

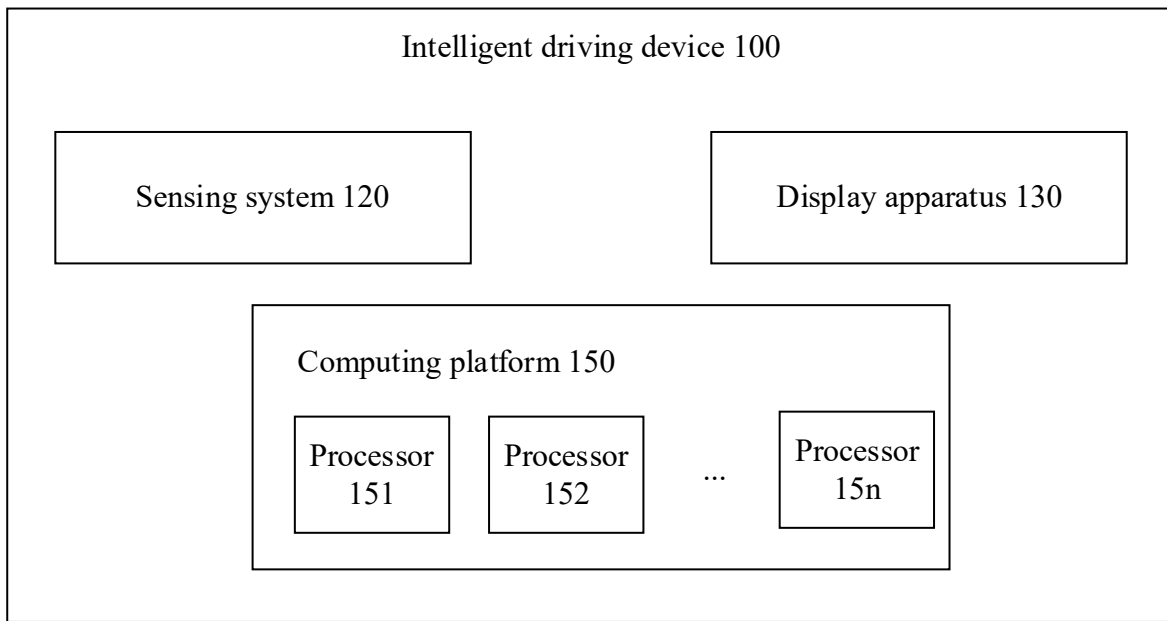


FIG. 1

