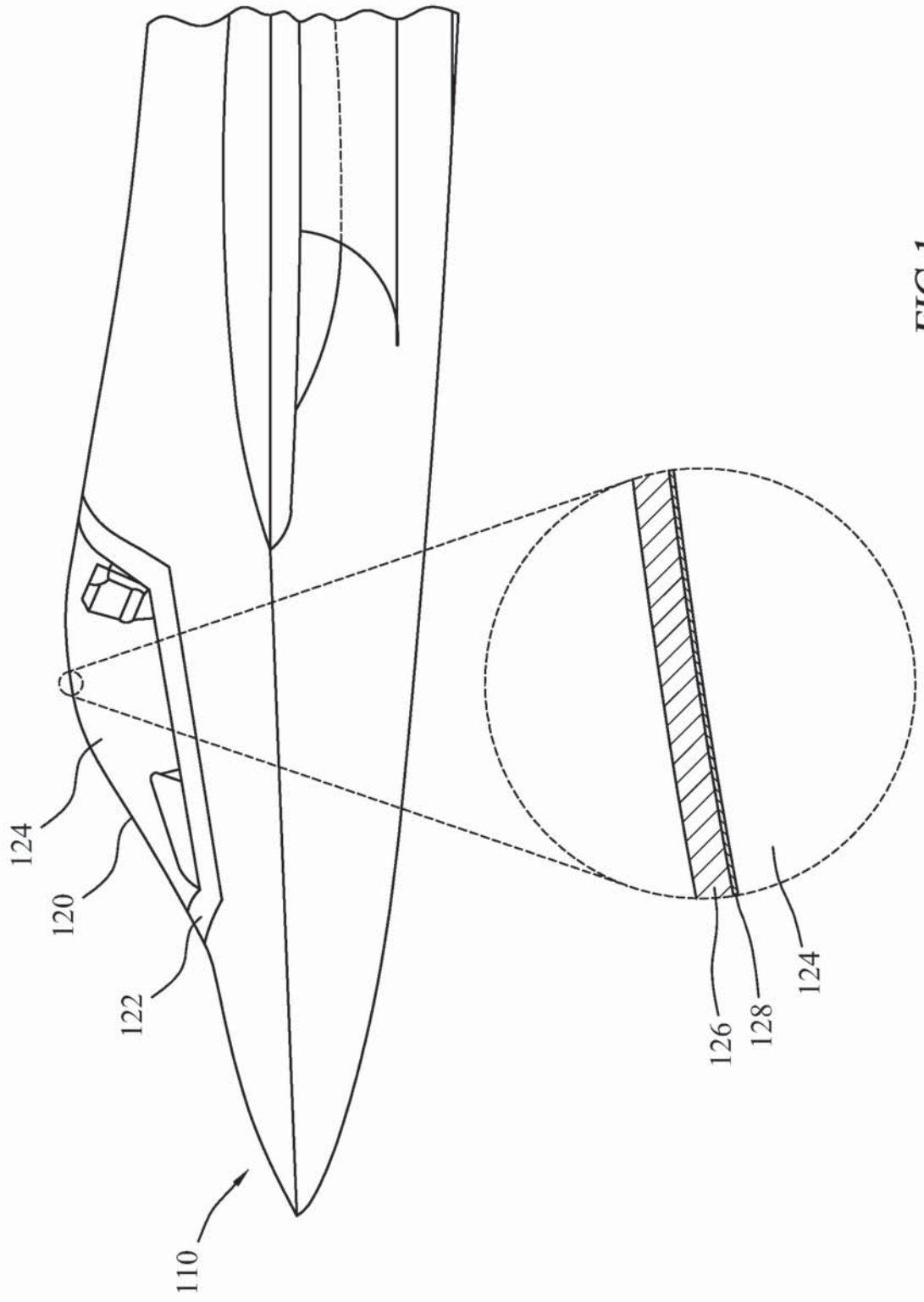


FIG.1

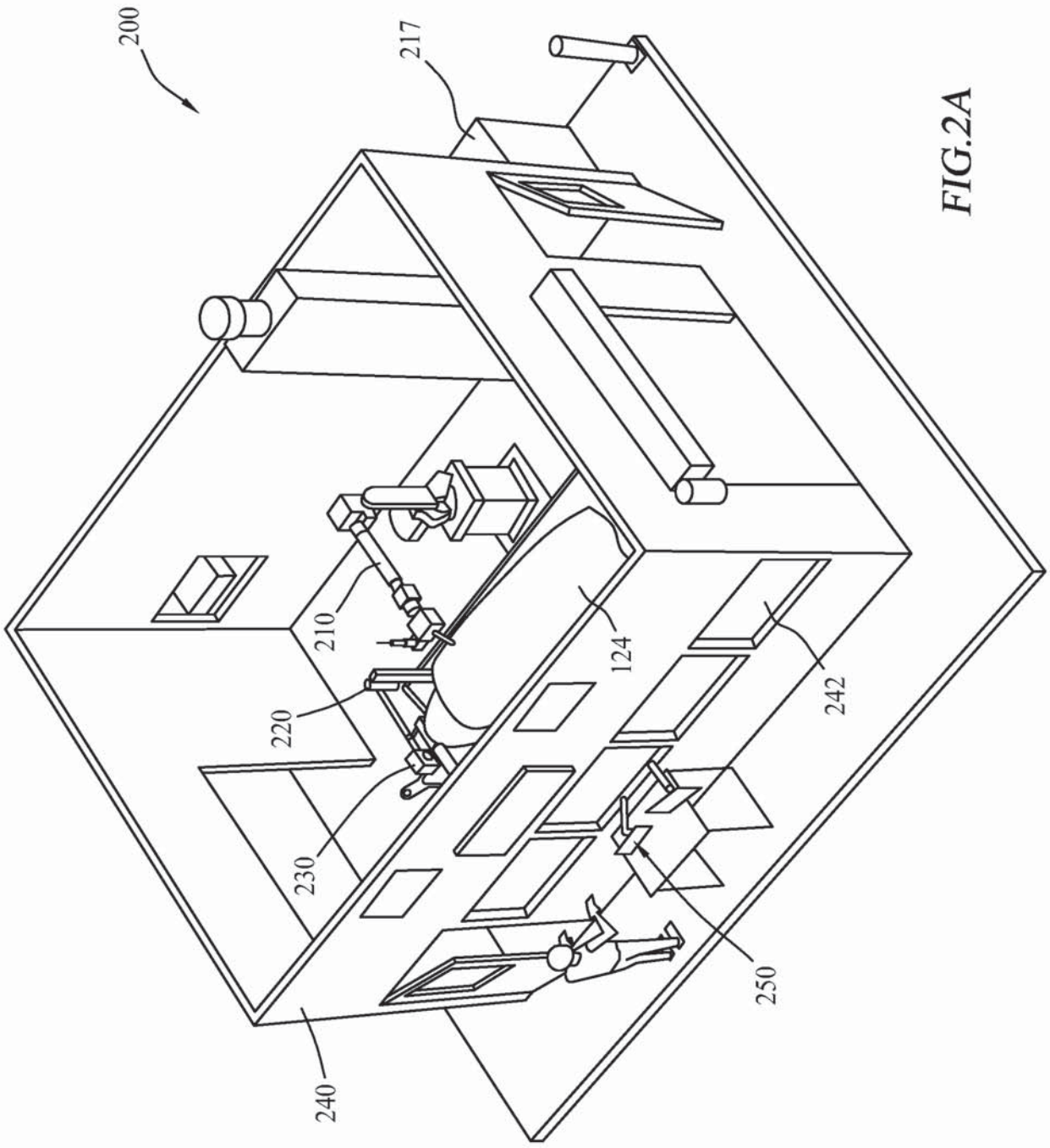


FIG.2A

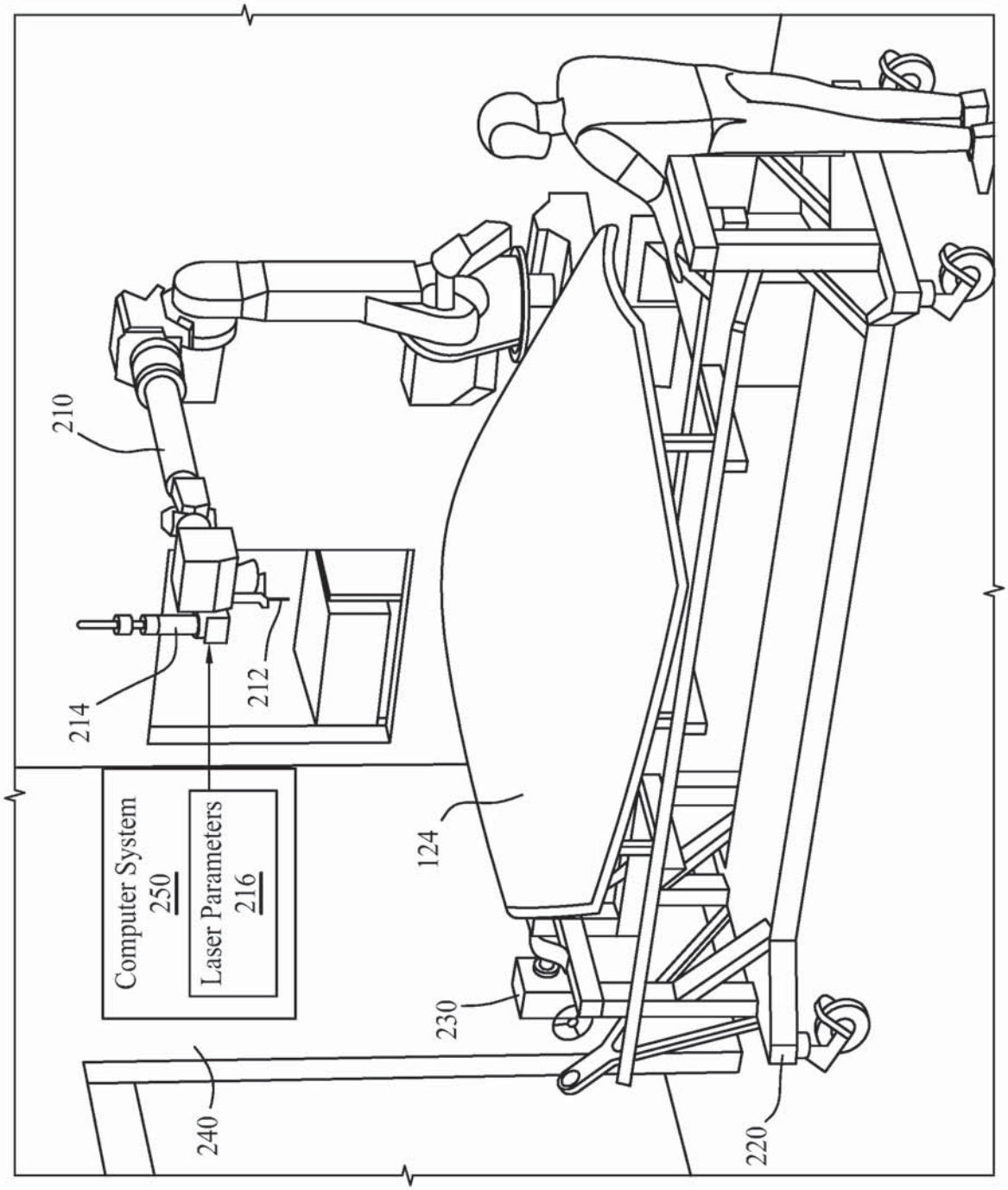

210
