

Apparatus and Method to Transform an Audio Stream

Description

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Embodiments of the present invention refer to an apparatus for transforming an audio stream with more than one channel into another representation. Further embodiments refer to a corresponding method and to a corresponding computer program.

10 Further embodiments refer to an apparatus for transforming an audio stream in a directional audio coding system. Further embodiments refer to a corresponding method and computer program.

Additional embodiments refer to an encoder comprising one of the above-defined
15 apparatuses into a corresponding method for encoding as well as to a decoder comprising one of the above-discussed apparatuses and a corresponding method for decoding. Preferred embodiments refer in general to the technical field of compression of audio channels by a prediction based on acoustic model parameters. Relevant prior art for the embodiments mainly comes from two previously known audio coding schemes:

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- Directional Audio Coding (DirAC); and
- A metadata-assisted EVS codec for spatial audio that was presented in the context of the 3GPP standards organization

25 Both concepts will be summarized briefly:

Directional Audio Coding

DirAC is a parametric technique for the encoding and reproduction of spatial sound fields [1, 2, 3, 4]. It is justified by the psychoacoustical argument that human listeners can only
30 process two cues per critical band at a time [4]: the direction of arrival (DOA) of one sound source and the inter-aural coherence [4]. Consequently, it is sufficient to reproduce two streams per critical band: a directional one comprising the coherent channel signals from one point source from a given direction and a diffuse one comprising incoherent diffuse signals [4].

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The analysis stage on the encoder side is depicted in the diagram of Fig. 1a. Fig. 1 shows an encoder claim having at the input side a bandpass filter 11 and two entities 12 and 13 for determining the energy and intensity. Based on the energy and intensity a diffuseness is determined by the diffuseness determiner 14 which may, for example, use a temporal averaging. The output of the diffuseness determiner 14 is ϕ . Based on the intensity a direction (Azi and Ele) is determined by the direction determiner 15. The information ϕ , Azi and Ele are output as metadata.

The input is provided in the form of four B-format channel signals and analyzed with a filter bank (FB). For each band of this FB, the DOA of the point source and the diffuseness are extracted [3, 4]. These two parameters in each band, the DOA represented by the azimuth and elevation angles and the diffuseness, comprise the DirAC metadata [3, 4], whose efficient compression has been treated in Ref. [3, 4, 5].

As it is shown by Fig. 1b, the two aforementioned streams are synthesized from the B-format signal and the metadata. The decoder 20 comprises a processor path 21 for processing the metadata ψ and a processing path 22 for processing the metadata Azi and Ele. Furthermore, the decoder 20 comprises a processing path 23 including bandpass filter and virtual microphones for processing the B-format signal (cf. Mic signal (W, X, Y, Z)). All the three processing paths 21-23 are then combined by the entity 24 including a decorrelator so as to output the loudspeaker channel signals. When decoding two loudspeakers is desired the directional stream can be obtained by panning a point source to the direction encoded in the DirAC parameters [3, 4] e.g. using vector-based amplitude panning (VBAP) [6]. For the diffuse stream decorrelated signals must be fed to the loudspeakers [4].

Fig. 2 shows a DirAC encoder from (5). Same comprises a DirAC analysis 31 and a subsequent spatial metadata encoder 32. The DirAC analysis processes the B-format so as to output the diffuseness and direction parameter to the spatial meta encoder 32. In parallel the B-format is performed by an entity for beamforming/signal selection (cf. reference numeral 33). The output of the entity 33 is then processed by the EVS encoder 34. Fig. 3 shows the corresponding DirAC decoder. The DirAC decoder of Fig. 3 comprises a spatial metadata decoder 41 and an EVS decoder 42. Both decoded signals are then used by the DirAC synthesis 43 so as to output the loudspeaker channels or FOA/HOA.

An extension of this system to higher-order Ambisonics (HOA) together with multi-channel (MC) or object based audio has been presented by Fuchs et al. [5]. There, the authors

propose to perform additional processing of the B-format input signal in order to select suitable downmix channels or find suitable beams of virtual microphones to capture the transport streams as depicted in Fig. 2, numeral 33. These transport streams are then encoded using an EVS encoder. On the decoder side, the corresponding decoder is applied. The signal paths in the encoder and decoder can be seen in Figs. 2 and 3. In addition, a sophisticated encoding scheme (cf. 32 in Fig. 2) is presented to ensure the transmission of the metadata at the lowest possible bitrate without any perceptible quality loss [5]. In contrast to the system of Ref. [2], the decoder output signal can be generated in HOA format again such that an arbitrary renderer can be employed to obtain the headphone or loudspeaker signals.

Hence, the stream of data transmitted from the encoder to the decoder must contain both the EVS bitstreams and the DirAC metadata streams and care must be taken to find the optimal distribution of the available bits between the metadata and the individual EVS-coded channels of the downmix.

Metadata Assisted EVS Codec

An alternative approach to the encoding and reproduction of spatial audio recordings that has previously been proposed in standards organizations is a metadata-assisted EVS coder [7]. It is also referred to as spatial audio reconstruction (SPAR) [7]. Fig. 4 shows the signal paths from the encoder input to the decoder output. Like DirAC, the SPAR encoder extracts metadata and a downmix from the FOA or HOA input signal [7]. This processing is performed in a FB domain [7] here too.

Fig. 4 shows a metadata assisted EVS coder for spatial audio as shown in [7]. The EVS coder 50 comprises a content ingestion engine 51 receiving the M objects, HOA scenes and channels so as to output the M objects together with the Nth order Ambisonics channels to a SPAR encoder 52. The SPAR encoder comprises downmix and WXYZ engine compaction transform. The SPAR metadata and FOA data are output together with the object metadata to the EVS and metadata encoder 53. This data stream is then processed by the mode switch 54 which distributes the high immersive quality data and low immersive quality data (SPAR metadata and object metadata together with FOA and prediction metadata) to the respective coders. The high immersive coder is marked by the reference numeral 55a and 55b, wherein the lower immersive coder is marked by the reference numeral 56a and 56b.

