

Abstract

The purpose of the present invention is to avoid obstacles appropriately. This control method for controlling a moving body that moves automatically comprises: a step for moving a moving body along a reference path; a step for causing a sensor provided on the moving body to detect an obstacle located on the side toward a first direction, which is the traveling direction of the moving body, while the moving body is moving along the reference path; a step for stopping the moving body if an obstacle exists on the side toward the first direction; a step for setting a retreat path for returning in a second direction opposite to the first direction, on the basis of the reference path; and a step for moving the stopped moving body along the retreat path.