

## BALL PISTON STEERING DEVICES AND METHODS OF USE

### TECHNICAL FIELD

The invention provides ball piston steering devices and methods for use of ball  
5 piston steering devices.

### BACKGROUND

Controlled steering or directional drilling techniques are commonly used in the oil,  
water, and gas industry to reach resources that are not located directly below a  
10 wellhead. The advantages of directional drilling are well known and include the ability to  
reach reservoirs where vertical access is difficult or not possible (e.g. where an oilfield is  
located under a city, a body of water, or a difficult to drill formation) and the ability to  
group multiple wellheads on a single platform (e.g. for offshore drilling).

With the need for oil, water, and natural gas increasing, improved and more  
15 efficient apparatus and methodology for extracting natural resources from the earth are  
necessary.

### SUMMARY OF THE INVENTION

The invention provides ball piston steering devices and methods for use of ball  
20 piston steering devices.

One aspect of the invention provides a ball piston steering device including: a  
sleeve in fluid communication with a fluid source and a ball received within the sleeve.  
The ball is movable within the sleeve from a recessed position and an extended  
position.

25 This aspect can have several embodiments. The ball can deflect the steering  
device from a wellbore when in the extended position. The ball piston steering device  
can also include a bias pad in proximity to the sleeve. The movement of the ball to an  
extended position can cause the bias pad to rise and deflect the steering device from a  
wellbore. The bias pad can pivot about a pin. The sleeve can include one or more  
30 grooves to exhaust fluid from the fluid source. The fluid source can be a pump. The  
ball can be a metal ball.

Another aspect of the invention provides a steerable rotary tool including: a rotary cylinder and one or more ball piston steering devices, located on the exterior of the cylinder. Each of the ball piston steering devices includes: a sleeve in fluid communication with a fluid source and a ball received within the sleeve. The ball is  
5 movable within the sleeve from a recessed position and an extended position.

This aspect can have several embodiments. The one or more ball piston steering devices can also include a bias pad in proximity to the sleeve. The movement of the ball to an extended position can cause the bias pad to rise. The bias pad can pivot about a pin. The sleeve can include one or more grooves to exhaust fluid from the  
10 fluid source. The fluid source can be a pump. The fluid source can be mud from a drill string. The ball can be a metal ball.

Another aspect of the invention provides a method of drilling a curved hole within a wellbore. The method includes providing a steerable rotary tool including a rotary cylinder, a cutting surface, and one or more ball piston steering devices located on the  
15 exterior of the cylinder; rotating the steerable rotary tool within the wellbore; and selectively actuating at least one of the one or more ball pistons to deflect the steerable rotary tool from the wellbore, thereby drilling a curved hole within the wellbore. The ball piston steering devices can include a sleeve in fluid communication with a fluid source and a ball received within the sleeve. The ball is movable within the sleeve from a  
20 recessed position and an extended position.

This aspect can have several embodiments. The steerable rotary tool can include a bias pad in proximity to the sleeve. The movement of the ball to an extended position can cause the bias pad to rise. The bias pad can pivot about a pin. The sleeve can include one or more grooves to exhaust fluid from the fluid source. The fluid source  
25 can be a pump. The fluid source can be mud from a drill string. The ball can be a metal ball.

## DESCRIPTION OF THE DRAWINGS

For a fuller understanding of the nature and desired objects of the present  
30 invention, reference is made to the following detailed description taken in conjunction

with the accompanying drawing figures wherein like reference characters denote corresponding parts throughout the several views and wherein:

FIG. 1 illustrates a wellsite system in which the present invention can be employed.

5        FIG. 2A illustrates a cross-section of a ball piston steering device in a neutral position in accordance with one embodiment of the invention.

FIG. 2B illustrates a cross-section of a ball piston steering device in an extended position in accordance with one embodiment of the invention.

