

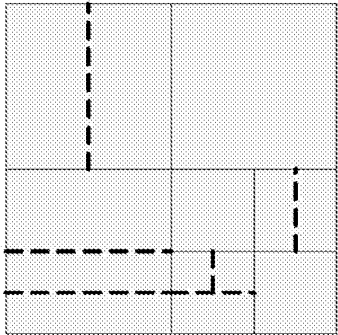


FIG. 1A

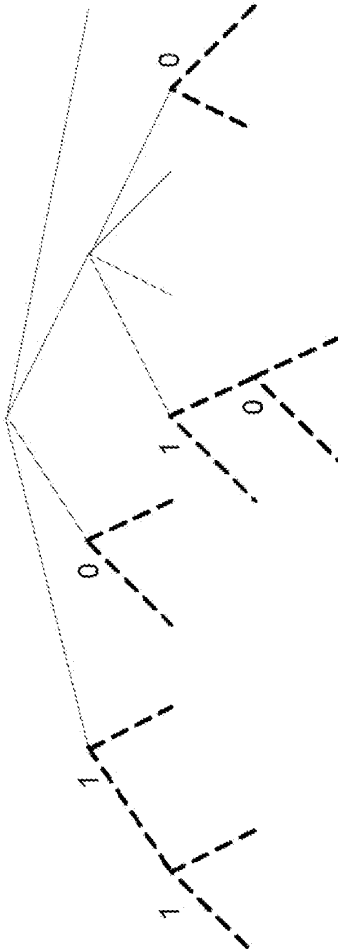
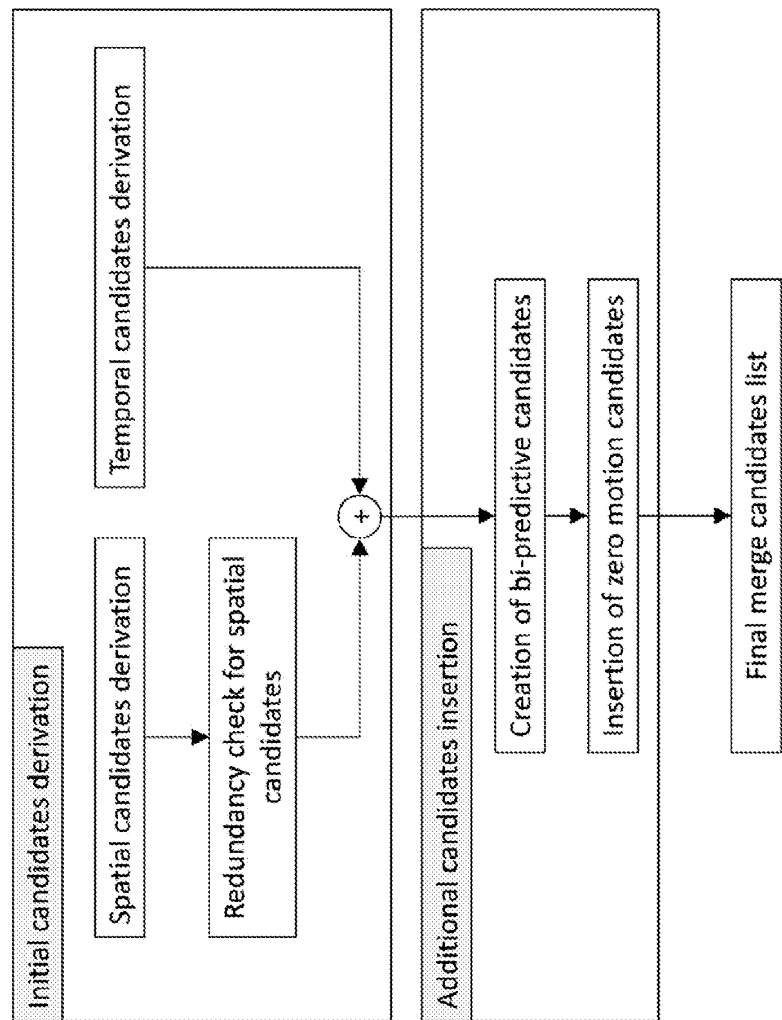


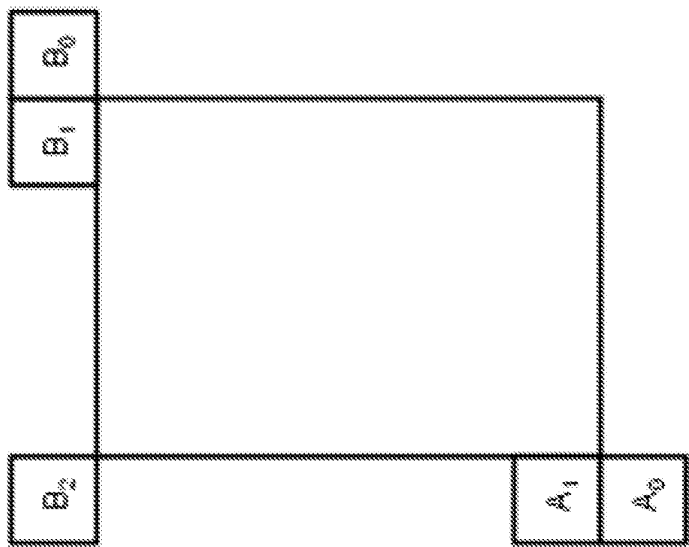
FIG. 1B

Illustration of a QTT structure



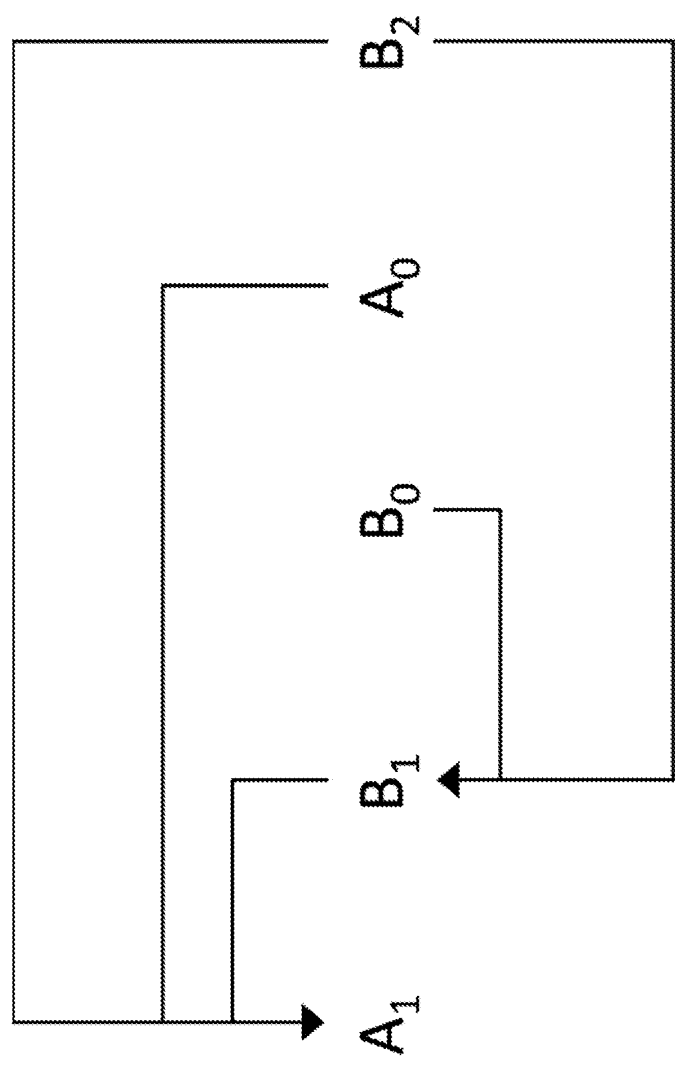
Derivation process for merge candidates list construction.

