

Abstract

Method and Device for Determining and Representing
Possible Target Parameters

The invention relates to a method for determining and representing possible target parameters, in particular of a target distance R , a target course C and/or a target speed V of a target. For this purpose, a plurality of different target tracks $Z(i, j)$ having associated quality information are determined from the possible solutions during each processing cycle of an optimization method that is applied. Future target positions (25), which together with the quality information form a future expectation area (42), are determined for said target tracks $Z(i, j)$. In addition, a distance solution space (34) and a vector indicating the best solution Z_{best} is determined from the possible solutions. The future expectation area (42), the distance solution space (34) and/or the best solution Z_{best} can then be represented in a single solution space in the form of a position representation on a display device (27).