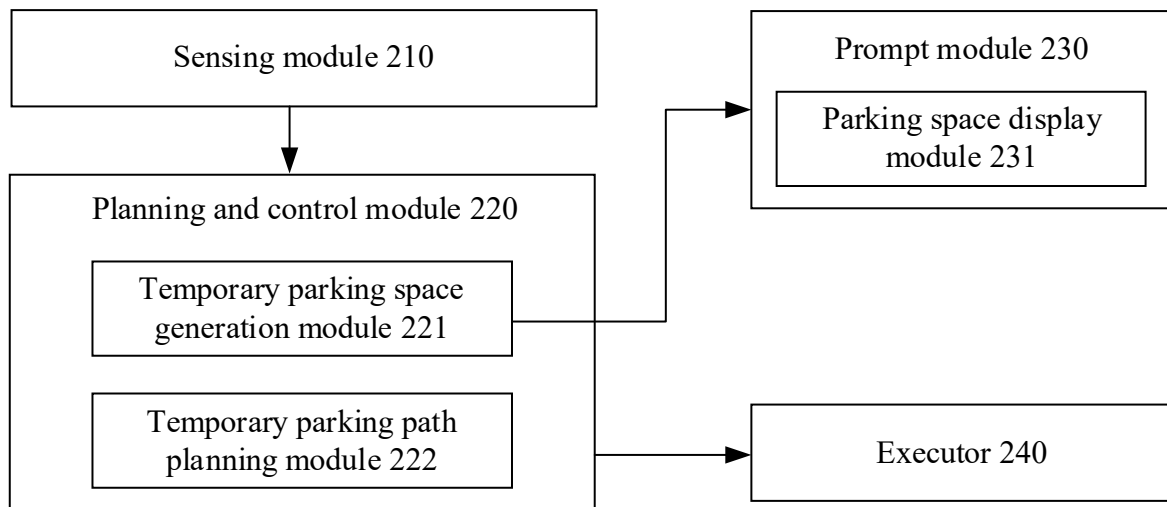


FIG. 2