The downmix is performed in such a way that an energy compaction of the FOA signal is achieved (see Fig. 4) and then encoded using up to 4 instances of the EVS mono encoder. These steps are analogous to the beamforming or channel selection and EVS encoding steps in DirAC in Fig. 2. On the decoder side, the FOA signal is reconstructed from the compacted downmix channels and the metadata, which contain the predictor coefficients (PC) [7]. According to the pseudocode in Ref. [7], this is realized by a band-wise multiplication of a smaller number of channels by a gain matrix. HOA signals can also be reconstructed using the transmitted SPAR metadata [7]. The metadata stream is compressed for transport by Huffman coding [7].

Head Tracking in Spatial Audio Reproduction

When spatial sound scenes are to be reproduced on headphones, it is required to track the movement of the listeners head and rotate the sound scene accordingly in order to produce a consistent and realistic experience. To this end, a widely-adopted technique is to rotate the scene in the Ambisonics domain by pre-multiplication of a rotation matrix to the vector of channel signals [8, 9, 0]. This rotation matrix is typically computed by the method of Ref. [11]. An alternative approach is to render the output signal to virtual loudspeakers and perform the rotation by amplitude panning [9, 6].

All of the above-described solutions have drawbacks as will be discussed below. A remedy for these drawbacks is part of the invention.

In both of the systems referenced above, some of the key challenges are to (i) select the most well-suited channels of the input signal for the transport via EVS, (ii) find a representation of these channels that reduces redundancies between them, and (iii) distribute the available bitrate between the metadata and the individual EVS encoded audio streams such that the best possible perceptual quality is attained. As these decisions are highly dependent on the signal characteristics, signal-adaptive processing must be implemented.

It is an objective of the present invention to enable a coding approach, where the amount of additional metadata required to enable the reconstruction of the downmix channels is reduced, while the coding efficiency is increased.

An embodiment of the present invention provides an apparatus for transforming an audio stream with more than one channel into another representation. The apparatus comprises means for transforming and means for deriving and/or means for receiving. The means for transforming are configured to transform the audio stream in a signal-adaptive way
5 dependent on one or more parameters. The means for deriving are configured to derive the one or more parameters describing an acoustic or psychoacoustic model of the audio stream (signal). Note at the decoder side the prediction parameter can be received (cf. means for receiving). Said parameters comprise at least an information on D
OA (direction of arrival), where the one or more parameters may be derived from the audio
10 stream, e.g. at the encoder side (or just received, e.g. at the decoder side).

According to further embodiments, the means for deriving are configured to calculate prediction coefficients or to calculate prediction coefficients based on a covariance matrix
15 or on parameters of an acoustic signal.

According to embodiments, the means for deriving are configured to calculate a covariance matrix from the model/acoustic model or in general based on the DOA or an additional
diffuseness factor or an energy ratio.

20 It should be noted that according to embodiments the one or more parameters comprise prediction parameters.

Embodiments of the present invention are based on the principle that prediction coefficients on both the encoder and decoder side can be approximated from a model like an acoustic
25 model or acoustic model parameters. In directional audio coding systems, these parameters are always present at the decoder side and, consequently, no additional metadata bits are transmitted for the prediction. Thus, the amount of additional metadata required to enable the reconstruction of the downmix channels at the decoder side is strongly reduced as compared to the naïve implementation of prediction. Expressed in other words, this means
30 that the combination of deriving one or more parameters describing an acoustic model and transforming the audio stream in a signal adaptive way provides an approach to compress downmix channels in directional audio coding systems or other applications *via* the application of inter-channel prediction based on acoustic models of the input signal.

35 In the above-discussed embodiments, mainly a DOA parameter has been discussed. According to further embodiments, additionally a diffuseness information/diffuseness factor

may be used. Thus, said parameters used for the means for transforming and derived by the means for deriving may comprise an information on a diffuseness factor or on one or more DOAs or on energy ratios. For example, the one or more parameters are derived from the audio stream itself.

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Regarding the prediction coefficients, it should be mentioned that according to further embodiments, the prediction coefficients are calculated based on the real or complex spherical harmonics $Y_{l,m}$ with degree l and index m evaluated at angles corresponding to a DOA

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Regarding the covariance matrix, it should be noted that according to further embodiments, the means for deriving are configured to calculate a covariance matrix based on an information about diffuseness, spherical harmonics and a time-dependent scalar-valued signal. For example, the calculation may be based on the following formula:

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$$C_{x/y/z,w} = \int dt s^2(t) Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

where $Y_{l,m}$ is a spherical harmonic with the degree and index l and m and where $s(t)$ is a time-dependent scalar-valued signal.

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According to further embodiments, the calculation may be based on a signal energy, for example, by using the following formula:

$$C_{x/y/z,w} = (1 - \Psi) E Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

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where E describes the signal energy.

Alternatively or additionally, the following formula may be used:

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$$C_{w,w} = (1 - \Psi) E Y_{0,0}(\theta_D) Y_{0,0}(\theta_D) + \Psi E$$

where E is again the signal energy.

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Alternatively or additionally, the following formula may be used:

$$C_{x,x} = (1 - \Psi) E Y_{1,-1}(\theta_D) Y_{1,-1}(\theta_D) + \frac{\Psi}{3} E$$

and analogously for the y and z channels .

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According to embodiments, the energy E is directly calculated from the audio stream (signal). Alternatively or additionally, the energy E is estimated from the model of the signal.

10 According to further embodiments, the audio stream is preprocessed by a parameter estimator or a parameter estimator comprising as metadata encoder or metadata decoder and/or by an analysis filterbank.

15 According to further embodiments, the input audio stream is a higher-order Ambisonics signal and the parameter estimation is based on all or a subset of these input channels. For example, this subset can comprise the channels of the first order. Alternatively it can consist of the planar channels of any order or any other selection of channels.

20 As discussed above, embodiments provide an encoder comprising the above-discussed apparatus. Further embodiments provide a decoder comprising the above-discussed apparatus. On the encoder side, the apparatus may comprise means for transforming which are configured to perform a mixing, e.g. a downmixing of the audio stream. On the decoder side, the means for transforming are configured to perform a mixing, e.g. an upmixing or an upmix generation of the audio streams.

