

**CONFIDENCE AND FRAME SIGNAL QUALITY DETECTION IN A SOFT DECISION
CONVOLUTIONAL DECODER**

The present application is concerned with transmission of data using convolutional codes and is particularly, though not exclusively, concerned with the
5 transmission of digitally coded speech signals.

According to one aspect of the present invention there is provided a method of decoding signals by processing received signals to provide confidence measure signals and using a soft decision decoder to decode the received signals, the method comprising:

- 10 (a) receiving known signals;
- (b) storing data representing the extent to which the confidence measure signals for the received known signals differ from a logarithmic representation of the error statistics of the received known signals;
- (c) receiving unknown signals;
- 15 (d) applying correction factors to the confidence measure signals for the received unknown signals, the correction factors being derived from the said stored data, so as to reduce the extent to which the confidence measures differ from the said logarithmic representation;
- (e) decoding the corrected signals using the soft decision decoder.

20 In another aspect the invention provides an apparatus for decoding signals comprising:

means for processing received digital signals to provide confidence measure signals;

translation means operable to apply correction factors to the confidence
25 measure signals so as to reduce the extent to which the confidence measure signals differ from a logarithmic representation of the error statistics of the received signals; and

a soft decision decoder to decode the corrected signals.

In a preferred embodiment the correction factors are derived from tests
30 performed by :

- (a) receiving known signals;

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(b) storing data representing the extent to which the confidence measure signals for the received known signals differ from a logarithmic representation of the error statistics of the received known signals.

The apparatus may also include

5 means to form a sum of the confidence measure signals for a frame period of the signal and

means to compare the sum with a threshold value to provide a signal indicating the quality of the frame.

In another aspect the invention provides

10 means for processing received digital signals to provide confidence measure signals;

means to form a sum of the confidence measure signals for a frame period of the signal;

15 means to compare the sum with a threshold value to provide a signal indicating the quality of the frame.

Preferably the apparatus may include means operable in response to the said signal indicating the quality of the frame to suppress further processing of those which are of a lower quality than that determined by the said threshold.

A further aspect of the invention provides a method of transmitting data
20 bits comprising, for each of successive frame periods, formatting the bits into a frame sequence, coding the bits by means of a convolutional coder, including generating error check bits which are a function of (a) bits formatted into the beginning of the frame sequence and (b) bits formatted into the end of the frame sequence.

25 Preferably the bits (a) may be taken from the first 50% of the frame and the bits (b) may be taken from the last 25% of the frame.

Some embodiments of the invention will now be described, by way of example, with reference to the accompanying drawings, in which:

Figure 1 is a block diagram of an apparatus for the transmission of speech signals;

30 Figures 2 and 3 show graphically the results of error tests on the speech coder used in the apparatus of Figure 1;

Figures 4 and 5 show graphically the results of error tests on the convolutional codes used in the apparatus of Figure 1;



Figures 6, 7, 8 and 9 are block diagrams of, respectively, the reordering unit 4, convolutional coder 6, masking unit 8 and CRC unit 5 of the apparatus of Figure 1 and Figure 10;

Figure 10 is a block diagram of an apparatus for receiving speech signals
5 and

Figure 11 shows a typical plot of the likelihood of a bit error against the confidence measure for that bit.

In Figure 1, speech signals are received in digital form at an input 1 and are supplied to a digital speech coder 2. The preferred coder is a codebook excited
10 linear predictive (CELP) coder, operating at 8 kbit/s, in accordance with standard G.729 of the International Telecommunications Union. However, other types of coder may be used, and, indeed, simple p.c.m. is not excluded.

The coder 2 analyses each 10 ms frame of speech samples and, for each, produces 79 bits representing a number of parameters (enumerated below) which
15 serve, at a receiver to drive a decoder which synthesises received speech signals. Certain of these parameters are re-coded using Gray code, in a unit 3.

These bits are to be formatted into a bit-serial frame for coding by means of convolutional codes. First, the bits are assembled into a specific order in a unit 4, then three cyclic redundancy check bits are generated in a unit 5 from the first
20 26 and last 6 bits of the frame, and appended to the beginning of the frame, which now has 82 bits. These are followed by six tailing bits of fixed value such as zero - a known expedient in convolutional encoding for clearing the coder memory and permitting the corresponding decoder to reset itself at the end of a frame to reduce error propagation.

