

FIG. 1

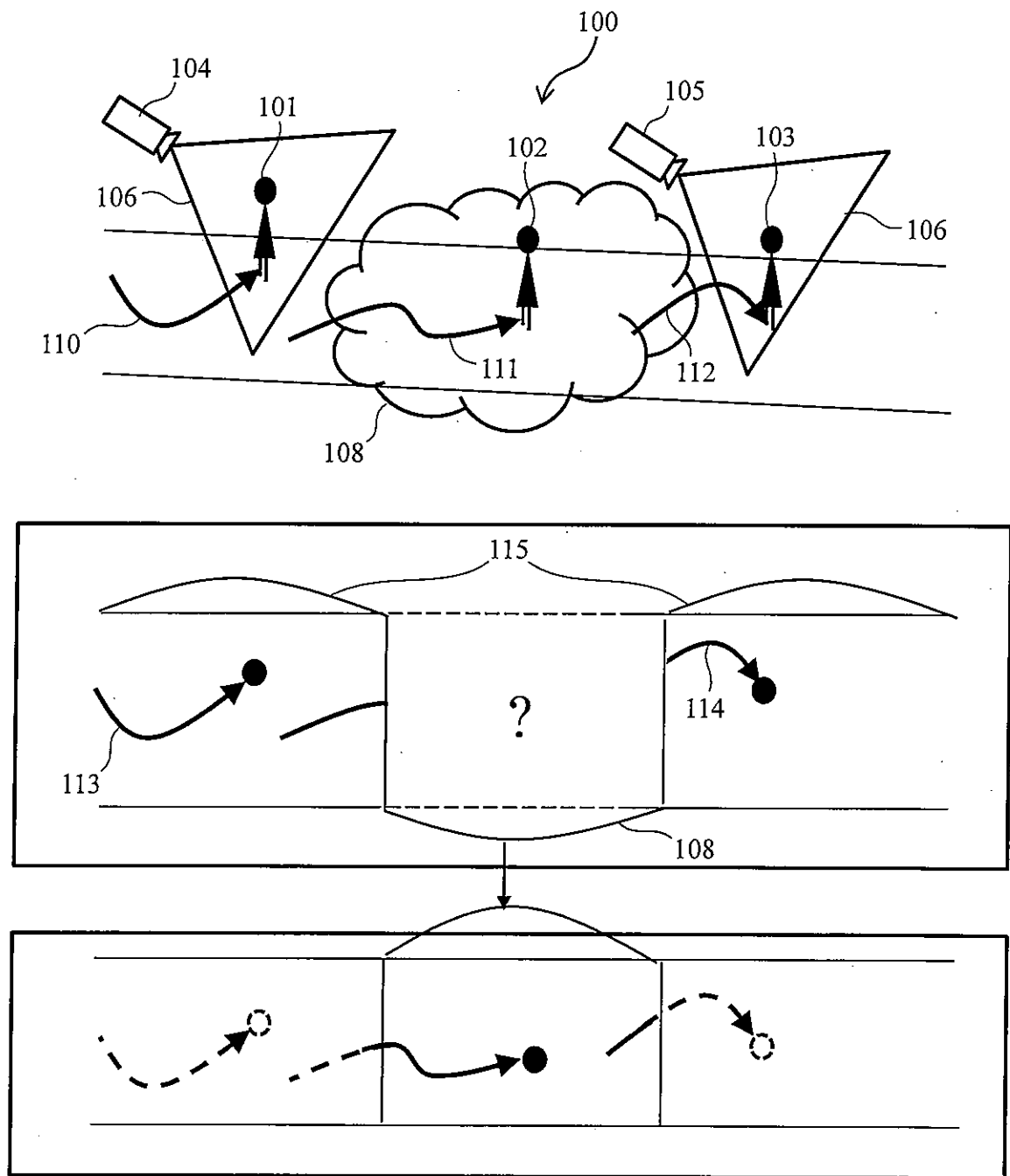


FIG. 2

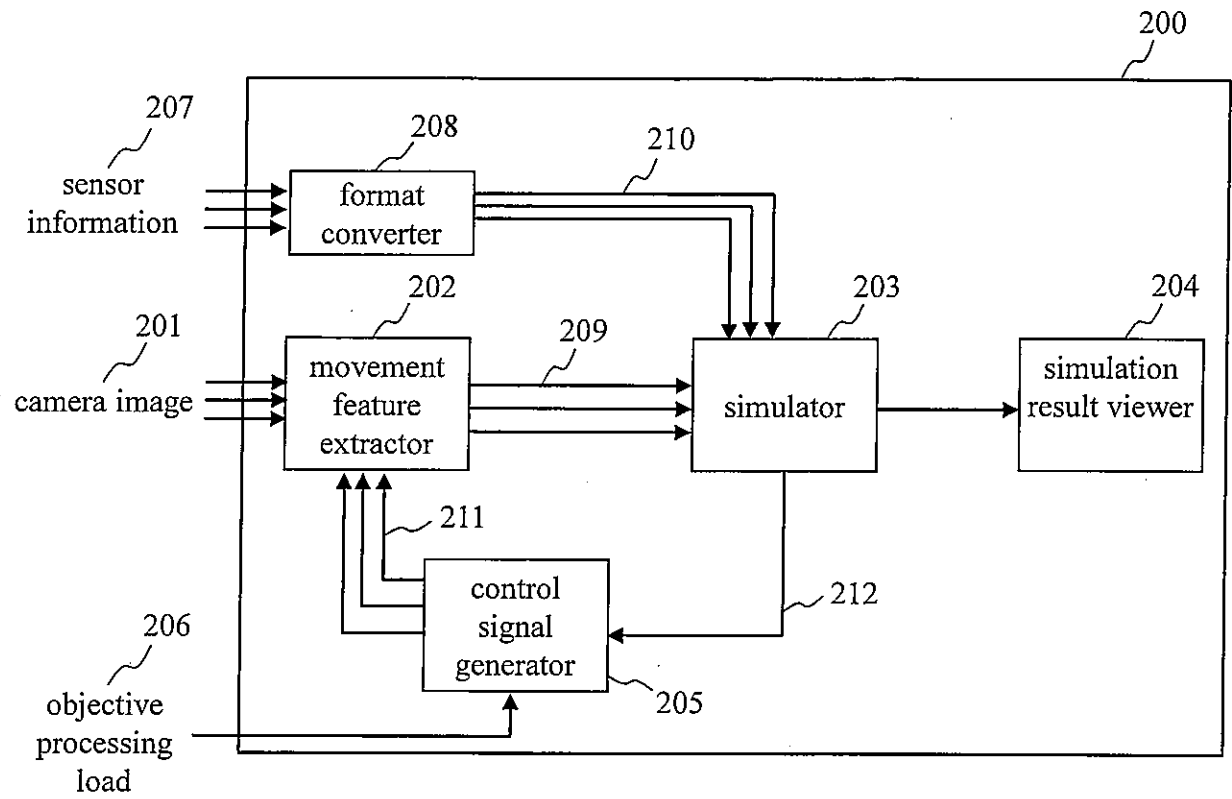


FIG. 3

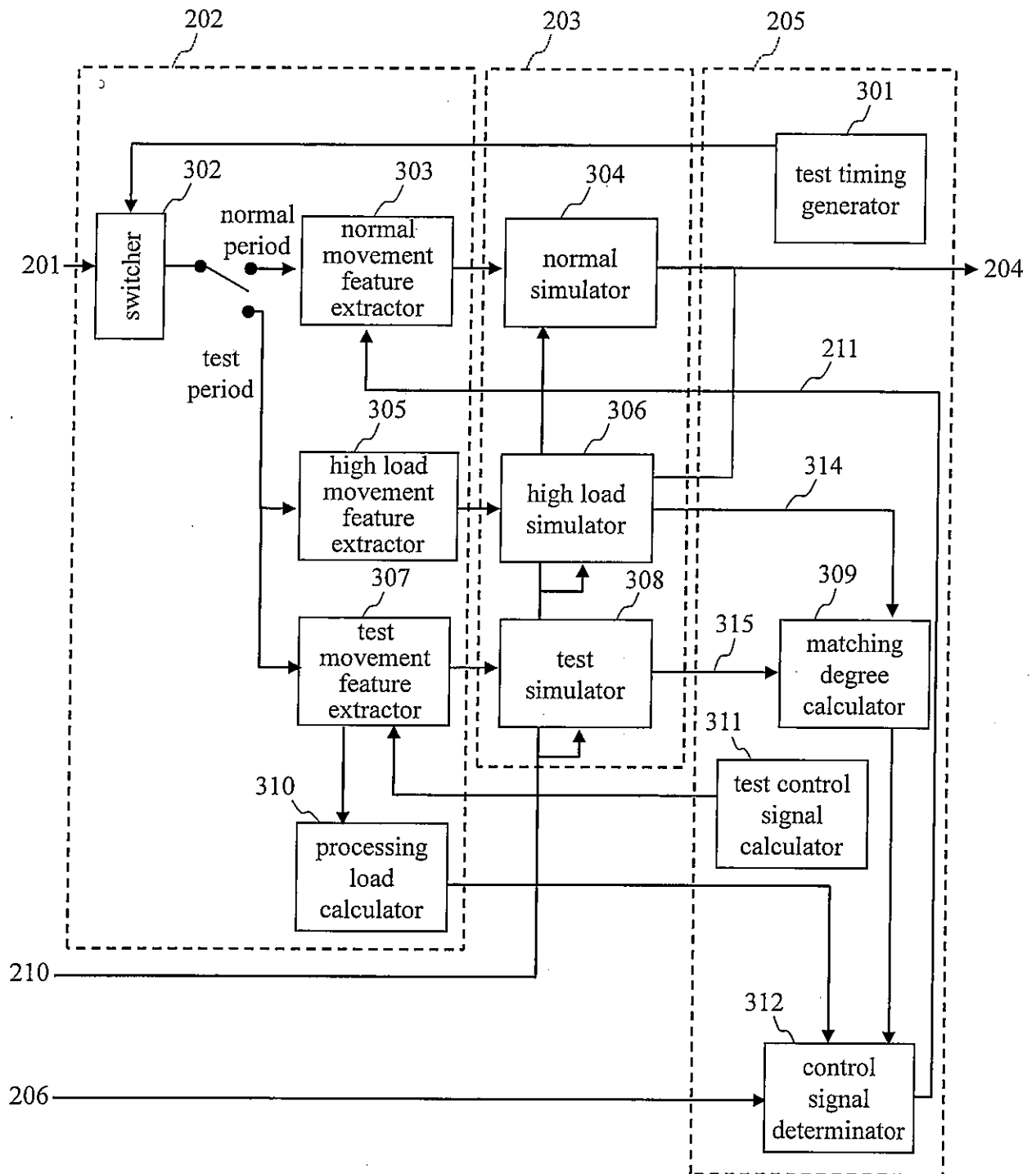


FIG. 4

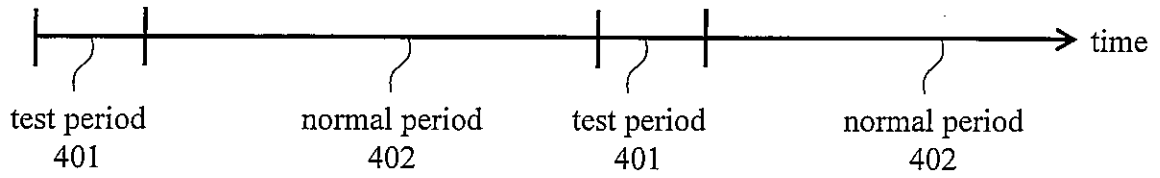


FIG. 5

501

500

control signal test pattern	camera A processing load	camera B processing load	camera C processing load	matching degree	ratio of processing load with respect to objective processing load	selected pattern
1	50%	100%	50%	70%	95%	
2	100%	50%	50%	75%	95%	
3	50%	50%	100%	80%	95%	○
4	100%	100%	50%	85%	145%	
5	50%	100%	100%	90%	145%	
6	100%	50%	100%	95%	145%	

