

INFORMATION PROCESSING DEVICE, INFORMATION PROCESSING METHOD,
AND PROGRAM

ABSTRACT

5 This information processing device comprises: a detection unit that detects a foreign
object which is not included in an image of a normal state, such detection performed in each
of a plurality of zones set for a passageway in the image in which the passageway is captured
from above; and a determination unit that determines whether a person corresponding to the
foreign object has passed through the passageway on the basis of a change over time in the
10 zone where the foreign object was detected.

[FIG. 3]