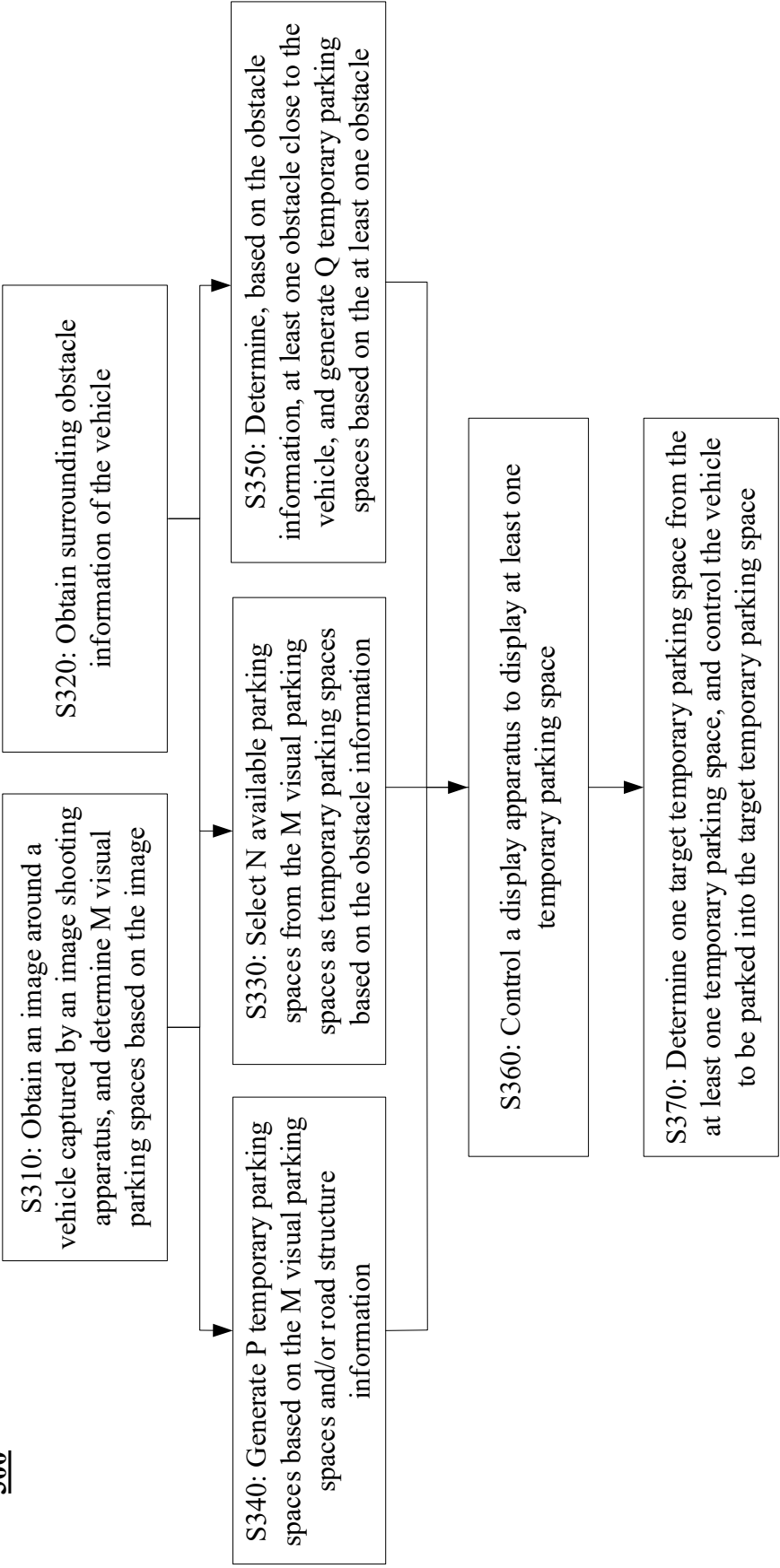
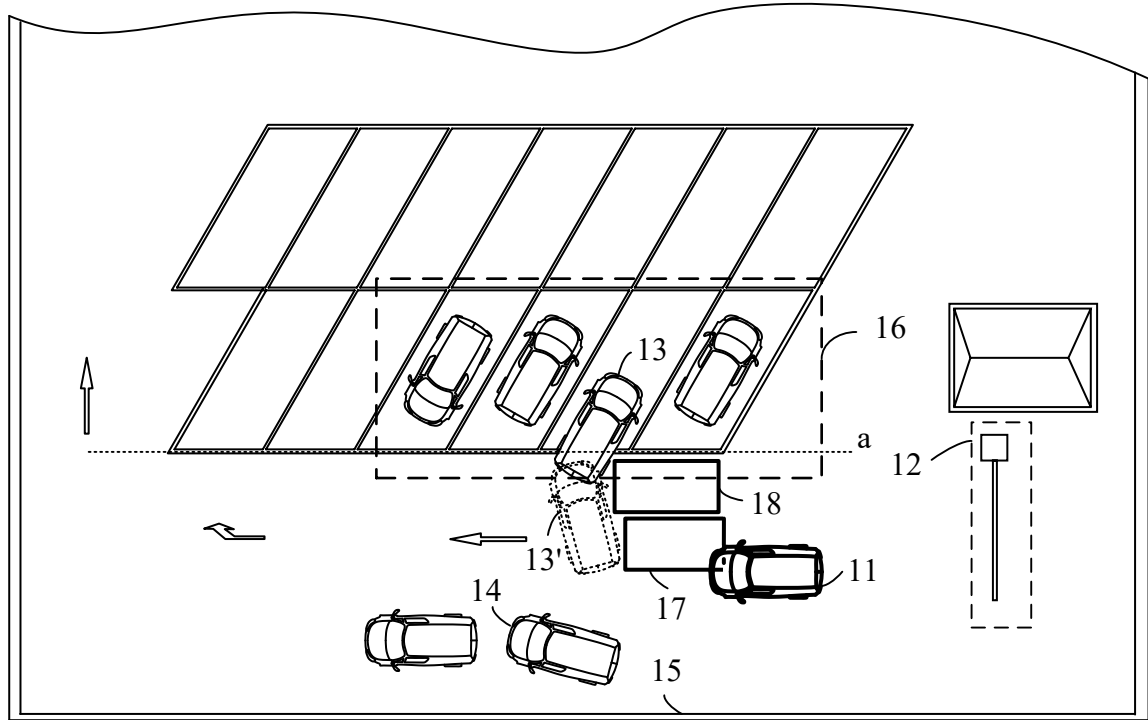