FIG. 6

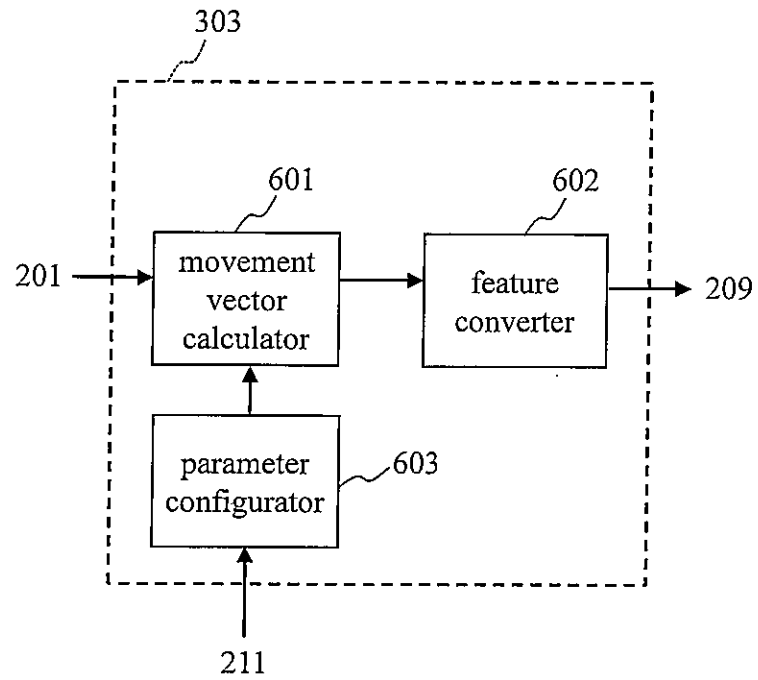


FIG. 7

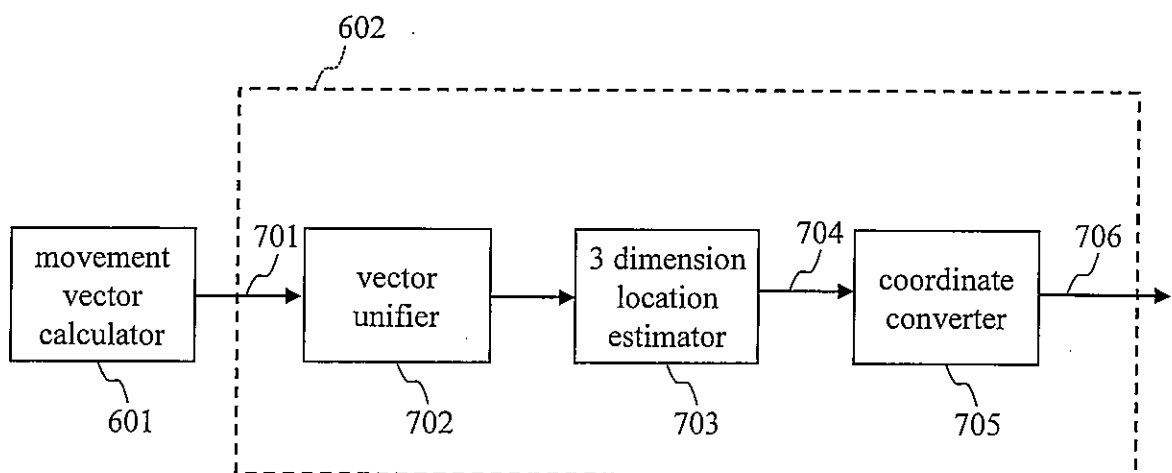


FIG. 8

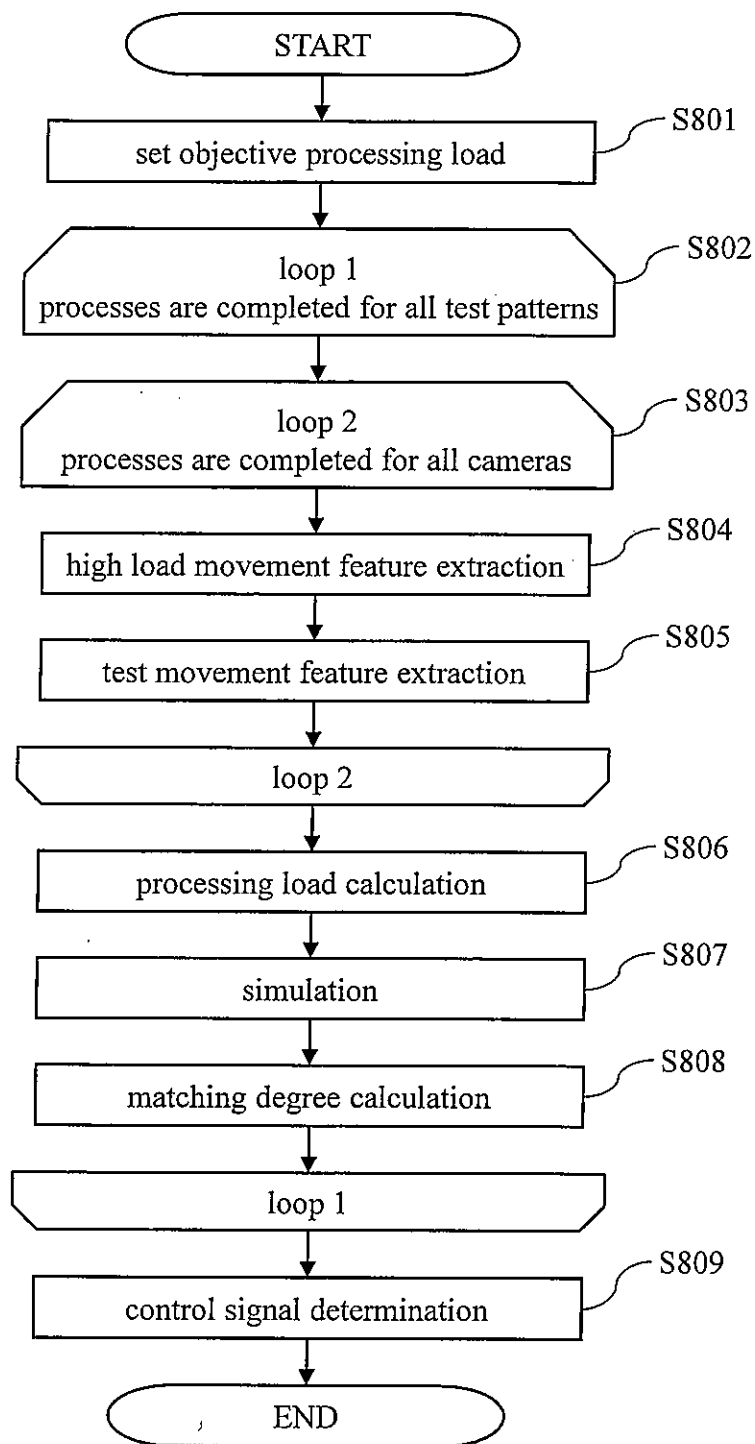


FIG. 9

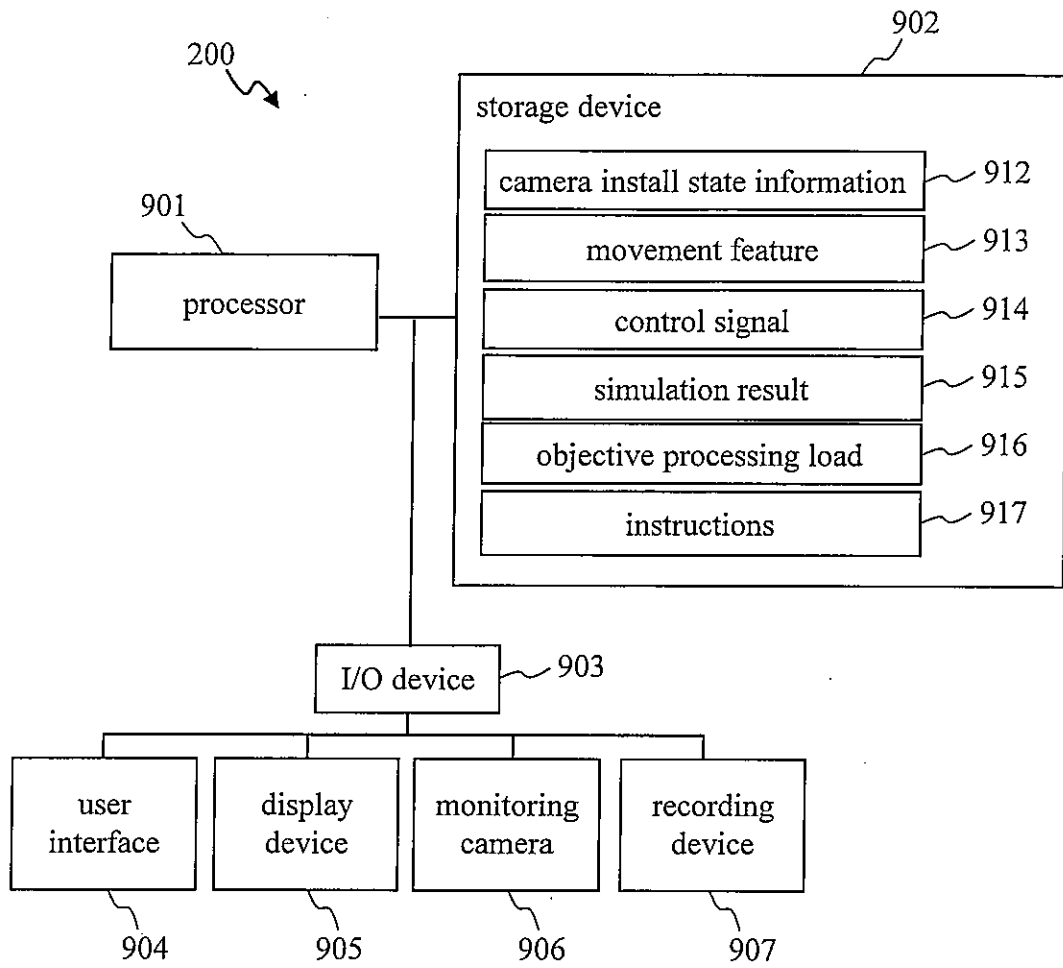


FIG. 10

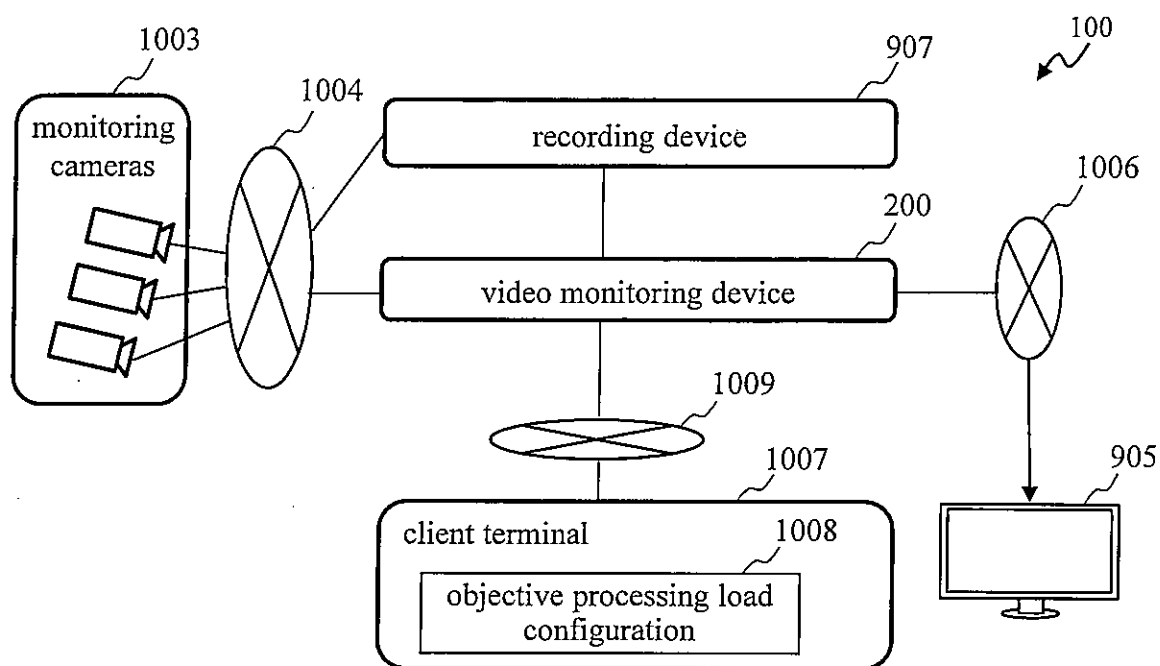


FIG. 11

