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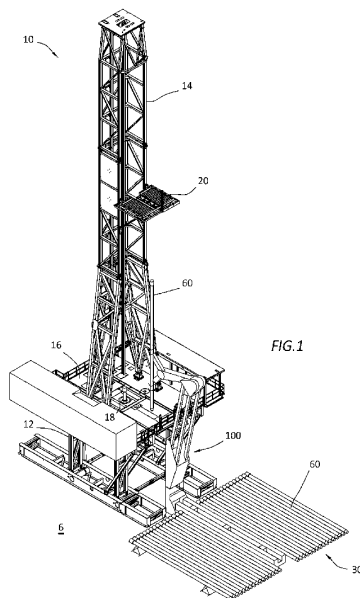
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(54) Title: TUBULAR HANDLING SYSTEM



(57) Abstract: A system including a pipe handler that can include a base, a support rotatably attached to the base at one end of the support, a first actuator configured to telescopically extend the support into engagement with a rig and telescopically retract the support to disengage from the rig, and a pipe handler mechanism rotatably attached to the support proximate an opposite end of the support, with the pipe handler mechanism being configured to grip and transport an object from a pick-up location to a delivery location and a system including a pipe handler that can be fixedly mounted to a rig floor with a pipe handler mechanism rotatably attached to the support, with the pipe handler mechanism being configured to grip and transport an object from a pick-up location to a delivery location.

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