

26. The robotic arm of claim 25, further comprising a set of eyelets formed in the drum, through which the tendon is routable such that the tendon is disposed on each of an outer surface of the drum and an inner surface of the drum.

5 27. The robotic arm of claim 26, further comprising an adhesive securing an outer surface of the tendon to portions of the drum.

28. The robotic arm of claim 23, wherein the drum structure carries a tendon along a tendon routing path from an outer side of the drum, into and through a thickness of
10 the drum to an inner side of the drum, and back through the thickness of the drum to the outer side of the drum.