

ABSTRACT

The present invention relates to a walking type intelligent robot cleaning device and, more particularly, a walking type intelligent robot cleaning device that can very simply and intelligently take away various wastes on roads through an automatic or manual mode while running in step with a worker, that allows a worker to manually clean up small spaces or corners while walking, especially, to efficiently clean up the spaces that street sweeper trucks have difficulty in reaching such as walkways, parks, and side streets, and that makes it possible to save fuel and reduce noise and carbon by being operated by electricity.

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