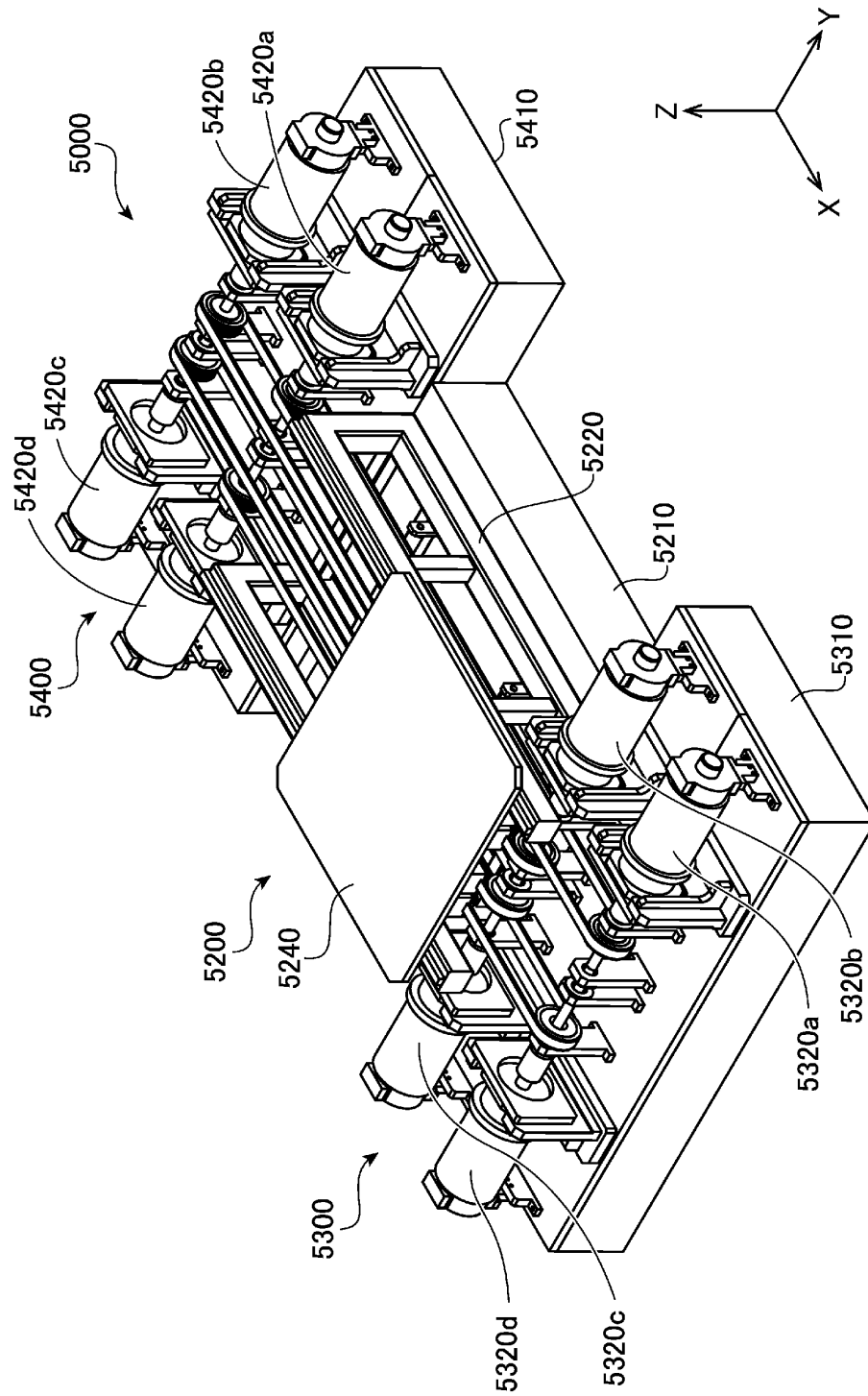




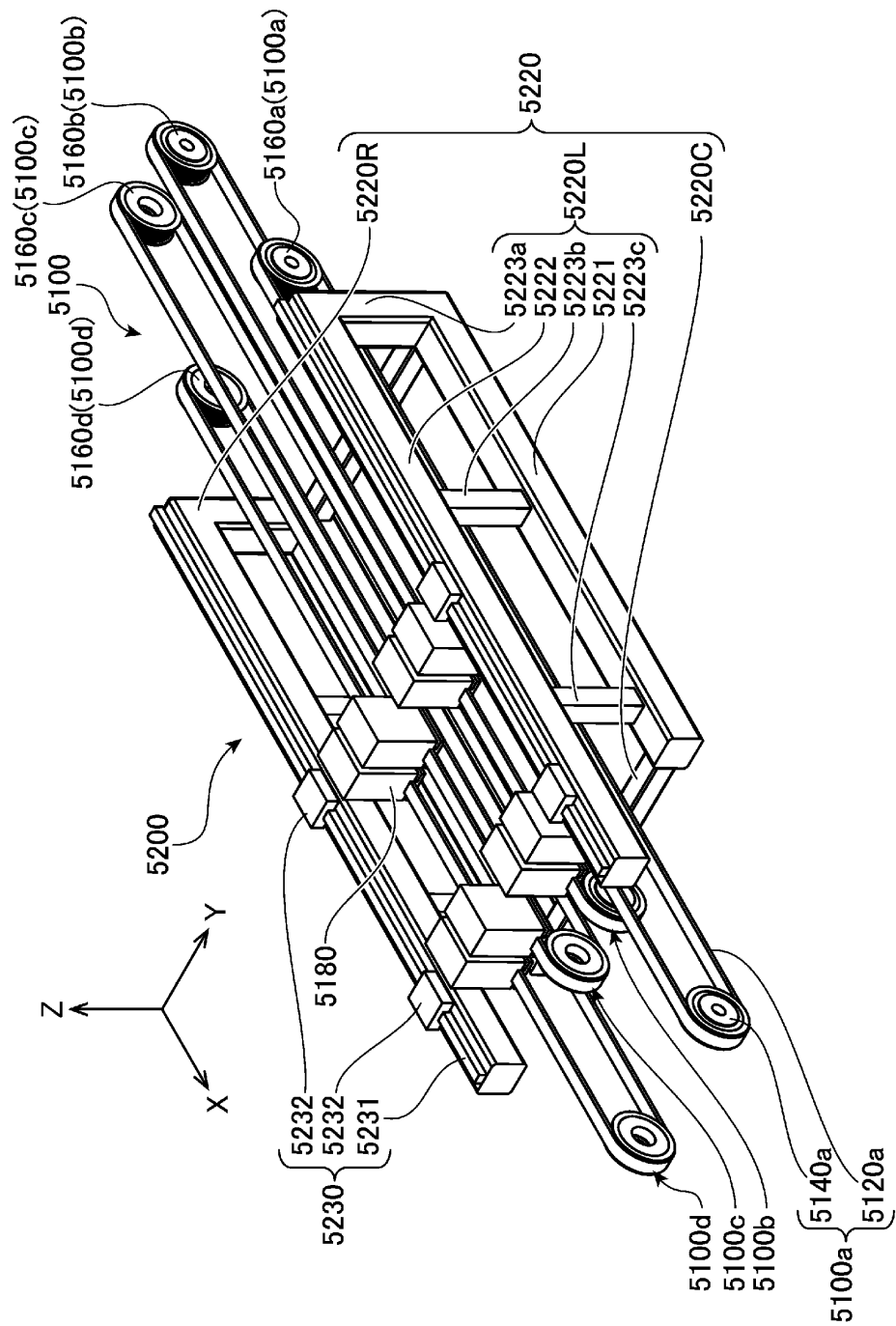


FIG. 4 is a schematic diagram of a vibration reduction device 4000. The device is mounted on a base 4013. It features a central vertical assembly with a VDR (Vibration Damper) 4015 and a VR (Vibration Resistor) 4016. The assembly includes a central shaft 4100 with a pulley 