25 The above-discussed apparatus may also be used for transforming an audio stream in a directional audio coding system. According to embodiments, the apparatus comprises means for transforming and means for deriving. The means for transforming are configured to transform the audio stream in a signal-adaptive way dependent on one or more acoustic model parameters. The means for deriving are configured to derive the one or more acoustic model parameters of a model of the audio stream (parametrized by the DOA and/or the diffuseness and/or energy-ratio parameter). Said acoustic model parameters are transmitted to restore all channels of the audio stream and comprise at least an information on DOA. The transmitted audio streams are derived by transforming all or a subset of the channels of the audio stream. According to embodiments, the transmitted parameters are
30 quantized prior to transmission. According to embodiments, the parameters are
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dequantized after transmission. According to further embodiments, the parameters may be smoothed over time. According to further embodiments the quantized parameters may be compressed by means of entropy coding.

- 5 Regarding the transform, it should be noted that according to further embodiments, the transform is computed such that correlations between transport channels are reduced. According to embodiments, the inter-channel covariance matrix of an input of the audio stream is estimated from a model of the signal of the audio stream. For example, a transform matrix is derived from a covariance matrix of a model of the audio stream signal. The
- 10 covariance matrix may be calculated using different methods for different frequency bands. Regarding the transformation performed by the means for transforming, it should be noted that according to an embodiment at least one of the transform methods is multiplication of the vector of the audio channels by a constant matrix. According to another embodiment, the transform methods use prediction based on the inter-channel covariance matrix of an
- 15 audio signal vector. According to another embodiment at least one of the transform methods uses prediction based on the inter-channel covariance matrix of the model signal described by DOAs and/or diffuseness factors and/or energy ratios.

According to another embodiment, and mainly applicable for the apparatus for transforming

20 an audio stream in a directional audio coding system, the scene encoded by the audio stream (signal) is rotatable in such a way that

- a vector of audio transport channel signals is pre-multiplied by a rotation matrix;
- model parameters are transformed in accordance with the transform of a
- 25 transport channel signal; and
- non-transport channels of an output signal are reconstructed using the transformed model parameters.

As discussed above, the apparatus may be applied to an encoder and a decoder. Another

30 embodiment provides a system comprising an encoder and a decoder. The encoder and the decoder are configured to calculate a prediction matrix and/or a downmix and/or upmix matrix from the estimated or transform parameters of the acoustic model independently of each other.

According to further embodiments, the above-discussed approach may be implemented by a method. Another embodiment provides a method for transforming an audio stream with more than one channel into another representation, comprising the following steps:

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- deriving or receiving the one or more parameters describing an acoustic or psychoacoustic model of an audio stream from the audio stream, said parameters comprise at least an information on DOA; and
 - transforming the audio stream in a signal-adaptive way dependent on one or more parameters.

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Another embodiment provides a method for transforming an audio stream in a directional audio coding system, comprising the steps:

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- deriving the one or more acoustic model parameters of a model of the audio stream (parametrized by DOAs and diffuseness parameters or energy ratios), said acoustic model parameters are transmitted to restore all channels of an input of audio stream and comprise at least an information on DOAs, wherein the transmitted audio stream is derived by transforming all or a subset of the channels of the audio stream; and
 - 20 - transforming the audio stream in a signal-adaptive way dependent on one or more acoustic model parameters.

According to further embodiments, the method may computer implemented. Thus, an embodiment provides a computer program for performing, wherein running on a computer, 25 the method according to the above-disclosure.

Embodiments of the present invention will subsequently be discussed referring to the enclosed figures, wherein:

30 Figs. 1a and 1b shows a schematic representation of a DirAC analysis and synthesis;

Fig. 2 shows a schematic representation of a DirAC encoder;

Fig. 3 shows a schematic representation of a DirAC decoder;

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- Fig. 4 shows a schematic representation of a metadata assisted EVS: for a spatial audio;
- 5 Fig. 5a shows covariance matrix elements for one frequency band as a function of the frame number (time) for a signal comprising only one panned point source, where model and exact matrices agree very well (to illustrate embodiments);
- 10 Fig. 5b shows covariance matrix elements for one frequency band as a function of the frame number (time) for a signal from an EigenMike recording (model and exact matrices show good qualitative agreement) to illustrate embodiments;
- 15 Fig. 6 shows a schematic representation of an apparatus for transforming an audio stream (as part of a decoder and/or encoder) according to a basic embodiment; and
- 20 Figs. 7a and b shows a schematic representation of a DirAC system with predictive coding of the transport channels according to further embodiments.

Below, embodiments of the present invention will subsequently be discussed referring to the enclosed figures, wherein identical reference numerals are provided to objects that have an identical or similar function, so that the description thereof is interchangeable or mutually applicable.

Before discussing embodiments of the present invention a discussion of some features of the invention will be given separately.

Channel Compression

For the compression of the transport channels it is known that the optimal decorrelation and therefore energy compaction would be obtained by the Karhunen-Loève transform (KLT) (see e.g. [12]). The KLT transforms the signal vector to a basis of the eigenvectors of the inter-channel covariance matrix. For a B-format input signal of the form

$$\mathbf{s}_B(t) = \begin{bmatrix} w(t) \\ x(t) \\ y(t) \\ z(t) \end{bmatrix} \quad (1)$$

the elements of the inter-channel covariance matrix

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$$\mathbf{C}[\mathbf{s}_B(t)] = \begin{pmatrix} C_{w,w} & C_{w,x} & C_{w,y} & C_{w,z} \\ C_{x,w} & C_{x,x} & C_{x,y} & C_{x,z} \\ C_{y,w} & C_{y,x} & C_{y,y} & C_{y,z} \\ C_{z,w} & C_{z,x} & C_{z,y} & C_{z,z} \end{pmatrix} \quad (2)$$

are given by

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$$C_{x,w} = \int dt w(t)x(t) \quad (3)$$

and analogously for the other channel combinations. With the KLT, the matrix $\mathbf{C}$ is diagonalized and all inter-channel correlations are fully removed, therefore yielding the least redundant representation of the signal. There are, however, two difficulties which prevent the implementation of the KLT in most real-world systems: the computational complexity of the required eigenvector calculations and the metadata bit usage for the transmission of the resulting transform matrices are often considered too high.