FIG. 2



Positions of spatial merge candidates

FIG. 3



Candidate pairs considered for redundancy check of spatial merge candidates

FIG. 4

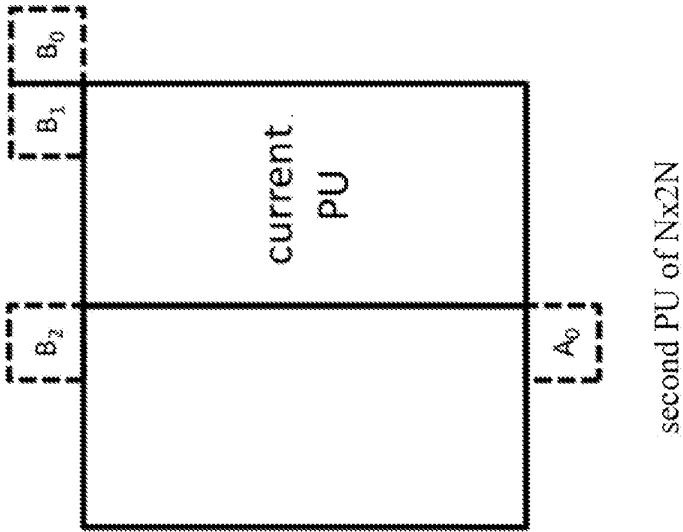


FIG. 5A

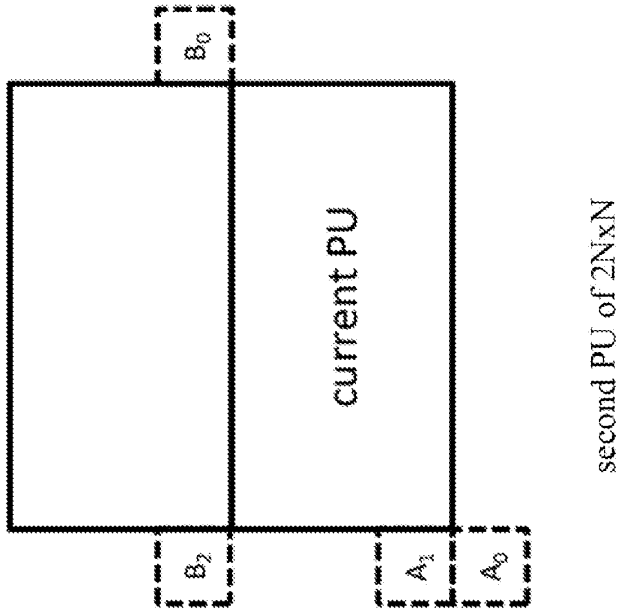


FIG. 5B

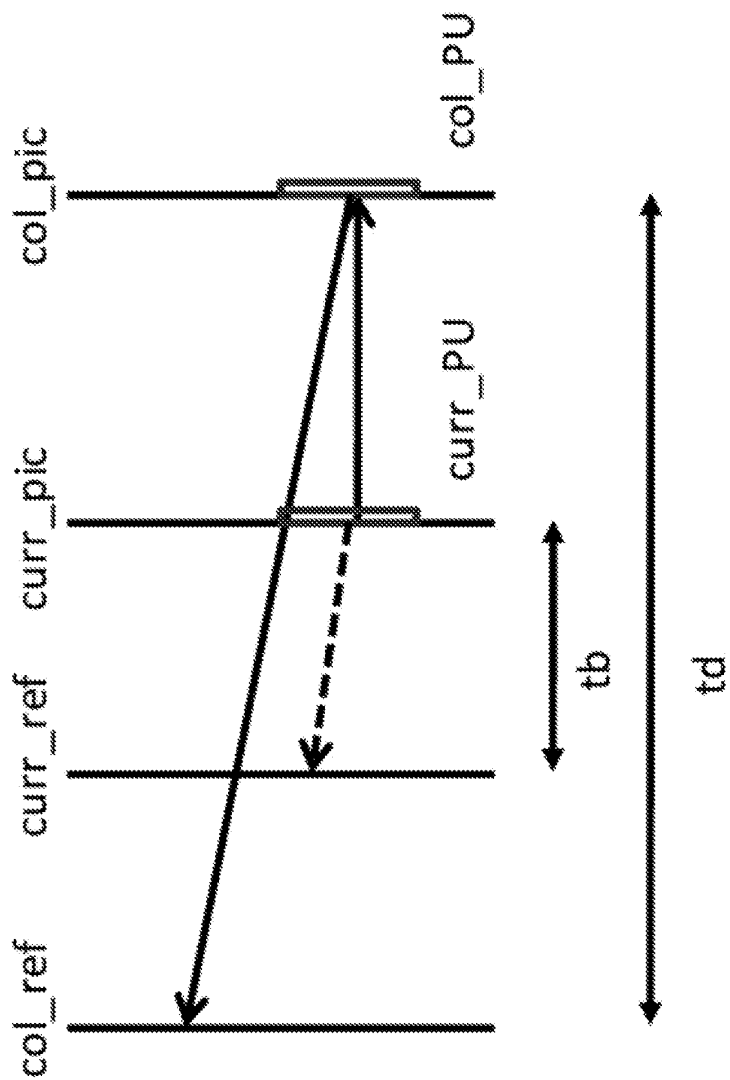
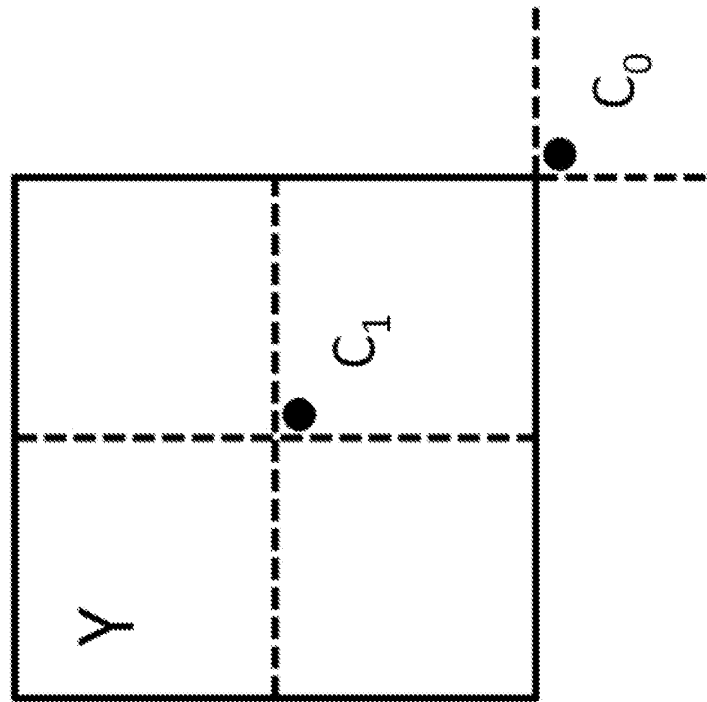


