

Method and device for controlling a zonally operated elevator installation

The invention relates to a method for controlling a zonally operated elevator installation, wherein on a changeover floor changing between the zones is made
5 possible, and wherein with a delivering elevator group and a collecting elevator group, transportation to and from the changeover floor is realized, and wherein a trip destination is entered via a destination-call control by each passenger to be transported. Further, the invention relates to an elevator installation for zonal operation in buildings with several elevators, wherein each elevator group contains
10 at least one destination-call input device for registering the destination of a passenger, each elevator is assigned to an elevator group, the building is divided into zones, and a changeover floor for changing between the elevator groups is arranged between the zones.

15 To meet the increasing need for transportation in tall buildings, intelligent elevator controls are used. For this purpose, the building is divided vertically into 2 or more zones or floor areas. In each of these zones, one or more elevator groups can be provided to allow transportation, especially of passengers. As soon as it is necessary to change elevators to reach a higher floor area, if the incidence of
20 traffic is high, queues can form on the changeover floors. These queues are caused mainly by unequal transportation capacities of the delivering and collecting elevator groups.

An elevator control is a central system in which the operating processes are
25 controlled by an intelligent station in the elevator system. This elevator control can be located in the machine room, or inside or outside the elevator cars.

The changeover floors between the zones, or between two zone systems, are also referred to as sky lobbies. The problem of possible overfilling of the changeover floor can also arise when changing between zone systems.

- 5 Elevators in very tall buildings occupy a significant part of the cross-section of the building. The amount of space available on the changeover floors is usually limited, and cannot be increased without very great constructional and financial outlay.
- 10 To effectively utilize these limited capacities on the changeover floors, use is known of devices for automatically detecting when the changeover floor is fully occupied. For this purpose, space monitoring devices such as light barriers, movement sensors, cameras, etc. are used. However, these devices provide only
inexact information concerning occupation of the changeover floors. Furthermore,
- 15 with these devices it is only possible to reduce or optimize the delivering transportation, and thereby avoid overfilling of the changeover floor and even greater delay in the transportation of passengers, at the cost of the overall transportation volume.
- 20 WO 02/14198 describes an elevator system in which group controls are used. The group controls use light barriers or weight sensors to record the number of persons. With this system, no exact forecast can be made of where the individual passengers travel to, or how many passengers are present on the changeover floor and when.

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With the measures known to date, it cannot be determined whether all the persons detected on the changeover floors want to use the connecting elevators of the upper or lower zone, or whether they leave the elevator lobby or

changeover floor for the purpose of visiting offices, restaurants, conference halls, etc. located on that floor.

- The solutions for preventing or limiting overfilling of the changeover floor or sky lobby known to date aim either to reduce the transportation capacity of the delivering elevator group, which at times of peak load contraproductively causes transportation peaks, or else propose measures for increasing the transportation capacity of the collecting elevator group which in practice can only be realized to a limited extent. Such measures may include, for example, increasing the speed or acceleration, or shortening the door-open times. However, in respect of motor rating and power supply, elevators are usually not overdimensioned, so that increasing their speed or acceleration can only be considered to a very limited extent. Moreover, increasing the acceleration negatively affects how passengers experience the ride, so that here also, only a very limited increase in the transportation capacity can be achieved. Shortening or optimization of the door-opening times is implemented as standard on most elevators. These measures do not allow any really noticeable increase in the transportation capacity to be achieved.
- Correspondingly, the purpose of the present invention is to reduce the above-mentioned disadvantages by creation of an elevator installation which allows an increase in the transportation capacity of the collecting elevator group, without reducing the transportation capacity of the delivering elevator group.
- Advantageous embodiments of the invention are stated in the dependent subclaims.

According to the present invention, the problems and shortcomings of the elevator controls according to the state of the art are solved by means of a method of controlling an elevator installation operated zonally, wherein changing between the

zones on a changeover floor is made possible, and wherein transportation to and from the changeover floor respectively is realized by means of a delivering elevator group and a collecting elevator group, and wherein a trip destination is entered via a destination-call control by every passenger to be transported, and
5 wherein the delivering elevator group and the collecting elevator group are combined into a multi-group which is controlled by a multi-control, and wherein the number of passengers who will change elevator group on the changeover floor is determined by the multi-group control from the trip destinations input by the passengers, and wherein the elevator groups are controlled by the multi-group
10 control depending on the number of passengers changing.