10       FIG. 2C illustrates a cross-section of a ball piston steering device including a groove to allow fluid to escape from the sleeve in accordance with one embodiment of the invention.

FIG. 2D illustrates a cross-section of a ball piston steering device with a bias pad in a neutral position in accordance with one embodiment of the invention.

15       FIG. 2E illustrates a cross-section of a ball piston steering device with a bias pad in an extended position in accordance with one embodiment of the invention.

FIG. 3 illustrates a bottom hole assembly component incorporating a ball piston steering device in accordance with one embodiment of the invention.

FIG. 4 illustrates the actuation of a steering device in accordance with one embodiment of the invention.

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## DETAILED DESCRIPTION OF THE INVENTION

The invention provides ball piston steering devices and methods for use of ball piston devices. Some embodiments of the invention can be used in a wellsite system.

### Wellsite System

25       FIG. 1 illustrates a wellsite system in which the present invention can be employed. The wellsite can be onshore or offshore. In this exemplary system, a borehole 11 is formed in subsurface formations by rotary drilling in a manner that is well known. Embodiments of the invention can also use directional drilling, as will be described hereinafter.

30       A drill string 12 is suspended within the borehole 11 and has a bottom hole assembly 100 which includes a drill bit 105 at its lower end. The surface system

includes platform and derrick assembly 10 positioned over the borehole 11, the assembly 10 including a rotary table 16, kelly 17, hook 18 and rotary swivel 19. The drill string 12 is rotated by the rotary table 16, energized by means not shown, which engages the kelly 17 at the upper end of the drill string. The drill string 12 is suspended from a hook 18, attached to a traveling block (also not shown), through the kelly 17 and a rotary swivel 19 which permits rotation of the drill string relative to the hook. As is well known, a top drive system could alternatively be used.

In the example of this embodiment, the surface system further includes drilling fluid or mud 26 stored in a pit 27 formed at the well site. A pump 29 delivers the drilling fluid 26 to the interior of the drill string 12 via a port in the swivel 19, causing the drilling fluid to flow downwardly through the drill string 12 as indicated by the directional arrow 8. The drilling fluid exits the drill string 12 via ports in the drill bit 105, and then circulates upwardly through the annulus region between the outside of the drill string and the wall of the borehole, as indicated by the directional arrows 9. In this well known manner, the drilling fluid lubricates the drill bit 105 and carries formation cuttings up to the surface as it is returned to the pit 27 for recirculation.

The bottom hole assembly 100 of the illustrated embodiment includes a logging-while-drilling (LWD) module 120, a measuring-while-drilling (MWD) module 130, a roto-steerable system and motor, and drill bit 105.

The LWD module 120 is housed in a special type of drill collar, as is known in the art, and can contain one or a plurality of known types of logging tools. It will also be understood that more than one LWD and/or MWD module can be employed, *e.g.* as represented at 120A. (References, throughout, to a module at the position of 120 can alternatively mean a module at the position of 120A as well.) The LWD module includes capabilities for measuring, processing, and storing information, as well as for communicating with the surface equipment. In the present embodiment, the LWD module includes a pressure measuring device.

The MWD module 130 is also housed in a special type of drill collar, as is known in the art, and can contain one or more devices for measuring characteristics of the drill string and drill bit. The MWD tool further includes an apparatus (not shown) for generating electrical power to the downhole system. This may typically include a mud

turbine generator (also known as a "mud motor") powered by the flow of the drilling fluid, it being understood that other power and/or battery systems may be employed. In the present embodiment, the MWD module includes one or more of the following types of measuring devices: a weight-on-bit measuring device, a torque measuring device, a vibration measuring device, a shock measuring device, a stick slip measuring device, a direction measuring device, and an inclination measuring device.

A particularly advantageous use of the system hereof is in conjunction with controlled steering or "directional drilling." In this embodiment, a roto-steerable subsystem 150 (FIG. 1) is provided. Directional drilling is the intentional deviation of the wellbore from the path it would naturally take. In other words, directional drilling is the steering of the drill string so that it travels in a desired direction.