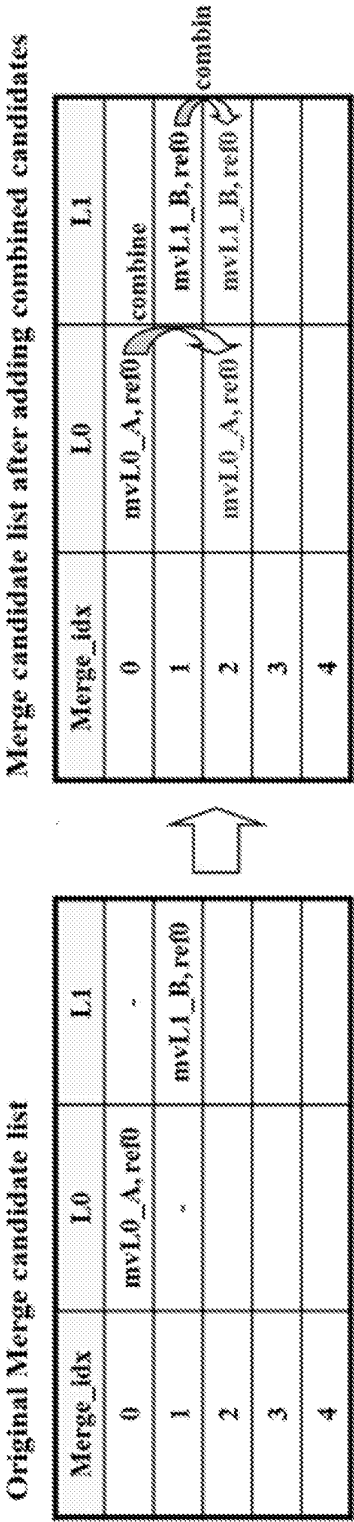
Illustration of motion vector scaling for temporal merge candidate