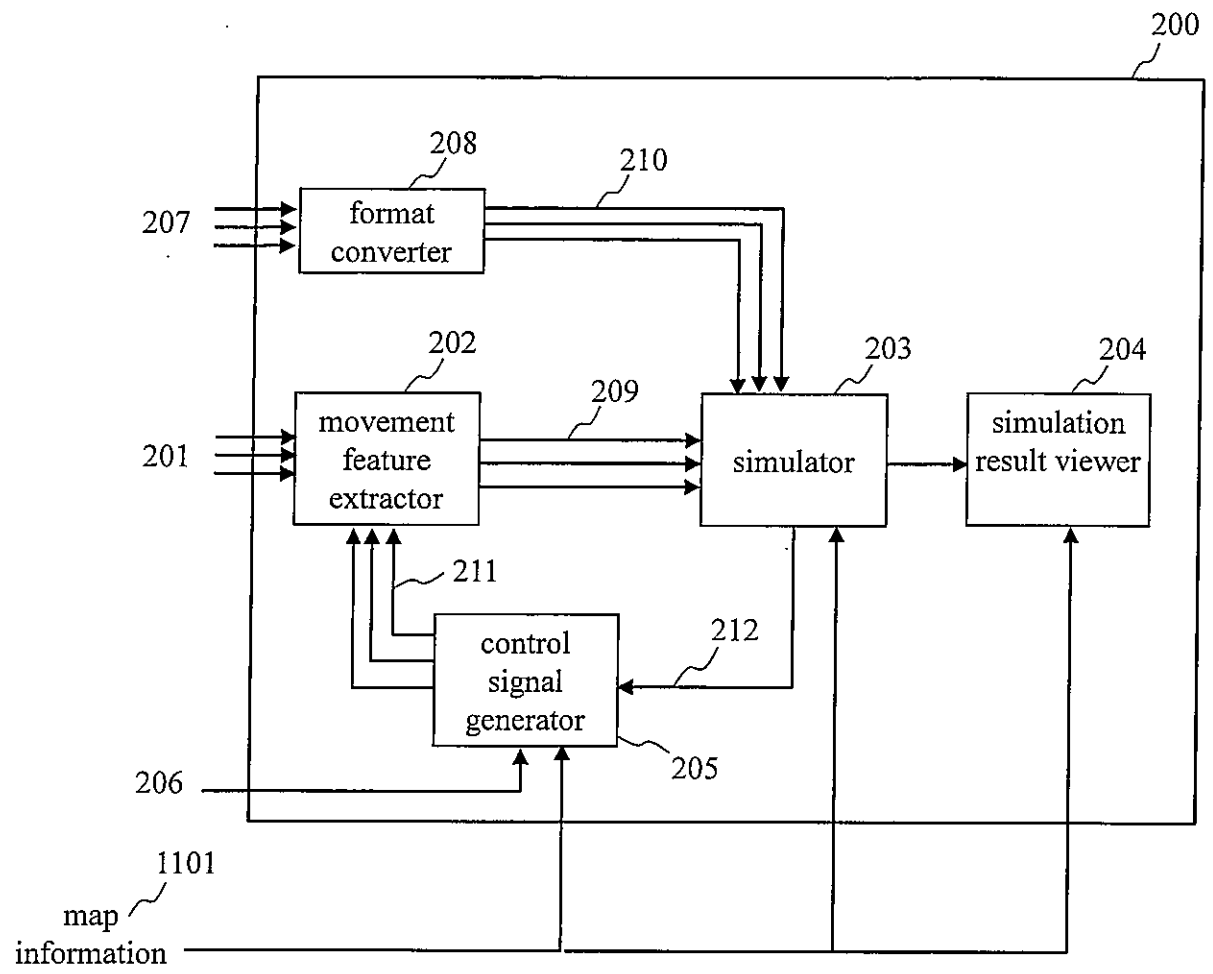


FIG. 12

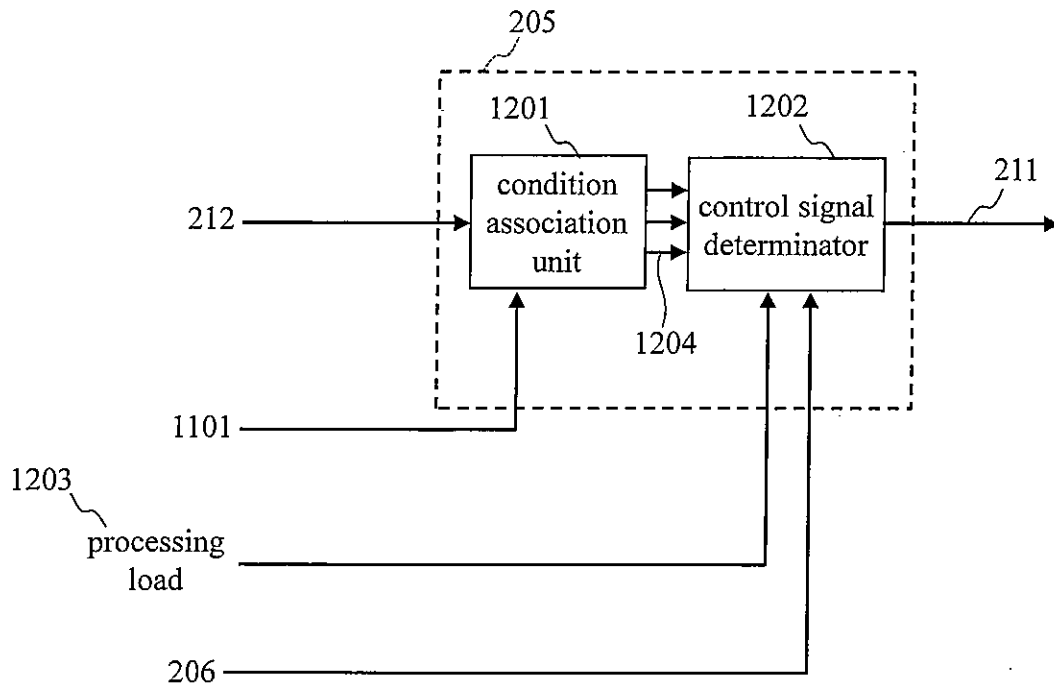


FIG. 13

1300 ↙

configuration pattern	priority	condition	camera A processing load	camera B processing load	camera C processing load
1	1	density of monitored objects at point A is 1.0 [number of objects / m ²] or below	50%	100%	100%
2	2	density of monitored objects at point B is 0.5 [number of objects / m ²] or below	100%	50%	100%
3	3	density of monitored objects at point C is 1.5 [number of objects / m ²] or below	100%	100%	50%
4	4	none of above	25%	25%	25%

