

REMOTE CONTROL SCHEDULER AND METHOD FOR AUTONOMOUS ROBOTIC DEVICE

ABSTRACT

A method of scheduling a robotic device enables the device (26, 104) to run autonomously based on previously loaded scheduling information. The method consists of a communication device (12), such as a hand-held remote device, that can directly control the robotic device (26, 104), or load scheduling information into the robotic device such that it will carry out a defined task at the desired time without the need for further external control. The communication device (12) can also be configured to load a scheduling application program into an existing robotic device, such that the robotic device can receive and implement scheduling information from a user.

Fig. 1