FIG. 6



Candidate positions for temporal merge candidate, C0 and C1

FIG. 7



Example of combined bi-predictive merge candidate

FIG. 8

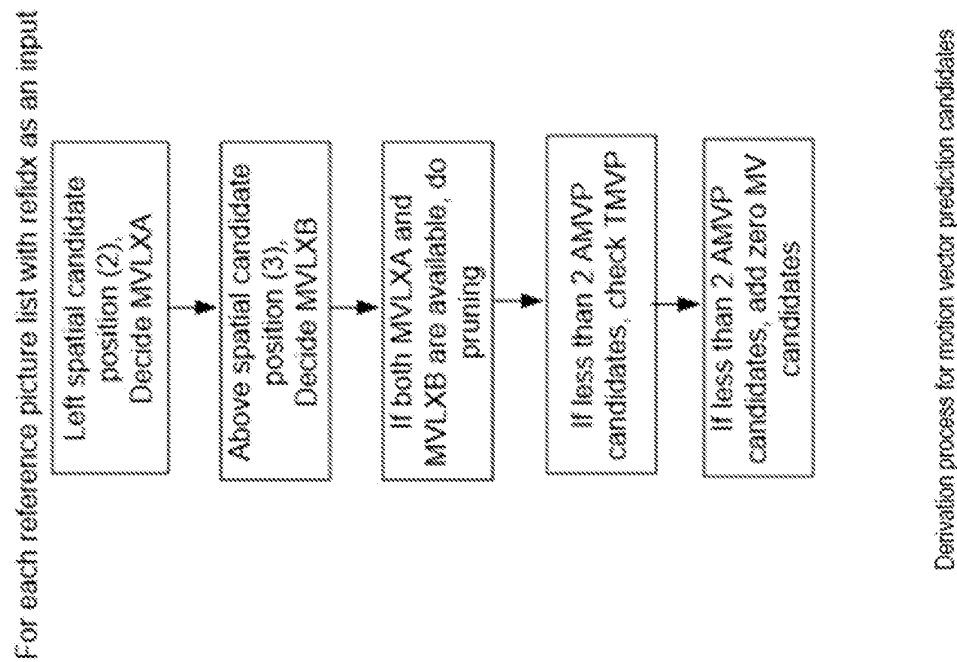


FIG. 9

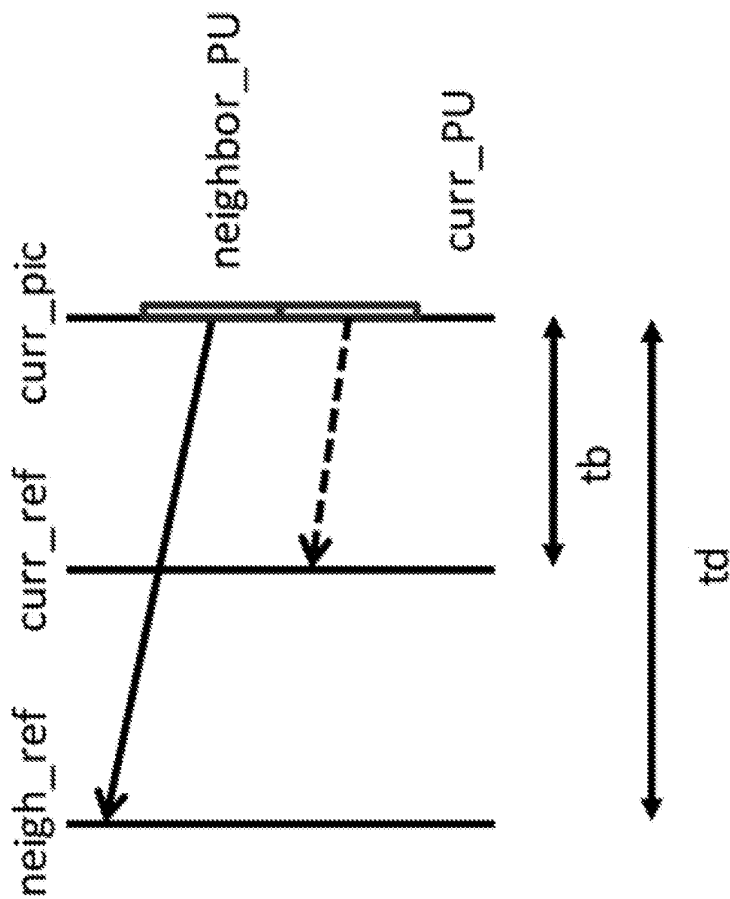