FIG. 14

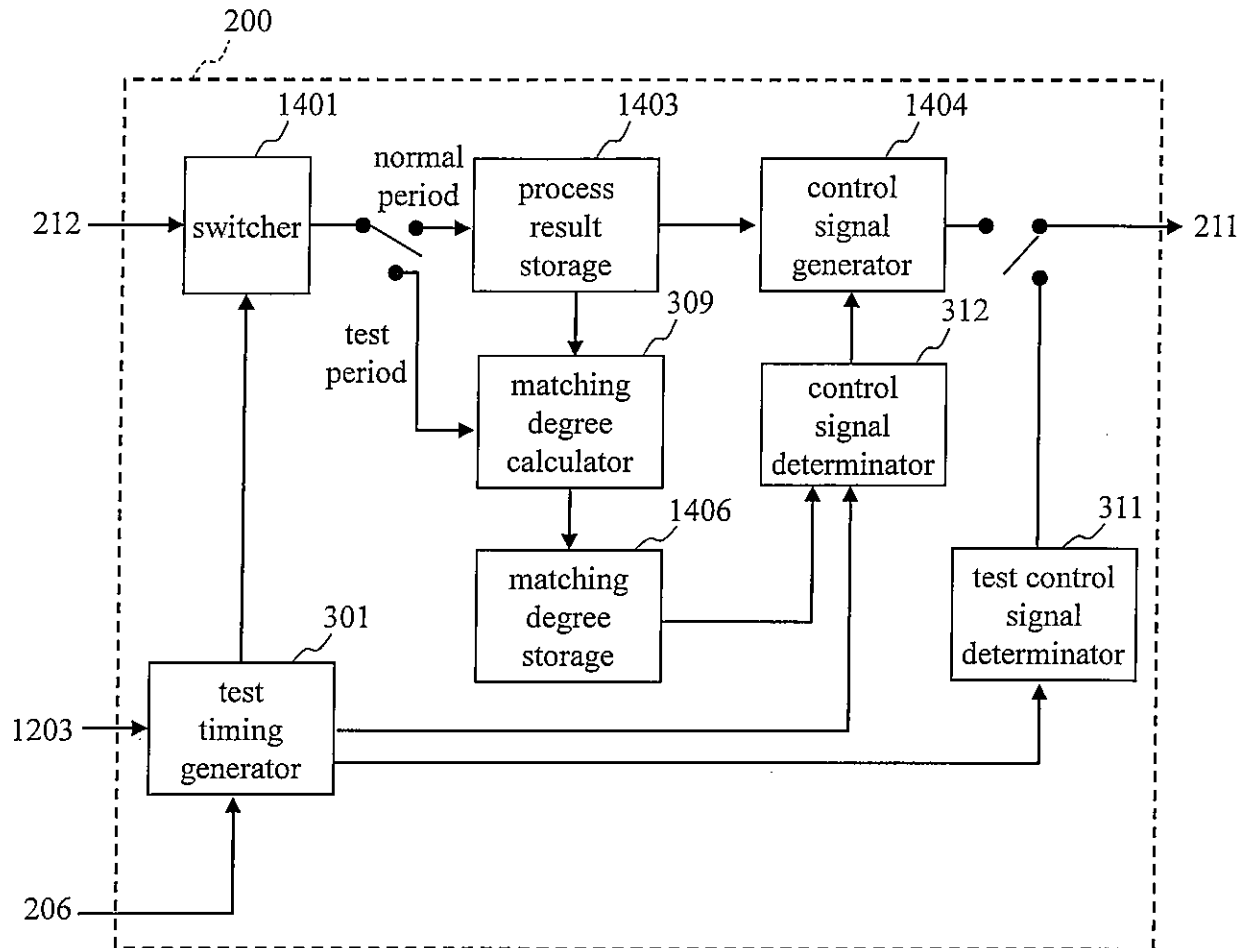


FIG. 15