25 The signals are then supplied to a convolutional coder which operates according to a basic code and two punctured codes derived from it, switching between these during the course of a frame. The basic code, in this example, has a rate of $1/3$ - i.e. it produces $3n$ output bits for every n bits input to it. A punctured code operates at a higher rate than the basic code, by simply deleting
30 some of the bits output by the basic coder; this increases the rate of the code but reduces its error-correcting ability. It has the advantage over using entirely unrelated codes of relative simplicity and not requiring the insertion of tailing bit between code changes. This process is shown in Figure 1 as a convolutional coder

6 operating according to the basic code, and hence producing $3 \times 82 = 246$ bits per frame, followed by a masking unit 7 which deletes bits according to a desired puncturing pattern.

5 The coded bits are then subjected to intra-frame and inter-frame interleaving (8,9) which serves to improve the robustness of the system against the burst errors common in radio transmission. Interleaving of this kind is well known.

The design is based on the following observations:

10 (a) some of the bits generated by the speech coder 2 are more sensitive to transmission errors than others. That is, the observed signal-to noise ratio at the output of a speech decoder at a receiver in the presence of a given error rate in a particular one of the 79 bits is, for some bits, relatively good and for others relatively poor.

15 (b) the level of received transmission errors over a given channel is higher for some of the bits in the frame than for others. More particularly, the error rate tends to be lower at the beginning and end of the frame (after interleaving has been removed) than in the middle, as in those regions the decoder for the convolutional code is commencing from (or converging on) a known state.

20 (c) the overall signal-to-noise ratio of the system can be improved by allocating sensitive bits to low-error positions in the frame and allocating less-sensitive bits to high-error positions in the frame.

25 (d) this effect may be further enhanced by switching between different code rates during the course of a frame so that the distribution of error rates over the frame can be shaped to improve the match between this and the distribution of sensitivity among the various bits produce by the speech coder. Whilst no systematic method of optimising this shaping has yet been found, in general terms one aims to keep the maximum bit error rate low, whilst the number of bit positions within the frame which have a
30 very low error rate is sufficient to accommodate all of the most sensitive bits.

The following table sets out the bits generated by the G.729 speech coder

TABLE I

index	label s(k)	no. of bits	description
00	LSP1MA	1	Predictor switch
01 to 07	LSP1	7	Codeword for vector-quantised predictor coefficient set
08 to 12	LSP2	5	Codeword for vector-quantised difference between the actual first five coefficients and those given by LSP1
13 to 17	LSP3	5	Codeword for vector-quantised difference between the actual second five coefficients and those given by LSP1
18 to 25	M1	8	Pitch period for long-term predictor - first 5 ms sub-block
26		1	Parity check bit (not used)
27 to 39	CB1	13	Codebook code for excitation positions for first 5 ms sub-block
40 to 43	S1	4	Codebook pulse signs
44 to 50	G1	7	Gains
51 to 55	M2	5	Pitch period for long-term predictor - second 5 ms sub-block (expressed as differential from M1)
56 to 68	CB2	13	Codebook code for excitation positions for second 5 ms sub-block
69 to 72	S2	4	Codebook pulse signs
73 to 79	G2	7	Gains

The sensitivity of these bits was measured by, for each bit,

(a) inverting the bit (i.e. simulating a 100% error rate)

5 (b) measuring the signal-to-noise ratio and spectral distortion at the output of a G.729 decoder.

The results are shown in Figure 2, where the horizontal axis shows the bit index number as shown in the table and the vertical axis shows the signal-to-noise ratio (SNR). A considerable variation in sensitivity is seen. The same results, plotted in ascending order of SNR is shown in Figure 3 for later reference.

- 5 Similar tests performed using Gray code to represent each variable show a small improvement in SNR on the pitch parameters M1 and M2 and codewords CB1 and CB2, but poorer performance on others, and for this reason Gray code is applied by the unit 3 only to those four parameters. Naturally, for CB1 and CB2, this improvement is contingent on adjacent Gray codes being assigned to
10 codebook entries representing mutually similar excitations.