Illustration of motion vector scaling for spatial motion vector candidate

FIG. 10

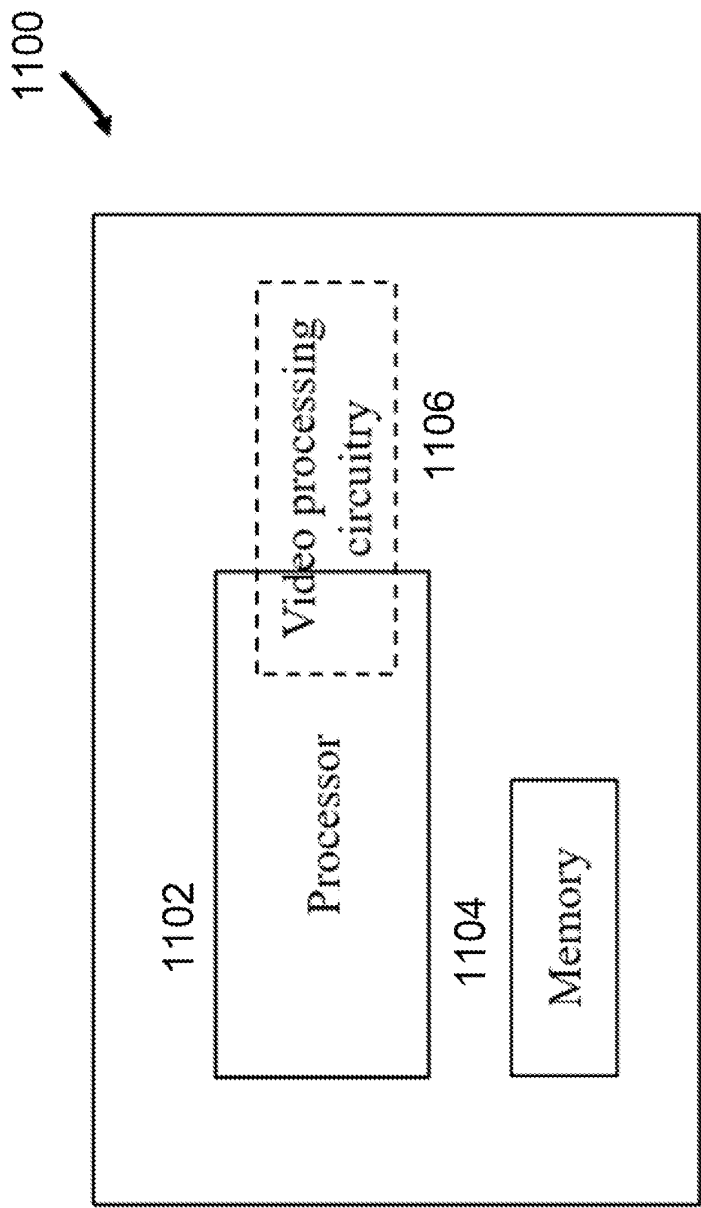


FIG. 11A

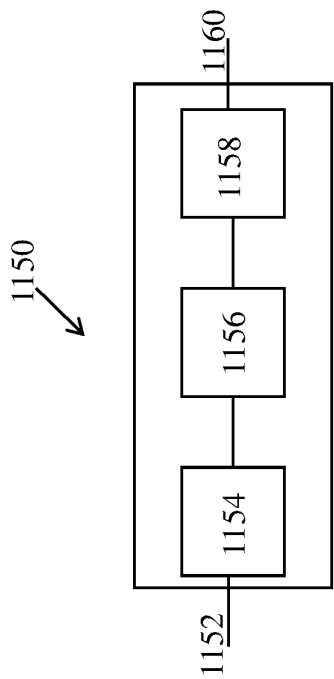
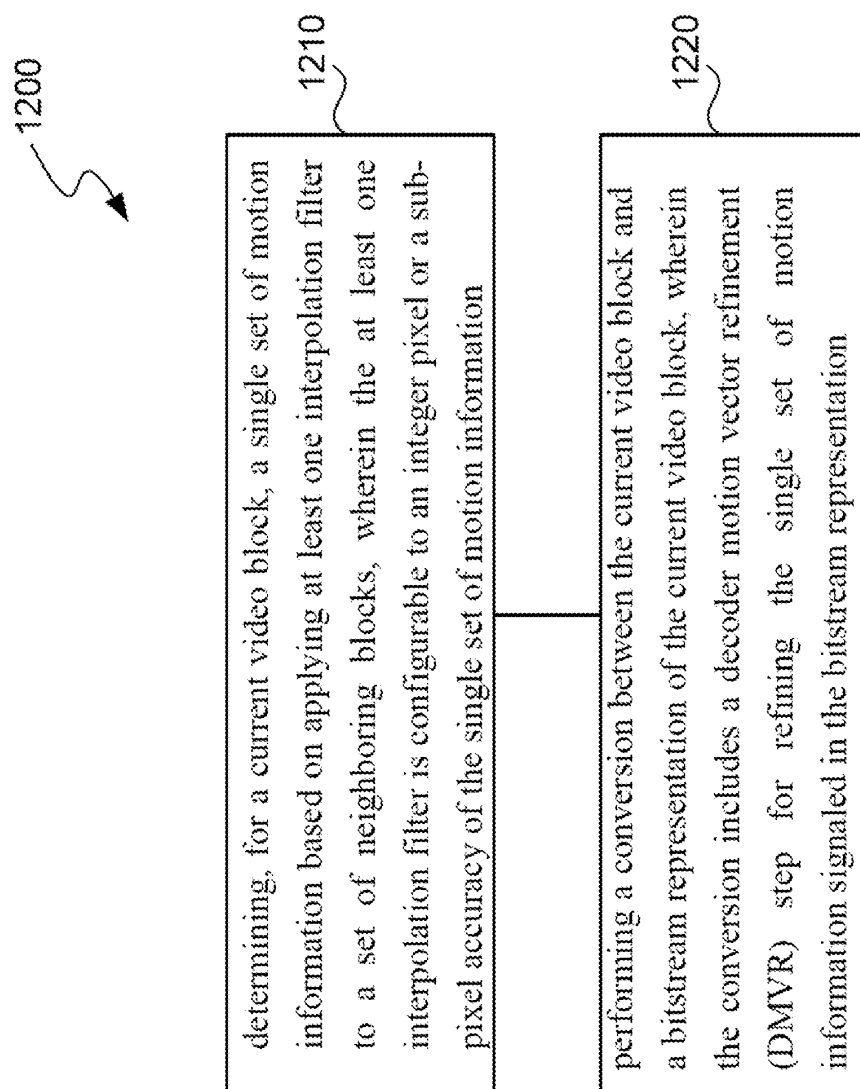