Destination-call controlled elevators allow the possibility of using the information entered into the elevator system through the destination-call control to optimize the transportation capacity. Combining delivering and collecting elevator groups
15 into a multi-group combined with a destination-call control makes it possible to determine the exact number of persons present on the changeover floor at any time. In consequence, the elevator groups can be controlled depending on the number of passengers on the changeover floor, which allows overfilling of the changeover floor to be avoided or limited.

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For this purpose, according to the invention it is proposed to activate the reserves in the transportation capacity in advance, with the result that overfilling of a changeover floor by a continuous flow of arriving passengers occurs later or, should the flow diminish, not at all.

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By means of the multi-group control it is possible to communicate to the changing passengers which elevator should be used first, and to communicate to the passengers in advance, before their arrival at the changeover floor, which elevator has been assigned as the best connecting elevator.

Arranged in an advantageous embodiment is a statistics unit. The statistics unit receives from the multi-group control, already when each changing passenger enters their first destination call, information as to the approximate time of arrival at the changeover floor. The multi-group control also transmits to the statistics unit the approximate boarding time. The exact boarding time is communicated after boarding has taken place. When the exact exiting time of the changing passengers on the changeover floor is known, this, together with the approximate time for boarding the connecting elevator, is communicated to the statistics unit VSE. As soon as the exact time of arrival of the connecting elevator is known, the multi-group control informs the statistics unit of the exact time of boarding the connecting elevator. This allows the statistics unit to maintain a future-oriented occupation statistic of the changeover floor, which is constantly made more precise with the notification of the exact arrival and departure times of each passenger.

Additionally, in an advantageous embodiment of the invention, the statistic of the occupation trend is maintained by the statistics unit. The positive or negative change in the number of persons on the changeover floor per interval of time is calculated. The statistics unit can use the approximate parameters to calculate a leading occupation of the changeover floor and a leading occupation trend. The statistic of the occupation trend complements the information regarding the number of passengers on the changeover floor, so that the correct conclusions regarding the development of the future occupation of the changeover floor can be drawn. By means of the leading statistic, the transportation capacity can be adapted in good time to the increasing or decreasing number of passengers on the changeover floor.

By the use of building-specific parameters, when a threshold value of the transportation capacity is exceeded, the transportation capacity of the collecting

elevator group can be increased. When this is done, the transportation capacity of the delivering group is kept unchanged, the building is optimally filled or emptied, and the changeover floor is not overfilled.

- 5 As soon as occupation of the changeover floor decreases, and the parameter value falls below another threshold value, and the trend of occupation points downward, the destination-call control parameters are reset to normal values, so that the passenger comfort is optimally set again with sufficient transportation capacity. These different threshold values allow realization of a hysteresis, so that
- 10 a stable control process can be assured.

The above measures cause only small reductions in the otherwise high convenience of a destination-call control. This manifests itself as full utilization of the car capacity and optimization of the waiting time depending on the time of

15 arrival of the delivering elevator group. With the given peak load, the time to destination remains optimal for the totality of the changing passengers.

The purpose is also fulfilled by an elevator installation for zonal operation in buildings with several elevators, wherein each elevator contains a destination-call

20 input device for registering the trip destination of a passenger, each elevator is assigned to an elevator group, the building is divided into zones, and arranged between the zones is a changeover floor for changing between the elevator groups, and in which a multi-group control for controlling a delivering elevator group and a collecting elevator group is arranged, and the multi-group control is

25 provided to calculate from the trip-destinations input by the passengers in the delivering elevator group and by the passengers in the collecting elevator group the number of passengers on the changeover floor, and the destination-call control parameters can be changed depending on the number of passengers on the changeover floor.

It is assumed that the expert reader recognizes that delivering and collecting elevator groups can be exchanged depending on their direction of travel. In the interest of greater clarity and comprehensibility, the invention is only described in
5 relation to the direction of travel from the bottom to the top of the building.