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Prediction

As a compromise, one can remove only the correlations of the x, y, and z with the w channel via the prediction matrix

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$$\mathbf{P} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -P_x & 1 & 0 & 0 \\ -P_y & 0 & 1 & 0 \\ -P_z & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -C_{x,w}/C_{w,w} & 1 & 0 & 0 \\ -C_{y,w}/C_{w,w} & 0 & 1 & 0 \\ -C_{z,w}/C_{w,w} & 0 & 0 & 1 \end{pmatrix}. \quad (4)$$

5 In this approach, no matrix diagonalization is required and only the three prediction coefficients $P_{x/y/z}$ are to be transmitted. Depending on the frame length and the signal characteristics, the amount of metadata for this approach can still be considerable. According to our experiments this is of the order of 10 kbps. This is especially noteworthy as these metadata would be transmitted along with those required for the DirAC system itself, raising the overall bit requirement.

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This naturally invites the question as to how these two metadata streams are connected. The invention described in the following clarifies the connection between the prediction for the purpose of the compression of the DirAC or SPAR transport channels and the model parameters transmitted in DirAC to allow for the decoder-side reconstruction of the full HOA input signal. We provide a path to the re-use of metadata already transmitted as part of the DirAC system for the compression of the transport channels. Our method can therefore improve the perceptual quality of DirAC as compared to a passive downmix by a static selection of transport channels while avoiding additional metadata transmission.

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Head Tracking

Both of the approaches to scene rotation as discussed above have significant drawbacks. For the former, the computational complexity is very high due to the matrix multiplication for every sample of the signal. For the latter, the quality is less than optimal [9]. It is therefore desirable to reduce the complexity of the former method without compromising on the quality too much. Our invention provides a path to applying the rotation in a lower-dimensional space. Within the framework of the two aforementioned systems for parametric coding of spatial audio, this can be realized by combining the rotation of a subset of the channels in the Ambisonics domain with a suitable transform in the metadata domain.

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Detailed Description of Embodiments

35 Above it has been established that a compression of transport channels can be achieved by reducing correlations *via* transforms derived from the covariance matrix. The below

discussion will show an approach how such transforms can be obtained independently on both the encoder and decoder side from the readily available DirAC model parameters or general acoustic model parameters.

- 5 According to embodiments a covariance matrix may be determined from the model signal.

It is considered one of the parameter bands of directional audio coding (c.f. above). For brevity, we omit the frequency-band index in the notation. First we focus on the non-diffuse directional part of the signal. Let

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$$r_{\text{DOA}} = \begin{pmatrix} \cos \phi \cos \theta \\ \sin \phi \cos \theta \\ \sin \theta \end{pmatrix} \quad (5)$$

15

be the direction of arrival (DOA) of the sound from a point source on the unit sphere specified by the compound angle variable $\theta_D := (\phi, \theta)$. The sound pressure due to this source on the unit sphere is then given by

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$$p(r = 1, \theta_D, t) = s(t) \Omega(\theta_D) \quad (6)$$

$$\Omega(\theta_D) = \delta(\theta - \theta_D) \quad (7)$$

- 25 with the time-dependent signal $s(t)$ and the Dirac distribution on the sphere $\delta(\theta)$.

We consider a B-format or first-order Ambisonics (FOA) signal that comprises a directional part from a panned point source at r_{DOA} and an uncorrelated diffuse part with no correlation between the individual channels. The signal vector for the directional part then becomes

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$$\begin{bmatrix} w(t) \\ x(t) \\ y(t) \\ z(t) \end{bmatrix} = \begin{bmatrix} s(t) Y_{0,0}(\theta_D) \\ s(t) Y_{1,-1}(\theta_D) \\ s(t) Y_{1,0}(\theta_D) \\ s(t) Y_{1,1}(\theta_D) \end{bmatrix} \quad (8)$$

where $Y_{l,m}$ are the spherical harmonics with the degree and index numbers l and m . This result can be readily read off from the expansion of the Dirac function in 7 up to the first order in the spherical harmonics (see also [13]).

$$\Omega(\theta) \approx Y_{0,0}(\theta_D) Y_{0,0}(\theta) + Y_{1,-1}(\theta_D) Y_{1,-1}(\theta) + Y_{1,0}(\theta_D) Y_{1,0}(\theta) + Y_{1,1}(\theta_D) Y_{1,1}(\theta) \quad (9)$$

Together with the diffuse part, the full B-format signal then becomes

$$\begin{bmatrix} w(t) \\ x(t) \\ y(t) \\ z(t) \end{bmatrix} = s(t) \begin{bmatrix} Y_{0,0}(\theta_D) \\ Y_{1,-1}(\theta_D) \\ Y_{1,0}(\theta_D) \\ Y_{1,1}(\theta_D) \end{bmatrix} + \begin{bmatrix} s_w^{\text{diff}}(t) \\ \frac{1}{\sqrt{3}} s_x^{\text{diff}}(t) \\ \frac{1}{\sqrt{3}} s_y^{\text{diff}}(t) \\ \frac{1}{\sqrt{3}} s_z^{\text{diff}}(t) \end{bmatrix}. \quad (10)$$

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The prefactor of $\frac{1}{\sqrt{3}}$ in the $l = 1$

components in the diffuse part arises from the normalization of the signal.

Given this model signal, one can now straightforwardly evaluate the covariance matrix elements. For the off-diagonal matrix elements we find

$$C_{x/y/z,w} = \int dt s^2(t) Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D) \quad (11)$$

where the terms involving integrals over the products $s_{w/x/y/z}^{\text{diff}}(t) s(t)$ vanish since the diffuse components are assumed to exhibit no correlations with $s(t)$ or between each other. With the directional energy of the signal $E^{\text{dir}} = \int dt s^2(t)$ this can be cast as

$$C_{x/y/z,w} = E^{\text{dir}} Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D) \quad (12)$$

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The diagonal matrix elements $C_{w,w}$ becomes

$$C_{w,w} = E^{\text{dir}} Y_{0,0}(\theta_D) Y_{0,0}(\theta_D) + E_w^{\text{diff}} \quad (13)$$

with the diffuse energy E_w^{diff} defined analogously to the directional one. The other diagonal matrix elements follow in the same way.

Figs. 5a and 5b show the covariance matrix elements as a function of the time for a signal panned point source and an EigenMike recording respectively. For the point source (Fig. 5a) the agreement is very accurate as can be seen with respect to the comparison of the DirAC model signal (broken blue line) and the exact calculation signal (solid red line). For the EigenMike recording, the model captures the signal features qualitatively.

Prediction in DirAC

Using Eqs. 4, 12, and 13 and expressing the direct and diffuse energies E^{dir} and E^{diff} by the total signal energy E , the only remaining parameters are the angles θ_D and the diffuseness or energy ratios which are present in the DirAC decoder at all times. Therefore, the need to transmit additional prediction coefficients can be entirely avoided.