FIG. 11B

**FIG. 12**

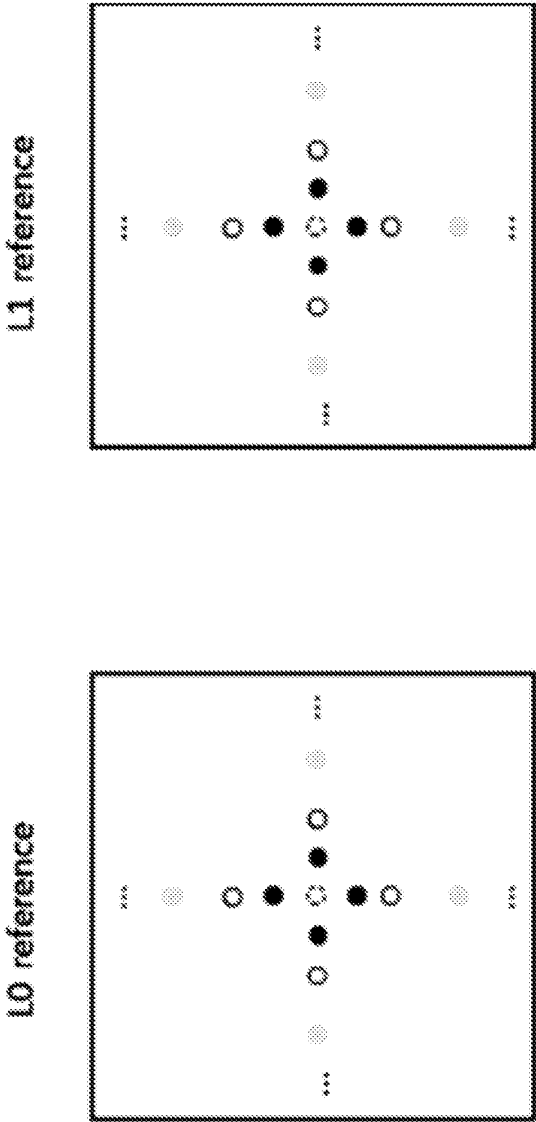


FIG. 13

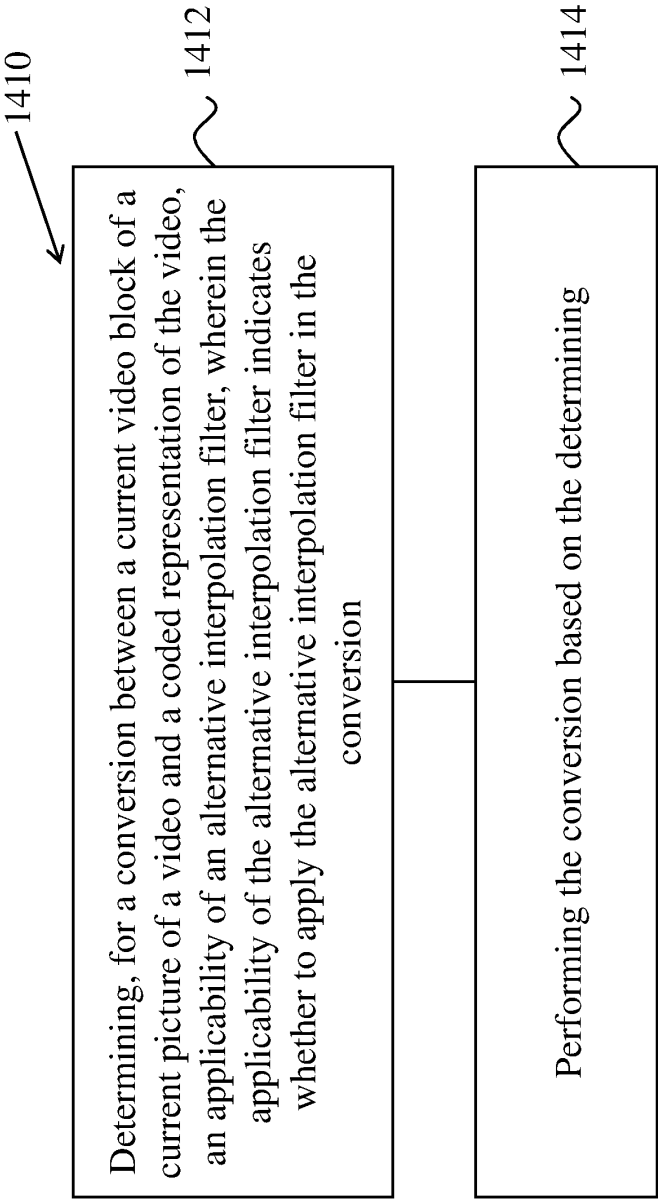


FIG. 14A

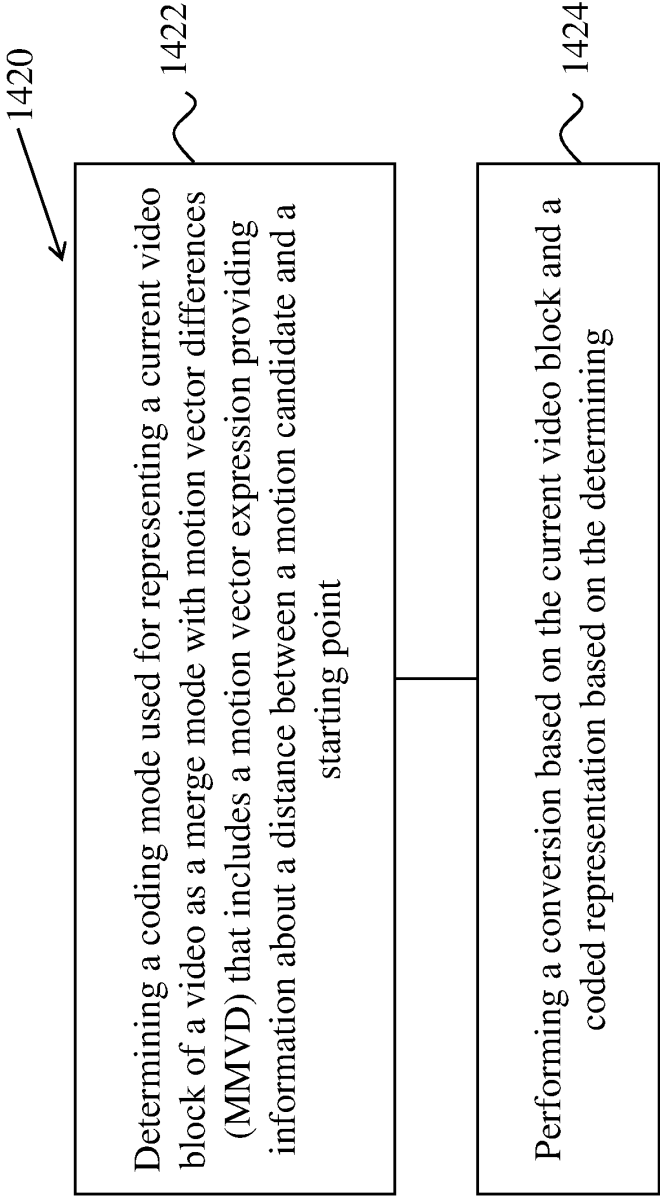


