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(54) Title: CLUTTER TIDYING ROBOT FOR NON-STANDARD STORAGE LOCATIONS

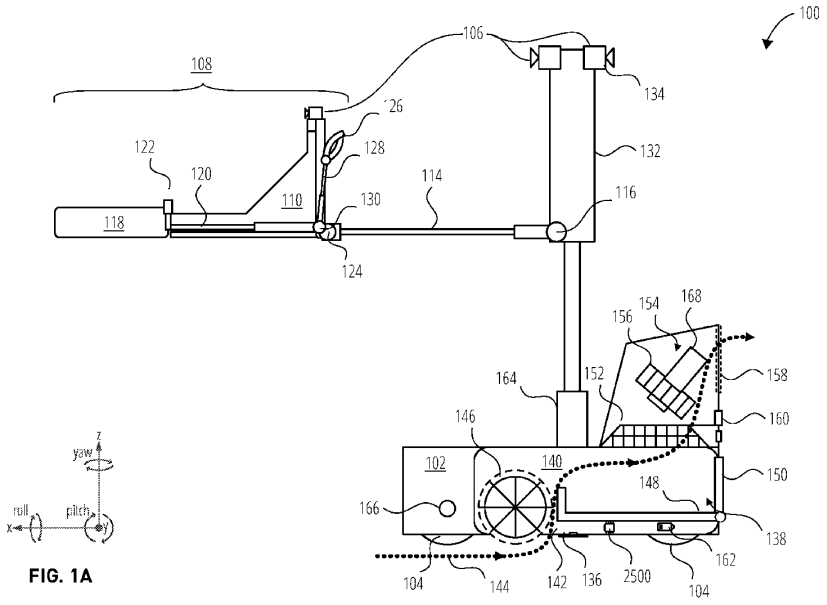


FIG. 1A

(57) Abstract: A method and computing apparatus are disclosed for allowing a tidying robot to organize objects into non-standard categories and deposit them at non-standard locations that match a user's needs. The tidying robot navigates an environment using cameras to map the type, size, and location of toys, clothing, obstacles, furniture, structural elements, and other objects. The robot comprises a neural network to determine the type, size, and location of objects based on input from a sensing system. An augmented reality view allows user interaction to refine and customize areas within the environment to be tidied, object categories, object home locations, and operational task rules controlling robot operations.

[Continued on next page]

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