

**MOVEMENT MANAGEMENT SYSTEM,
MOVEMENT MANAGEMENT METHOD, AND PROGRAM**

ABSTRACT

An object of the present disclosure is to restrict the operation of a robot more accurately. A movement management system (1) includes a positioner (131), a generator (132), and a notification processor (133). The positioner (131) determines the location of a robot (2) based on a beacon signal (B2) received at a scanner (3) installed in a facility. The beacon signal (B2) is transmitted from a robot beacon (23) built in the robot (2) moving autonomously. The generator (132) generates movement guidance information. The notification processor (133) transmits the movement guidance information to the robot (2). The movement guidance information includes: location information about the location of the robot (2) that has been determined by the positioner (131); and restriction information about a range of a restricted area where an operation of the robot (2) is restricted in the facility.

(Fig. 1)