Turning now to the convolutional coding, the basic code used in this example is a 1/3 rate code, defined by the generator polynomials:

$$g1 = 1 + X^2 + X^3 + X^5 + X^6$$

$$g2 = 1 + X + X^2 + X^3 + X^6$$

15 $g3 = 1 + X + X^2 + X^3 + X^4 + X^5 + X^6$

- In addition, two punctured versions of this code are employed, namely a second code having a rate of 2/5 in which alternate bits $g3$ are omitted and a third code, of rate 1/2, in which all bits $g3$ are omitted. Punctured codes are well known per se - see for example, J. Hugenaur, N. Seshadri and C.E.W. Sundberg, "The
20 Performance of Rate-Compatible Punctured Codes for Future Digital Mobile Radio" IEEE Vehicular Technology Conference, June 1988.

The codes are assigned to bit positions within the frame, as follows:

TABLE II

No. bits	Rate	Bits generated	Use
3	1/3	9	CRC bits
26	1/3	78	speech coder bits
34	2/5	85	speech coder bits
7	1/2	14	speech coder bits
12	2/5	30	speech coder bits
6	1/2	12	tailing bits
88		228	

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This convolutional coder was tested for 12000 frames under simulated transmission error conditions using an error test file EP3 as described in "Error patterns for the qualification test of TCH-HS" ETST:TM3/TCH-HS, TD No. 89/1 for the ETSI GSM mobile radio standard and the residual bit error rate (RBER) - i.e. the error rate after decoding by a Viterbi decoder - measured. In these tests, a cyclic redundancy check was performed and frames failing this test were rejected. The RBER results for the non-rejected frames are plotted for each speech bit position in Figure 4 (and in Figure 5 in ascending order of RBER).

A comparison of Figure 5 with the sensitivity distribution of Figure 3 does not of course show an identity of shape: indeed such identity is probably not achievable; moreover, a number of other considerations are applied, as will be discussed below.

The allocation of coder and CRC bits to frame positions performed in the assembly unit 4 is as shown in Table III.

Underlying this allocation is the notion that one allocates sensitive bits from the speech coder to low-error rate positions within the frame supplied to the convolutional coder. If this were the only consideration, one would simply take the speech coder bits in ascending order of SNR and allocate them to frame positions in ascending order of RBER. This of course would produce a workable system, but the allocation given above has some advantages. First, it is a characteristic of the Viterbi decoders generally used for the decoding of convolutional codes that when the channel error conditions reach a level such that errors occur in the decoded output, then there is a tendency for such errors to be grouped - e.g. with a pair of consecutive decoded bits being incorrect. It is therefore preferred not to allocate consecutive frame positions to the same one of the speech coder parameters; i.e. a degree of bit-interleaving is also applied prior to the convolutional coding. This is not performed as a separate operation but is inherent in the allocation table.

TABLE III

Conv. Coder Frame	Speech Coder Frame	Conv. Coder Frame	Speech Coder Frame	Conv Coder Frame	Speech Coder Frame
0	1	30	41	60	60
1	18	31	0	61	32
2	2	32	42	62	61
3	50	33	54	63	33
4	19	34	43	64	62
5	3	35	55	65	34
6	46	36	35	66	63
7	20	37	64	67	25
8	4	38	36	68	69
9	45	39	65	69	70
10	21	40	37	70	71
11	5	41	66	71	72
12	44	42	38	72	77
13	22	43	67	73	78
14	6	44	39	74	73
15	23	45	68	75	76
16	8	46	13	76	74
17	7	47	27	77	75
18	47	48	56	78	79
19	9	49	14		26
20	51	50	28		
21	10	51	57		
22	52	52	15		
23	11	53	29		
24	49	54	58		
25	12	55	16		
26	48	56	30		
27	53	57	59		
28	40	58	17		
29	24	59	31		

The second consideration is that whilst signal-to-noise ratio is a useful indication, nevertheless it is found that some speech coder parameters are

5 subjectively more sensitive than others in that the effect of errors on one parameter may be more objectionable to the listener than errors in another parameter, even though the SNR is the same in both instances. Thus the above allocation table also reflects the fact that, based on listening tests, certain of the speech coder bits have been allocated frame positions that are more (or less) error-

free than the SNR figures would suggest. If one examines the effect of the above allocations, for example by plotting the measured SNR of each speech coder bit graphically against the measured RBER of the corresponding allocated frame position, one sees that, whilst the very sensitive bits (with SNRs below 4 dB) all
 5 occupy frame positions with RBER values less than 20, and those with SNRs greater than 16 occupy frame positions with RBERs greater than 80, the plot shows a considerable scatter about the monotonically increasing line that one would expect to see based on only the "simple" allocation method.