The invention is explained in greater detail by reference to drawings representing only one direction of embodiment as follows:

- 10 Fig. 1 a diagrammatic representation of an elevator installation with zonal operation;
- Fig. 2 a diagrammatic construction of the control for an elevator installation;
- Fig. 3 a representation of the trend of occupation over time.

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Figure 1 shows diagrammatically the construction of an elevator installation. The building is divided into several zones, Z1, Z0. Each zone comprises several floors. Zone Z0 comprises floors S1 to S4, and zone Z1 comprises floors S4 to Sn. In these zones, the elevators A-F are used for the transportation of passengers. The
20 elevators A-F are divided into elevator groups GR1 and GR2. The elevators are controlled via a destination-call control device ZEG (not shown). The elevator group GR1 transports the passengers in zone Z0 from floor S1 to S4, and the elevator group GR2 transports the passengers in zone Z1 from floor S4 to Sn. It is also possible to reach floor S1 with the elevator group GR2. The elevator groups
25 GR1 are controlled by group controls GRS1 for the first elevator group, and GRS2 for the second elevator group. The elevators are connected via a group bus GB to the group controls GRS1 and GRS2 respectively. The individual floors are connected to the group controls via a group peripheral bus GPB. For the purpose of controlling the elevator installation according to the invention, a multi-group

control 1 is provided. This is connected via a multi-group bus 2 to the group controls GRS1 and GRS2. Also connected via the multi-group bus 2 is a statistics unit 5. In this exemplary embodiment, the floor S4 is a changeover floor or sky lobby, since changing between the zones of the building is made possible there.

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Figure 2 shows a detailed diagrammatic representation of the control. Building parameters GPAR are fed to the multi-group control 1. These building parameters GPAR can include characteristics of the elevator as well as conditions on the changeover floors. Connected via the multi-group bus 2 are the group controls GRS1 and GRS2, and the statistics unit 5 is also connected to the multi-group control 1. The statistics unit 5 comprises an evaluation unit 51, a unit for determining the occupation trend 52, and a unit for determining the occupation statistic 53.

15 The functioning of the invention is explained below by reference to the exemplary embodiment represented in figures 1 and 2.

From the delivering elevator group (A, B, C) and the collecting elevator group (D, E, F) a multi-group is formed. Through the combination, the multi-group control 1 detects by means of the destination-call control how many of the passengers must change elevators at the changeover floor S4. The multi-group control 1 detects whether a passenger has as final destination a floor higher than S4, or whether the passenger may possibly visit a lecture theater, a restaurant, etc. and therefore not need to be regarded as filling the elevator lobby.

25 The multi-group control 1 first communicates to the changing passengers the elevator A, B, C to be used. Further, the best connecting elevator D, E, F is also communicated to the passengers in advance, before arrival at the changeover floor S4. A statistics unit is also arranged. The statistics unit 5 receives from the multi-group control 1, already when each changing passenger enters their first

destination call, information as to the approximate time of arrival AAZ at the changeover floor S4. As soon as the exact exiting time GAZ of the changing passengers on the changeover floor becomes known, it is communicated to the statistics unit 5 together with the approximate time of boarding AEZ the connecting
5 elevator D, E, F. As soon as the exact time of arrival GAZ of the connecting elevator D, E, F becomes known, the multi-group control 1 communicates the exact boarding time GEZ to the statistics unit 5. By this means, the statistics unit 5 can maintain a future-oriented occupation statistic for the changeover floor, which is constantly made more precise by the messages regarding the exact times of
10 arrival and departure of each passenger. An occupation trend BT is also registered by the statistics unit 5. The positive or negative change in the number of persons on the changeover floor S4 per time interval is determined. The statistic regarding the occupation trend complements the information about the number of passengers on the changeover floor S4, so as to enable the correct
15 conclusions regarding the development of the future occupation of the changeover floor to be drawn. In the statistics unit 5, two parameters MAXAPE (maximum number of passengers on the changeover floor: switch the increased transportation capacity on) and MAXAPA (maximum number of passengers on the changeover floor: switch the increased transportation capacity off) are used. The
20 two values must be selected individually for each building and changeover floor, because they depend on the respective architectural solution of the elevator lobbies, and on the possible difference in the transportation capacities between the delivering and collecting elevator groups. Each of these two parameters MAXAPE, MAXAPA specifies a number of persons. If the occupation statistic
25 maintained by the statistics unit 5 reaches a value which follows immediately after the parameter MAXAPE, and if the momentary occupation trend shows a corresponding positive gradient, the destination-call control parameters of the collecting elevator group (D, E, F) are automatically adapted by the multi-group control 1 in such manner that the maximum transportation capacity of this
30 collecting elevator group is activated. This is also referred to as peak traffic mode. The transportation capacity of the delivering group is maintained, the building is