Alternatively, the model can be enabled for a subset of the frequency bands only. For the other bands the prediction coefficients will then be calculated from the exact covariance matrix and transmitted explicitly. This can be useful in cases where a very accurate prediction is required for the perceptually most relevant frequencies. Often it is desirable to have a more accurate reproduction of the input signal at lower frequencies, e.g. below 2 kHz. The choice of the cross-over frequencies can be motivated from two different arguments.

Firstly, the localization of sound sources is known to rely on different mechanisms for low and high frequencies [14]. While the inter-aural phase difference (IPD) is evaluated at low frequencies, the inter-aural level difference (ILD) dominates for the localization of sources at higher frequencies [14]. Therefore, it is more important to achieve a high accuracy of the prediction and a more accurate reproduction of the

phases at lower frequencies. Consequently, one may wish to resort to the more demanding but more accurate transmission of the prediction parameters for lower frequencies.

- 5 Secondly, perceptual audio coders for the resulting downmix channels, because of the above argument, often reproduce low frequency bands more accurately than higher ones. For example at low bitrates, higher frequencies can be quantized to zero and restored from a copy of lower ones [15]. In order to deliver consistent quality across the whole system, it can therefore be desirable to implement a cross-over frequency according to
10 the internal parameters of the core coder employed.

The signal path of the resulting DirAC system is depicted in Fig. 7a/b. The main improvement as compared to the previously presented system in Figs. 2 and 3 is the adaptive compression of the transport channels using the acoustic model parameters.

- 15 After the usual estimation of the DOA angles and diffuseness in each band, the model covariance matrix and the prediction coefficients are calculated according to Eqs. 12 to 14. Then the input channels are mixed down and coded using EVS. On the decoder side, the prediction coefficients are calculated from the transmitted model parameters again and the transform is inverted. Then the non-transport channels are reconstructed
20 by the DirAC decoder as discussed above.

Head tracking with Low Complexity

- Let $\mathbf{s}_{\text{HOA-L}}(t)$ be the vector of the output channel signals in HOA of order L . The
25 dimension of this vector is then given by $N = (L + 1)^2$. In order to perform a rotation of the scene by the conventional method, this signal would first be reconstructed in the DirAC or SPAR decoder and multiplied by a rotation matrix $\mathbf{R}_{\text{HOA-L}}$ of the size $N \times N$ at each sample of the signal.

- 30 Let now $\mathbf{s}_{\text{trans}}(t)$ be the signal vector of the transported channels after applying the inverse transform as shown in Fig. 7, numeral 110d. The dimension of the vector $\mathbf{s}_{\text{trans}}(t)$ is $M < N$ since most of the channels of $\mathbf{s}_{\text{HOA-N}}(t)$ are reconstructed parametrically. We now chose the order L_1 such that all channels in $\mathbf{s}_{\text{trans}}(t)$ belong to a basis function (spherical harmonic) with degree $l \leq L_1$ and apply the rotation via
35 pre-multiplication of $\mathbf{R}_{\text{HOA-L}_1}$ to all channels up to the order L_1 . Consequently all

channels with $l > L_1$ are not affected by the rotation, leaving the signal vector in an inconsistent state.

The key novelty of our invention is now to exploit the properties of $\mathbf{R}_{\text{HOA-L}}$: it is block diagonal with each block belonging to a specific degree l and the matrix elements for $l = 1$ are identical to those of the same rotation applied to any vector in $\mathbb{R}^3$ [11]. Consequently, one can apply the $l = 1$ block of $\mathbf{R}_{\text{HOA-L}}$ to the DOA vector prior to the reconstruction of the channels with $l > L_1$. As a result, these channels are reconstructed including the scene rotation and the need to perform a matrix multiplication with the full dimensionality N can be avoided, yielding a large reduction in computational complexity.

The above discussed approach can be used by an apparatus as it is shown by Fig. 6. The apparatus 100 may be part of an encoder or decoder and comprises at least means for transforming 110 and means for deriving 120. This apparatus 100 is applicable to the encoder and the decoder side. First the functionality of the apparatus at the encoder side will be discussed.

It is assumed that the apparatus 100 being part of an encoder receives a HOA representation. This representation is provided to the entities 110 and 120. For example a preprocessing of the HOAs signal, e.g. by an analysis filterbank or DirAC parameter estimator is performed (not shown). The one or more parameters describing an acoustic or psychoacoustic model of the input audio stream HOA. For example, they may comprise at least an information on a direction of arrival (DOA) or optionally information on a diffuseness or an energy ratio end of insertion.

The entity 120 performs a deriving of one or more parameters, e.g. prediction parameters/prediction coefficients.

The diffuseness and/or direction of arrival may be parameters of the mentioned acoustic model. Based on the acoustic model or based on the parameters describing the acoustic model, the prediction coefficients may be calculated by the entity 120. According to a further embodiment an interim step may be used. The prediction coefficient according to further embodiments is calculated based on a covariance matrix which is also calculated by the means for deriving 120, e.g. from the acoustic model. Often such a covariance matrix is

calculated based on information about the diffuseness, spherical harmonics and/or a time-dependent scalar-valued signal. For example, the formula

$$C_{x/y/z,w} = \int dt s^2(t) Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

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where $Y_{l,m}$ is a spherical harmonic with the degree and index l and m and where $s(t)$ is a time-dependent scalar-valued signal. The discussion of the calculation of a covariance matrix has been made above in great detail. According to further embodiments the additional calculation methods as discussed above may be used.

10

This means, that according to embodiments the entity 120 performs the following calculation. Extracting acoustic or psychoacoustic model parameters like a DOA or diffuseness out of the audio stream HOA

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- deriving a covariance matrix based on set parameters of the acoustic model
- calculating prediction parameters based on the covariance matrix, wherein the prediction parameters can be used by another entity, e.g. the entity 110. Consequently, the output of the entity 120 are parameters, especially prediction parameters which are forwarded to the entity 110.

20

The entity 110 is configured to perform transformation, e.g. downmix generation. This downmix generation is based on the input signal, here the HOA signal. However, in this case, the transformation is applied in a signal adaptive way dependent on the one or more parameters as derived by the entity 120.