Directional drilling is, for example, advantageous in offshore drilling because it enables many wells to be drilled from a single platform. Directional drilling also enables horizontal drilling through a reservoir. Horizontal drilling enables a longer length of the wellbore to traverse the reservoir, which increases the production rate from the well.

A directional drilling system may also be used in vertical drilling operation as well. Often the drill bit will veer off of an planned drilling trajectory because of the unpredictable nature of the formations being penetrated or the varying forces that the drill bit experiences. When such a deviation occurs, a directional drilling system may be used to put the drill bit back on course.

A known method of directional drilling includes the use of a rotary steerable system ("RSS"). In an RSS, the drill string is rotated from the surface, and downhole devices cause the drill bit to drill in the desired direction. Rotating the drill string greatly reduces the occurrences of the drill string getting hung up or stuck during drilling.

Rotary steerable drilling systems for drilling deviated boreholes into the earth may be generally classified as either "point-the-bit" systems or "push-the-bit" systems.

In the point-the-bit system, the axis of rotation of the drill bit is deviated from the local axis of the bottom hole assembly in the general direction of the new hole. The hole is propagated in accordance with the customary three point geometry defined by upper and lower stabilizer touch points and the drill bit. The angle of deviation of the drill bit axis coupled with a finite distance between the drill bit and lower stabilizer results

in the non-collinear condition required for a curve to be generated. There are many ways in which this may be achieved including a fixed bend at a point in the bottom hole assembly close to the lower stabilizer or a flexure of the drill bit drive shaft distributed between the upper and lower stabilizer. In its idealized form, the drill bit is not required to cut sideways because the bit axis is continually rotated in the direction of the curved hole. Examples of point-the-bit type rotary steerable systems, and how they operate are described in U.S. Patent Application Publication Nos. 2002/0011359; 2001/0052428 and U.S. Patent Nos. 6,394,193; 6,364,034; 6,244,361; 6,158,529; 6,092,610; and 5,113,953.

In the push-the-bit rotary steerable system there is usually no specially identified mechanism to deviate the bit axis from the local bottom hole assembly axis; instead, the requisite non-collinear condition is achieved by causing either or both of the upper or lower stabilizers to apply an eccentric force or displacement in a direction that is preferentially orientated with respect to the direction of hole propagation. Again, there are many ways in which this may be achieved, including non-rotating (with respect to the hole) eccentric stabilizers (displacement based approaches) and eccentric actuators that apply force to the drill bit in the desired steering direction. Again, steering is achieved by creating non co-linearity between the drill bit and at least two other touch points. In its idealized form the drill bit is required to cut side ways in order to generate a curved hole. Examples of push-the-bit type rotary steerable systems, and how they operate are described in U.S. Patent Nos. 5,265,682; 5,553,678; 5,803,185; 6,089,332; 5,695,015; 5,685,379; 5,706,905; 5,553,679; 5,673,763; 5,520,255; 5,603,385; 5,582,259; 5,778,992; and 5,971,085.

#### Ball Piston Steering Device

FIG. 2A depicts a cross-section of a ball piston steering device 200a in accordance with one embodiment of the invention. A ball 202 is provided within a sleeve 204. The sleeve includes an orifice 206 for communication with a fluid source. Fluid 208 enters orifice 206 to push ball 202 to an extended position as depicted in FIG. 2B. Lip 210 retains the ball within the sleeve.

When the ball 202 is in the extended position, the ball contacts a wellbore and generates a reactionary force that generally pushes away from the wellbore, thereby effecting a steering force that can be used to steering a bottom hole assembly.

Referring to FIG. 2C, a ball piston steering device 200b is provided in which the sleeve 204 includes a groove 212 to allow the fluid to escape from the sleeve 204. The groove 212 can advantageously provide lubrication for the ball and a bottom hole assembly that the steering device is incorporated in. Additionally, the groove 212 can assist in providing a fluid pathway capable of removing debris in the region of the ball 202 and sleeve 204 interface.