FIG. 14B

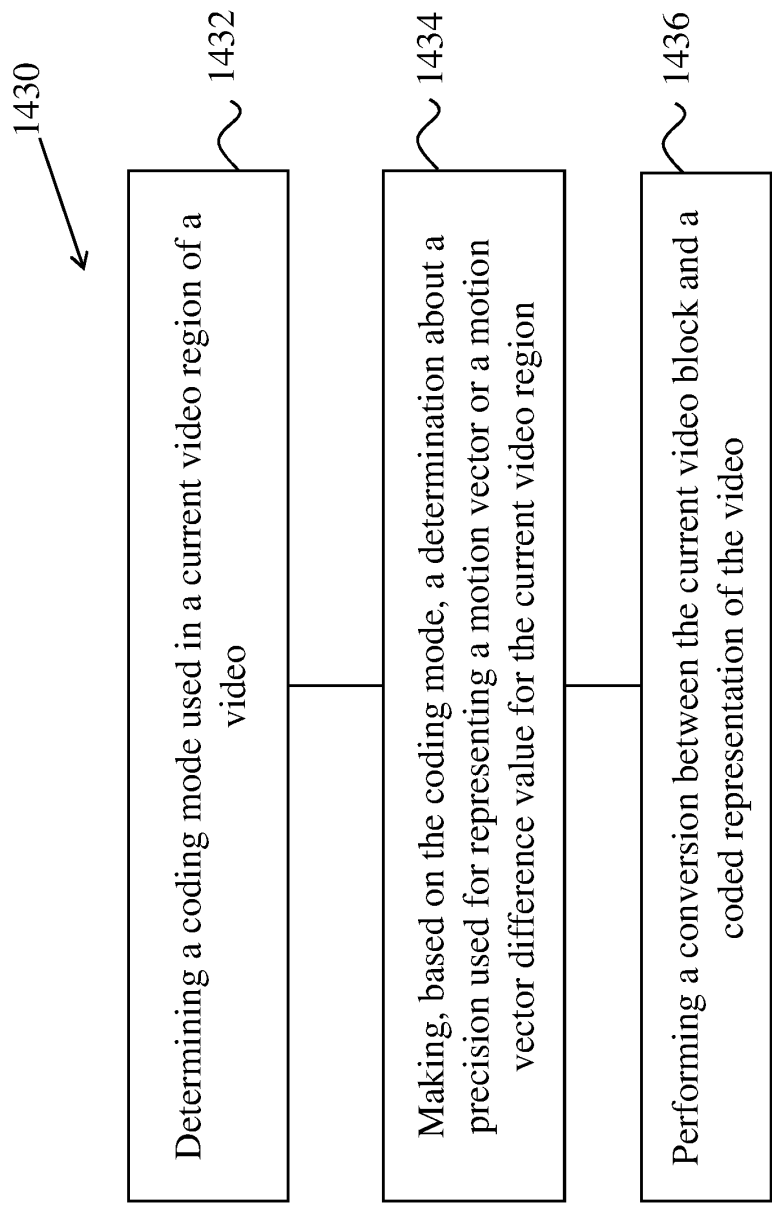


FIG. 14C

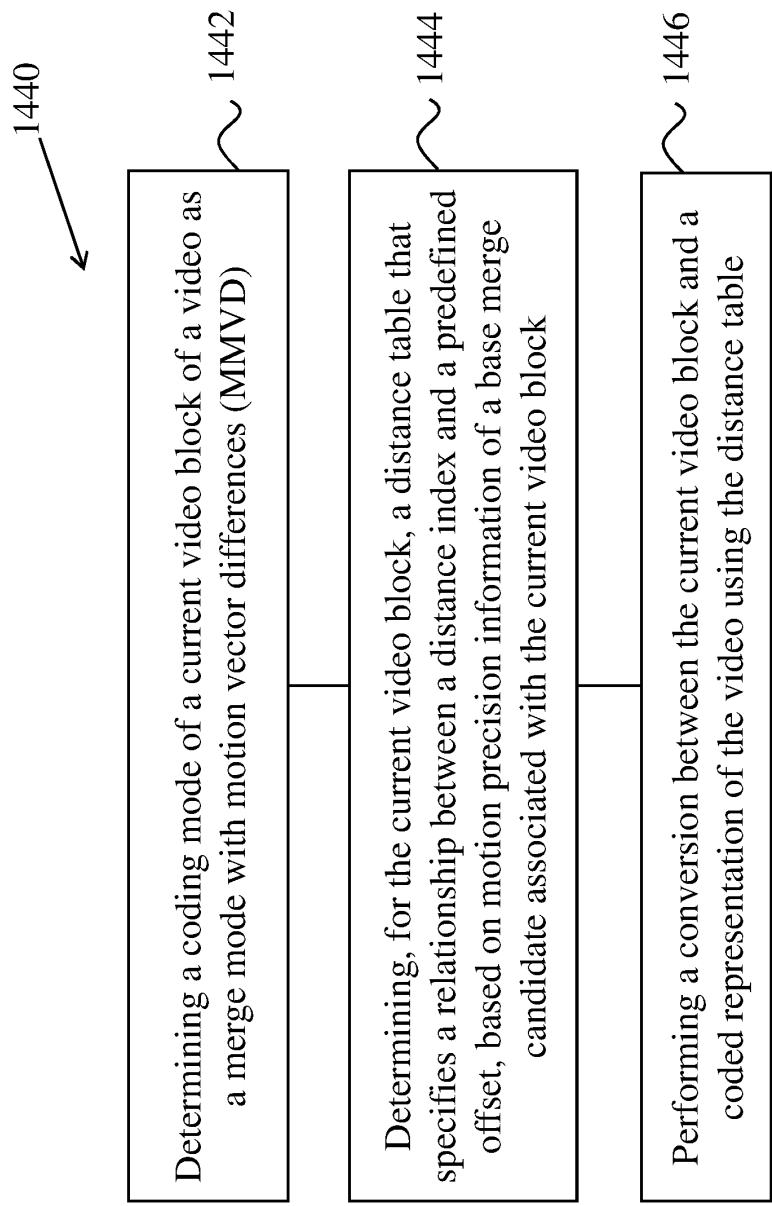
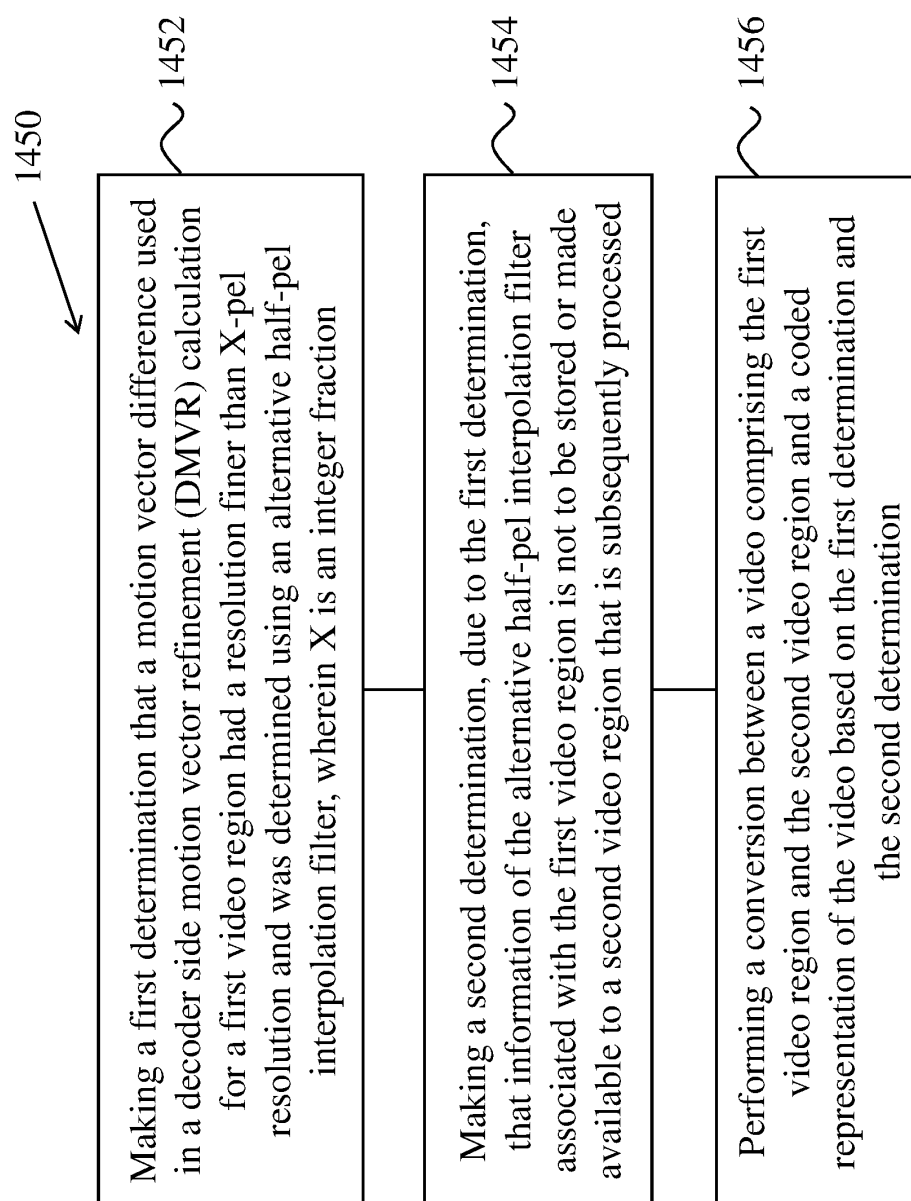


