

INTELLIGENT DRIVING CONTROL METHOD AND APPARATUS, ELECTRONIC DEVICE, PROGRAM AND MEDIUM

ABSTRACT

An intelligent driving control method and apparatus, an electronic device, a program and a medium. The method comprises: acquiring a detection result of of a lane line of a vehicle driving environment (S101); according to a driving state of the vehicle and a detection result of the lane line detection, determining an estimated distance by which a vehicle drives out of the lane line (S102); in response to the estimated distance being greater than a first preset distance value and less than or equal to a second preset distance value, determining an estimated time for which the vehicle drives out of the lane line (S103); and performing intelligent driving control according to the estimated time (S104). The intelligent control over a driving state of the vehicle based on a lane line is realized, so as to reduce or avoid the traffic accidents when the vehicle drives out of the lane line, and to improve driving safety.

[FIG. 1]