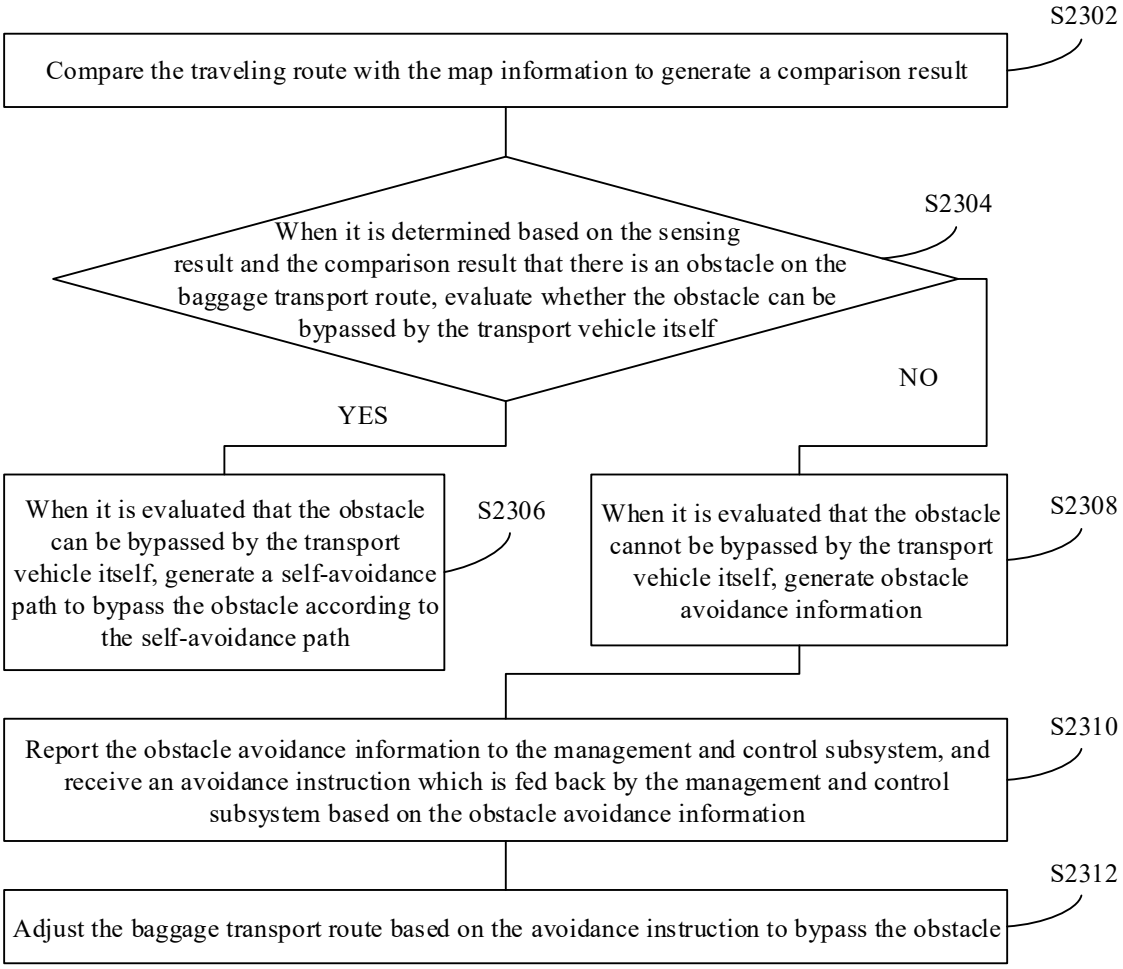
S2302
Compare the traveling route with the map information to generate a comparison result
S2304
When it is determined based on the sensing result and the comparison result that there is an obstacle on the baggage transport route, evaluate whether the obstacle can be bypassed by the transport vehicle itself
YES
NO
S2306
When it is evaluated that the obstacle can be bypassed by the transport vehicle itself, generate a self-avoidance path to bypass the obstacle according to the self-avoidance path
S2308
When it is evaluated that the obstacle cannot be bypassed by the transport vehicle itself, generate obstacle avoidance information
S2310
Report the obstacle avoidance information to the management and control subsystem, and receive an avoidance instruction which is fed back by the management and control subsystem based on the obstacle avoidance information
S2312
Adjust the baggage transport route based on the avoidance instruction to bypass the obstacle

FIG. 23


106
1086
1084
1082

FIG. 24