The reordering unit 4 is shown in more detail in Figure 6. It consists of an
 10 88-bit serial-in, parallel-out shift register 41; the 79 speech coder output bits, the three outputs of the CRC unit 5 and six zeroes (tailing bits) are connected in accordance with the bit allocation table above to the parallel inputs. It is loaded in parallel by a frame pulse f_1 from a clock generator 10 and the bits clocked out by a
 88xframe rate pulses f_1 from the clock generator. For convenience of illustration
 15 the Gray coder 3 is shown as separate units 3a to 3d. In the interests of clarity, only a few of the connections set out in Table III are shown. In the description which follows, the output of the PISO register 41 is referred to as $u(k)$ where:
 $u(0)$, $u(1)$ and $u(3)$ are the CRC bits ;

$u(3)$ to $u(81)$ are the speech coder bits numbered 0 to 78 in the "Conv,
 20 coder bits" column of Table II and in box 41 in Figure 6, and in the same order;
 $u(82)$ to $u(87)$ are zero (tailing bits).

The convolutional coder 6 is shown in Figure 7 and has six delay stages
 61 to 66 and three exclusive-or gates 66, 67, 68 connected to the taps of the delay stages in accordance with the generator polynomials given earlier. The
 25 outputs are $g1(k)$, $g2(k)$ and $g3(k)$.

The masking unit is shown in Figure 8. When the first (rate 1/3) code is used, all bits $g1(k)$, $g2(k)$, $g3(k)$ are forwarded to the output of the unit, cyclically ($g1(0)$, $g2(0)$, $g3(0)$, $g1(1)$, $g2(1)$ etc..). When the second (punctured) code (rate 2/5) is in force, the masking unit serves to omit alternate ones of the bits $g3(k)$,
 30 whilst when the third (rate 1/2) code is use, all bits $g3$ are omitted. As shown in the Figure, the bits $g1$, $g2$, $g3$ are clocked into serial-in parallel-out shift registers 81, 82, 83 respectively (each of 88 bits capacity) under control of the clock pulses ϕ_1 and then loaded in parallel into a parallel-in serial-out shift register 84, 228 bits



in length by clock pulses ϕ_1 , whence they may again be clocked out serially using ϕ_1 . Only a few of the connections are shown; these are connected in the sequence mentioned, except that the bits $g3(k)$ are, for the following values of k , omitted:

- 5 $k = 30, 32, 34 \dots 64$ (i.e. even numbers from 30 to 62)
 $k = 63$ to 69 inclusive
 $k = 71, 73, 75, \dots 81$ (i.e. odd numbers from 71 to 81)
 $k = 82$ to 87 inclusive.

The output bits are referred to as $c(k)$.

- 10 The effect of the convolutional code and the following puncturing may be summarised by expressing the coded bits $(c(0), c(1), \dots, c(227))$ in terms of $u(0), \dots, u(87)$, as follows:

CRC bits and class I:

- $c(3k) = u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6)$
 15 $c(3k+1) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6)$
 $c(3k+2) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-4) + u(k-5) +$
 $u(k-6)$ for $k = 0, 1, \dots, 28$

Class II:

- $c(\frac{5k+1}{2} + 13) = u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6)$
 20 $c(\frac{5k+1}{2} + 14) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6)$
 $c(\frac{5k+1}{2} + 15) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-4) + u(k-5) + u(k-6)$
 for $k = 29, 31, \dots, 61$

- $c(\frac{5k}{2} + 14) = u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6)$
 $c(\frac{5k}{2} + 15) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6)$
 25 for $k = 30, 32, \dots, 62$

Class III:

$$c(2k+45) = u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6)$$

$$c(2k+46) = u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6) \text{ for } k = 63, 64, \dots, 69$$