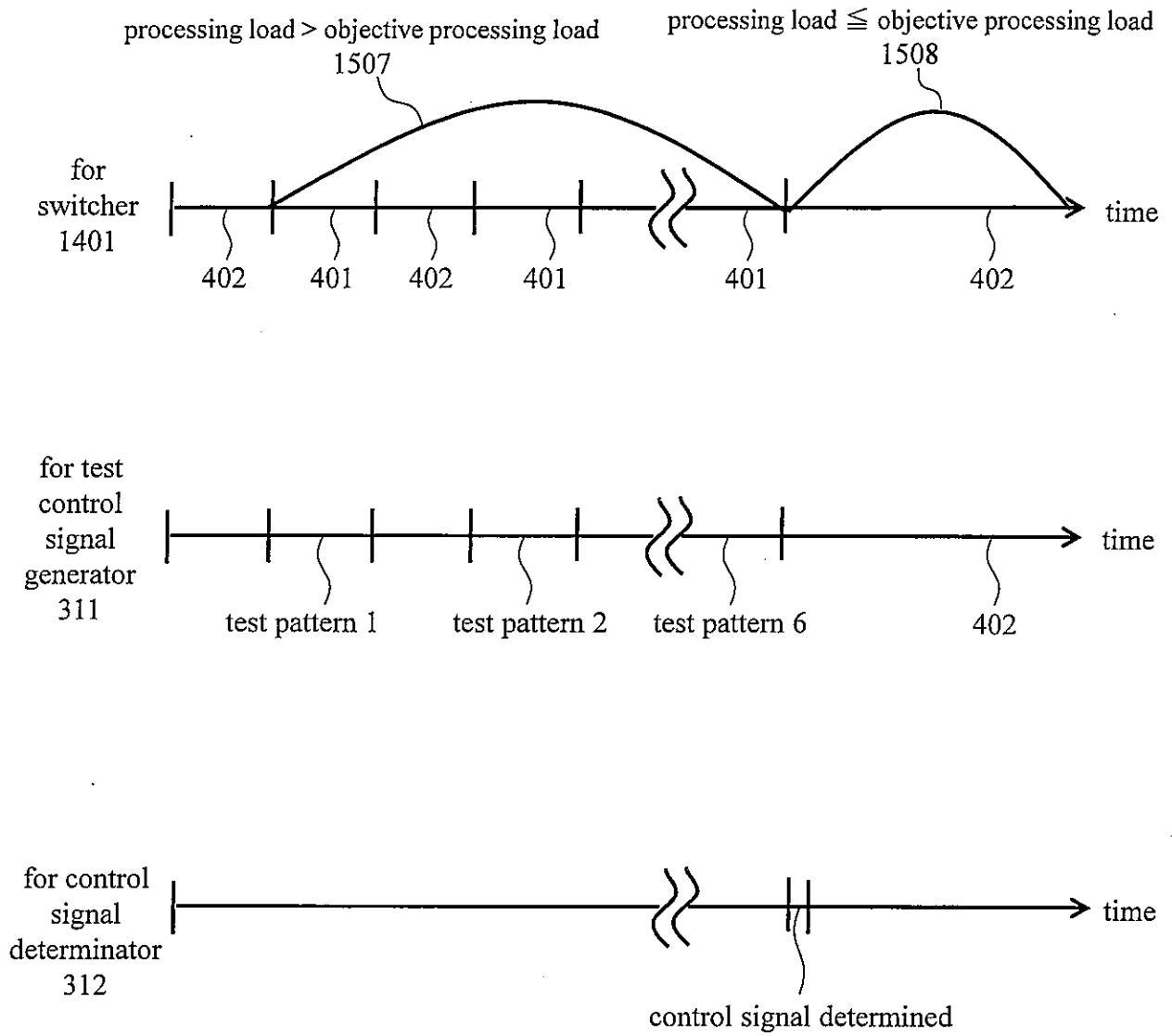


FIG. 16

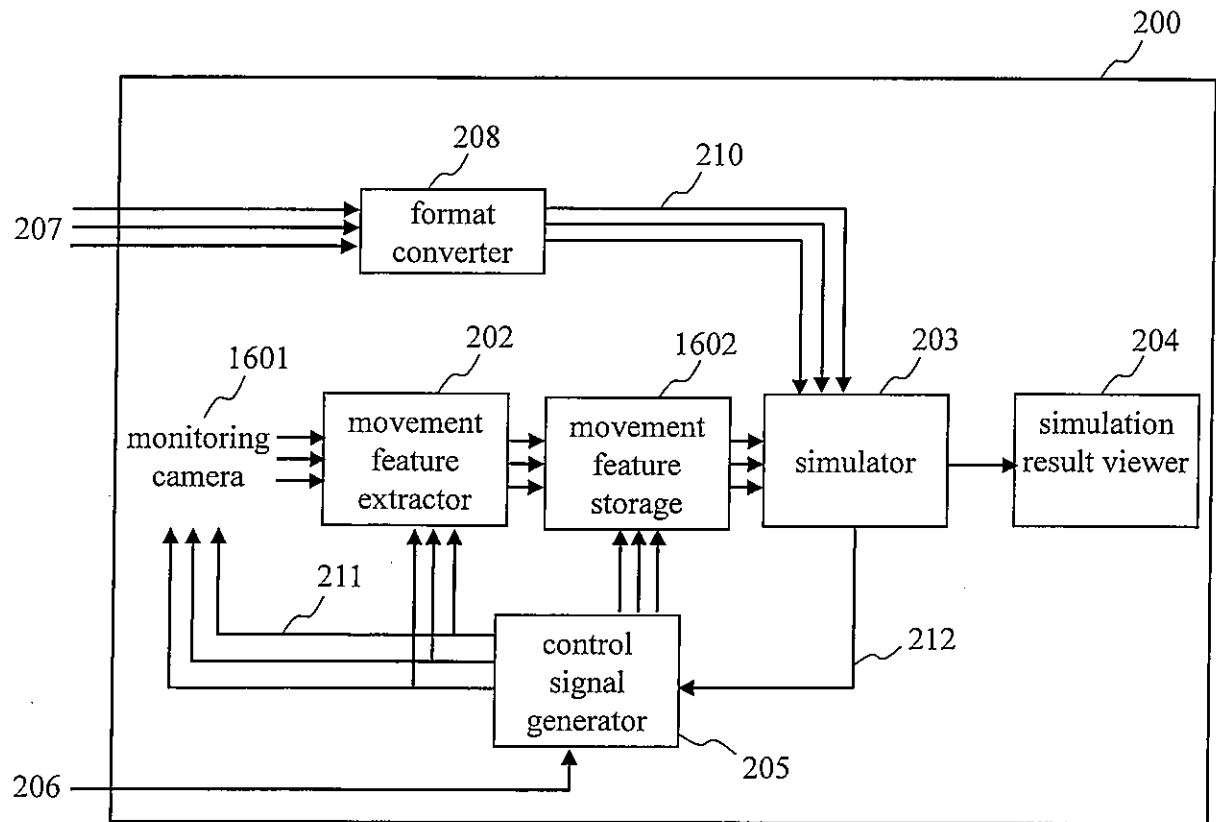


