

[ABSTRACT]

A patrolling robot includes a driving unit being autonomously moveable in a construction field; an imaging unit being able to capture an image; and a patrol processing unit performs an autonomous movement by the driving unit based on map information of the construction field and a predetermined patrol route including a node as a location to acquire state information indicating a state of a surrounding environment of the construction field, and in a case in which the node is reached, makes the imaging unit to capture the image and acquire the state information at least including the image.