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(71) Applicant: SUPERCRITICAL SYSTEMS, INC. [—/US]; 4160-A Technology Drive, Fremont, CA 94538 (US).

(72) Inventors: BIBERGER, Maximilian, A.; 737-6 Loma Verde Avenue, Palo Alto, CA 94303 (US). LAYMAN, Frederick, Paul; 433 Miwok Court, Fremont, CA 94539 (US). SUTTON, Thomas, Robert; 1790 Chevalier Drive, San Jose, CA 95124 (US).

(74) Agents: HAVERSTOCK, Thomas, B. et al.; Haverstock & Owens LLP, Suite 420, 260 Sheridan Avenue, Palo Alto, CA 94306 (US).

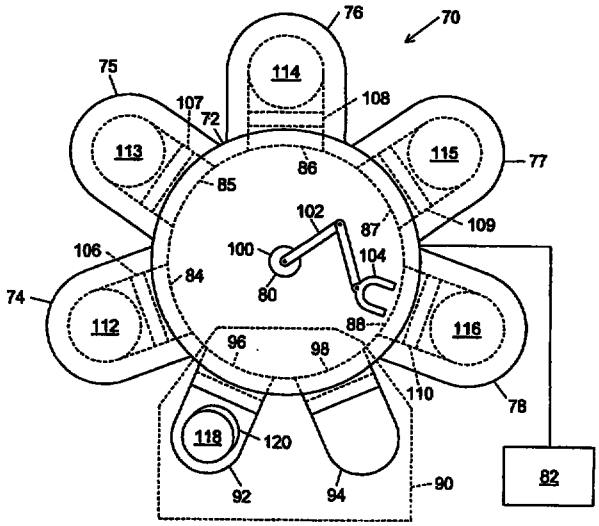
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(54) Title: METHOD AND APPARATUS FOR SUPERCRITICAL PROCESSING OF MULTIPLE WORKPIECES



(57) Abstract: An apparatus for supercritical processing of multiple workpieces comprises a transfer module, first and second supercritical processing modules, and a robot. The transfer module includes an entrance. The first and second supercritical processing modules are coupled to the transfer module. The robot is preferably located with the transfer module. In operation, the robot transfers a first workpiece from the entrance of the transfer module to the first supercritical processing module. The robot then transfers a second workpiece from the entrance to the second supercritical processing module. After the workpieces have been processed, the robot returns the first and second workpieces to the entrance of the transfer module. Alternatively, the apparatus includes additional supercritical processing modules coupled to the transfer module.

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