

ABSTRACT

MARKING ROBOT SYSTEM AND METHOD FOR CONTROLLING MARKING ROBOT
SYSTEM

5 A marking robot system is configured to include a marking
robot performing mark printing on the basis of marking
information using a printer, a tracking-type three-dimensional
measurement device measuring a position of the marking robot,
and a control operation unit controlling the marking robot. The
10 marking information stored in the marking robot is composed of
basic marking information and editable information corresponding
to the basic marking information. The control operation unit
displays an editing screen for editing the editable information
on the basis of the marking information, and an operator operates
15 the editing screen. The control operation unit generates
customized marking information on the basis of an operation
result and transmits the customized marking information to the
marking robot. The marking robot performs the mark printing on
the basis of the customized marking information.

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Figure 1.