Class IV:

$$\begin{aligned} 5 \quad c\left(\frac{5k}{2} + 10\right) &= u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6) \\ c\left(\frac{5k}{2} + 11\right) &= u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6) \\ c\left(\frac{5k}{2} + 12\right) &= u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-4) + u(k-5) + u(k-6) \end{aligned}$$

$$\text{for } k = 70, 72, \dots, 80$$

10

$$\begin{aligned} c\left(\frac{5k+1}{2} + 11\right) &= u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6) \\ c\left(\frac{5k+1}{2} + 12\right) &= u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6) \text{ for } k = 71, 73, \dots, 81 \end{aligned}$$

Tail:

$$\begin{aligned} 15 \quad c(2k+52) &= u(k) + u(k-2) + u(k-3) + u(k-5) + u(k-6) \\ c(2k+53) &= u(k) + u(k-1) + u(k-2) + u(k-3) + u(k-6) \text{ for } k = 82, 83, \dots, 87 \end{aligned}$$

The interleaving functions performed by the units 8 and 9 are optional, and if included may be performed by any of a number of known algorithms. A particularly preferred implementation for the present context is however as follows, using modulo arithmetic with a step-size of 59. This value was chosen by trial and error to optimise the burst error performance over a particular radio channel and may be varied to suit particular channel conditions.

Each frame $c(k)$ of the convolutionally coded punctured sequence is mapped to a new frame $l(j)$ using the mapping

$$m(j) = 59j \bmod 228 \quad \text{for } j = 0, \dots, 227$$

And $l(j) = c(m(j))$.

For example, bit $l(4)$ of the output frame l from the intra-frame interleaving unit 8 is obtained from bit $c(5)$ of its input;

since $j = 4$

$$m(j) = m(4) = [59 \times 4] \bmod 228 = 233 \bmod 228 = 5$$

5 so $l(4) = c(m(4)) = c(5)$.

Although shown, for clarity, as a separate unit 8, this function can be implemented simply by rearranging the connection to the shift register 84 in Figure 8.

10 The inter-frame interleaving performed in the unit 9 may be performed as follows, on the assumption that it is desired to generate 114-bit frames B_1 and B_0 for transmission. Each such pair of frames contains bits from four of the frames $l(j)$. We refer to the current frame as l_0 , l_1 the last and so on. The mapping between l and B is given by:

15 $B_1(k) = l_{3 - k \bmod 4}(k) \quad \text{for } k = 0, 1, \dots, 113$

$$B_0(k) = l_{3 - (k+2) \bmod 4}(k+114) \quad \text{for } k = 0, 1, \dots, 113$$

B_1 and B_0 carry data bits from four speech frames and they are transmitted in that order. Figure 12 illustrates how the process is carried out. Note how one 228 bit frame is spread over eight 114-bit blocks, with a fixed
20 pattern of allocating 28 or 29 bits in each block from a single frame.

The CRC unit 5, in this example, operates in accordance with the polynomial $1 + X + X^3$, which may be implemented by the circuit of Figure 9, with three one-bit delays 51, 52, 53 and two exclusive-OR gates, 54, 55. The 32 bits from which the CRC bits are to be generated are supplied serially to the input 56.
25 The 32 bits used are the first 26 and the last six speech bits of the frame supplied to the convolutional coder - i.e. $u(3)$ to $u(28)$ and $u(76)$ to $u(81)$. In general, it is found that by choosing bits at the beginning and end of the frame, the effectiveness of a receiver check to identify "bad frames" is enhanced and thus the error rate in the remaining "good frames" is improved. The choice of 26 at the
30 start and six at the end as opposed to, say, 24 and 8, was made by trial and error to minimise the measured good frame error rate during tests.

Figure 10 shows a suitable receiver for use with the apparatus of Figure 1. Signals received at an input 110 are assumed to have arrived over a

communications path such as a telephone line or radio link and to have been demodulated by a demodulator which provides not only demodulated bits but also a confidence measure for use by a soft decision decoder. For the purposes of the present description, it is assumed that the modulation scheme used transmits one
 5 bit per symbol, so that a confidence measure is provided for each bit. However, this may not always be the case; in transmission systems carrying more than one bit per symbol, then one obtains a confidence measure (or measures) for each symbol. These data are then supplied to a channel equaliser 111, followed by an inter-frame interleavers 112, both being of conventional construction. This is
 10 followed by a soft decision transformation unit 113, whose function will be discussed below, and an intra-frame interleaver 114. Units 112 and 114 remove the effects of the interleavers 8 and 9 of Figure 1. The signal then passes to a "demasker" 115 which reinserts into the bit stream the "g3" bits which were deleted in the mask 7. Of course, the values of these bits is not known, and (as
 15 is usual for decoding of punctured codes) one may insert bit values of zero with an accompanying confidence measure of zero. Sometimes inserting zeros (or ones) may result in decoder bias and if desired, random bit values may be inserted.