25

Due to the novel approach that parameters, e.g. inter-channel prediction coefficients are derived from the acoustic signal model or the parameters of the acoustic signal model it is possible to perform a transformation like a mixing/down mixing in a signal-adaptive way. For example, this principle can be used to develop an extension to the DirAC system for spatial audio signals. This extension improves the quality as compared to static selection of a subset of the channel of the HOA input signal as transport channels. In addition, it reduces the metadata bit usage as compared to previous approaches to signal-adaptive transforms that reduce the inter-channel correlation. The savings on the metadata can in turn free more bits for the EVS bitstreams and further improve the perceptual quality of the system. The additional computational complexity is negligible. These advantages result directly from the derivation of a mathematical connection between the signal model considered in the DirAC

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system and prediction coefficients typically transmitted as side information in predictive coding schemes.

Though the principle has been discussed in context of an encoder it can also be applied to
5 the decoder side. At the decoder side the apparatus also comprises transforming means
and means for deriving one or more parameters (*c.f.* reference number 120) which are used
at the transforming means 110. For example, the decoder receives metadata comprising
information on the acoustic/psychoacoustic model or parameters of the
acoustic/psychoacoustic model (in general parameters enabling to determine the prediction
10 coefficients) together with a coded signal, like an EVS bitstream. The EVS bitstream is
provided to the transforming means 110, wherein the metadata are used by the means for
deriving 120. The means for deriving 120 determine based on the metadata parameters,
e.g. comprising an information on a DOA. For example, the parameters to be determined
may be prediction parameters. It should be noted, that metadata are derived from the audio
15 stream *e.g.* at the encoder side. These parameters/prediction parameters are then used by
the transforming means 110 which may be configured to perform an inverse transforming
like an upmixing so as to output a decoded signal like a FOA signal which can then be
further processed so as to determine the HOA signal or directly a loudspeaker signal. The
further processing may, for example comprise a DirAC synthesis including an analysis
20 filterbank.

It should be noted that the calculation of the prediction coefficients may be performed in the
same way in the decoder as in the encoder. In this case, the parameters, may be
preprocessed by a metadata decoder.

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With respect to Figs. 7a and 7b a detailed implementation of the above discussed approach
at the decoder side and the encoder side will be discussed.

Fig. 7a shows the encoder 200 having the central entities means for transforming 110e and
30 means for deriving one or more parameters 120e according to embodiments the means for
transforming 110e can be implemented as downmix generation processing HOA data
received from the input of the encoder 200. These data are processed taking into
consideration the parameters received from the entity 120e, *e.g.* prediction coefficients. The
output of the downmix generation may be fit to a bit allocation entity 212 and/or to a
35 synthesis filterbank 214. Both data streams processed by the entities 212 and 214 are

forwarded to the EVS coder 216. The EVS coder 216 performs the coding and outputs the coded stream to the multiplexer 230.

5 The entity 120e comprises in this embodiment two entities, namely an entity for determining a model and/or model covariance matrix which is marked by the reference numeral 121 as well as an entity for determining prediction coefficients which is marked by the reference numeral 122. According to embodiments the entity 122 performs the determination of the covariance matrix, e.g. based on one or more model parameters, like the DOA . The entity 122 determines the prediction coefficients, e.g. based on the covariance matrix.

10

The entity 120e may according to further embodiments receive a HOA signal or a derivative of the HOA signal e.g. preprocessed by a DirAC parameter estimator 232 and an analysis filterbank 231. The output of the DirAC parameter estimator 232 may give information on a direction of arrival (DOA as it was discussed above). This information is then used by the entity 120e and especially by the entity 121. According to further embodiments the estimated parameters of the entity 232 may also be used by a metadata encoder 233, wherein the encoded metadata stream is multiplexed together with the EVS coded stream by the multiplexer 230 so as to output the encoded HOA signal/encoded audio stream.

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20 Fig. 7b shows the decoder 300 which comprises according to embodiments at the input a demultiplexer 330. The decoder 300 comprises the central entities 120d and 110d. The entity 110d is configured to perform a transformation, e.g. an inverse transformation like an upmixing of a signal received from the demultiplexer 330. The received input signal may be a EVS coded signal which is decoded by the entity 316 and further processed by the analysis filterbank 314. The output of the transformer 110d is a FOA signal which can then be further processed by a DirAC synthesis taking into account metadata received via the demultiplexer 330. For this, the metadata path may comprise a metadata decoder 333.

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The DirAC synthesis entity is marked by the reference numeral 335 the output of the DirAC synthesis entity 335 may be further processed by a synthesis filterbank 336 so as to output a HOA signal or headphone/loudspeaker signal.

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The metadata, e.g. the metadata decoded by the metadata decoder 333 are used for determining the parameters obtained by the entity 120d. In this case, the entity 120d comprised the two entities for determining the model/the model covariance matrix as marked by reference numeral 121 and the entity for determining the prediction

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coefficients/general parameters (marked by the reference numeral 122). The output of the entity 120d is used for the transformation performed by the entity 110d.

Below, further aspects may be discussed. The above discussed embodiments start from
5 the assumption, that an audio stream with more than one channel should be transformed into another representation. The above discussed embodiments may also be applied for transforming audio streams in a directional audio coding system. Thus embodiments provide an apparatus and method to transform audio streams in a directional audio coding system where

- 10 a) acoustic model parameters are transmitted to restore all channels of the input signal,
 - b) the parameters comprise at least one (or more) DOA and diffuseness,
 - c) the transmitted audio streams are derived by transforming all or a subset of the channels of the input signal,
 - 15 d) this transform is derived from a model of the input signal parametrized by the DOA and diffuseness parameters, and
 - e) this transform is calculated in a signal-adaptive way independently on both the encoder and decoder side.
- 20 According to embodiment a sound scheme can be rotated in such a way that
- a) the vector of the transport channel signals is pre-multiplied by a rotation matrix in a suitable domain,
 - b) the model parameters and/or prediction coefficients are transformed in accordance with the transform of the transport channel signals, and
 - 25 c) the non-transport channels of the output signal are reconstructed using these transformed model parameters and/or prediction coefficients.

In general embodiments refer to an apparatus and method to transform audio streams with more than one channel into another representation such that

- 30 a) the transform is derived from parameters describing an acoustic or psychoacoustic model of the signal,
- b) these parameters comprise at least one DOA and diffuseness, and
- c) the transform is calculated in a signal-adaptive way.