optimally filled, and by exchanging the delivering elevator group A, B, C and collecting elevator group D, E, F, emptied, and the changeover floor is not overfilled.

- 5 The transportation capacity is achieved, for example, by full utilization of the maximum allowable number of persons. Furthermore, by corresponding time-related control of the collecting elevator group, in the case of impending overfilling, the maximum available transportation capacity for collection can be made available. For this purpose, for example, the elevators belonging to the collecting
10 elevator group are preferably sent to the changeover floor, or the arrival time of the collecting elevators is adapted to the very full arriving, or delivering, elevators.

As soon as occupation of the changeover floor S4 falls, and the parameter value MAXAPA is reached, and the occupation trend points downward, the destination-
15 call control parameters are reset to normal values or a normal traffic mode, as a result of which the passenger comfort is set optimally again with sufficient transportation capacity by the multi-group control 1. The parameter value MAXAPA typically lies above the value MAXAPE so as to assure a stable control process by means of the corresponding hysteresis.

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In Figure 3, the increase in the number of persons AP on the changeover floor S4 is plotted against time t. Based on the calculation of the occupation statistic and the occupation trend of the respective units 52, 53 in the statistics unit 5, it is possible to create a leading statistic VAP.

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By this means, a time-lead ZVVS necessary for prevention of overfilling is created. As the figure shows, the curve of the leading number of persons (VAP) matches almost exactly the real number of persons (RAP) with a displacement in time. With RAPP the curve of the number of persons on the changeover floor with changing

parameters according to the invention is shown. Without the changing parameters, the number of persons would match the curve RAPOP, and very quickly lead to an overfilling of the changeover floor. When the parameter MAXAPE is exceeded with a rising occupation trend, the transportation capacity of the collecting elevator group is increased by, for example, fully utilizing the maximum allowable number of persons for each elevator, or by minimizing the number of stops. With MTAGK a transportation capacity is represented which offers maximum comfort for transportation of persons. After the change in the destination-call control parameters, the maximum transportation capacity with reduced comfort MTAGOK is activated. With this transportation capacity, more passengers can be transported away from the changeover floor. These changed destination-call control parameters are maintained until the number of persons on the changeover floor falls below the value of the parameter MAXAPA, and the occupation trend BT is also downward. The destination-control parameters are then reset to normal transportation capacity. Referenced with OCL is the threshold value for the number of persons on the changeover floor at which the changeover floor is overfilled.

Patent Claims

1. Method for controlling a zonally operated elevator installation wherein on a changeover floor (S4) changing between the zones (Z0, Z1) is made possible, and by means of which with a delivering elevator group (GR1; GR2) and a collecting elevator group (GR2; GR1) transportation to and from the changeover floor (S4) is realized, and by means of which a trip destination is entered via a destination-call control system by each passenger to be transported,
characterized in that
the delivering elevator group (GR1; GR2) and the collecting elevator group (GR2; GR1) are combined into a multi-group which is controlled by a multi-group control (1), and in that the number of passengers who will change elevator group (GR1, GR2) on the changeover floor (S4) is determined by the multi-group control (1) using the trip destinations entered, and in that the elevator groups (GR1, GR2) are controlled by the multi-group control (1) depending on the number of passengers changing.
2. Method according to Claim 1,
characterized in that
by means of the multi-group control (1), the optimal elevator (A, B, C) of an elevator group (GR1) depending on the trip destination is communicated to the passengers, and the optimal connecting elevator (D, E, F) on the changeover floor (S4) is communicated to the changing passengers.
- 3.
4. Method according to Claim 1,
characterized in that
by means of the multi-group control (1) the number of passengers who will not use any connecting elevator group (GR1, GR2) is determined, and this

number together with the number of changing passengers is fed to a statistics unit (5).