The signal has now been formatted in accordance with the first (1/3 rate) convolutional code and is now supplied to a Viterbi decoder 115 (of conventional
 20 construction) which operated according to that code. A CRC unit 117 performs a cyclic redundancy check, and the decoder bits are assembled (118) for use by a speech decoder 120 (G.729) with the Gray-coded bits being recoded at 119.

The output of the cyclic redundancy check is supplied to the speech decoder 12 so that in the event of failure the relevant decoded frame is discarded,
 25 the speech decoder regenerating the discarded information using the error concealment method described in the G.729 standard. It is observed, however, that there is a limit to the number of errors such methods can detect, so that, when channel conditions are extremely bad, the number of errors may be such that a "bad frame" indication is not obtained. Thus, additionally, a further error
 30 detector 122 is provided, which serves to sum the confidence measures for each bit of a frame to form a "frame score" b - viz.

$$b = \sum_{k=0}^{227} c(k)$$

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where $e(k)$ are confidence measures in the range 0 to +127. This frame score could equally well be calculated after the soft decision transformation process, described below, in which case the error detector 122 would receive its input from the soft decision transformer 113.

5 A threshold is applied at 123 and if b exceeds 2100 (for example) a bad frame indication is output which is combined in an OR gate 124 with the output from the CRC check unit 117 so that rejection also occurs for all frames with $b > 2100$. If, of course a different range of values is used for $e(k)$ then a different threshold value will be appropriate.

10 We return now to the soft decision transformation unit 113. The soft decision inputs for the Viterbi decoder are produced by the channel equaliser 111. Ideally these inputs should be logarithmically inversely proportion to the likelihood of a bit error having occurred, or, in other words, directly proportional to $\log \frac{1 - P_e}{P_e}$

where P_e is the probability of an error in the bit in question. Tests show however
15 that this is not always the case. The method for testing a channel is as follows:

- (a) transmit test data
- (b) record the received data and associate confidence measures $e(k)$
- (c) compare the received data with the original to determine which bits are in error
- 20 (d) for each value of $e(k)$ (from 0 to 127), count the number of bits N received with that measure and the number of bits n actually in error; compute $P_e = n/N$ and hence

$$\epsilon = \log \frac{1 - P_e}{P_e}. \text{ Figure 11 shows a typical plot of } \epsilon \text{ against } e. \text{ As is seen,}$$

25 this deviates significantly from a straight line. The Viterbi algorithm produces the best results when true log likelihoods of error are used. This is because it operated by adding these values to obtain accumulated distance metrics, which is not equivalent to taking the products of the error probabilities (which is what is really required) unless a logarithmic relationship is adhered to.

30 Thus the purpose of the transformation unit 113 is to provide a correction for this nonlinear characteristic. It is implemented as a look-up table having 128



locations accessed using e as the address. The contents of the lookup table are the values of e in Figure 11, i.e.

for $e = 0$ to 127:

$\epsilon(e) = \{$

5	0,	1,	2,	3,	5,	7,	9,	11,	13,	15,
	18,	20,	23,	25,	27,	30,	32,	35,	37,	39,
	42,	44,	47,	48,	51,	52,	55,	57,	59,	61,
	63,	65,	67,	69,	70,	72,	74,	77,	77,	79,
	82,	81,	85,	86,	89,	87,	92,	91,	95,	95,
10	96,	94,	95,	107,	107,	112,	109,	115,	108,	106,
	114,	119,	114,	107,	127,	110,	105,	126,	126,	126,
	117,	127,	127,	127,	125,	127,	125,	127,	127,	127,
	124,	115,	127,	127,	127,	127,	123,	127,	127,	127,
	127,	127,	127,	127,	127,	127,	127,	127,	127,	127,
15	127,	127,	127,	127,	127,	127,	127,	127,	127,	127,
	127,	127,	127,	127,	127,	127,	127,	127,	127,	127,
	127,	127,	127,	127,	127,	127,	127,	127,	127,	127,