214
212
Computer System
250
Laser Parameters
216
124
230
240
220

FIG.2B

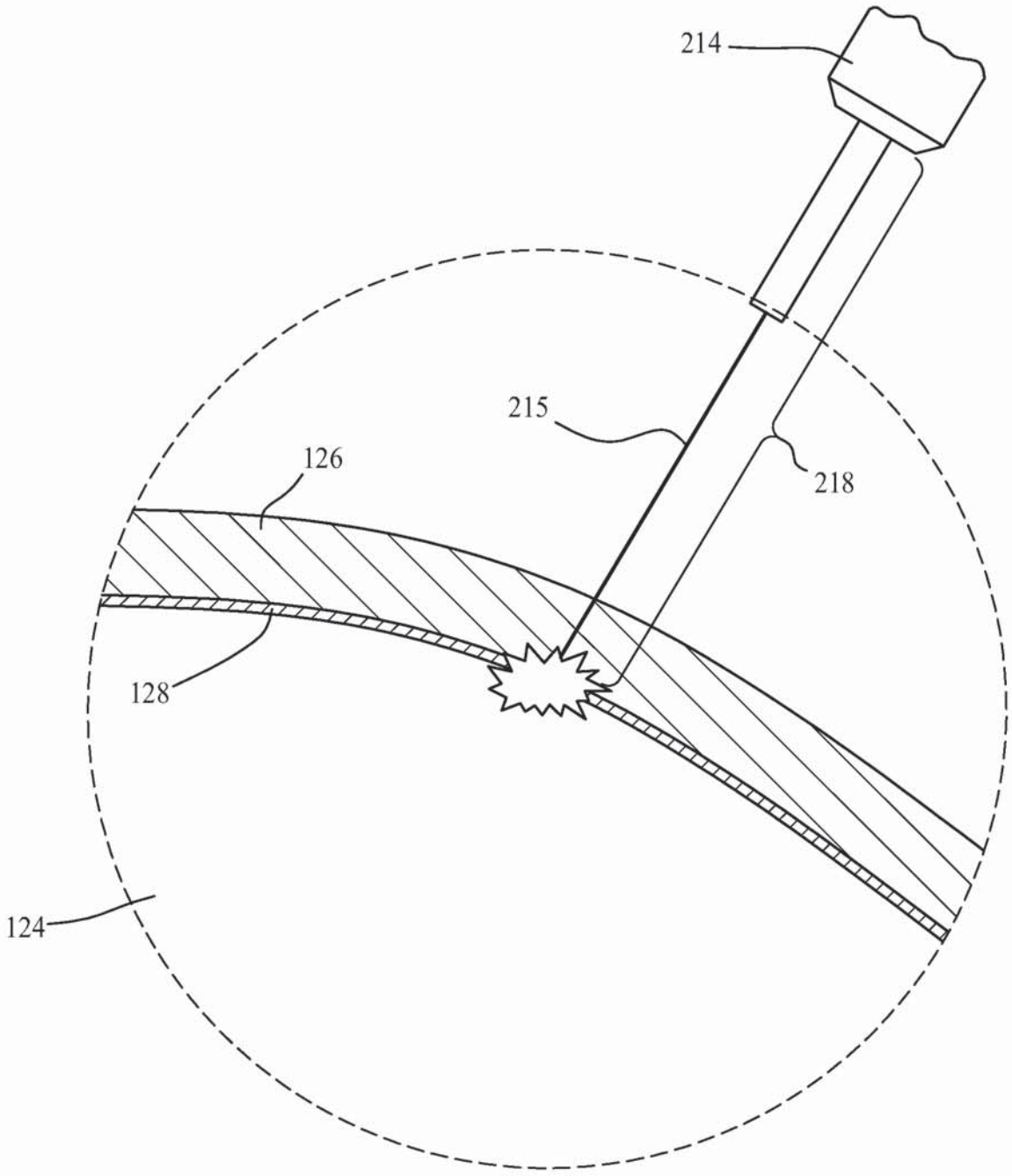


FIG.3A

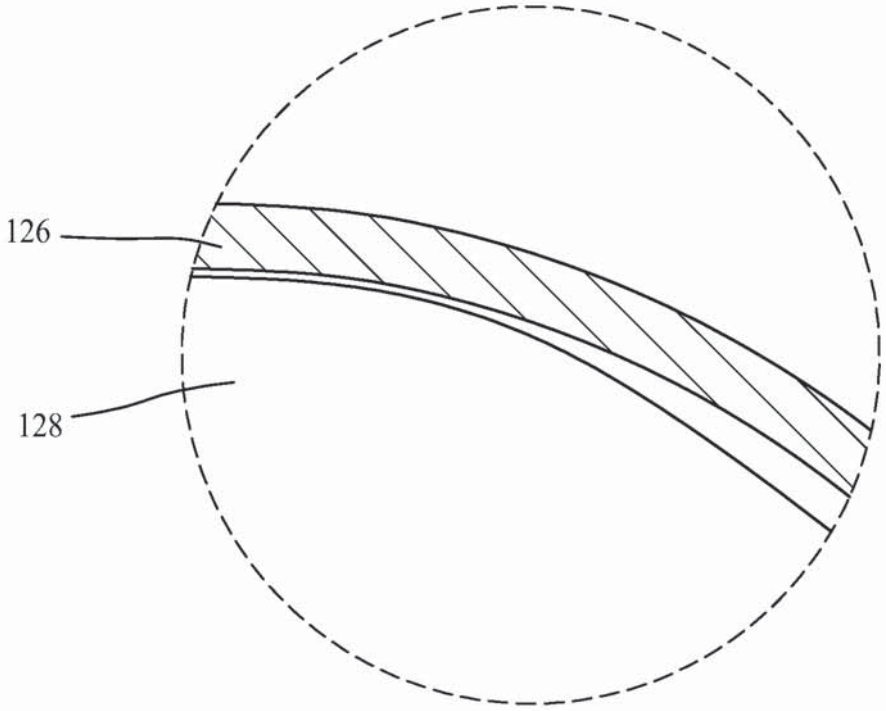

