

SYSTEMS AND METHODS OF SERVICING EQUIPMENT

ABSTRACT

A robotic assembly for servicing equipment, the robotic assembly including an area configured to receive components associated with a workscope of the equipment; an environmental capture device configured to capture information associated with an environment in which the robotic assembly is disposed; and one or more computing devices configured to: locate the equipment in the environment; autonomously navigate the robotic assembly through the environment to the equipment; and autonomously adjust a position of the robotic assembly in response to the workscope.

[Figure 2]