FIG. 17

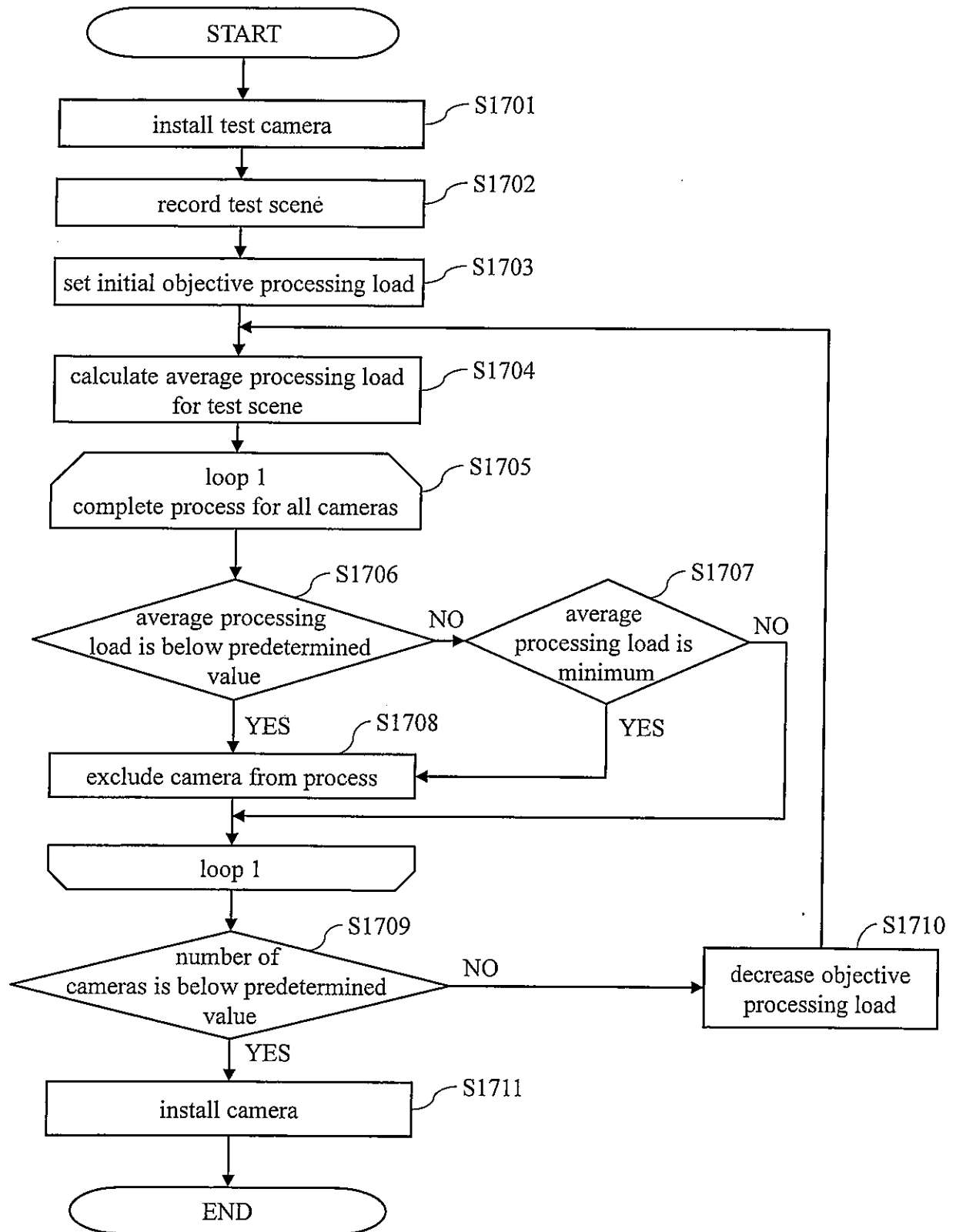


FIG. 18