126
128

FIG.3B

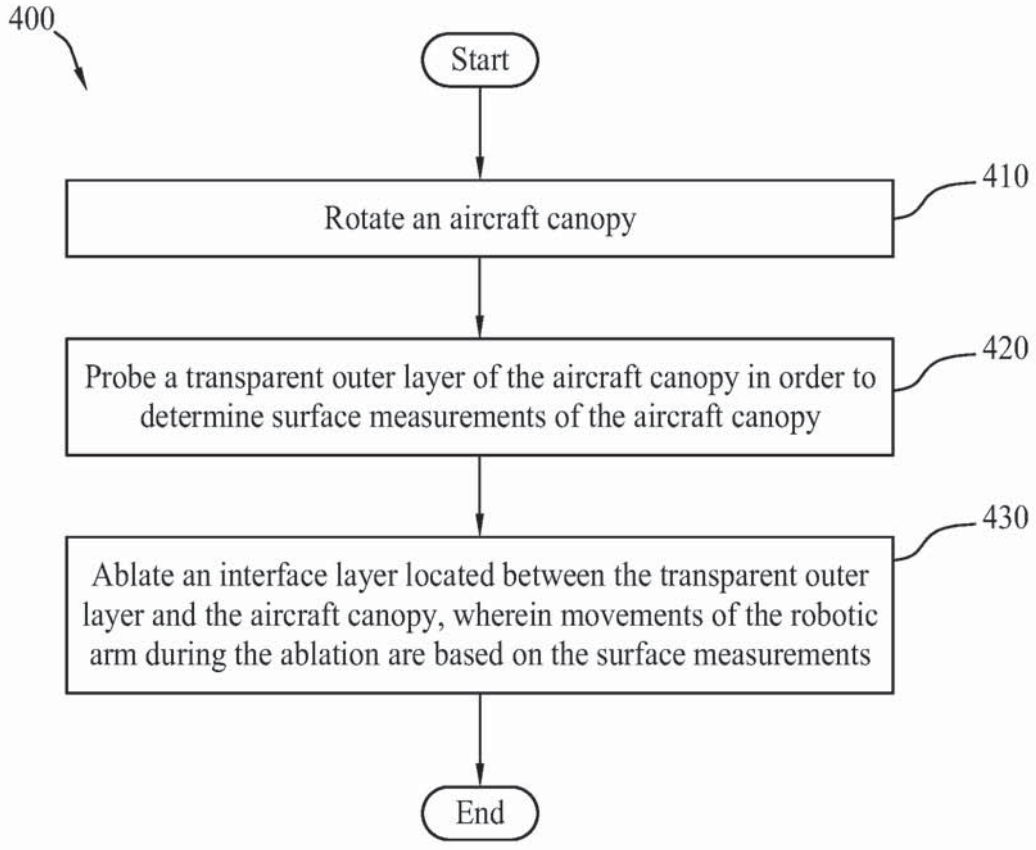

400
Start
Rotate an aircraft canopy
410
Probe a transparent outer layer of the aircraft canopy in order to determine surface measurements of the aircraft canopy
420
Ablate an interface layer located between the transparent outer layer and the aircraft canopy, wherein movements of the robotic arm during the ablation are based on the surface measurements
430
End