35 According to further embodiments the transform is computed such that correlations between the transport channels are reduced. For example, an inter-channel covariance matrix may

be used. Here the inter-channel covariance matrix of the input signal is estimated from a model of the signal. According to further embodiments a transform matrix is derived from the covariance matrix of the model. According to embodiments such as for matrices calculated using different methods for different frequency bands.

5

Although some aspects have been described in the context of an apparatus, it is clear that these aspects also represent a description of the corresponding method, where a block or device corresponds to a method step or a feature of a method step. Analogously, aspects described in the context of a method step also represent a description of a corresponding block or item or feature of a corresponding apparatus. Some or all of the method steps may be executed by (or using) a hardware apparatus, like for example, a microprocessor, a programmable computer or an electronic circuit. In some embodiments, some one or more of the most important method steps may be executed by such an apparatus.

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15 The inventive encoded audio signal can be stored on a digital storage medium or can be transmitted on a transmission medium such as a wireless transmission medium or a wired transmission medium such as the Internet.

Depending on certain implementation requirements, embodiments of the invention can be implemented in hardware or in software. The implementation can be performed using a digital storage medium, for example a floppy disk, a DVD, a Blu-Ray, a CD, a ROM, a PROM, an EPROM, an EEPROM or a FLASH memory, having electronically readable control signals stored thereon, which cooperate (or are capable of cooperating) with a programmable computer system such that the respective method is performed. Therefore, 20 the digital storage medium may be computer readable.

25

Some embodiments according to the invention comprise a data carrier having electronically readable control signals, which are capable of cooperating with a programmable computer system, such that one of the methods described herein is performed.

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Generally, embodiments of the present invention can be implemented as a computer program product with a program code, the program code being operative for performing one of the methods when the computer program product runs on a computer. The program code may for example be stored on a machine readable carrier.

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Other embodiments comprise the computer program for performing one of the methods described herein, stored on a machine readable carrier.

In other words, an embodiment of the inventive method is, therefore, a computer program
5 having a program code for performing one of the methods described herein, when the computer program runs on a computer.

A further embodiment of the inventive methods is, therefore, a data carrier (or a digital storage medium, or a computer-readable medium) comprising, recorded thereon, the
10 computer program for performing one of the methods described herein. The data carrier, the digital storage medium or the recorded medium are typically tangible and/or non-transitionary.

A further embodiment of the inventive method is, therefore, a data stream or a sequence of
15 signals representing the computer program for performing one of the methods described herein. The data stream or the sequence of signals may for example be configured to be transferred via a data communication connection, for example via the Internet.

A further embodiment comprises a processing means, for example a computer, or a
20 programmable logic device, configured to or adapted to perform one of the methods described herein.

A further embodiment comprises a computer having installed thereon the computer program for performing one of the methods described herein.

25

A further embodiment according to the invention comprises an apparatus or a system configured to transfer (for example, electronically or optically) a computer program for performing one of the methods described herein to a receiver. The receiver may, for example, be a computer, a mobile device, a memory device or the like. The apparatus or
30 system may, for example, comprise a file server for transferring the computer program to the receiver .

In some embodiments, a programmable logic device (for example a field programmable gate array) may be used to perform some or all of the functionalities of the methods
35 described herein. In some embodiments, a field programmable gate array may cooperate

with a microprocessor in order to perform one of the methods described herein. Generally, the methods are preferably performed by any hardware apparatus.

5 The above described embodiments are merely illustrative for the principles of the present invention. It is understood that modifications and variations of the arrangements and the details described herein will be apparent to others skilled in the art. It is the intent, therefore, to be limited only by the scope of the impending patent claims and not by the specific details presented by way of description and explanation of the embodiments herein.

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Claims

- 5 1. Apparatus (100) for transforming an audio stream with more than one channel into another representation comprising:

means for deriving (120, 120e, 120d) or means for receiving one or more parameters describing an acoustic or psychoacoustic model of the audio stream, wherein the
10 means for deriving (120, 120e, 120d) are configured to calculate prediction coefficients as the one or more parameters,

means for transforming (110, 110e, 110d) the audio stream in a signal-adaptive way dependent on the one or more parameters; and

15 wherein the one or more parameters comprise at least an information on at least one DOA,

wherein the means for transforming (110, 110e, 110d) are configured to perform a
20 downmixing of the audio stream on the encoder (200) side; and/or wherein the means for transforming (110, 110e, 110d) are configured to perform upmix generation of the audio stream on the decoder (300) side.

2. Apparatus (100) according to one of the previous claims, wherein the prediction
25 coefficients are calculated based on a covariance matrix or on the one or more parameters.

3. Apparatus (100) according to claim 2, wherein prediction coefficients are calculated
based on $Y_{l,m}$, especially based on the formula

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$$\mathbf{P} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -C_{x,w}/C_{w,w} & 1 & 0 & 0 \\ -C_{y,w}/C_{w,w} & 0 & 1 & 0 \\ -C_{z,w}/C_{w,w} & 0 & 0 & 1 \end{pmatrix}, \quad (4)$$

with the matrix elements

$$C_{x/y/z,w} = E^{\text{dir}} Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

and

$$C_{w,w} = E^{\text{dir}} Y_{0,0}(\theta_D) Y_{0,0}(\theta_D) + E_w^{\text{diff}} \quad (13)$$

where $Y_{l,m}$ are real spherical harmonics with degree and index l and m .