FIG. 14D

**FIG. 14E**

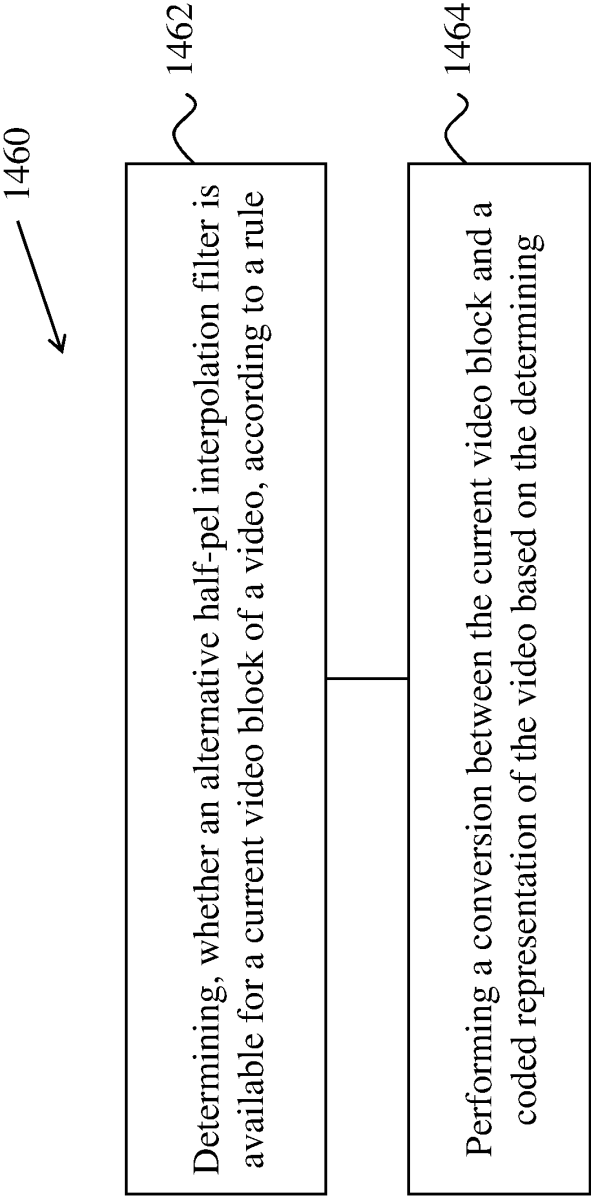


FIG. 14F

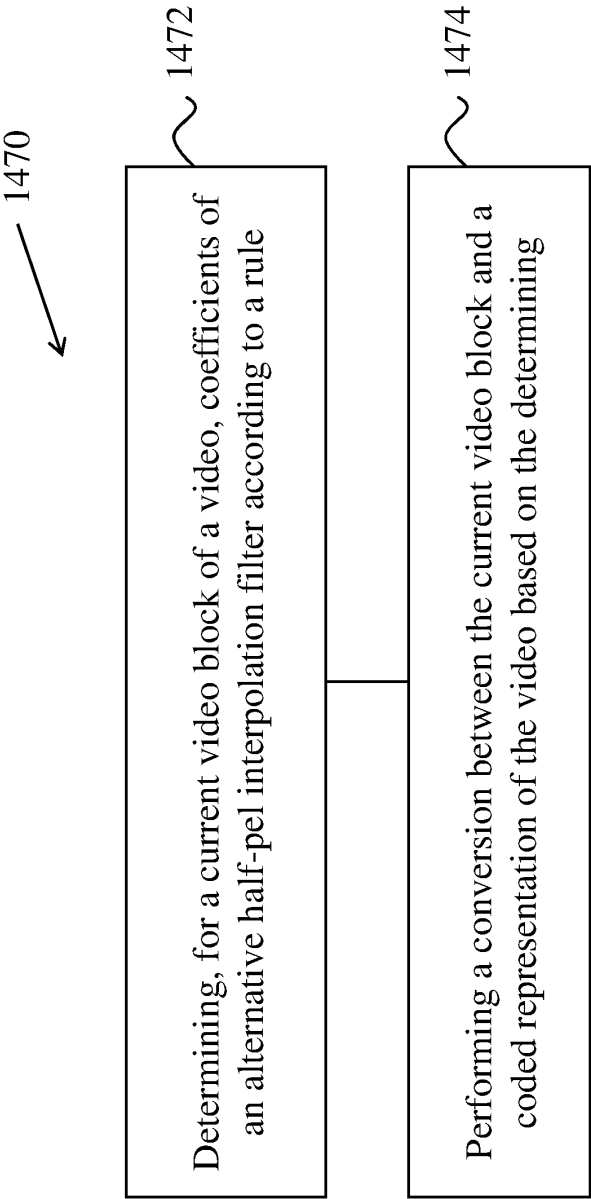


FIG. 14G

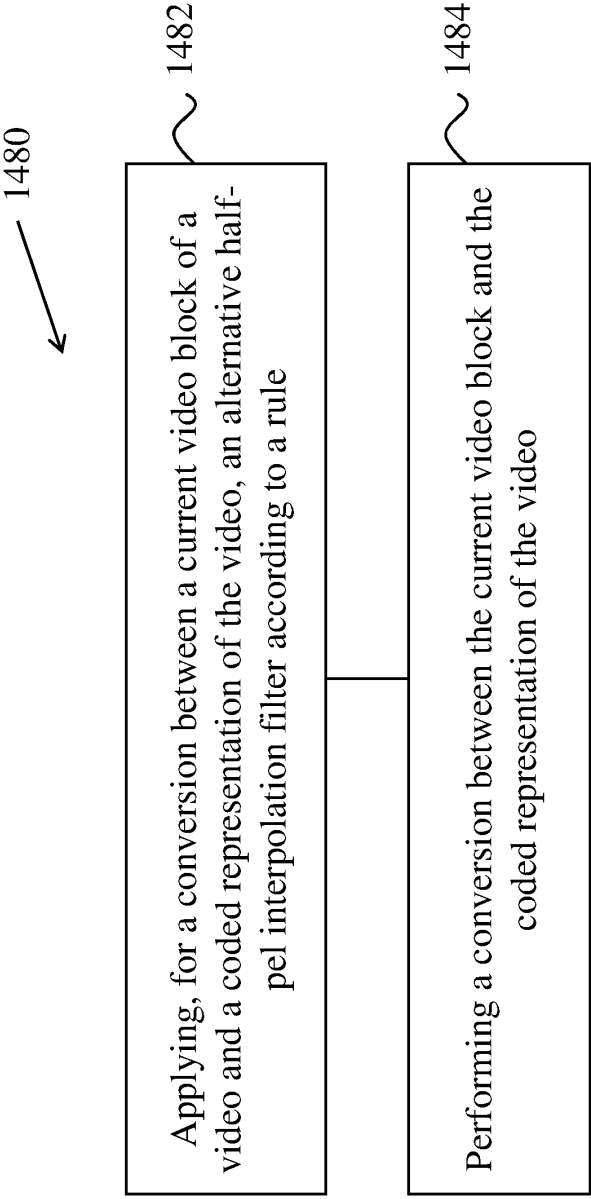


FIG. 14H

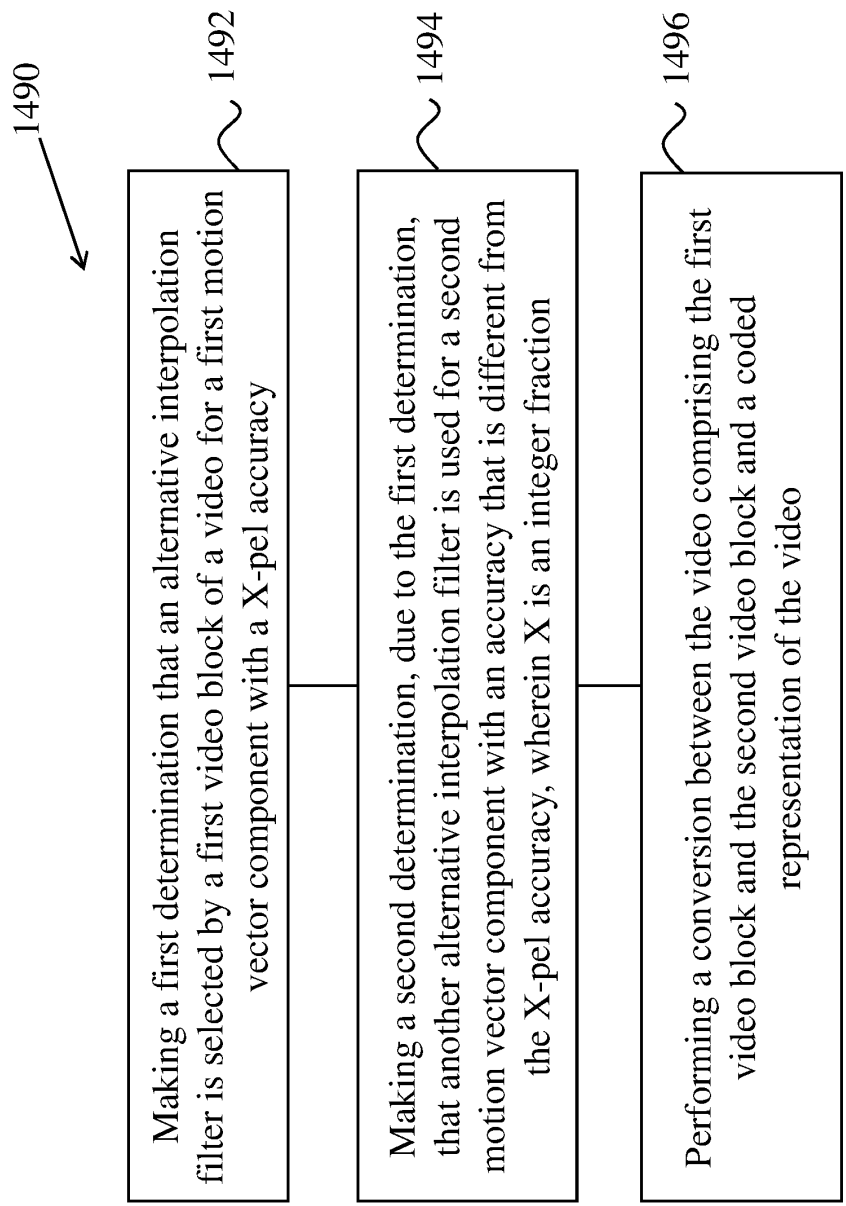


FIG. 14I