FIG.4

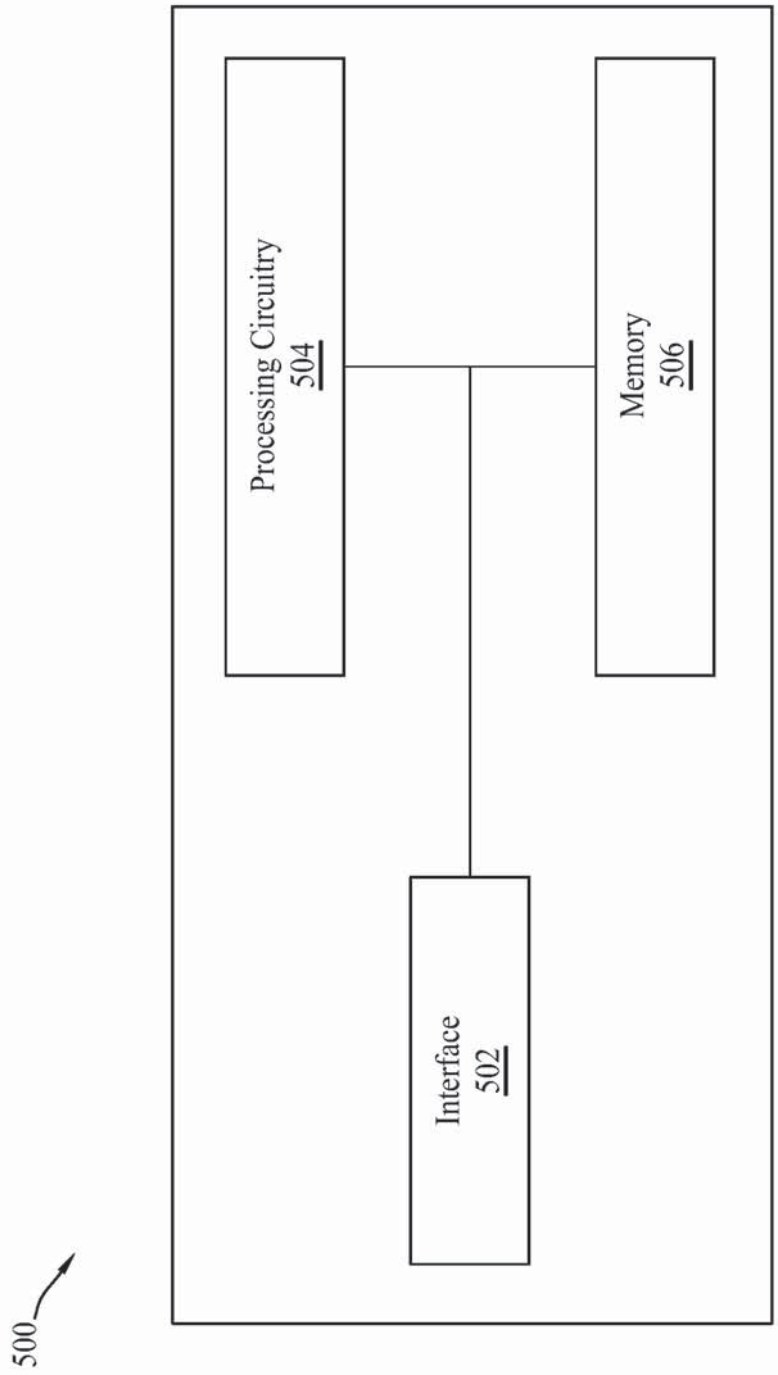


FIG.5