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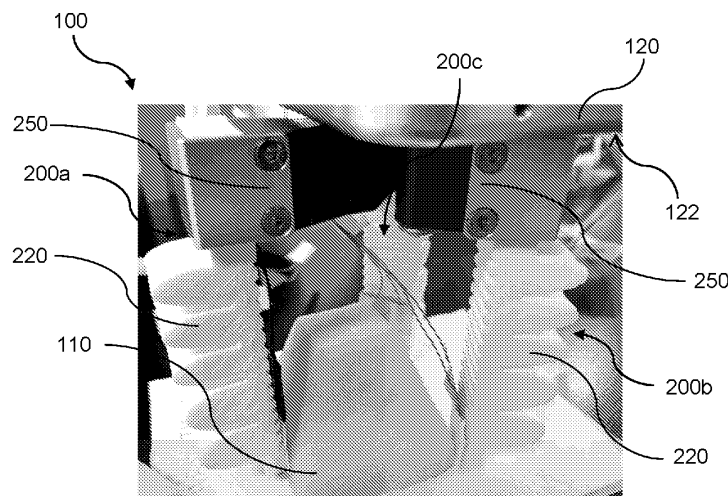


Figure 1A

(57) Abstract: A robotic gripper and a method for configuring the robotic gripper thereof is disclosed. The robotic gripper comprises a body, a plurality of displacement mechanisms, a plurality of finger modules removably connected or connectable to the body, such that each finger module engages with a respective displacement mechanism, each finger module comprising a finger actuator cooperative with the other finger actuators for gripping an object and each displacement mechanism is configured for moving the respective finger module to adjust its arrangement on the body, thereby configuring the robotic gripper for gripping the object. A method for handling objects with the robotic gripper is also disclosed. A method of manufacturing a product comprising the robotic gripper via additive manufacturing is also disclosed. Such robotic gripper can be used in food picking and packaging for automation process.

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