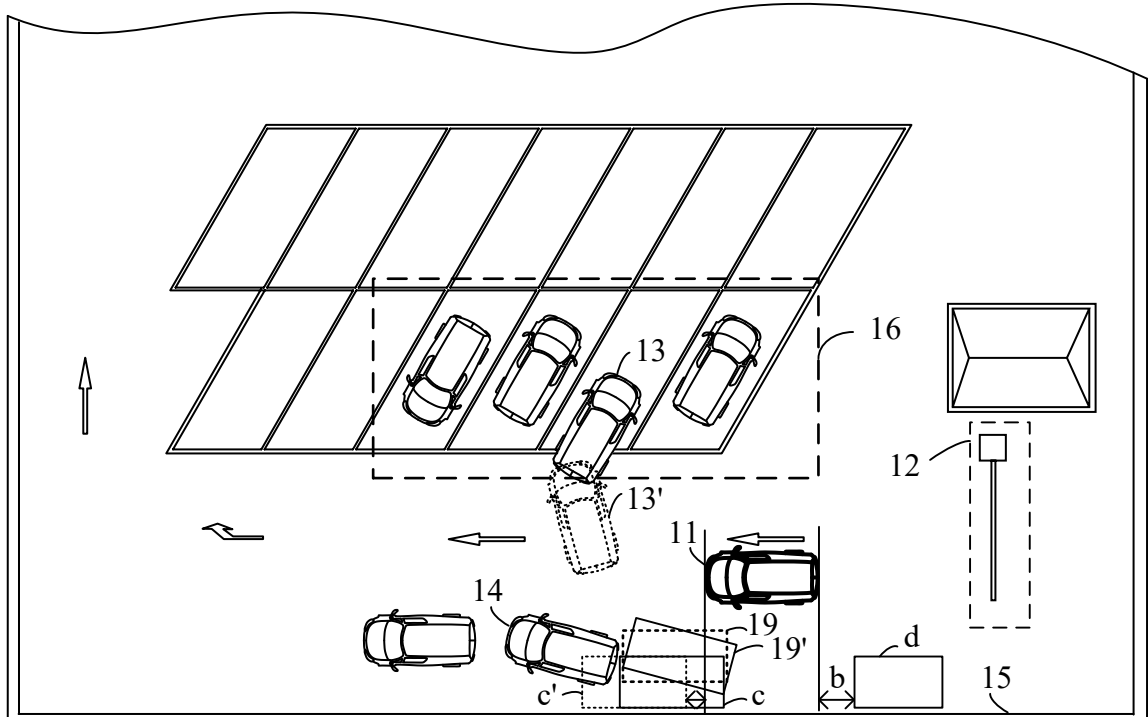