5. Method according to Claim 3,

5 **characterized in that**

after a destination-call is entered, the approximate exiting time (AAZ) on the changeover floor (S4) is transmitted to the statistics unit (5).

6. Method according to Claim 4,

10 **characterized in that**

the exact exiting time (GAZ) of the passengers on the changeover floor (S4), and the approximate time of boarding (AEZ) the connecting elevator, are transmitted to the statistics unit.

15 7. Method according to Claim 1,

characterized in that

as soon as the exact time of boarding (GEZ) the connecting elevator is known, the multi-group control (1) transmits this exact time of boarding the connecting elevator to the statistics unit (5).

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8. Method according to Claims 3 to 6,

characterized in that

in the statistics unit (5) from the determined times the number of passengers on the changeover floor (S4) at any time is determined.

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9. Method according to Claims 3 to 6 and 7,

characterized in that

the statistics unit (5) determines from the exact times of boarding and exiting a real number of persons on the changeover floor (RAP), and from the approximate times of boarding and exiting a leading number of persons

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on the changeover floor (VAP).

10. Method according to Claim 1,
characterized in that
5 the building parameters (GPAR) are fed to the multi-group control (1).
11. Method according to Claim 1,
characterized in that
10 should a parameter (MAXAPE) be exceeded, this being exceeded is transmitted to the multi-group control (1) and the transportation capacity of the collecting elevator group is adjusted by changing the destination-call control parameters for the collecting elevator group.
12. Method according to Claim 10,
15 **characterized in that**
should the parameter (MAXAPE) be exceeded and the occupation trend have a positive gradient, the transportation capacity of the collecting elevator group is adjusted by changing the destination-call control parameters for the collecting elevator group, and a maximum transportation
20 capacity with reduced comfort (MTAGOK) is set for the collecting elevator group.
13. Method according to Claim 1,
characterized in that
25 should a parameter (MAXAPA) be fallen below and the occupation trend (VAP, RAP) be negative, the destination-call control parameters are changed to a normal transportation capacity with normal comfort (MTAGK).
14. Method according to Claims 11 and 12,
30 **characterized in that**

the value of the parameter MAXAPE is smaller than the value of the parameter MAXAPA.

15. Method according to Claims 11, 12, and 13

5 **characterized in that**

the parameters MAXAPA and MAXAPE are adjustable.

16. Elevator installation for zonal operation in buildings with several elevators (A, B, C, D, E, F) wherein each elevator contains at least one destination-call input device (ZEG) for recording the destination of a passenger, each
10 elevator is assigned to an elevator group (GR1; GR2), the building is divided into zones (Z0, Z1), and arranged between the zones is a changeover floor (S4) for changing between the elevator groups (GR1; GR2),

15 **characterized in that**

a multi-group control (1) for controlling a delivering elevator group (GR1) and a collecting elevator group (GR2) is arranged, and the multi-group control (1) is provided to calculate from the trip-destination entries of the passengers in the delivering elevator group (GR1) and the passengers in
20 the collecting elevator group (GR2) the number of passengers on the changeover floor (S4), and that the destination-call control parameters can be changed depending on the number of passengers on the changeover floor (S4).

- 25 17. Device according to Claim 15,

characterized in that

the multi-group control (1) is assigned to a statistics unit (5) to which the parameters determined by the multi-group control can be fed, and the statistics unit is provided for calculating the number of persons on the
30 changeover floor and the occupation trend on the changeover floor (VAP,

RAP), and it is possible to operate the multi-group control (1) in a peak-traffic mode (MTAGOK) when a specifiable maximum parameter (MAXAPE) is exceeded, and in a normal-traffic mode (MTAGK) when a further parameter (MAXAPA) is fallen below.