4. Apparatus (100) according to claim 1, 2 or 3, wherein the one or more parameters
5 further comprise at least an information on a diffuseness factor or on one or more
DOAs or on energy ratios, and/or wherein the one or more parameters are derived
from the audio stream.
5. Apparatus (100) according to claim 1, wherein the means for deriving (120, 120e,
10 120d) are configured to calculate a covariance matrix or a covariance matrix from
the acoustic or psychoacoustic model.
6. Apparatus (100) according to one of the previous claims, wherein the means for
deriving (120, 120e, 120d) are configured to calculate a covariance matrix based on
15 the DoA and a diffuseness factor or an energy ratio.
7. Apparatus (100) according to claim 6, wherein the means for deriving (120, 120e,
120d) are configured to calculate a covariance matrix based on an information about
diffuseness, spherical harmonics and a time-dependent scalar-valued signal,
20 especially based on the formula

$$C_{x/y/z,w} = \int dt s^2(t) Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

25 where $Y_{l,m}$ is a spherical harmonic with the degree and index l and m and where
 $s(t)$ is a time-dependent scalar-valued signal; and/or

based on a signal energy, especially based on the following formula

30

$$C_{x/y/z,w} = (1 - \Psi) E Y_{0,0}(\theta_D) Y_{1,-1/0/1}(\theta_D)$$

where ψ describes the diffuseness and where E describes the signal energy for
the audio stream; and/or based on the formula

35

$$C_{w,w} = (1 - \Psi) E Y_{0,0}(\theta_D) Y_{0,0}(\theta_D) + \Psi E$$

where E is the signal energy; and/or based on the formula

$$C_{x,x} = (1 - \Psi) E Y_{1,-1}(\theta_D) Y_{1,-1}(\theta_D) + \frac{\Psi}{3} E$$

and for the y and z channels analogously.

8. Apparatus (100) according to claims 7, wherein the signal energy E is directly
calculated from the audio stream; and/or

wherein the energy E is estimated from the model of the audio stream .

9. Apparatus (100) according to one of the previous claims, wherein the audio stream
is preprocessed by a parameter estimator (232) or a parameter estimator (232)
comprising a metadata encoder (233) or metadata decoder (333) and/or by an
analysis filterbank.

10. Apparatus (100) according to one of the previous claims, wherein the means for
transforming (110, 110e, 110d) are configured to perform a mixing of the audio
stream on the encoder (200) side.

11. Apparatus (100) according to one of the previous claims, wherein the one or more
parameters comprise prediction parameters.

12. Apparatus (100) for transforming an audio stream in a directional audio coding
system comprising:

means for deriving (120, 120e, 120d) or receiving one or more acoustic model
parameters of a model of the audio stream, wherein the one or more parameters are
transmitted to restore all channels of the audio stream and comprise at least an
information on DoA,

means for transforming (110, 110e, 110d) the audio stream in a signal-adaptive way
dependent on the one or more acoustic model parameters; and

where the audio stream is derived by transforming all or a subset of the channels of the audio stream;

5

wherein the means for transforming (110, 110e, 110d) are configured to perform a downmixing of the audio stream on the encoder (200) side; and/or wherein the means for transforming (110, 110e, 110d) are configured to perform upmix generation of the audio stream on the decoder (300) side.

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13. Apparatus (100) according to one of the previous claims, wherein the one or more parameters are quantized prior to a transmission.

14. Apparatus (100) according to one of the previous claims, wherein the one or more parameters are dequantized after a transmission.

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15. Apparatus (100) according to one of the previous claims, wherein the parameters are smoothed over time.

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16. Apparatus (100) according to one of the previous claims, wherein the transform is computed such that correlations between transport channels are reduced by use of Karhunen-Loève transform or prediction matrix.

17. Apparatus (100) according to one of the previous claims, wherein an inter-channel covariance matrix of an input of the audio stream is estimated from a model of a signal of the audio stream.

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18. Apparatus (100) according to one of the previous claims, wherein a transform matrix is derived from a covariance matrix of a model of the audio stream.

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19. Apparatus (100) according to one of the previous claims, wherein a transform matrix is calculated using different methods for different frequency bands.

20. Apparatus (100) according to one of the previous claims, wherein at least one of transform methods used by the means for transforming is multiplication of a vector of audio channels by a constant matrix.

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21. Apparatus (100) according to one of the previous claims, wherein at least one of transform methods used by the means for transforming uses prediction based on the inter-channel covariance matrix of an audio signal vector of audio channels.
- 5
22. Apparatus (100) according to one of the previous claims, wherein at least one of transform methods used by the means for transforming uses prediction based on the inter-channel covariance matrix based on the DOA and an additional diffuseness factor or an energy ratio.
- 10
23. Apparatus (100) according to one of the previous claims, wherein the means for deriving (120, 120e, 120d) the one or more parameters are configured to process all or a subset of the channels of a first-order or higher-order Ambisonics input signal of the audio stream.
- 15
24. Apparatus (100) according to one of claims 12-23, wherein a sound scene of the audio stream is rotatable in such a way that:
- a vector of audio transport channel signals is pre-multiplied by a rotation matrix;
 - 20 - model parameters and/or prediction coefficients are transformed in accordance with the transform of a transport channel signal; and
 - non-transport channels of an output signal are reconstructed using the transformed model and/or prediction coefficients parameters.
- 25
25. Encoder (200) comprising an apparatus (100) according to one of the claims 1-24.
26. Decoder (300) comprising an apparatus (100) according to one of the claims 1-24.
- 30
27. A system comprising an encoder (200) according to claim 25 and a decoder (300) according to 26, wherein the encoder (200) is configured to calculate a prediction matrix and/or a downmix and wherein decoder (300) is configured to calculate an upmix matrix from estimated parameters or the one or more parameters of the acoustic model independently of each other.
- 35

28. Method for transforming an audio stream with more than one channel into another representation, comprising the following steps:

5 deriving or receiving the one or more parameters describing an acoustic or psychoacoustic model of an audio stream from the audio stream, wherein deriving comprises calculating prediction coefficients as the one or more parameters and wherein the one or more parameters comprise at least an information on DOA; and

10 transforming the audio stream in a signal-adaptive way dependent the on one or more parameters; wherein transforming comprises a downmixing of the audio stream on the encoder (200) side; and/or wherein transforming comprises upmixing of the audio stream on the decoder (300) side.

- 15 29. Method for transforming an audio stream in a directional audio coding system, comprising the steps:

20 deriving or receiving one or more acoustic model parameters of a model of the audio stream parametrized by DOA and diffuseness or energy-ratio parameters, said acoustic model parameters are transmitted to restore all channels of an input of audio stream and comprise at least an information on DOA, wherein the transmitted audio stream is derived by transforming all or a subset of the channels of the audio stream; and

25 transforming the audio stream in a signal-adaptive way dependent on one or more acoustic model parameters, wherein transforming comprises a downmixing of the audio stream on the encoder (200) side; and/or wherein transforming comprises upmixing of the audio stream on the decoder (300) side.

- 30 30. Computer program for performing, when running on a computer, the method according to claims 28 or 29.