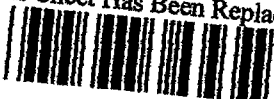
It should be noted that this mapping needs to suit the channel equaliser in use: in general each equaliser will have its own characteristics and therefore the contents of the look-up table need to be based on tests performed - as described above - on that particular design. If desired, the system may be made adaptive with transmissions including a known test sequence which may be analysed at intervals using the above-described method and the results used to update the contents of the look-up table.

**CLAIMS**

1. A method of decoding signals by processing received signals to provide
5 confidence measure signals and using a soft decision decoder to decode the
received signals, the method comprising:
- (a) receiving known signals;
 - (b) storing data representing the extent to which the confidence
10 measure signals for the received known signals differ from a logarithmic
representation of the error statistics of the received known signals;
 - (c) receiving unknown signals;
 - (d) applying correction factors to the confidence measure signals for the
received unknown signals, the correction factors being derived from the
said stored data, so as to reduce the extent to which the confidence
15 measures differ from the said logarithmic representation;
 - (e) decoding the corrected signals using the soft decision decoder.
2. A method according to Claim 1 including:
- forming a sum of the confidence measure signals for a frame period
20 of the signal; and
 - comparing the sum with a threshold value to provide a signal indicating
the quality of the frame.
3. A method of decoding signals comprising:
- 25 processing received digital signals to provide confidence measure signals;
 - forming a sum of the confidence measure signals for a frame period of the
signal; and
 - comparing the sum with a threshold value to provide a signal indicating
the quality of the frame.

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4. A method according to Claim 2 or Claim 3 including, in response to the said signal indicating the quality of the frame, suppressing further processing of those frames which are of a lower quality than that determined by the said
5 threshold.

5. An apparatus for decoding signals comprising:
means for processing received digital signals to provide confidence
measure signals;

10 translation means operable to apply correction factors to the confidence
measure signals so as to reduce the extent to which the confidence measure
signals differ from a logarithmic representation of the error statistics of the
received signals; and

a soft decision decoder to decode the corrected signals.

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6. An apparatus according to Claim 5 in which the correction factors are
derived from tests performed by :

(a) receiving known signals;

(b) storing data representing the extent to which the confidence
20 measure signals for the received known signals differ from a logarithmic
representation of the error statistics of the received known signals.

7. An apparatus according to Claim 5 or Claim 6 including:

25 means to form a sum of the confidence measure signals for a frame period
of the signal; and

means to compare the sum with a threshold value to provide a signal
indicating the quality of the frame.

8. An apparatus for decoding signals comprising:

30 means for processing received digital signals to provide confidence
measure signals;

means to form a sum of the confidence measure signals for a frame period
of the signal; and





means to compare the sum with a threshold value to provide a signal indicating the quality of the frame.

9. An apparatus according to Claim 7 or Claim 8 including means operable in
5 response to the said signal indicating the quality of the frame to suppress further processing of those frames which are of a lower quality than that determined by the said threshold.
10. A method of transmitting data bits comprising, for each of successive
10 frame periods, formatting the bits into a frame sequence, and coding the bits by means of a convolutional coder, including generating error check bits which are a function of (a) bits formatted into the beginning of the frame sequence and (b) bits formatted into the end of the frame sequence.
- 15 11. A method according to Claim 10 in which the bits (a) are taken from the first 50% of the frame and the bits (b) are taken from the last 25% of the frame.
12. An apparatus for transmitting data bits comprising:
means for formatting the bits into a frame sequence;
20 means for convolutional coding; and
means for generating error check bits which are a function of (a) bits formatted into the beginning of the frame sequence and (b) bits formatted into the end of the frame sequence.
- 25 13. An apparatus according to Claim 12 wherein the bits are taken from the first 50% of the frame and the bits are taken from the last 25% of the frame.
14. Apparatus for the decoding of digital signals substantially as herein described with reference to the accompanying drawings.

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