Referring to FIG. 2D, a ball piston steering device 200c can include a bias pad 214 coupled to the sleeve 204 by a pin 216. Referring to FIG. 2E, when the ball 202 extends, the ball 202 presses against the bias pad 214 to push the bias pad 214 outward. In some embodiments, a spring, such as a torsion spring or an extension spring can act to return the bias pad 214 to an unextended position. One skilled in the art will readily appreciate that the sleeve 204 may be incorporated into a directional drilling tool or rotary directional system 150 of Figure 1.

Ball 202 and/or bias pad 214 can, in some embodiments, be coated or comprised of a wear-resistant material such a metal, a resin, or a polymer. For example, the ball 202 and/or bias pad 214 can be fabricated from steel, "high speed steel", carbon steel, brass, copper, iron, polycrystalline diamond compact (PDC), hardface, ceramics, carbides, ceramic carbides, cermets, and the like. Suitable coatings are described, for example, in U.S. Patent Publication No. 2007/0202350, herein incorporated by reference.

Referring to FIG. 3, one or more steering devices 302a, 302b, 302c can be integrated into a bottom hole assembly component 300 in a drill string. For example, three steering devices can be arranged approximately 120 degrees apart.

Bottom hole assembly component 300 can further include a control unit (not depicted) for selectively actuating steering devices 302a, 302b, 302c. Control unit maintains the proper angular position of the bottom hole assembly component 300 relative to the subsurface formation. In some embodiments, control unit is mounted on a bearing that allow control unit to rotate freely about the axis of the bottom hole

assembly component 300. The control unit, according to some embodiments, contains sensory equipment such as a three-axis accelerometer and/or magnetometer sensors to detect the inclination and azimuth of the bottom hole assembly. The control unit can further communicate with sensors disposed within elements of the bottom hole

5 assembly such that said sensors can provide formation characteristics or drilling dynamics data to control unit. Formation characteristics can include information about adjacent geologic formation gather from ultrasound or nuclear imaging devices such as those discussed in U.S. Patent Publication No. 2007/0154341, the contents of which is hereby incorporated by reference herein. Drilling dynamics data may include  
10 measurements of the vibration, acceleration, velocity, and temperature of the bottom hole assembly.

In some embodiments, control unit is programmed above ground to following an desired inclination and direction. The progress of the bottom hole assembly 300 can be measured using MWD systems and transmitted above-ground via a sequences of  
15 pulses in the drilling fluid, via an acoustic or wireless transmission method, or via a wired connection. If the desired path is changed, new instructions can be transmitted as required. Mud communication systems are described in U.S. Patent Publication No. 2006/0131030, herein incorporated by reference. Suitable systems are available under the POWERPULSE™ trademark from Schlumberger Technology Corporation of Sugar  
20 Land, Texas.

In order to urge the bottom hole assembly component 300 and the entire bottom hole assembly in a desired direction, steering device 302a (and, optionally, steering devices 302b and 302c) is selectively actuated with respect to the rotational position of the steering device 302a. For illustration, FIG. 4 depicts a borehole 11 within a  
25 subsurface formation. A cross section of bottom hole assembly 300 is provided to illustrate the placement of steering device 302a. In this example, an operator seeks to move bottom hole assembly 300 (rotating clockwise) towards point 402, a point located entirely within the x direction relative to the current position of bit body 300. Although steering device 302a will generate a force vector having a positive x-component if  
30 steering device 302a is actuated at any point when steering device 302a is located on the opposite side of borehole 11 from point 402 (i.e. between points 404 and 406),

steering device 302a will generate the maximum amount of force in the x direction if actuated at point 408. Accordingly, in some embodiments, the actuation of steering device 302a is approximately periodic or sinusoidal, wherein the steering device 302a begins to deploy as steering device passes point 404, reaches maximum deployment at point 408, and is retracted by point 406.