4110b. Two side pulleys 4011b and 4011d are connected by a belt 4010b. The belt is supported by a frame 4017b. The entire assembly is supported by springs 4014 and a base 4013. A coordinate system (X, Y) is shown on the right, and a vertical arrow indicates the direction of vibration.

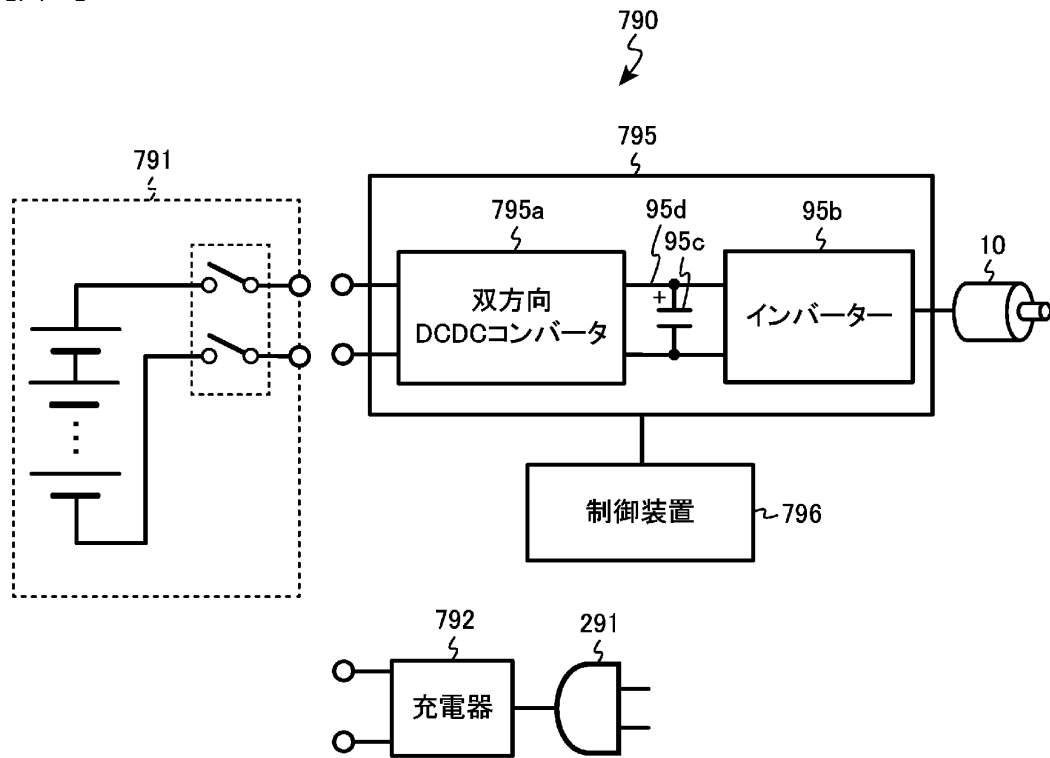
[図35]



[図36]



[図37]



[図38]