FIG. 3



(a)



(b)

FIG. 4

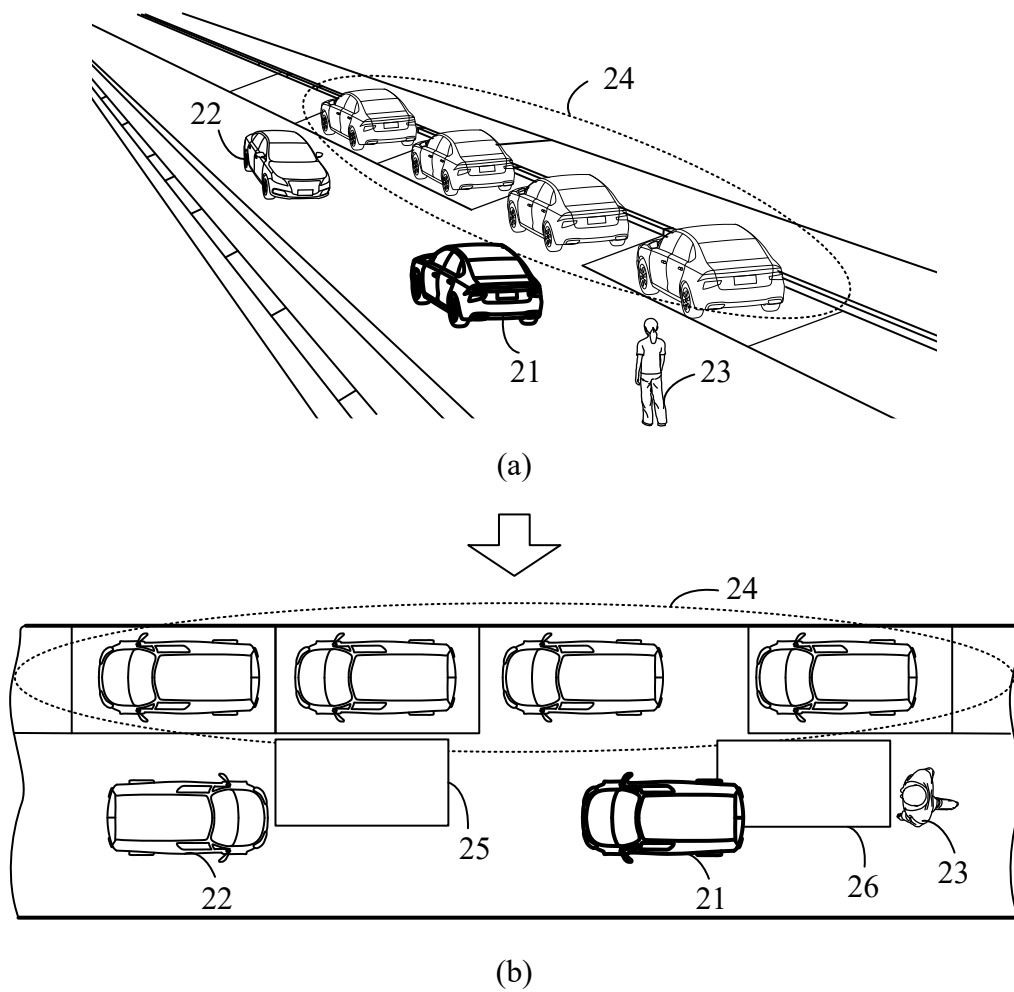


FIG. 5

**600**

S610: Determine at least two types of temporary parking spaces based on surrounding obstacle information of the intelligent driving device and surrounding environment information of the intelligent driving device, where the environment information includes parking space information and/or road structure information, the at least two types of temporary parking spaces include a first-type parking space and a second-type parking space, the first-type parking space is a parking space generated based on the obstacle information, and the second-type parking space is a parking space generated based on the environment information



S620: Control the intelligent driving device to park into a target temporary parking space, where the at least two types of temporary parking spaces include the target temporary parking space

FIG. 6

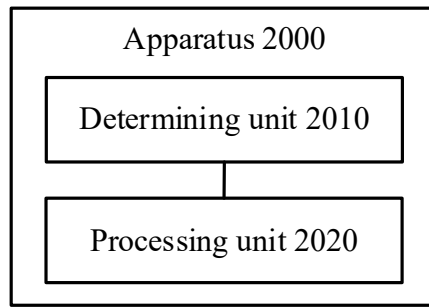


FIG. 7

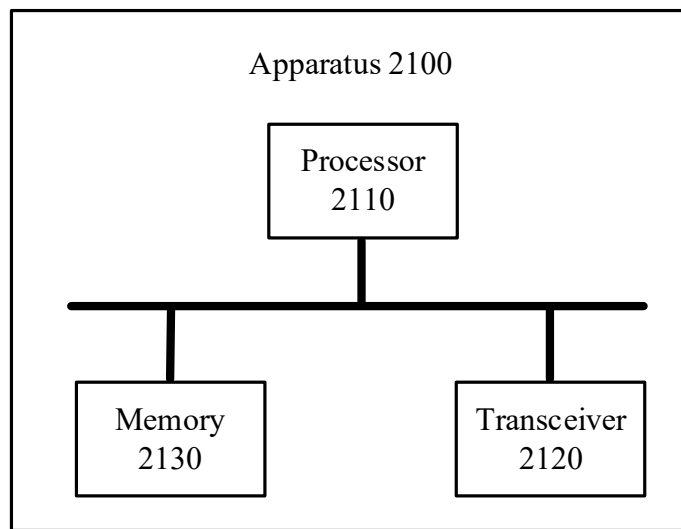


FIG. 8