In some embodiments, a rotary valve (also referred to a spider valve) can be used to selectively actuate steering device 302a (and 302b and 302c). Suitable rotary valves are described in U.S. Patent Nos. 4,630,244; 5,553,678; 7,188,685; and U.S. Patent Publication No. 2007/0242565.

#### 10 INCORPORATION BY REFERENCE

All patents, published patent applications, and other references disclosed herein are hereby expressly incorporated by reference in their entireties by reference.

#### EQUIVALENTS

15 Those skilled in the art will recognize, or be able to ascertain using no more than routine experimentation, many equivalents of the specific embodiments of the invention described herein. Such equivalents are intended to be encompassed by the following claims.

1. A piston device comprising:  
a sleeve in fluid communication with a fluid source; and  
a loose element received within the sleeve;  
wherein the loose element is movable within the sleeve between a recessed position and an extended position.
2. The piston device of claim 1, wherein the loose element deflects the device from a wellbore when in the extended position.
3. The piston device of claim 1 further comprising:  
a bias pad in proximity to the sleeve;  
wherein the movement of the loose element to an extended position causes the bias pad to rise and deflect the device from a wellbore.
4. The piston device of claim 3, wherein the bias pad pivots about a pin.
5. The piston device of claim 1, wherein the sleeve includes one or more grooves to exhaust fluid from the particulate laden fluid source.
6. The ~~ball~~ piston device of claim 1, wherein the particulate laden fluid source is a pump.
7. The piston device of claim 1, wherein the loose element is substantially spherical.
8. A steerable rotary tool comprising:  
a rotary cylinder; and  
one or more piston steering devices, located on the exterior of the cylinder, each of the piston steering devices comprising:  
a sleeve in fluid communication with a particulate laden fluid source; and  
a loose element received within the sleeve;

wherein the loose element is movable within the sleeve between a recessed position and an extended position.

9. The steerable rotary tool of claim 8, wherein the one or more piston steering devices also include:

a bias pad in proximity to the sleeve;

wherein the movement of the loose element to an extended position causes the bias pad to rise.

10. The steerable rotary tool of claim 9, wherein the bias pad pivots about a pin.

11. The steerable rotary tool of claim 8, wherein the sleeve includes one or more grooves to exhaust fluid from the fluid source.

12. The steerable rotary tool of claim 8, wherein the particulate laden fluid source is a pump.

13. The steerable rotary tool of claim 8, wherein the particulate laden fluid source is drilling mud.

14. The steerable rotary tool of claim 8, wherein the loose element is substantially spherical.

15. A method of drilling a curved hole within a wellbore comprising:  
providing a steerable rotary tool comprising:

a rotary cylinder;

a cutting surface; and

one or more piston steering devices, located on the exterior of the cylinder, each of the piston steering devices comprising:

a sleeve in fluid communication with a particulate laden fluid source; and

a loose element received within the sleeve;  
wherein the loose element is movable within the sleeve from a  
recessed position and an extended position;  
rotating the steerable rotary tool within the wellbore; and  
selectively actuating at least one of the one or more pistons to deflect the  
steerable rotary tool from the wellbore, thereby drilling a curved hole within the wellbore.

16. The method of claim 15, wherein the steerable rotary tool includes:  
a bias pad in proximity to the sleeve;  
wherein the movement of the loose element to an extended position  
causes the bias pad to rise.
17. The method of claim 16, wherein the bias pad pivots about a pin.
18. The method of claim 15, wherein the sleeve includes one or more grooves to  
exhaust fluid from the particulate laden fluid source.
19. The method of claim 15, wherein the particulate laden fluid source is a pump.
20. The method of claim 15, wherein the particulate laden fluid source is drilling mud.
21. The method of claim 15, wherein the loose element is substantially spherical.